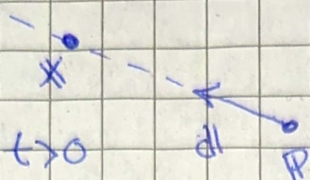


1a - Ray tracing

Ray

$$X = p + td$$



In ray tracing, we're only interested in $t > 0$.

Ray intersection

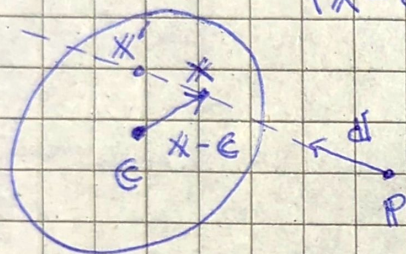
Implicit surface: $f(X) = f(p + td) = 0, \exists t \Rightarrow \text{Hit!}$
 $\neq 0 \forall t \Rightarrow \text{Miss!}$

Ray-sphere intersection

$$f(X) = x^2 + y^2 + z^2 - r^2 = (X - c) \cdot (X - c) - r^2 = 0$$

$$|X - c| = r \Rightarrow \sqrt{(X - c) \cdot (X - c)} = r$$

$$(X - c) \cdot (X - c) = r^2$$



$$f(X) = (X - c) \cdot (X - c) - r^2$$

$$= (p - c + td) \cdot (p - c + td) - r^2$$

$$= \underbrace{(d \cdot d)}_a t^2 + \underbrace{2d \cdot (p - c)}_b t + \underbrace{(p - c) \cdot (p - c) - r^2}_c$$

Two roots $\Rightarrow X, X'$
 One root $\Rightarrow X$ tangent

$$at^2 + bt + c = 0, t_{1,2} = \frac{-b \pm \sqrt{\Delta}}{2a}$$

$$X \text{ is } t = \frac{-b - \sqrt{\Delta}}{2a}$$

$$X' \text{ is } t = \frac{-b + \sqrt{\Delta}}{2a}$$

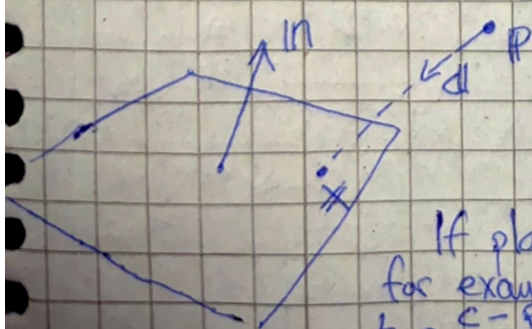
$$\Delta < 0 \Rightarrow \text{Miss!}$$

$$\Delta \geq 0 \Rightarrow \text{Hit!}$$

$$\Delta = b^2 - 4ac$$

Only one we're interested in, because it's smaller
 $X - c$ is surface normal at X .

Ray-plane intersection



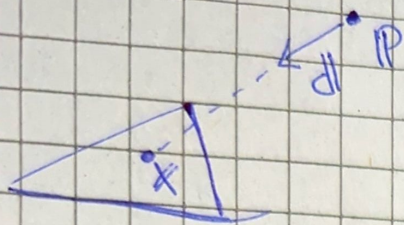
$$f(X) = X \cdot n - c = (p + td) \cdot n - c = 0$$

$$\Rightarrow t = \frac{c - p \cdot n}{d \cdot n}$$

If plane is axis-aligned,
 for example $n = \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}$, then
 $t = \frac{c - p_z}{d_z}$ for the example.

if $d \cdot n = 0$, d is perpendicular to plane.
 need to check for that.

Ray-triangle intersection



We can see the triangle as a plane, and then use the same method for finding the intersection. We however also need to check that the intersection is inside the triangle using barycentric coordinates.

Ray tracing algorithm

for each ray
 for each primitive
 if ray intersects primitive
 if closest hit
 store

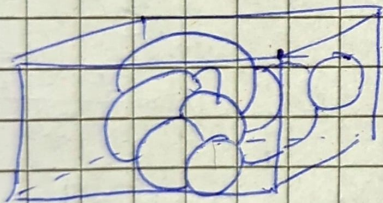
Massively slow



(will be used in project)

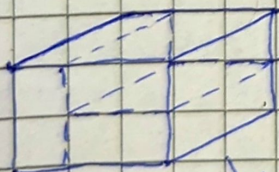
Ray tracing acceleration (acceleration structures/space partitioning)

Axis-Aligned Bounding Box

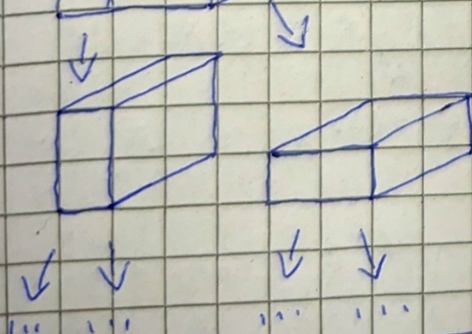


The ray only needs to check if the ray intersects with the box or not.

Bounding volume hierarchy (BVH)



First checks outer box, then inner etc. creates a tree structure, i.e. acceleration structure.



GPU ray tracing (hardware acceleration)

Rasterization

Vertex shader

Rasterization

Fragment shader

Ray tracing

Ray generation
shader

Acceleration
structure
traversal

Miss
shader

Closest
hit
shader

Any hit
shader

Intersection
shader

Software ray tracing on the GPU

Uses the rasterization pipeline to just draw a quad filling the screen. Then we can implement ray tracing in the fragment shader.

Can also interpolate the primary rays in the rasterizer.