

Problem Set 8 Solutions

Problem 1 The BFS (Breadth-First Search) algorithm given in the lecture notes uses multiple lists. Modify the algorithm so that it uses only one queue to replace multiple lists.

Solution:

The main algorithm remains the same. The breadth-first search algorithm starting with a vertex is modified as follows:

```
Algorithm BFS(G, s)
{
  Create an empty queue L;
  L.enqueue(s);
  setLabel(s, VISITED);
  while ( ! L.isEmpty() )
  {
    v = L.dequeue();
    for all e ∈ G.incidentEdges(v)
      if ( getLabel(e) = UNEXPLORED )
      {
        w = opposite(v,e);
        if ( getLabel(w) = UNEXPLORED )
        {
          setLabel(e, DISCOVERY);
          setLabel(w, VISITED);
          L.enqueue(w);
        }
        else
          setLabel(e, CROSS);
      }
  }
}
```

Problem 2 Describe, in pseudo code, an $O(n+m)$ -time algorithm for computing all the connected components of an undirected graph G with n vertices and m edges.

Solution:

```
Algorithm connectedComponents(G)
Input: An undirected graph  $G$ 
Output: All the connected components of  $G$ 
{
  for each vertex  $v$  in  $G$  do
    visited( $v$ )=0;
  i=0;
  for each vertex  $v$  in  $G$  do
```

```

{
  if ( visited(v)=0 )
  {
    create a new list  $L_i$ ; // Each  $L_i$  stores a connected component
    perform the depth-first search or the width-first search starting with v;
    for each vertex u visited in the search do
      { add u to  $L_i$ ;
        visited(u)=1;
      }
    i=i+1;
  }
}

```

Problem 3 Given an undirected graph G and a vertex v_i , describe an algorithm for finding the shortest paths from v_i to all other vertices. The shortest path from a vertex v_s to a vertex v_t is a path from a vertex v_s to a vertex v_t with the minimum number of edges. What is the running time of your algorithm?

Solution: For each vertex v we introduce a list $Q(v)$ to store the shortest path from v_i to v . We can modify the breadth-first search algorithm given in Q1 to compute the shortest path from v_i to v as follows:

Algorithm BFS(G, v_i)

```

{
  for each vertex v of G do
    Create an empty list  $Q(v)$ ;
    Create an empty queue L;
    L.enqueue( $v_i$ );
    setLabel( $v_i$ , VISITED);
    while ( ! L.isEmpty() )
    {
      v = L.dequeue();
      for all e  $\in$  G.incidentEdges(v)
        if ( getLabel(e) = UNEXPLORED )
        { w = opposite(v,e);
          if ( getLabel(w) = UNEXPLORED )
          {
            setLabel(e, DISCOVERY);
            setLabel(w, VISITED);
            L.enqueue(w);
             $Q(w)=Q(v)+\{v,w\}$ ;
          }
        }
        else
          setLabel(e, CROSS);
      }
    }
}

```

The first for loop takes $O(n)$ time, and “ $Q(w)=Q(s)+\{v,w\}$ ” takes $O(1)$ time. Hence, the running time of the algorithm is $O(m+n)$.

Problem 4 A connected undirected graph is said to be biconnected if it contains no vertex whose removal would divide G into two or more connected components. Give an $O(n+m)$ -time algorithm for adding at most n edges to a connected graph G , with $n>3$ vertices and $m>n-1$ edges, to guarantee that G is biconnected.

Solution: Number the vertices 0 to $n-1$. Now add an edge from vertex i to vertex $(i+1) \bmod n$, if that edge does not already exist. This connects all the vertices in a cycle, which is itself biconnected.

Time complexity analysis:

We can use an adjacency list to represent G .

1. It takes $O(n)$ time to number all the n vertices.
2. Adding an edge from vertex i to vertex $(i+1) \bmod n$ takes $O(\text{degree}(i))$ time, where $\text{degree}(i)$ is the degree of vertex i . Since the total degree of all the vertices is $2m$, where m is the number of edges in G . Therefore, the time complexity of adding all the edges is $O(2m)=O(m)$.

As a result, the time complexity of this algorithm is $O(n)+O(m)=O(n+m)$.

Problem 5 An n -vertex directed acyclic graph G is **compact** if there is some way of numbering the vertices of G with the integers from 0 to $n-1$ such that G contains the edge (i, j) if and only if $i < j$, for all i, j in $[0, n-1]$. Give an $O(n^2)$ -time algorithm for detecting if G is compact.

Solution:

Algorithm compactGraphChecking(G)

Input: A directed graph G

Output: true if G is compact; or false

```
{
    Perform topological sorting on  $G$ ;
    Let  $TSN(v_i)$  be the topological number of vertex  $v_i$ .
    for each vertex  $v_i$  in  $G$  do
         $TSN(v_i) = TSN(v_i) - 1$ ;
    Let  $a[0:n-1]$  be an array of all the vertices sorted in increasing order of their topological numbers;
    for  $i=0$  to  $n-2$  do
        for  $j=i+1$  to  $n-1$  do
            if no edge exists from  $a[i]$  to  $a[j]$ 
                return false;
    return true;
}
```

Running time analysis: Topological sorting on G takes $O(n+m)$ time, where e the number of edges of G . The array $a[]$ can be obtained by modifying the topological sorting algorithm without changing its time complexity. The first **for** loop takes $O(n)$ time. The nested **for** loop takes $O(n^2)$ time. Therefore, the total running time is $O(n+m)+O(n)+O(n^2)=O(n^2)$.

Problem 6 An Euler tour of a directed graph G with n vertices and m edges is a cycle that traverses each edge of G exactly once according to its direction. Such a tour always exists if G is connected and the in-degree equals to the out-degree for each vertex in G . Describe an $O(n+m)$ -time algorithm for finding an Euler tour of such a directed graph.

Solution: Hierholzer proposed an efficient algorithm in 1873 which works as follows:

1. Arbitrarily select a starting vertex v .
2. Find a cycle C starting and ending at v such that C contains all the edges going into and out of v , and insert each edge of C into a doubly linked list L in the order of the cycle C .
3. Traverse L to find the first vertex v' which has an outgoing unvisited edge. If such a vertex v' is not found, the algorithm terminates. Otherwise, let (v', v'') be the next edge in L when v' is found, and find a cycle C' starting and ending at v' such that C' contains all the edges going into and out of v' , and insert each edge of C' into L in the order of the cycle such that all the edges of C' appear before (v', v'') in L . Repeat this step starting at the first edge of C' in L .

This algorithm visits each vertex and each edge in $O(1)$ time. Therefore, the time complexity is $O(m+n)$, where m is the number of edges and n is the number of vertices in the graph. Since a directed graph with an Euler tour must be strongly connected, we have $O(m+n)=O(m)$.

Problem 7 An independent set of an undirected graph $G=(V, E)$ is a subset I of V such that no two vertices in I are adjacent. That is, if u and v are in I , then (u, v) is not in E . A maximal independent set is an independent set such that if any additional vertex is added to it, it will not be an independent set. Give an efficient algorithm for finding a maximal independent set for an undirected graph, and analyse its time complexity.

Solution: We can use a greedy algorithm to find a maximal independent set as follows:

1. Create an empty set maxSet .
2. Arbitrarily select a vertex v , and add v to maxSet .
3. Repeat the following until no vertex can be added to maxSet :
 - Find a vertex v' that is in V and not adjacent to any vertex in maxSet , add v' to maxSet .

Time complexity analysis: Assume that the adjacency matrix structure is used to represent the input graph. Adding one vertex to maxSet takes $O(n)$ time. Notice that the maximum size of a maximal independent set is n , where n is the number of vertices in the graph. Therefore, the time complexity of this algorithm is $O(n^2)$.

Comments: The maximum independent set problem is different from this problem, and NP-complete.