



Non-invasive electrical and magnetic stimulation of the brain, spinal cord, roots and peripheral nerves: Basic principles and procedures for routine clinical and research application. An updated report from an I.F.C.N. Committee



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ARTICLE INFO

Article history:

Accepted 1 February 2015

Available online 10 February 2015

Keywords:

Non-invasive stimulation

Transcranial magnetic stimulation

Human cortex

Clinical neurophysiology

HIGHLIGHTS

- This review is an up-date document on basic aspects of non-invasive stimulation of brain, spinal cord and nerve roots.
- The main physiological, theoretical and methodological features of transcranial magnetic stimulation (TMS) are described.
- Instructions for practical use of non-invasive stimulation in clinical applications and research are provided.

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A B S T R A C T

These guidelines provide an up-date of previous IFCN report on “Non-invasive electrical and magnetic stimulation of the brain, spinal cord and roots: basic principles and procedures for routine clinical application” (Rossini et al., 1994). A new Committee, composed of international experts, some of whom were in the panel of the 1994 “Report”, was selected to produce a current state-of-the-art review of non-invasive stimulation both for clinical application and research in neuroscience.

Since 1994, the international scientific community has seen a rapid increase in non-invasive brain stimulation in studying cognition, brain–behavior relationship and pathophysiology of various neurologic and psychiatric disorders. New paradigms of stimulation and new techniques have been developed. Furthermore, a large number of studies and clinical trials have demonstrated potential therapeutic applications of non-invasive brain stimulation, especially for TMS. Recent guidelines can be found in the literature covering specific aspects of non-invasive brain stimulation, such as safety (Rossi et al., 2009), methodology (Groppa et al., 2012) and therapeutic applications (Lefaucheur et al., 2014).

This up-dated review covers theoretical, physiological and practical aspects of non-invasive stimulation of brain, spinal cord, nerve roots and peripheral nerves in the light of more updated knowledge, and include some recent extensions and developments.

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1. Introduction

It has been 20 years since the publication of the first IFCN-endorsed report on “Non-invasive electrical and magnetic stimulation of the brain, spinal cord and roots: basic principles and procedures for routine clinical application” (Rossini et al., 1994). This report has been useful and has been cited 1805 times to date (Google Scholar, 7th December 2014). Over 20 years there have been many developments, some foreshadowed in 1994, some unforeseen. Accordingly, a new Committee has been tasked with updating the report. In 20 years much has been learnt about plasticity of the nervous system in healthy subjects and patients with neurological and neuropsychiatric dysfunction. The development of new techniques, new coils, new stimulus paradigms and the introduction of neuronavigation have rendered research and clinical studies more accurate, more insightful and of greater clinical value. These developments have allowed non-motor areas of the brain to be probed and for non-invasive brain stimulation to be trialled as a therapeutic measure. Comprehensive coverage of the entire field would constitute a sizable monograph and of necessity this Report focuses on those areas of greatest interest to practicing clinical neurophysiologists. Recently published guidelines cover the safety of non-invasive brain stimulation (Rossi et al., 2009), its methodology (Groppa et al., 2012) and therapeutic applications (Lefaucheur et al., 2014).

2. Physiology

Stimulation of the human brain, like the peripheral nerve, involves depolarizing neuronal membranes in order to initiate action potentials. Experience from invasive stimulation during neurosurgery or epilepsy monitoring shows that stimulation parameters for the central nervous system are relatively similar to those needed for peripheral nerve: short pulses with a duration of less than 1 ms and with an amplitude of few milliamperes. Transcranial methods for brain stimulation face the problem of delivering such a stimulus across the high resistance barrier of the periencephalic ‘layers’, including scalp, skull, meninges and cerebrospinal fluid.

Early approaches involved applying high-voltage electric stimuli through electrodes on the scalp. Although a large proportion of the current travels along the scalp between the electrodes, a small portion of the current penetrates the brain and activates neurons. This method, pioneered by Merton and Morton (1980), is known as transcranial electrical stimulation (TES; a term which should be differentiated from the generic term used for any transcranial electrical stimulation method, usually abbreviated as TES, and including those employing weak electric currents, see below). TES did have the huge merit of introducing a neurophysiological technique for studying for the first time excitability and propagation properties along central nervous system fibers in intact and cooperative human beings. However, the fields of application declined rapidly with the introduction of transcranial magnetic stimulation (TMS) in 1985 by Barker et al. (1985) because high-voltage TES is uncomfortable.

Another important electrical stimulation approach, which is not covered in this review, is low-intensity transcranial electrical stimulation using low-intensity currents applied through scalp electrodes (Nitsche and Paulus, 2000). The most common protocol is transcranial direct current stimulation in which a constant current of 1–2 mA is applied continuously for 10–20 min. Currents of this magnitude cannot directly initiate action potentials in a resting cell or its axon; instead they cause small changes in the membrane potential of cell bodies or the axonal terminations of neurons and have been proven to modulate spontaneous firing rates (Nitsche and Paulus, 2011; Paulus et al., 2013; Filmer et al., 2014). This is thought to bias excitability of populations of neurons and influence information transmission in neural networks. Finally, many other techniques of TES have been proposed for more than a century (Guleyupoglu et al., 2013), using, for example, non-polarizing high-frequency pulsed biphasic balanced current (Limoge et al., 1999) or weak brain oscillation-locked alternating current (Reato et al., 2013).

2.1. Transcranial electrical stimulation (TES) using short-duration high-intensity pulses

High-voltage TES delivers a capacitively coupled pulse that has a time constant of 50–100 μ s duration and an electrical potential difference of several hundred Volts using a bipolar electrode arrangement. It produces a brisk sensation because it activates local pain receptors in the skin and causes local contraction of scalp muscles. In the motor cortex, neural stimulation occurs preferentially in the cortex underlying the anode and elicits motor evoked potentials (MEPs) on the opposite side of the body. A single pulse of anodal stimulation delivered on the scalp elicits brain current that enters superficial dendrites of pyramidal neurons of layer 5 and exits in deeper layers where it depolarizes the cell membrane and initiates an action potential. Experiments on primates using surface stimulation of the exposed cortex show that activation occurs in the subcortical white matter, a few nodes distant to the axon hillock region (Ranck, 1975; Amassian et al., 1987). The same is thought to be true in humans for TES (see below). As the action potentials descend to the spinal cord via the pyramidal tract, they can be recorded as a D-wave (D = direct, which reflects direct activation of axons). At higher intensities, the stimulus recruits synaptic inputs to the same corticospinal neurones, causing them to discharge at later intervals. This produces I-waves (I = indirect [synaptic] activation of corticospinal neurons), in recordings of the descending volleys from the spinal cord.

Initial invasive experiments characterised D- and I-waves in monkeys and cats (Adrian and Moruzzi, 1939; Patton and Amassian, 1954; Kernell and Chien-Ping, 1967; Amassian et al., 1987; Edgley et al., 1997) (Fig. 1), and similar data have been obtained in humans by recording the descending activity produced by TES of motor cortex from electrodes inserted into the epidural space of the cervical spinal cord in patients during spinal surgery (Boyd et al., 1986; Berardelli et al., 1990; Burke et al., 1990, 1993; Thompson et al., 1991) and, more recently, in conscious patients implanted for pain control (Di Lazzaro et al., 2004a). The mechanisms that generate I-waves wave are still unclear (Di

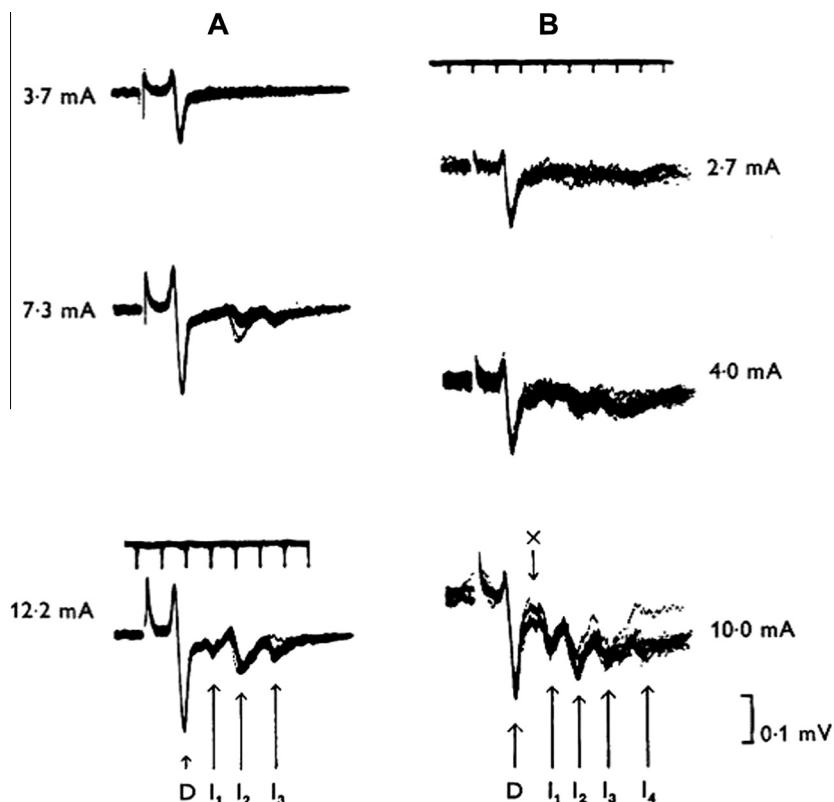


Fig. 1. The pyramidal tract waves (from Kernell and Chien-Ping, 1967 – with permission). The records of Fig. 1 are from two different baboons (A and B, respectively), and they were obtained with an electrode resting on the dorsolateral surface of the cervical spinal cord. Weak stimuli are seen to elicit only a brief single ‘wave’ which has an initial positive and a more prominent negative phase (D-wave). At higher stimulus strengths the D wave attains a greater amplitude, and it is then succeeded by a series of rapidly recurring, smaller, and predominantly negative-going waves (I-waves). The interval between the various waves is of the order of 1–2 ms. The various I waves were numbered according to their latency at strong cortical stimuli, and they are referred to as the I1 (arrow marked “x”), I2, I3 and I4 waves, respectively.

Lazzaro et al., 2004a): why should corticospinal neurones tend to discharge synchronously at a frequency of around 600 Hz? One possibility is that the pyramidal neurones or a class of excitatory input neurones have an intrinsic capacity to discharge repetitively in response to a strong depolarizing input. Such fast spiking neurones have been described in somatosensory cortex (Ozaki and Hashimoto, 2011) in response to electrical stimulation of afferents in peripheral nerves (Baker et al., 2003). Other possibilities are reverberating chains of oscillating interneurons or even separate monosynaptic, di- and tri-synaptic inputs. Detailed neural models that have been developed incorporate both the intrinsic electrical properties of pyramidal cells as well as reasonable estimates of their inputs and can produce high frequency repetitive activity using known cortical circuitry (Esser et al., 2005; Rusu et al., 2014), but the technology to test the models using direct recordings of cortical neurones during stimulation is still being developed (Mueller et al., 2014).

TES at just supra-threshold intensity evokes a very short latency response (around 20 ms) in contralateral hand muscles when they are pre-activated (the motor evoked potential, MEP). Very often no response is seen to the same stimulus in volunteers at rest; only when the intensity is increased do responses regularly occur in relaxed individuals, although these are often 2–3 ms or more later than the earliest onset in active muscle (Rossini et al., 1987a; Day et al., 1989). The reason for this “latency jump” between relaxed and contracted MEPs is that just supra-threshold pulses recruit only a single D-wave, which generates a monosynaptic EPSP onto spinal motoneurons. In resting motoneurons, this EPSP will be insufficient to bring the neuron to threshold. However, if motoneurons are near their discharge threshold, as most of them are during a mild voluntary contraction, they will fire an action potential and

produce a short-latency EMG response in the hand. This hypothesis is partly confirmed by recordings in awake monkeys (Lemon et al., 1998). Recruitment of later I-waves at higher intensities produces a sequence of EPSPs that temporally summate and eventually discharge motoneurons, albeit at a longer latency than the initial D-wave (Day et al., 1989; Rossini et al., 1995). Another – non mutually exclusive – explanation is that the relaxed MEPs mainly reflect the activation of low-threshold, small and slowly propagating pyramidal tract neurones at the cortical level, while the contracted MEPs mainly reflect activation of higher-threshold central and peripheral pyramidal neurones having faster propagations and producing larger action potentials which finally govern large motor units in the target muscle (Liddell and Phillips, 1952; Henneman et al., 1974; Rossini et al., 1995). This issue is still a matter of debate. One should be aware that the volleys recorded from the spinal cord surface in humans do not necessarily reflect those to the target muscle from which the MEPs are recorded.

The repetitive discharge evoked by TES combined with the synaptic relays in the pathway from cortex to muscle makes the electromyographic (EMG) responses to TES (MEPs) more complex than the compound muscle action potential (CMAP) recorded from electrical stimulation of a peripheral nerve (Day et al., 1989). Most of our knowledge has come from examination of TES-induced MEPs in small hand muscles to stimulation of the hand area of primary motor cortex (M1). These MEPs differ from CMAPs in three important respects. First, the threshold for evoking a MEP is lower in actively contracting muscle than it is in muscles at rest. Second, the latency of a MEP evoked at rest is often 1–3 ms longer than a response of the same size evoked in active muscle. Third, the MEP amplitude and shape differ from the peripherally evoked CMAPs. The shape of the MEP becomes polyphasic and the MEP

has a longer duration than the peripherally evoked CMAP, particularly at high intensities of stimulation. The maximal MEP amplitude evoked by a single stimulus is always substantially lower than the maximal CMAP amplitude evoked by supramaximal peripheral electrical stimulation (Rossini et al., 1987a; Day et al., 1989). In contrast to peripherally evoked CMAPs, cortically evoked MEPs show substantial trial-to-trial variability even when extrinsic stimulation settings, such as stimulus intensity and position are kept constant. This variability can be attributed to intrinsic fluctuations of corticomotor excitability, both cortical and spinal.

The reason why the threshold is lower during contraction than at rest is that, in a contracting muscle, spinal motoneurons are firing randomly and the effect of a liminal excitatory input from the corticospinal tract (CST) will be to advance and synchronize the activity of motoneurons that were just about to discharge (see Day et al., 1989). A single TES evoked descending volley can therefore discharge the spinal motoneurons during a tonic contraction while the same volley cannot do so at rest. Resting motoneurons will require a larger descending input to evoke an MEP. The lowest threshold volley evoked by TES is the D-wave initiated in the cortex and its threshold is unaffected by volitional contraction (Di Lazzaro et al., 1998). H-reflex measurements provide further support for a spinal mechanism mediating at least in part the reduction in corticomotor threshold during voluntary contraction of the target muscle (Day et al., 1987).

Regarding factors that contribute to the shorter latency of MEPs under active conditions, one should note that the latency of descending corticospinal volleys recorded from the spinal cord is similar in active and relaxed muscles (Di Lazzaro et al., 1998, 1999b). As noted above, the D-wave evoked during active contraction produces an excitatory input to the spinal motor pool that is capable of recruiting already-firing motor units and produce a MEP. At rest, TES brings spinal motoneurons to threshold at a later time and this accounts for the later onset of MEP in relaxed muscle (Day et al., 1987). If the stimulus intensity is increased, later I-waves are recruited and their excitatory postsynaptic potentials (EPSPs) summate at motoneurons with the EPSP from the initial D-wave, leading to larger MEPs. It is worth noting that with TES, large MEPs tend to have a shorter latency than small MEPs (particularly in relaxed muscle) (Rothwell et al., 1987; Day et al., 1987). This would be in accordance with the size principle of motor unit recruitment, discussed later, such that larger motoneurons with faster conducting peripheral motor axons are recruited in the larger MEP and therefore the latency is correspondingly shorter (Henneman, 1985). However a larger D wave produced by suprathreshold stimuli would also contribute to this.

The final difference between MEPs and peripheral CMAPs is that MEPs are more polyphasic especially at high stimulus intensities. As the intensity of the pulse increases, the number of descending volleys increases, each of which may produce EPSPs in spinal motoneurons. The net effect is that the motoneurons may discharge on receipt of any one of these, leading to temporally dispersed activation of motor units and a polyphasic MEP. In fact, the multiple descending inputs can even cause some single units to discharge twice within the same MEP (Day et al., 1989). This can be confirmed by collision methods. If correctly timed, a supramaximal CMAP can collide with the orthodromic activity in peripheral motor axons set up by a high intensity transcranial pulse. If spinal motoneurons discharge only once in response to the transcranial input, then there should be total collision with the antidromic activity set up by the CMAP. In the EMG, all that will be visible is the CMAP. However, if transcranial or proximal peripheral stimulation made motoneurons fire twice the second discharge of the units will be visible following the CMAP, unless the collision is incomplete due to motoneuron loss (Day et al., 1987; see also Magistris et al., 1999, for application to TMS evoked MEPs). Finally, it is important to remember that

although the initial response of a muscle to TES is caused by activity in rapidly conducting monosynaptic corticospinal projections (the corticomotoneuronal connection), the same stimulus can also activate other slower conducting and probably multi-synaptic inputs. These are often not visible in the EMG because they sit in the “shadow” of the large corticomotoneuronal MEP. However, they can be revealed by using H-reflexes to test motoneuron excitability in response to sub-MEP threshold stimulation in relaxed muscle (Cowan et al., 1986). Following the initial period of excitation, there is often a short period of inhibition, which is probably due to activation of the Ia reciprocal inhibitory interneuron in the spinal cord. This is followed by a longer phase of excitation, some of which might result from the activation of propriospinal interneurons by the initial descending volley (Mazevet et al., 1996; Pierrot-Deseilligny and Burke, 2012).

As mentioned previously both for TES and TMS, there is a clear “latency jump” of about 3 ms when MEPs are recorded in relaxed and contracting MEPs (Merton and Morton, 1980; Merton et al., 1982). The “latency jump” and amplitude facilitation observed in MEPs during contraction vs. relaxation involves a number of mainly spinal mechanisms, presumably including the size principle of motoneuron recruitment (Henneman et al., 1965; Desmedt, 1983; Rossini et al., 1985, 1987a,b).

2.2. Transcranial magnetic stimulation (TMS)

TMS uses electromagnetic induction as a highly effective painless way to generate suprathreshold current in the brain, much as does TES. A simple TMS device consists of a few circular turns of copper wire connected to the terminals of a large electrical capacitance via a switch. The capacitance is discharged by closing the switch so that a large current of several thousands of Amperes flows transiently through the wire coil for a period of less than 1 ms. This large current can have a monophasic or biphasic pulse configuration. The monophasic current pulse consists of a strong initial current which is balanced by a dampened return current. Only the first phase of the stimulus produces current flow in the stimulated brain: the dampened reverse current produces no neuronal stimulation. In biphasic pulse configuration an initial current rise is followed by a reversed current and by a subsequent increase of current: therefore, the current direction is reversed twice during a biphasic pulse. Both phases of the biphasic pulse induce physiologically significant current fluxes in brain tissue, and these flow in the same or opposite direction. Because the reversal phase is longer and wider than the initial rising phase and the second phase is more effective for biphasic TMS (Kammer et al., 2001; Groppa et al., 2012). The monophasic or biphasic current pulse produces a rapidly changing and brief magnetic field at the orthogonal angles to the coil plane. The peak magnetic field strength is similar to that of the static field in a magnetic resonance imaging (MRI) scanner (1–2 T). Magnetic fields readily penetrate into the brain without attenuation by the scalp or skull and generate a current according to the Faraday’s law of electromagnetic induction (Fig. 2). Several comprehensive reviews on the technical aspects of magnetic stimulators are available in the literature and are beyond the scope of the present document (Kammer et al., 2001; Sauve and Crowther, 2014).

2.2.1. TMS coil design (Fig. 3)

TMS was introduced using large circular coils of wire with a diameter of around 10 cm. When a circular coil configuration is used for TMS, stimulation is most effective circularly under the coil with minimal stimulation in the center of the ring. When the circular coil is placed tangentially on the scalp, the site of stimulation covers a large area of brain but the depth of penetration into the brain is small: the intensity of the induced current falls as a matter

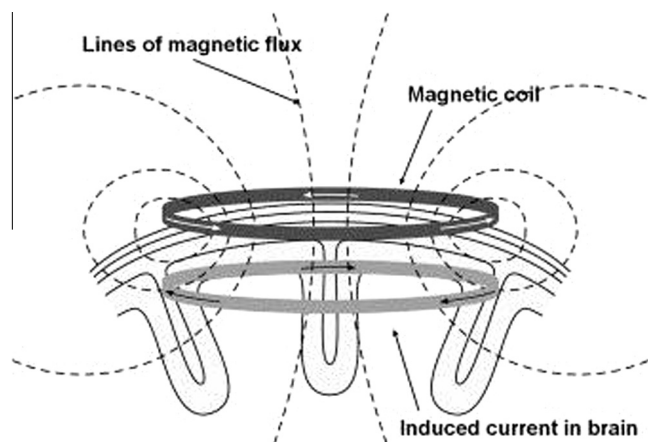


Fig. 2. Illustration of direction of current flows in a magnetic coil and the induced current in the brain (from Hallett, 2007 – with permission). In magnetic stimulation, a brief, high-current pulse is produced in a coil of wire, called the magnetic coil. A magnetic field is produced with lines of flux perpendicular to the plane of the coil, which ordinarily is placed tangential to the scalp. The magnetic field can be up to about 2 T and typically lasts for about 100 μ s. An electric field is induced perpendicularly to the magnetic field. The voltage of the field itself may excite neurons, but the induced currents are likely to be more important. In a homogeneous medium, spatial change of the electric field will cause current to flow in loops parallel to the plane of the coil, which will be predominantly tangential in the brain. The loops with the strongest current will be near the circumference of the coil itself. The current loops become weak near the center of the coil, and there is no current at the center itself. Neural elements are activated by the induced electric field by two mechanisms. If the field is parallel to the neural element, then the field will be most effective where the intensity changes as a function of distance. If the field is not completely parallel, activation will occur at bends in the neural element.

eight coil is classically used to stimulate a given brain region more selectively, for example in the context of therapeutic applications of TMS or for brain mapping. The smaller the diameter the more focal the TMS and the more rapidly the coil heats up during repetitive stimulation. Recent reviews have addressed this issue, comparing the various types of coil used in TMS practice (see Peterchev et al., 2013; Deng et al., 2014; Mueller et al., 2014).

2.2.2. TMS recruits I-waves at lower thresholds than D-waves

Most of the basic principles discussed earlier for TES are also valid for TMS. However, there is one important difference between TMS and TES. TMS of the motor cortex tends to activate I-waves at lower intensities than the D-wave, although this depends on coil orientation (Di Lazzaro et al., 2004a).

Most of the reported data comes from motor cortex stimulation, and the most direct evidence comes from epidural recordings from the spinal cord in conscious patients. They show that the earliest wave recruited by TES, the presumed D-wave, is not recruited at threshold by a TMS pulse. Dependent on coil orientation, TMS of the motor cortex evokes a wave corresponding to the I1 wave, and the D-wave is only recruited at intensities much greater than threshold. The resulting effect of this can be observed in MEP recordings. When MEPs are recorded in voluntarily activated muscle, the minimal latencies can be measured, and MEP latency at just-suprathreshold intensities is usually approximately 1.5 ms longer than the latency of similar-sized MEPs evoked by TES. At higher intensities, the latency to TMS shortens and becomes equal to TES, because the stronger TMS evokes D-waves (Day et al., 1989; Di Lazzaro et al., 2004b). Whether this concept generalizes to all areas of cortex is unknown, and more research on non-motor areas should be carried out. Even in the motor cortex there is some debate over the extent to which this is true for TMS of the leg area as compared with the arm area. Early studies that used the same single motor unit and surface EMG approaches in the tibialis anterior muscle suggested that, in contrast to stimulation of the hand area, TES and TMS of the leg area both evoke D-waves (Priori et al., 1993; Terao et al., 1994; Nielsen et al., 1995). However, recordings from the thoracic cord suggested that TMS tended to evoke I-waves rather than D-waves (Di Lazzaro et al., 2001b; Terao et al., 2000).

2.2.3. What and where does TMS stimulate?

Both TES and TMS stimulate axons rather than cell bodies of neurons since the latter have a much longer electrical time constant and higher threshold. This has been confirmed experimentally by comparing the strength–duration (S–D) time constants of peripheral nerve and cortex. Measurements made with varying durations of electrical pulses yield similar S–D time constants for both nerve and cortex suggesting that their targets are large diameter myelinated axons (Burke et al., 2000). Two key features need to be considered. The first is that the currents induced in the brain by TMS (and TES) have an important directional component. In the case of TMS, early modeling studies of the induced electric field showed that charge build-up at surface boundaries makes the majority of induced current flow parallel to the surface of the brain, rather than perpendicular to the grey matter (Tofts and Branston, 1991). The second concept is that the threshold for stimulation of neurons depends strongly on the relative current direction: axons are best stimulated by that component of current that flows nearly in parallel with their main orientation. This explains why electrical stimulation occurs best with the anode and cathode placed along the length of a peripheral nerve rather perpendicular to it. In fact, the physics of nerve stimulation state that if we take an axon, then it will be best activated at the point where the second spatial derivative of the electric field along its length is maximal. With respect to TMS, this means that

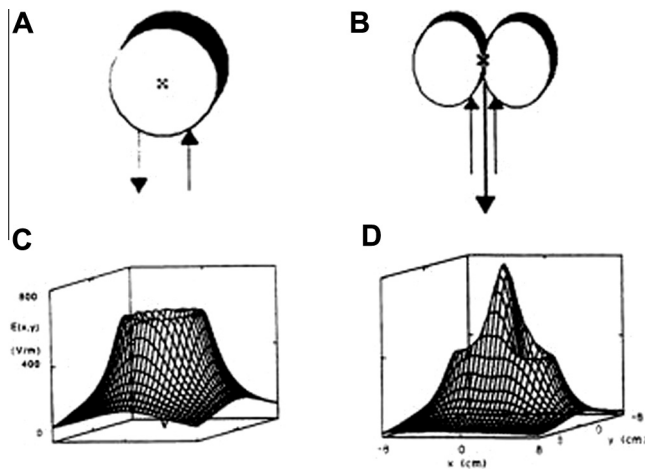


Fig. 3. Magnetic coil shape determines the pattern of the electric field (from Hallett, 2007 – with permission). Two magnetic coils with different shapes (A and B) and their resultant electric fields (C and D).

of distance following a mathematical function; for instance, at a given strength of stimulation, the resulting current intensity induced 5 cm from the coil surface is only about 1/3 of the peak value (Mills et al., 1987). Thus, the stimulation of deep structures always comes at the cost of stimulation at higher intensity of the more shallow ones using “classical” coils. This problem has not been solved even by specific coils which have been designed to stimulate deep structures, such as the “H-coil” (Zangen et al., 2005). Shallower stimulation will result in a concurrent and more intense focal neural stimulation, achieved by overlapping two small round coils with oppositely directed currents into a figure-of-eight shape (Ueno and Matsuda, 1992). The figure-of-

stimulation often occurs at the point where the axon bends out of the field and the change in electric field is greatest (Maccabee et al., 1993). Thus EMG responses to TMS at just supra-threshold intensities are usually 1.5 ms or so later than after TES. At higher intensities, the latency to TMS shortens and approaches that of TES when TMS finally evokes D-waves (Di Lazzaro et al., 2004b). Detailed modeling studies of the electric field distributions induced by TMS in realistic models of the brain are still being undertaken (Thielscher et al., 2011; Laakso et al., 2014a, 2014b).

Day et al. (1989) initially argued that with TMS stimulation is most likely to occur in the part of the motor cortex nearest to the scalp surface, which would correspond to the crown of the anterior bank of the central sulcus. If TMS induced horizontal current flow through this region, then it would be unlikely to activate pyramidal neurons directly (and evoke D-waves). Instead, it was postulated that TMS might preferentially activate horizontally oriented axons of cortical interneurons that activated pyramidal neurons trans-synaptically (I1-waves). Later, imaging studies have suggested that this assumption was erroneous, because motor cortex TMS evoked activation deep in the central sulcus using PET assessment (Fox et al., 2004) or distant from the site of stimulation using fMRI assessment (Bestmann et al., 2004). However, these results do not allow identification of the precise location of TMS-induced axonal activation, because this site may be different from the neural structures identified by functional brain imaging. The biological effect depends on the neuronal circuits that are finally recruited and can be anatomically different from the site where axons are activated by the TMS-induced electrical field. An example is seen with the analgesic effects resulting from motor cortex stimulation (Lefaucheur, 2013). Therefore, modeling studies may be more relevant than imaging studies to determine where TMS activation occurs in the brain. Several detailed modeling studies, mostly of motor cortex stimulation, have taken into account tissue inhomogeneities in the cortex as well as boundaries between cerebrospinal fluid (CSF/grey and grey/white matter), and have shown that induced electric fields are strongest in the crown of the gyrus, although there can also be hot spots within the subcortical white matter (Opitz et al., 2013). When this type of calculation is combined with models of typical varieties of cortical and subcortical neurons, it seems likely that TMS of the motor cortex will activate cortical interneurons in the gyral crown or lip of the sulcus, as well as pyramidal neurons in the lip of the sulcus or slightly deeper (Salvador et al., 2011; Opitz et al., 2013). Excitation threshold depends on the orientation and membrane properties of the axons impacted by the TMS-induced electrical field. The influence of subcortical white matter activation remains to be studied in detail, but could well be important since the subcortical white matter is primarily composed of the axons of cortico-cortical loop fibers which may well have strong connections to the corticospinal output neurons. Indeed, another modeling study has proposed that the activation site in TMS involves the crown, anterior bank and white matter (Laakso et al., 2014a). The results of imaging studies employing neurovascular coupling reflect the cumulative effects of TMS over several seconds, not merely the one triggered by the initial part of the stimulus as reflected in the MEP, and prudence should be employed in considering the conclusions of such studies.

2.2.4. Stimulation with TMS is directionally specific

When a figure-of-eight TMS coil is placed over the hand area of motor cortex, thresholds from a monophasic stimulator are lowest when the coil is oriented to produce an approximately posterior–anterior (PA) current flow perpendicular to the central sulcus (Werhahn et al., 1994; Sakai et al., 1997). Recordings of descending corticospinal activity from the spinal epidural space suggest preferential recruitment of the first I-wave (I1-wave) (Di Lazzaro et al., 2001c). If the coil orientation on the scalp is reversed to

induce an anterior–posterior (AP) current then the first recruited I-waves often occur 1–3 ms later (Di Lazzaro et al., 2001c). Similar differences in latency are evident in the surface EMG recorded MEPs (Werhahn et al., 1994; Sakai et al., 1997). It is not clear whether the late I-waves from AP stimulation are the same late I-waves as recruited by higher intensity PA current (Di Lazzaro and Ziemann, 2013). Nevertheless, changing the current direction seems to recruit different inputs to the corticospinal output neurons. Orienting the coil to induce a latero-medial current reduces the threshold for D-wave activation (Di Lazzaro et al., 1998). All these differences are less evident at higher intensities of stimulation. Interestingly, the extent to which they are present differs between individuals, possibly meaning that they depend on details of individual neuroanatomy and tissue anisotropy, such as the orientation and location of neurons relative to the TMS coil; needless to say, this aspect is valid for any type of cortical area and not only for the motor cortex. Models of electric fields induced by TMS can account for some of this selectivity and have been recently implemented (Rotem et al., 2014). They show that larger fields are induced in the crown of the precentral gyrus by perpendicular than parallel stimulation. However, they do not readily explain why there is a difference between PA and AP stimulation, particularly if TMS primarily activates horizontal interneurons at the gyral surface (Salvador et al., 2011; Day et al., 1989). This is because these neurons are distributed isotropically and therefore should be equally well activated by both AP and PA directionality of TMS. Since this cannot be the case, it suggests that some other (at present unknown) elements are stimulated preferentially by PA stimulation.

These observations relate to monophasic magnetic pulses, which are commonly used for single-pulse experiments, while repetitive TMS (rTMS) is usually performed with biphasic stimuli because of a lower energy requirement (Sommer et al., 2006). Biphasic stimulation is thought to be more powerful than monophasic stimulation, in particular in producing motor evoked potentials (MEPs) (Kammer et al., 2001). However, rTMS using monophasic pulses activates a relatively uniform population of neurons and could therefore be more effective in producing sustained after-effects than biphasic pulses which generate a more complex pattern of neural activation. For example, MEP size reduction following 1 Hz-rTMS delivered over M1 (Taylor and Loo, 2007) and MEP enhancement following 10 Hz-rTMS (Arai et al., 2007) are more marked and prolonged when monophasic pulses are used. Importantly, the effects of monophasic and biphasic magnetic pulses can be compared only if the second and decisive phase of the biphasic pulse is taken as the equivalent of the initial monophasic pulse (Di Lazzaro et al., 2001a; Sommer et al., 2013). Studies may be confusing when the initial phase of the biphasic pulse is retained for comparison, also given that the direction of the current can be reversed depending on the manufacturer (Kammer et al., 2001).

3. TMS in clinical settings

TMS of the motor cortex has a well-established role in clinical neurophysiology and is used worldwide to assess the conduction of the descending cortico-nuclear and cortico-spinal connections (Table 1). The motor cortex is a favoured target area for neuroscientific studies because changes in motor activation and excitability can be readily assessed by recording MEPs. Neurophysiological measures, such as corticomotor threshold (MT), MEP amplitude and latency, Cortical Silent Period (CSP) duration, Central Motor Conduction Time (CMCT) or MEP recruitment curves among others, can be used to provide evidence of disease-related changes in motor cortical control or corticospinal output in patients.

Table 1
Neurophysiological measurements in various neurological disorders.

Neurological disorder	MEP amplitude	CMCT	MT	CSP
Multiple sclerosis	Reduced	Increased	Increased	Prolonged
Stroke	Reduced	Increased	Increased or reduced	Shortened or prolonged*
Cervical myelopathy	Reduced	Increased	Increased	Shortened
Amyotrophic lateral sclerosis	Reduced	Increased	Increased (late) reduced (early)	Normal or shortened
Parkinson's disease	Facilitated (r)	Normal	Normal	Shortened
Dystonia	Normal (r) facilitated (a)	Normal	Normal	Shortened
Cerebellar ataxias	Normal or reduced	Increased	Increased	Prolonged
Epilepsies	Normal or reduced	Normal	Normal, reduced or increased	Normal, shortened or prolonged

MEP, motor evoked potential; CMCT, central motor conduction time; MT, motor threshold; CSP, cortical silent period; (r), at rest; (a), during activation.

* CSP duration is variable in stroke, depending on the site of the stroke. The CSP is typically shortened if M1 is affected, but often grossly prolonged if areas outside M1 (e.g. S1 or parietal cortex) are affected.

Table 2
Normative values of motor threshold (MT) obtained for a group of 50 healthy subjects (modified from Rossini et al. (1994)).

Muscle	MT (%)
Deltoid	50–60
Biceps	50–60
Extensor digitorum brevis	38–45
Thenar*	39–46
Recti abdomini	55–65
Quadriceps	60–80
Tibialis anterior	60–80
Soleus	70–90
Abductor hallucis**	55–75
Anal sphincter	75–100
Bulbo-cavernosus	75–100

Threshold is expressed as a percentage of the maximal stimulator output (%) connected to a circular coil of 7 cm diameter.

* In young subjects (18–44 years) = $39.4 \pm 3.5\%$ S.D.; in elderly subjects (45–80 years) = $44.2 \pm 6.1\%$ S.D.

** In young subjects (18–44 years) = $56.3 \pm 6.7\%$ S.D.; in elderly subjects (45–80 years) = $66.2 \pm 10.1\%$ S.D.

However, as for any other neurophysiological variables, each laboratory needs to establish its own normative data set for reliable diagnostic testing in clinical practice.

4. Motor threshold

In clinical practice and in scientific studies, the intensity of TMS is individually adjusted to the “cortical” Motor Threshold (MT) defined as the minimal intensity of motor cortex stimulation required to elicit a reliable MEP of minimal amplitude in the target muscle. Lowest thresholds are found for hand and forearm muscles, followed by progressively higher thresholds for truncal, lower limb and pelvic musculature (Tables 2 and 3). Face musculature can also be examined, but this is more difficult because the facial nerve and muscles can be directly stimulated in the TMS-induced electrical field, resulting in contamination of “cortical” MEPs by “direct” peripheral neuromuscular responses and facial muscle reflexes (i.e. blink reflex).

As previously stated the MT can be defined as the lowest transcranial stimulus intensity at which TMS of motor cortex produces an EMG response in the ‘target’ muscle or a visible muscle twitch. However, even if a twitch-based MT estimation is easier to perform, MT determination based on this is discouraged because it is associated with high intra- and inter-rater variability. In addition, visually estimated twitch-based MTs are approximately 10% (0–30%) higher than MTs determined on EMG recordings (Westin et al., 2014).

Intrinsic fluctuations of the excitability of cortical and spinal neurons cause trial-to-trial variability in MEP amplitude. This “physiological noise” introduces some uncertainty when

estimating the MT (Adrian and Moruzzi, 1939). While physiological noise cannot be eliminated, other technical and physiological variables can and should be kept constant during MT measurements, such as coil position and orientation, the motor state (e.g. background activity of the target muscle), the individual arousal level, and environmental noise. Before determining MT, the optimal position and orientation of the coil for stimulation of the target muscle has to be identified (cf. sections on mapping and basic physiology).

4.1. Determining the “cortical” motor threshold

Resting MT (RMT) is determined while the target test muscle is at rest. Complete relaxation can be controlled by checking the absence of EMG at high-gain amplification either visually or by acoustic feedback or both. Active MT (AMT) is usually determined during a slight tonic contraction of the target muscle at approximately 20% of the maximal muscle strength. The active MT corresponds closely to the threshold for inducing descending volleys in the fast-conducting neurons of the corticospinal tract. This is because the first recruited descending volleys are able to effectively discharge those spinal motoneurons that are close to firing threshold in an active condition.

MEP responses to individual, successive stimuli when elicited in active muscles using threshold intensities may fluctuate in amplitude from 0 to about 1 mV, with a median value around 0.2 mV. If relaxed, variability is less, around 0–0.5 mV.

The following procedure is recommended to define the MT precisely using a figure-of-eight coil (see also Groppa et al., 2012) (Figs. 4 and 5). Localize the “hot spot” with the coil on M1 contralateral to the examined limb (cf. section on mapping). The lowest threshold for the hand area can usually be determined by orienting the coil 45° towards the contralateral forehead in order to guarantee current flow approximately perpendicular to the central sulcus. Orientation is at least as critical as position (Sakai et al., 1997; Opitz et al., 2013). For stimulation of the foot area (abductor hallucis muscle) a lateral orientation of the handle of the butterfly or figure-of-8 perpendicular to the interhemispheric cleft (i.e. lateral) produces the highest MEP amplitudes and shortest latencies. However Richter et al. (2013) report that rotating the coil ~30° anteriorly results in a MT that is lower by $8.0 \pm 5.9\%$ of maximal stimulator output compared with the standard lateral orientation.

The following methods have been used for MT determination.

4.1.1. Relative frequency methods

The relative frequency method has been described in the 1994 “Report” (Rossini et al., 1994) and recently modified slightly (Groppa et al., 2012): TMS should start with a subthreshold intensity. One may start with a stimulus intensity of 35% of the maximal stimulator output (MSO) with the coil placed over the optimal site for stimulation. To determine RMT, stimulus intensity is gradually increased in steps of 5% MSO until TMS consistently evokes MEPs

with peak-to-peak amplitudes of $>50 \mu\text{V}$ in each trial. Thereafter, stimulus intensity is gradually lowered in steps of 1% MSO until there are less than 5 positive responses out of 10 trials. This stimulus intensity plus 1 is then defined as RMT. In active muscles with ongoing activity, MEPs greater than 0.1 mV (100 μV) are judged to be positive. Of note, an analogous procedure for MT determination has been used in classic physiology with direct cortical stimulation in experimental preparations (Patton and Amassian, 1954). The procedure is more complicated for AMT than RMT, since TMS interferes with the ability to maintain a steady muscle contraction with stable background EMG activity of 10–20% of maximal contraction (Rossini et al., 1995). As with any other method, accuracy increases with the number of stimuli per intensity level.

However, when using at least 5 positive MEPs out of 10 trials (Groppa et al., 2012) it has been calculated that measurement accuracy, defined as “probability to obtain a diagnostically acceptable estimator for this subject exceeds 0.95” (Awiszus, 2012), is only 47.6%. With 10 MEPs out of 20 trials (Rossini et al., 1994) accuracy is 96.2% (Awiszus, 2012). On this basis it can be said that for both for clinical and research purposes 10 out of 20 trials are required to produce reproducible results.

Table 3
Summary of different MT normative measurements (modified from Mills and Nithi (1997)).

Muscle	Age	MT% (M \pm SD)	References
FDI	39.6 \pm 13.8	48 \pm 6	Maertens de Noordhout et al. (1992)
ADM	–	56 \pm 7.2	Reutens and Berkovic (1992)
ADM	12–49	55.8 \pm 12.9	Reutens et al. (1993)
APB	–	61.3 \pm 9.6	Valls-Solé et al. (1994)
R APB	–	38.5 \pm 6	Triggs et al. (1994)
L APB	–	41.6 \pm 7	Triggs et al. (1994)
ADM	–	50.4 \pm 8.3 (range 33–67)	Di Lazzaro et al. (1994)
FDI	–	– (range 41–83)	Ridding et al. (1995a)
APB	16–35	39.4 \pm 3.5	Rossini et al. (1992)
APB	51–86	43.9 \pm 6.4	Rossini et al. (1992)
ADM	28–47	49 \pm 8	Macdonell and Donnan (1995)

MT%, motor threshold expressed as a percentage of maximal stimulator output; M, mean; SD, standard deviation; FDI, first dorsal interosseous; ADM, abductor digiti minimi; APB, abductor pollicis brevis; R, right; L, left.

4.1.2. Adaptive methods

Adaptive methods use an S-shaped metric function to model the probabilistic nature of MT and the relationship between TMS intensity and the probability of eliciting a MEP. At each trial, the model recalculates by an adaptive stair-case procedure a TMS intensity that yields a 50% probability of evoking a MEP which is then selected as the intensity for the next TMS pulse. Examples of adaptive methods to determine the MT are Parameter Estimation by Sequential Testing (PEST) (Awiszus, 2003) and Maximum Likelihood Regression. A computer program is necessary to run the maximum-likelihood threshold tracking algorithm, and was made freely available by Awiszus and Borckardt (“Adaptive PEST” <http://www.clinicalresearcher.org/software.htm> (Mishory et al., 2004)).

As summarized recently (Groppa et al., 2012), a typical program starts with defining an upper and lower boundary. A conservative approach uses 0% of MSO as lower boundary and 100% as upper boundary. More effectively, one might select the boundaries based on the known threshold distribution in the target population (e.g. $\pm 20\%$). 14 up to 17 stimuli without specific *a priori* assumptions have been calculated to be necessary for reliable MT estimation (Awiszus, 2011). In the only study carrying out a comparative analysis for adaptive methods (Silbert et al., 2013) it was concluded that the relative frequency method requires significantly more trials than the PEST method (see below). The median difference between PEST and relative frequency estimates of MT was 2.3% of MSO with a maximal individual difference of up to 5%: higher MTs were found for PEST (Silbert et al., 2013).

As a conclusion, each of the methods described above can be used in research or clinical settings to provide a sufficiently accurate MT estimation. However, adaptive methods based on threshold-tracking algorithms provide a more accurate and usually faster MT estimation because it may require a smaller number of stimuli (Awiszus, 2011; Qi et al., 2011).

5. MEP amplitude

The MEP is commonly recorded over the target muscle using surface electrodes in a bipolar belly-tendon arrangement. The placement of the electrodes and the filter and amplification

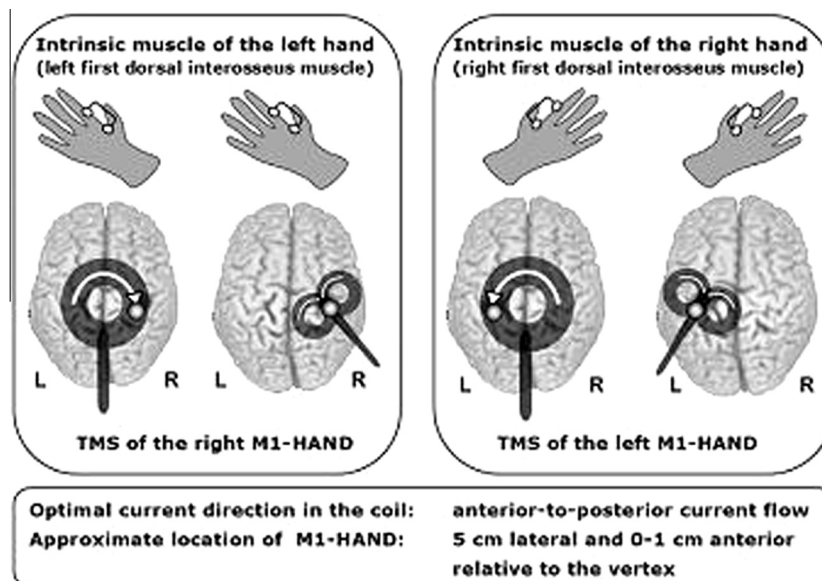


Fig. 4. Coil placement for MT determination of an intrinsic hand muscle (from Groppa et al., 2012 – with permission). In this and in the following figure the current flowing in the brain has an opposite direction to that flowing in the coil. Optimal coil orientation refers to monophasic pulse or the second phase of a biphasic pulse. Current direction in the coil can differ across commercially available stimulators.

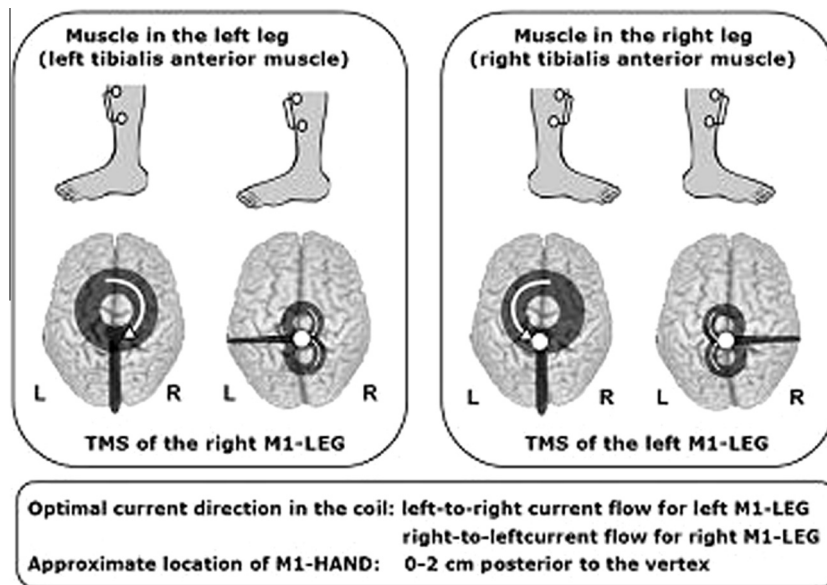


Fig. 5. Coil placement for MT determination of a leg muscle (from Groppa et al., 2012 – with permission).

settings are identical to the standards used for recording the CMAP evoked by peripheral nerve stimulation (PNS). However, the peripherally evoked and transcranially evoked motor responses have different neurobiological properties, and these need to be considered when using the MEP amplitude as a neurophysiological measure of corticomotor excitability. These differences were discussed earlier and explain why the TMS-evoked and PNS-evoked motor responses only resemble each other: there are differences in amplitude, duration, and shape.

5.1. Temporal dispersion of corticomotor excitation

As described in detail in the previous sections a single TMS pulse applied to M1 gives rise to a series of temporally dispersed descending corticospinal volleys (Di Lazzaro et al., 2004a; Groppa et al., 2012; but see Rusu et al., 2014 on the plausibility of an alternative mechanism behind D- and I-wave generation through computational modeling). At spinal level the dispersed corticospinal volleys result in activation of motoneurons at slightly different latencies, dependent on their thresholds, and this asynchrony is accentuated by conduction in the peripheral nerve. This produces phase cancellation of motor unit potentials (MUAPs) and MEPs that are significantly less synchronized, more prolonged, and of lower amplitude than CMAPs (Rossini et al., 1995; Magistris et al., 1998). This observation cannot be overcome during brain stimulation by increasing the TMS intensity. In fact, phase cancellation of the motor unit potentials contributing to the whole MEP is prominent at high stimulation intensities and causes a discrepancy between the size of the mechanical and electrical muscle response to TMS. At TMS intensities that cause maximal stimulation of the fast-conducting corticomotor pathway, TMS elicits a muscle twitch in the target muscle that can exceed the force of muscle twitches evoked by supramaximal peripheral nerve stimulation. This is because some motoneurons may discharge more than once to the intense corticospinal volley.

Phase cancellation of MUAPs can be reduced to a level that is comparable to PNS with a triple stimulation technique (TST). The TST is a collision method that has been introduced by Magistris et al. (1998) and “resynchronizes” corticomotor excitation at the level of the peripheral motor axon. MEP amplitudes recorded with TST closely match that of the maximal electrically evoked CMAP so

that the MEP/CMAP ratio in normal subjects is close to 1. TST can be implemented as a clinical routine procedure to assess corticomotor conduction to distal limb muscles in patients, but has been rarely employed in neuroscientific studies on healthy individuals.

5.2. The effect of stimulus intensity

Both, extrinsic factors (e.g. ‘conditioning’ stimuli preceding a ‘test’ TMS stimulus) and intrinsic factors (e.g. the mental activity) can change cortico-motor excitability and change MEP amplitude. As a general rule, increasing the stimulus intensity will induce a stronger descending excitatory drive resulting in faster temporo-spatial summation at the cortico-motoneuronal synapses, and MEP amplitude increases gradually with increasing stimulus intensity. The relationship between stimulus intensity and MEP amplitude can be formally modeled by a cumulative Gaussian and described by a sigmoid curve (Devanne et al., 1997; Pitcher et al., 2003; Möller et al., 2009). The sigmoid curve indicating the relationship between stimulus intensity and MEP amplitude is called the “stimulus–response curve”, “recruitment curve”, or “input–output curve”. The initial segment of the sigmoid curve is relatively flat and deviates from zero at the stimulus intensity that corresponds to the MT. The second part of the sigmoid curve is an ascending line caused by an approximately linear increase in MEP amplitude with increasing stimulus intensity. This part of the recruitment curve corresponds to TMS intensities between 120% and 140% of resting MT (Davey et al., 1999; Han et al., 2001). The stimulus–response relationship can then be assessed by calculation of the amplitude ratio of the MEP obtained at 140% of resting MT to that obtained at 120% (Lefaucheur et al., 2006a) or of the slope of the IO-curve within this range of stimulation intensities (Lefaucheur et al., 2012). This slope reflects the gain in MEP amplitude with increasing stimulus intensity. Proton magnetic resonance spectroscopy has revealed a positive correlation between the slope of the MEP input–output curve (IO-curve) and cortical glutamate levels in the motor cortex, suggesting a link between glutamatergic neurotransmission and corticospinal excitability (Stagg et al., 2011). At higher stimulus intensities, the stimulus–response curve plateaus with no further increase in MEP amplitude despite of an increase in stimulus intensity. The plateau at high stimulus intensities is due in part to the increasing phase cancellation of the motor unit action potentials

(MUAPs) that constitute the MEP (Magistris et al., 1998). In summary, the stimulus–response curve is determined by the progressively higher number of recruited corticospinal fibers and the temporal dispersion of the spikes propagating along the corticomotor pathways. Therefore, clinical use of the MEP IO-curve has been promoted in acute (e.g. stroke) and slowly progressive (e.g. amyotrophic lateral sclerosis) diseases affecting the number of pyramidal tract fibers.

An increase in neural excitability at the cortical or spinal level, due to, e.g., voluntary contraction of the target muscle, will facilitate cortico-motor excitability and result in larger MEP amplitudes without a change in stimulus intensity. This implies that the sigmoid stimulus–response function reflecting the relation between stimulus intensity and MEP amplitude is not invariant, but is subject to dynamic changes which reflect the present physiological state of the motor system. For instance, different IO-curves will be obtained in the same muscle depending on whether the target muscle is relaxed or active, in a movement preparation period, or in a condition of mental motor imagery without real contraction (Starr et al., 1988; Rossini et al., 1988; Tomberg and Caramia, 1991). The flexible tuning of the stimulus–response function by physiological variables explains why measurements of MEP amplitude are the most popular electrophysiological “read out” to assess after-effects of repetitive TMS and other non-invasive brain stimulation protocols applied over M1 on corticospinal excitability (Siebner and Rothwell, 2003; Ziemann et al., 2008).

5.3. Inter-trial variability of MEP amplitude

Intrinsic fluctuations in neural excitability at the cortical and spinal levels render the MEP amplitude highly variable even in an apparently resting state with complete relaxation of the ‘target’ muscle. This intrinsic trial-to-trial variability has to be taken into account when measuring threshold under resting conditions (Rossini et al., 1994) and using the mean MEP amplitude as a state marker of cortico-motor excitability (Wassermann, 2002). Recent TMS–EEG studies have shown that TMS-induced MEP amplitudes depend on the state of ongoing EEG phase and power fluctuations which may account at least partially for the inter-trial variability of MEP amplitudes (Bergmann et al., 2012; Ferreri et al., 2014b; Keil et al., 2014). For instance, MEPs are consistently larger when evoked during the up-states than during down-states of slow oscillations in non-REM sleep (Bergmann et al., 2012). During wakefulness, the MEP amplitude correlate with the power and phase of EEG and EMG activity in a frequency band around 18 Hz, and high beta-band cortico-muscular coherence shows a positive linear relationship with the MEP amplitude (Keil et al., 2014). Together, these results show that the inter-trial variability of MEP amplitudes may contain important information about the state-dependency of corticomotor excitability (Ferreri et al., 2014b).

5.4. Measuring MEP size

The size of a single MEP is usually expressed as peak-to-peak amplitude, but the “area under the curve” of the rectified MEP or the amplitude from pre-MEP baseline can also be used. As mentioned above, intrinsic fluctuations of neural excitability at the cortical and spinal levels introduce a substantial variability of the MEP amplitude from trial to trial. Therefore, several MEPs need to be consecutively recorded to obtain a reliable estimate of the MEP size. This is particularly relevant in TMS studies during which MEP amplitude measurements need to be repeated several times during the same experiment. In this context neuronavigated TMS is advantageous to monitor coil position relative to the cortical target site and to correct any shift in coil position or angulation during serial measurements.

MEP amplitude measured at a single TMS intensity provides no information about the stimulus–response characteristics of corticospinal excitability. TMS intensities are usually expressed as a percentage of either individual MT or MSO. MEP measurements can be performed during relaxation or during tonic contraction of the target muscle. The stimulus–response relationship between TMS intensity and MEP amplitude can then be determined by averaging the MEP amplitudes for each intensity level. Alternatively, the MEP amplitudes for each trial are plotted against the corresponding TMS intensity and the stimulus–response function is derived by curve fitting, e.g., by fitting a Boltzmann function. A change in corticospinal excitability may result in a right- or leftward shift of the entire stimulus–response curve and/or a change in its slope depending on whether the excitability change is similarly expressed across the entire intensity range or not. Hysteresis effects have been described for TMS at a relatively short inter-trial interval of 5 s (but not 20 s) in the relaxed (but not active) target muscle and may introduce systematic biases in clinical and research studies (Möller et al., 2009). Stimulus–response curves are not static but undergo rapid modifications under physiological conditions. A simple example is a change in motor state of the target muscle from rest to tonic contraction, which will result in a leftward shift of the curve, a steeper slope and a higher maximal amplitude. Motor skill training can also change the recruitment curve. After motor skill training of rapid wrist extension, the slope of the recruitment curve of the agonist muscle increased, while the slope decreased in the antagonist muscle (Suzuki et al., 2012). Further, stimulus–response curves can be modified by CNS-active drugs. For example, lorazepam and lamotrigine suppress the stimulus–response curve in healthy individuals (Boroojerdi et al., 2001) (for recent review, see Ziemann et al., 2014).

The stimulus–response curve is altered by neurological diseases that impair corticomotor conduction. Within the central nervous system, a disease-related loss of corticospinal axons, conduction block or demyelination may result in an attenuated slope of the stimulus–response curve and reduced maximal amplitude. Accordingly, abnormal stimulus–response curves have been reported in patients with motor stroke (Ward et al., 2006) and amyotrophic lateral sclerosis [ALS] (Vucic and Kiernan, 2007). In patients with chronic motor stroke, the slope of the stimulus–response curve predicted the magnitude of task-related brain activation (Ward et al., 2006). The flatter the slope of the stimulus–response curve, the more patients recruited secondary motor networks in both hemispheres “in an attempt to generate motor output to spinal cord motoneurons” (Ward et al., 2006). In ALS, the stimulus–response curve often shows hyperexcitability of the corticospinal neurons, especially in the early stages of the disease (Vucic et al., 2013). It is worth pointing out that the stimulus–response curve is also sensitive to disease-related alterations in corticospinal excitability in conditions which do not cause structural damage to the CST, e.g. Parkinson's disease (Valls-Solé et al., 1994) and dystonia (Siebner et al., 1999) (cf. Table 1).

5.5. Practical considerations

The estimation of the probabilistic distribution of MEP amplitudes is relevant in scientific studies of corticospinal excitability and requires a large number of MEPs to be recorded for each muscle. In many studies, however, experimental constraints allow only the assessment of the MEP size at a single intensity rather than assessing the entire stimulus–response curve. In these situations, TMS intensity is usually set to 115–125% of the individual's RMT to ensure that the experiment probes the MEP size on the rising phase of the stimulus–response curve where there is a roughly linear increase with TMS intensity. Many plasticity studies target an

intensity that generates a MEP size of about 1 mV, or MEP size of half maximum.

In contrast to scientific studies, the primary goal of diagnostic TMS is to elicit a maximal corticomotor response. Hence, TMS intensity should be sufficiently high to excite all high-threshold, fast-conducting corticospinal neurons and spinal motoneurons (Groppa et al., 2012). An optimal intensity for diagnostic TMS is an intensity that marks the transition from the rising slope to the flat portion (plateau) of the sigmoid stimulus–response curve: 140% of RMT, corresponding to approximately 170% of AMT (Groppa et al., 2012). In addition, the efficacy of TMS in exciting the corticomotor output may be increased by asking the patient/subject to preactivate the target muscle at 10–20% of maximum strength. For each muscle, 5–6 consecutive MEPs should be recorded during tonic contraction and only the MEP with the largest amplitude should be considered. In patients with an inability to contract the target muscle (for instance due to severe paresis), CST excitation may be facilitated by voluntary activation of the homologous muscle of the other side, motor imagery of target muscle contraction, or tonic vibration of the target muscle, though to a lesser extent than voluntary contraction of the target muscle.

There is a further practical consideration here. In cognitive studies, where repetitive TMS around threshold intensity is used, one cannot assume a stable state of the cortex being stimulated for many hundreds of trials; nor can we directly measure the cognitive outputs as we can do with the motor cortex. This is a complex issue, but not one that can be ignored (see Silvanto et al., 2008).

6. Cortical Silent Period

As initially mentioned by Merton and Morton (1980), a period of electrical silence in the surface EMG activity occurs immediately after the MEP when TES is delivered to M1 during a tonic muscle contraction. Using focal TMS of the motor cortex hand representation using suprathreshold intensities, a silent period (cortical silent period, CSP) can be evoked in a contralateral hand muscle, lasting up to 100–300 ms following the MEP. The duration of the CSP gradually increases with the intensity of TMS (Fig. 6), while the level of contraction plays an insignificant role (Haug et al., 1992; Inghilleri et al., 1993; Roick et al., 1993; Rossini et al., 1995; Orth and Rothwell, 2004; Kimiskidis et al., 2005). The physiology of this inhibitory phenomenon is particularly complex and different spinal and supraspinal sources contribute to its genesis. It is now generally agreed that several spinal inhibitory mechanisms contribute to the CSP (Pierrot-Deseilligny et al., 1976; Person and Kozhina, 1978),

including recurrent inhibition due to activation of Renshaw cells, the refractoriness of spinal motor neurons after excitation, postsynaptic inhibition by activation of Ia inhibitory interneurons. However, because of their short duration, these spinal mechanisms are limited to the early part of CSP, i.e. the initial ~50 ms (5–10 ms, except recurrent inhibition ~35 ms; Fuhr et al., 1991; see Pierrot-Deseilligny and Burke, 2012) while the later part of CSP is generated by inhibitory mechanisms within M1. Hence, the total duration of the CSP is usually altered only by cortical mechanisms. TMS applied even at moderate stimulation intensities produces a CSP significantly longer than the one induced by TES (Inghilleri et al., 1993; Brasil-Neto et al., 1995); as TMS preferentially activates axons of excitatory intracortical interneurons which in turn stimulate pyramidal neurons (Day et al., 1989; Di Lazzaro et al., 2004a) while TES directly depolarizes subcortical axons of pyramidal neurons (Edgley et al., 1990). This observation confirms the above finding and suggests a predominant role of intra-cortical inhibitory phenomena in the genesis of CSP. The recording from epidural electrodes by Chen et al. (1999b) demonstrated that I-waves of descending corticospinal volley evoked by TMS were suppressed if a second TMS pulse was given 100–200 ms after a conditioning first TMS pulse, i.e., during the CSP.

The inter-hemispheric difference in CSP duration is very small, typically less than 10 ms, and interindividual differences and the inter-session variability of the CSP duration are larger (Haug et al., 1992; Cicinelli et al., 1997; Orth and Rothwell, 2004), ranging from 20% to 35% (Orth and Rothwell, 2004).

Since the duration of the CSP mostly reflects cortical mechanisms and it can be readily probed with single-pulse TMS, the CSP is a useful measure of intracortical inhibition in human M1 and can be used to detect intracortical excitability changes in brain diseases (i.e. in epilepsy, see Cicinelli et al., 2000) during clinical studies.

The following two methods can be used to estimate the CSP duration, as recommended by Groppa et al., 2012 (based on 5/6 trials per muscle):

- The first method calculates the mean CSP duration (or median) based on trial-by-trial measurements of the CSP duration. In a single trial, the CSP is measured as the time elapsing from the onset of the MEP until the recurrence of voluntary tonic EMG activity.
- The second method averages 5–6 MEP/CSP rectified traces. The rectified and averaged trace provides a good visualization of the voluntary EMG activity level at baseline (i.e., prior to the TMS

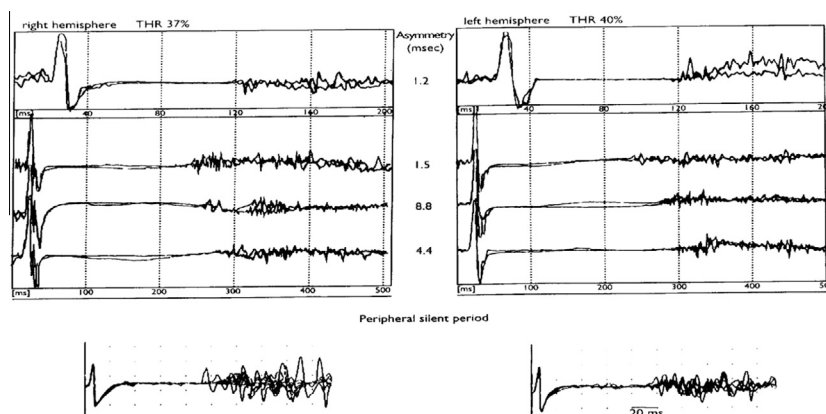


Fig. 6. A representative case of a linear pattern of increase of the CSP duration (right and left hemisphere, recordings from left and right FDI, respectively) as a function of transcranial stimulation intensity which was increased by about 20% from motor threshold (from Cicinelli et al., 2000 – with permission). The values of the CSP duration interhemispheric asymmetry (ms) are shown. The bottom part of the figure shows the peripheral SP recorded from FDI muscles following supramaximal electrical stimulation of the ulnar nerve at the wrist.

pulse). Therefore, the end of the CSP can be defined more precisely by the reappearance of voluntary EMG activity relative to the tonic baseline EMG level.

Pharmacological studies suggested that the CSP reflects particularly long-lasting cortical inhibition mediated through gamma-aminobutyric type B receptors (GABA_BR). Stetkarova and Kofler (2013) demonstrated that CSP duration increased progressively after the administration of intrathecal baclofen (a specific GABA_B receptor agonist). These findings contrast with previous observations: no effect after single oral (McDonnell et al., 2006) or intravenous (Inghilleri et al., 1996) doses of baclofen, but they concur with the significant CSP prolongation observed during the continuous administration of high-dose intrathecal baclofen in a patient with generalized dystonia (Siebner et al., 1998). These discrepancies can be explained by different routes of administration, dose, effective drug concentration and observation periods. Other studies (Werhahn et al., 1999; Pierantozzi et al., 2004) demonstrated that the administration of tiagabine (a GABA re-uptake inhibitor) or vigabatrin (an inhibitor of the GABA-degrading enzyme GABA transaminase) lengthen the CSP, suggesting the involvement of both GABA_AR and GABA_BR. In relation to this, it has been shown that lorazepam (a GABA_AR positive allosteric modulator) prolonged CSP duration if assessed at low stimulation intensity but shortened it if assessed using a high stimulation intensity (Kimiskidis et al., 2006). These data support the idea that at the lower range of stimulus intensities (i.e. short CSPs are elicited) CSP duration reflects the activation of GABA_ARs, while at the higher range of stimulus intensities (i.e., when long CSPs > 100 ms are elicited) it reflects the activation of GABA_BRs.

7. Central motor conduction measurements

After the introduction of TMS by Barker et al. (1985), the first clinical use of this new technique was to estimate the CMCT in humans by recording MEPs to stimulation of the motor cortex

and spinal roots (Table 4). We here summarize the most frequently employed techniques.

1. Central motor conduction time (CMCT)

CMCT is a neurophysiological measure that reflects conduction between the primary motor cortex and spinal cord. With electrical stimulation, it includes the times for impulse propagation via the fast-conducting neurons in the corticospinal tract and excitation of the spinal motoneurons sufficient to exceed their firing threshold. With TMS, it also includes the times for trans-synaptic excitation of the cortical motoneurons in the M1 via cortical interneurons. CMCT can be estimated by subtracting the conduction time from the spinal roots/nerves to the muscle, referred to as peripheral motor conduction time (PMCT) from the latency of MEPs evoked electrically or magnetically by transcranial cortical stimulation (Fig. 7).

Two methods are employed to measure PMCT: motor root stimulation and the F wave technique (Merton et al., 1982; Rossini et al., 1985, 1986, 1987a,b). The first approach activates motor roots (spinal nerves) at their exit foramina using electrical or magnetic stimulation over the spinal enlargements (Mills and Murray, 1986; Ugawa et al., 1989b; Matsumoto et al., 2013b). In this method, CMCT includes the time taken for at least one synaptic delay and the time in proximal motor root in the spinal canal, in addition to the true CMCT (time needed for conduction in the CST) (Cowan et al., 1984; Mills and Murray, 1985; Hess et al., 1987; Rossini et al., 1987a; Ugawa et al., 1988a,b, 1989a, 1990). The second approach is the use of F-waves (Rossini et al., 1987a; Chu, 1989; Eisen and Shtybel, 1990; Claus, 1990). The F wave latency measures antidromic conduction in motor axons to the spinal motoneuronal pool, the “turn-around” time at the motoneuron pool (generally considered to be 1 ms) and then orthodromic conduction from the motoneuron pool to the muscle. Accordingly, the conduction time from the motoneuron pool can be estimated by taking half of the result of adding the F wave

Table 4
Normative data for the upper and lower limbs (modified from Wassermann et al. (2008)).

Muscle	CML (ms)	R/L diff. (ms)	PML (ms)	CMCTm (ms)	R/L diff. (ms)	CMCTf (ms)	R/L diff. (ms)	References
Biceps brachii	9.4 ± 1.7 12.5 ± 1.2 10.2 ± 0.5	0.65 ± 0.6		6.0 ± 1.2 7.1 ± 1.1 5.1 ± 0.3 7.6 (3SD)	0.60 ± 0.51			Eisen and Shtybel (1990) Furby et al. (1992) (21–54 y.) Abbruzzese et al. (1993) Di Lazzaro et al. (1999a)
Abductor digiti minimi	20.5 ± 1.7 18.8 ± 1.2 (f) 19.7 ± 1.0 (m) 19.7 ± 1.0		11.8 ± 1.0 12.7 ± 1.1 14.0 ± 1.5	7.4 ± 1.2 7.0 ± 0.8 7.1 ± 1.1 6.0 ± 0.9 7.0 ± 0.9	2.4	5.8 ± 0.8 6.1 ± 1.0	1.8	Barker et al. (1987) Chu (1989) Chu (1989) Claus (1990) Furby et al. (1992) (21–54 y.)
Abductor pollicis brevis	21.1 ± 1.5 21.8 ± 1.8 21.4 ± 1.5 20.2 ± 1.6	6.5 ± 2.0	14.4 ± 1.4 14.8 ± 1.2	8.0 ± 1.2 7.2 ± 1.8 6.6 ± 1.4 7.9 ± 2.1		6.5 ± 2.0 5.66 ± 0.84 5.45 ± 0.72		Barker et al. (1987) Tabaraud et al. (1989) Ludolph et al. (1989) Eisen and Shtybel (1990) Rossini et al. (1992) (16–35 y.) Rossini et al. (1992) (51–86 y.)
Rectus femoris	21.5 ± 1.7	0.88 ± 0.85		14.2 ± 1.5 16.6 (3SD)	0.93 ± 0.90 1.8			Furby et al. (1992) (21–54 y.) Di Lazzaro et al. (1999a)
Tibialis anterior	29.1 ± 1.4 27.4 ± 2.6		16.1(3SD)	14.4 ± 0.9 14.2 ± 1.7 17.1 (3SD)	2.0	10.7 ± 1.77 14.7 (3 SD)	2.1	Abbruzzese et al. (1993) Garassus et al. (1993) Di Lazzaro et al. (1999a)
Abductor hallucis	41.2 ± 3.4 39.1 ± 2.5 39.4 ± 2.7	1.5 ± 1.13 0.8 ± 0.6	17.1(3SD)	16.7 ± 2.4 18.2 (3SD) 16.9 ± 0.9	0.5 ± 0.4	15.9 (3SD) 12.5 ± 2.2 12.4 ± 1.2	1.6 ± 1.02 0.9 ± 0.4	Barker et al. (1987) Di Lazzaro et al. (1999a) Osei-Lah and Mills (2004) Di Lazzaro et al. (2004c)

CML, cortical motor latency (after cortical magnetic stimulation); R/L diff., side-to-side difference; PML, peripheral motor latency (after paravertebral magnetic stimulation); CMCTm, central motor conduction time calculated using magnetic nerve root stimulation; CMCTf, central motor conduction time calculated using the F-wave method; SD, standard deviation; (f), females; (m), males.

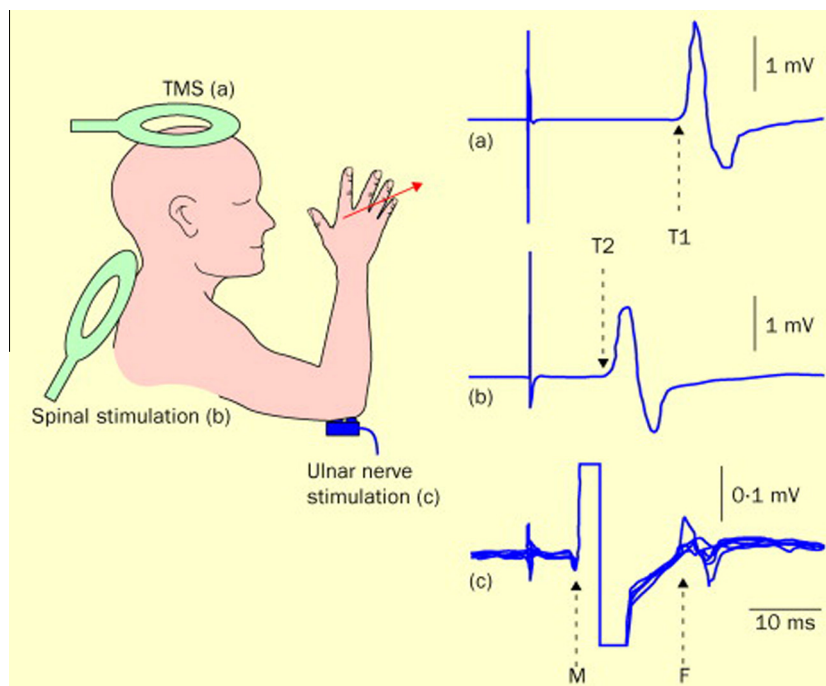


Fig. 7. Schematic representation of the calculation of central motor conduction time (CMCT) (from Kobayashi and Pascual-Leone, 2003 – with permission). Motor evoked potential induced by TMS. (b) MEP after cervical spinal root stimulation. (c) F-waves after ulnar nerve electric stimulation. CMCT is estimated by onset latency of T1 minus onset latency of T2. By use of F-wave latency CMCT can be estimated more precisely as $T1 - (F + M - 1)/2$. T1 = onset latency of MEP elicited by TMS; T2 = onset latency of MEP elicited by the coil placed on the back of cervical spine. M = onset latency of M-wave by electrical ulnar nerve stimulation. F = onset latency of F-wave by electrical ulnar nerve stimulation.

latency and the M wave latency to nerve stimulation (cathode proximal) and subtracting 1 ms, i.e. $(F + M - 1)/2$ (Rossini et al., 1987a). The peripheral conduction time measured using F waves is slightly longer (1–1.5 ms) than the latency of the CMAP produced by “spinal stimulation”. This is because the site of stimulation with the latter is not at the motoneuron pool, as discussed below.

Both techniques have disadvantages:

- *F waves.* The major disadvantage of this method is that F waves can be measured routinely only for distal muscles, unless complex collision techniques are used. In addition, the latency of the fastest F waves provides a measure of conduction in the fastest motor axons, but their motoneurons are not those recruited first by corticospinal volleys particularly with near-threshold stimuli and a relaxed target muscle. The IO-curve for motor axons is normally quite steep, so that the resulting discrepancy will be small if the MEP is relatively large and well-synchronized. However, in presence of damage to the descending motor pathways or the spinal motoneurons the MEP may be small, reflecting only the recruitment of the lowest-threshold motoneurons. On the other hand, peripheral nerve damage may disperse the MEP, and this could create difficulties when trying to exclude central abnormalities in patients with peripheral nerve damage.

If F wave persistence is low, whether this is normal for that particular muscle (e.g., tibialis anterior) or due to disease, the recorded F wave sequence may not sample the fastest axons. This will produce a spuriously short CMCT.

- *Stimulation over the spinal segment.* Here the latency of the CMAP produced by stimulation over the spinal segment is subtracted from the latency of the MEP. Stimulation may be electrical or electromagnetic. Electrical stimuli are commonly delivered using the high-voltage stimulators developed for TES. As in conventional nerve conduction studies, the effective stimulus is cathodal (unlike the optimal polarity for transcranial stimulation of the motor cortex; Rothwell et al., 1987; Burke et al., 1990). The

cathode is placed over T1 for the upper limb and the relevant root exit zone for the lower limb, with the anode over the spine, some centimeters more rostrally, e.g., over C5 for the upper limb. Using TMS, the coil is centered over the cervical or lumbar root exit zone.

When recordings are carried out from muscles of small volume surrounded by other muscles the final MEP will always be somewhat “contaminated” by cross-talk: volumetric spread of MEPs from adjacent muscles, often innervated by different spinal roots and/or nerve trunks. Only with needle electrodes can one be certain that the MEP arises from a specific muscle, and this is particularly so when recording from atrophic muscles. On the other hand, MEPs can be recorded from muscles which are anatomically relatively isolated (e.g. ADM for the hand).

With both high-voltage surface stimulation and electromagnetic stimulation, current is sprayed over a large area, even when focal coils (e.g., figure-of-8) are used. Motor axons may then be activated at some distance from the cathode. However, the bend in axons and the tissue inhomogeneities alter the electrical and electromagnetic fluxes such that motor axons are preferentially activated at the vertebral foramina for both the upper and lower limb outflows (e.g. Mills and Murray, 1986; Ugawa et al., 1989b; Alfonsi et al., 2003). As mentioned above, this implies that the measure of CMCT derived using peripheral stimulation is contaminated by the inclusion of conduction across the motoneuron and its axon. This will be greater with lower limb muscles because of the longer conduction path through the cauda equina. Whatever the method of stimulation employed it is important to monitor the CMAP carefully because, as stimulus intensity is increased to supramaximal, the site of activation of some axons will shift distally, even as far as the brachial plexus with stimulation over the cervical spinal cord (Plassman and Gandevia, 1989). Stimulation of nerve roots or the plexus will activate axons projecting to muscles other than the target one, regardless of whether high voltage or electromagnetic stimuli are employed. Contamination of the EMG recording over the target muscle by activity of neighboring

muscles (cross-talk) is inevitable, and may be hard to detect when there is peripheral nerve pathology. In addition the electrical and electromagnetic stimuli inevitably activate afferent axons, and reflex discharges could contribute to late components of a dispersed CMAP.

There is no perfect technique that will be optimal for all occasions: for measuring CMCT the F wave technique is more accurate, while for peripheral nerve/root pathology, spinal stimulation may be preferred. In diagnostic studies, routine usage of the TST as described by Magistris et al. (1999) is more complicated (and uncomfortable), but its use may be necessary to clarify the findings in individual patients as well as in specific conditions in research studies.

For CMCT measurements TMS is usually delivered during voluntary contraction of the target muscle, thereby providing the shortest MEP latency. In this situation, the spinal motoneuronal pools will be close to firing threshold and a discharge could be generated by the earliest descending volley. In some disorders, however (i.e. in multiple sclerosis), a prolonged CMCT may be due to impaired temporal and spatial summation of descending volleys at the spinal motoneurons. For CMCT measurement, after superimposing the responses, the reproducible onset latency should be measured. If conduction block in proximal peripheral nerves is suspected, supramaximal electrical or magnetic root stimulation should be tried to identify the conduction block (Mills and Murray, 1986; Matsumoto et al., 2009a, 2010e, 2013b,c,d).

CMCT and MEP latency mature in parallel with the development of the central nervous system, specifically with maturation of the corticospinal tracts, and in neonates they are markedly longer in latency than in adults, particularly given size (Duron and Khater-Boidin, 1988; see Fig. 8). While CMCT reaches adult values around 3 years of age, the threshold of transcranial

stimulation is too high for reliable responses until about 10 years of age (Koh and Eyre, 1988; Müller et al., 1991; Caramia et al., 1993; Fietzek et al., 2000). In adults, CMCT has no correlation or only a weak correlation with age (Ugawa et al., 1989a; Claus, 1990; Eisen and Shtybel, 1990; Mano et al., 1992; Rossini et al., 1992; Mills and Nithi, 1997; Matsumoto et al., 2012). CMCT for upper limbs has no correlation or only a weak correlation with body height, whereas CMCT for lower limbs is strongly correlated with height (Rossini et al., 1987b; Chu, 1989; Ugawa et al., 1989a; Claus, 1990; Ghezzi et al., 1991; Ravnborg et al., 1991; Toleikis et al., 1991; Furby et al., 1992; Wochnik-Dyjas et al., 1997; Matsumoto et al., 2010a). Most studies show no gender differences in CMCT once data are corrected for height (Ugawa et al., 1989a; Claus, 1990; Toleikis et al., 1991; Furby et al., 1992; Mills and Nithi, 1997; Tobimatsu et al., 1998). Most studies have reported no significant side differences in CMCT in the healthy subjects (Ugawa et al., 1989a; Eisen and Shtybel, 1990; Mills and Nithi, 1997); the side-to-side difference in CMCT is therefore a clinically useful measure.

2. Cortico-brainstem and brainstem-spinal root conduction times (C-BST and BST-R CTs)

Stimulation at the brainstem or foramen magnum levels (Ugawa, 1999a; Terao and Ugawa, 2002) (Fig. 9) can be achieved by electrical (Ugawa et al., 1991b, 1995a) or magnetic stimulation (Ugawa et al., 1994). For TMS the center of a double cone coil is placed over theinion or the midpoint between theinion and the ipsilateral mastoid process to induce upward current in the brain (Ugawa et al., 1994; Shirota et al., 2011) where it likely activates the CST at the pyramidal decussation due to high induced current concentration at the foramen magnum (Ugawa et al., 1992, 1996).

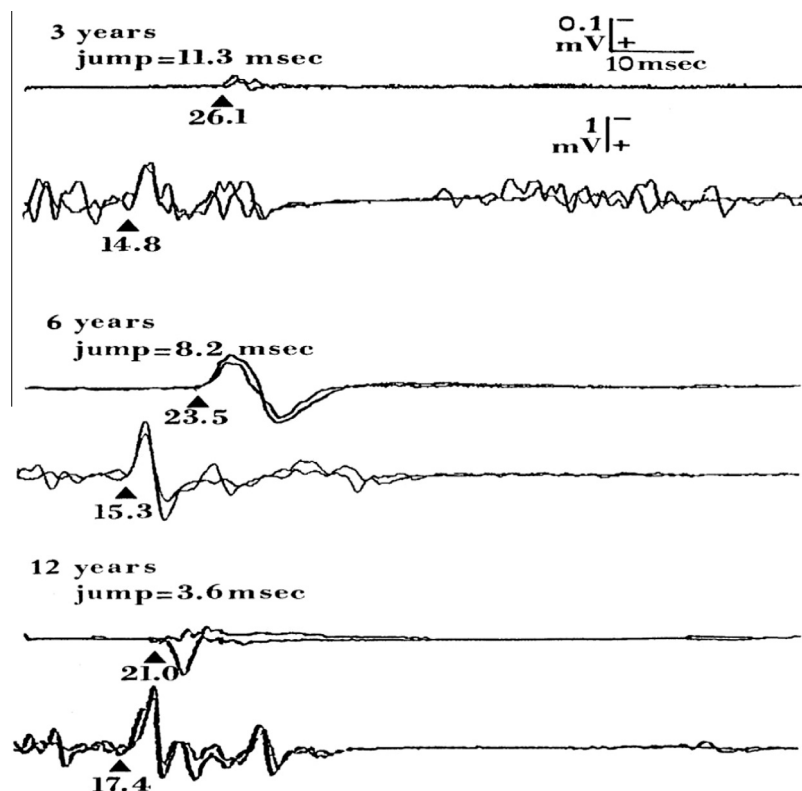


Fig. 8. Age effects on absolute latencies and 'latency jump' between "relaxed" and "contracted" motor evoked potentials (from Caramia et al., 1993 – with permission). Magnetic brain stimulation was carried out in children from 2 to 12 years. The latency of MEPs recorded during voluntary contraction increased in a linear fashion with age and body size. The latency of MEPs recorded when relaxed had a much slower "maturation," and gained the adult value at about 10–12 years of age. The same effect is observed with TES.

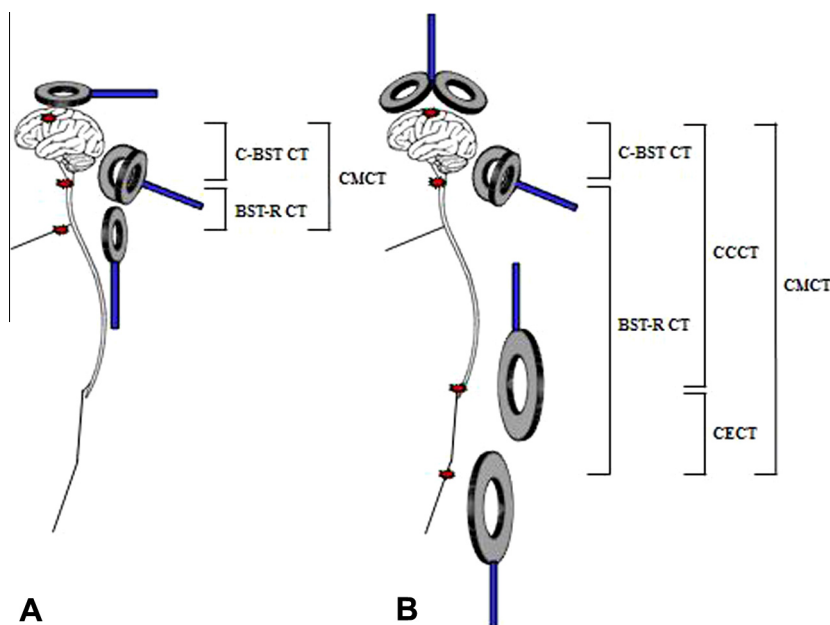


Fig. 9. Central motor conduction studies using magnetic stimulation in humans. (A) CMCT for upper limbs, (B) CMCT for lower limbs. For upper limbs, cortical-brainstem conduction time (C–BST CT) and brainstem–cervical root conduction time (BST–R CT) can be measured as well as CMCT. For motor cortex and motor root stimulation, a round coil is usually used, whereas for brainstem stimulation, a double cone coil is required. For lower limbs, cortical-brainstem conduction time (C–BST CT) and brainstem–lumbar root conduction time (BST–R CT) also can be measured. Furthermore, cortico–conus motor conduction time (CCCT) and cauda equina conduction time (CECT) can be measured. For cortical stimulation, a round coil or double cone coil is used, whereas for motor root stimulation, a round coil or MATS coil is used. For conus stimulation, the MATS coil is required.

It produces a single descending volley (Ugawa et al., 1994), in contrast to the multiple descending volleys with cortical stimulation. Brainstem stimulation can be employed to calculate the cortical–brainstem conduction time (C–BST CT) and the brainstem–spinal root conduction time (BST–R CT) (Ugawa et al., 1992, 1996). Such measurements enable localization of a CST lesion above or below the pyramidal decussation. Brainstem stimulation may also be used in research to investigate changes in spinal excitability (Ugawa, 2002). Possible drawbacks of this method are that slowly conducting descending tracts may be activated in patients with severe damage to the CST (Ugawa and Kanazawa, 1999b) and the inability to elicit a MEP in patients with severe CST involvement. In such cases, paired-pulse magnetic brainstem stimulation may be able to elicit MEPs by producing artificial temporal summation of EPSPs at the spinal motoneurons (Matsumoto and Ugawa, 2008; Matsumoto et al., 2010b).

3. Cortico–conus and cauda equina conduction times (CCCT and CECT)

A newly developed TMS method is able to activate the conus medullaris in the spinal canal (Matsumoto et al., 2009a, 2013b) (Fig. 9). This method is not currently recommended for routine clinical activity. Conus activation can be achieved by electrical (Ugawa et al., 1988a,b, 1989a, 1990, 1995a; Claus, 1990) or magnetic stimulation (Maccabee et al., 1996; Maegaki et al., 1997; Matsumoto et al., 2009b, 2010a,c,d). For magnetic conus stimulation, a 20-cm diameter coil designated as a Magnetic Augmented Translumbosacral Stimulation (MATS) coil has been developed, with which the induced currents are strong enough to elicit MEPs in leg muscles reliably (Matsumoto et al., 2009a, 2009b). With conus stimulation both electrical and magnetic pulses are likely to activate axons at the root exit zone from the conus medullaris, i.e. the most proximal cauda equina, where the electrical conductivity changes abruptly (Ugawa et al., 1995a; Maccabee et al., 1996; Laakso et al., 2014b). These activation sites

with the MATS coil have recently been confirmed by the induced current estimation using a spinal cord and canal model (Laakso et al., 2014b). The latency difference between MEPs to cortical stimulation and conus stimulation (cortico–conus motor conduction time (CCCT)) estimates the conduction time within the CST not including any peripherally generated components. In patients with severe peripheral neuropathy, therefore, CCCT was found to be not prolonged while CMCT was, because of peripheral conduction delays within the cauda equina (Matsumoto et al., 2010d). This method also enables calculation of cauda equina conduction time (CECT) which reflects conduction within the cauda equina (Matsumoto et al., 2010a, 2013a). However, supramaximal stimulation of the conus is usually impossible, limiting the ability to detect conduction block in the cauda equina.

8. Cortical mapping of motor representations

TMS can be used to map brain function and explore the excitability of different cortical regions (Rossini et al., 1994; Hallett, 2007; Wagner et al., 2007; Dayan et al., 2013). The only widespread experience in brain mapping with TMS has been of the motor cortex. In theory, any TMS effect can be mapped to its cortical location, but the most commonly employed is the motor homunculus because the MEP constitutes a reliable output measure. For motor mapping, the territory where MEPs can be produced is identified. Stimulation intensity is generally fixed at a percentage of the MSO above resting MT. Stimuli are applied at various scalp sites using a figure-of-eight coil and a coordinate spatial system referenced to the vertex (Thickbroom et al., 1999), and the amplitude of MEPs evoked in contralateral muscles is measured. Then, a map of sites on the scalp from which responses can be obtained in each muscle of interest is defined. The target muscle representation has a maximum value (optimal site), a center of gravity (CoG) (elements of the representation can be used to form a weighted average of their location, in which the weights are

given by the normalized value of the element), and a surface area. The CoG provides a spatial average optimal site rather than the one site of largest MEP response, which is the “hot spot”. This approach can allow the distinction of the representations for two or more hand muscles (Figs. 10 and 11). Maps of the M1 representation for APB and ADM muscles were produced by fitting a continuously defined 3D function to findings gathered from stimulation at specific scalp sites and projecting such function onto a 2D surface via a radial projection (Wilson et al., 1993). The maps of APB and ADM overlap, but with a statistically significant separation, the APB map being more lateral than the ADM map. Changing the coil direction may also help refine maps. Maps for ADM, APB and FDI muscles have been studied by systematically rotating the coil to determine the direction of induced current for each scalp site of the map expressing the optimal ones as an angle relative to individual central sulcus directionality (Bashir et al., 2013). There is considerable evidence that CoG-based TMS mapping is spatially

accurate, especially when using a navigation system (see next section), and has been recently validated by direct electrical stimulation of cortex in patients with brain tumors (Opitz et al., 2014).

Another mapping variable is the map volume, i.e., the sum of the average MEP amplitude at each location stimulated, normalized to the average MEP at the location of the largest response. This measure provides information on the overall excitability of the cortical representation but does not inform about the topography of the representation of a given muscle. The area of the MEP map increases with the intensity of TMS (Najib et al., 2011), and changes in spinal cord excitability may influence the magnitude of motor maps.

The vast majority of reports agree that upper limb/hand muscle maps are quite symmetrical in terms of spatial coordinates on the two hemispheres (Wassermann et al., 1992; Wilson et al., 1993; Cicinelli et al., 1997). This means that intra-individual interhemispheric mapping differences are normally small or absent, regardless of the inter-individual differences in the absolute values of such coordinates. Therefore, in case of a lesion or excitability changes affecting the motor cortical system of one hemisphere, the spatial characteristics of the maps from the hemisphere not involved in the lesion/experiment could be used as a reference for a given subject (Traversa et al., 1997, 1998), although plastic changes can impact on the unaffected hemisphere via transcallosal influences. Thus, the right/left or affected/unaffected hemispheres can be reliably compared on follow-up studies, if the mapping procedure is rigorously performed (e.g., with the use of a navigation system) and the method is kept constant (Traversa et al., 1997; Cicinelli et al., 2000).

In some circumstances, both physiological and pathological, it is possible to identify topographic differences in the localization of the CoG of a muscle representation with respect to normal and/or the unaffected hemisphere (Liepert et al., 1999). For example, a shift of the CoG of a hand muscle representation towards the face

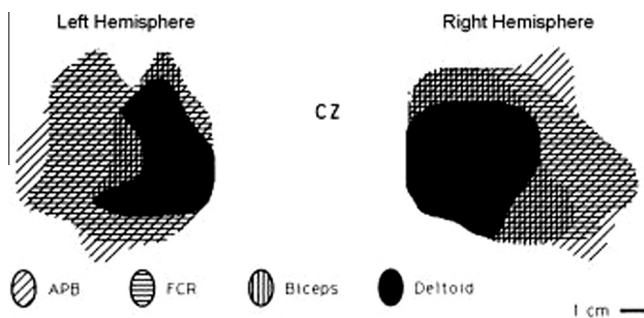


Fig. 10. TMS mapping of upper extremity muscles in right and left sides of one normal subject after stimulation of the contralateral M1s (from Wassermann et al., 1992 – with permission). Note that hand muscles are represented more laterally than proximal arm muscles. CZ, vertex.

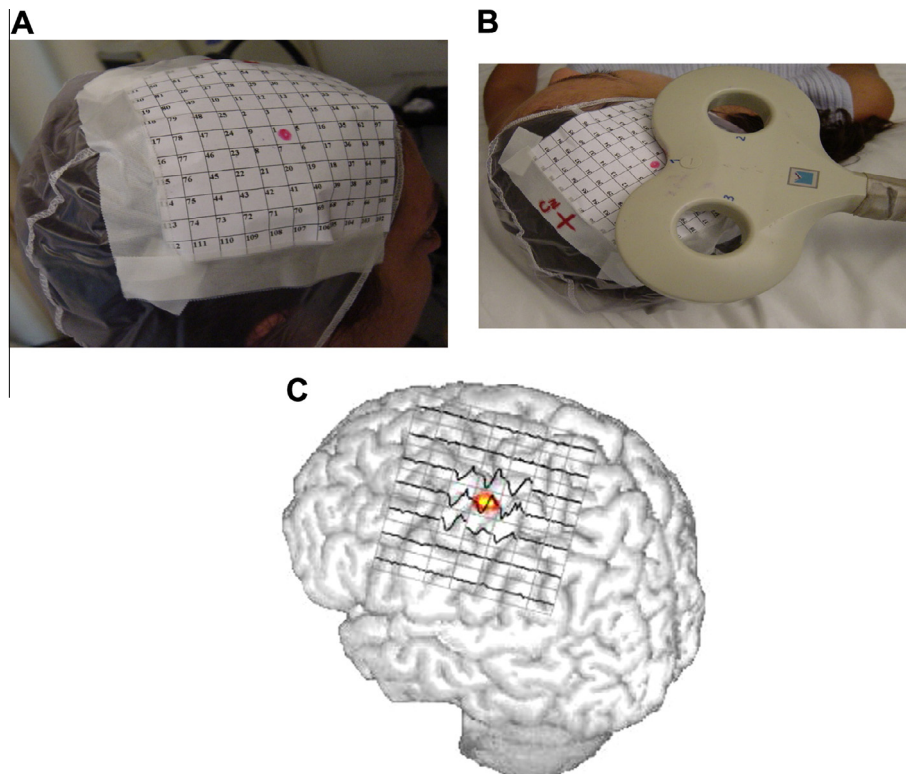


Fig. 11. Cortical mapping procedure. (A) Threshold defined on the “hot spot” of the “target muscle”. (B) 4–8 stimuli for each position at intensity of MT +10%. (C) Create MEP amplitude maps and calculate the center of gravity.

representation may indicate plastic reorganization (either “functional” or “aberrant”) in the motor cortex. The representations of different body parts, such as arm and leg, are generally separate, but there is overlap for muscle representations in the same body part, much as has been documented in experimental models and in fMRI mapping (Pascual-Leone et al., 1993; Donoghue and Sanes, 1994; Melgari et al., 2008). Motor mapping can also demonstrate the presence of weak and probably polysynaptic ipsilateral corticospinal pathways to upper extremity muscles (Wassermann et al., 1994; Ziemann et al., 1999). Additionally, CSPs can be mapped (Wassermann et al., 1993).

9. Principles of neuronavigation

Introduced some years ago, navigation systems, integrating individual brain imaging data and dedicated to TMS practice, serve several objectives (Lefaucheur, 2010): (i) to determine the exact cortical location of a TMS target; (ii) to ensure the reproducibility of TMS targeting during repeated sessions or follow-up studies; (iii) to improve the accuracy of TMS motor mapping methods; (iv) to determine the functional involvement of a cortical region (e.g., motor ability or speech), especially in the context of presurgical mapping. However, various approaches have been proposed before image-guided systems became available.

A common method to identify a brain area uses its spatial relationship with functional criteria such as motor responses or phosphenes obtained from stimulation of the primary motor or visual cortices, respectively. The position of the coil over the skull is varied until the desired effect is obtained; so the optimal stimulation site is defined by this effect. This approach was used for the localization of functional responses like speech arrest (Pascual-Leone et al., 1991), and for the detection of visual phenomena like phosphenes over the occipital cortex (Amassian et al., 1998). However, it is important to monitor and to correct the coil position to avoid the risk of not reaching the target area of the subject when non-motor brain areas represent the TMS ‘target’, or during long stimulation sessions such as for the therapeutic applications of repetitive TMS, or during mapping procedures, or when the same target brain area is to be accessed in follow-up sessions. Accurate localization of specific brain areas to stimulate requires a precise online matching system between the orientation of the coil on the scalp and the site of stimulation. To solve this problem several TMS research groups have determined the stimulation site using other strategies such as a standardized function-guided procedure (see Pascual-Leone et al., 1996, for locating the dorsolateral prefrontal cortex) or the international EEG 10–20 system [American Soc. EEG, 1991] (Rossini et al., 1987a, 1987b; Seyal et al., 1992; Walsh et al., 1998). Given the assumption that there is a consistent correlation between scalp locations and underlying brain structures, the coil is placed above a certain 10–20 position to depolarize neurons in the underlying cortex. The accuracy of these methods in finding the exact coil position related to certain cortical areas is, however, in the range of centimeters. Furthermore, these techniques do not take into account inter- and intra-individual variability of cortical anatomy, so it remains difficult to compare results from different subjects in studies using this information on coil positioning.

A more accurate solution to the problem of coil placement is offered by stereotaxic neuronavigation devices that enable the precise location of the magnetic coil with respect to the underlying brain anatomy; moreover, if MRI guided systems utilize individual MR images of that specific subject, individual brain structures can be taken into full account. The frameless stereotaxic neuronavigation system combines magnetic resonance imaging (MRI) data with TMS, guiding the coil to regions selected on the

MR images (Krings et al., 1997; Ettinger et al., 1998; Boroojerdi et al., 1999; Paus, 1999; Gugino et al., 2001; Herwig et al., 2001a, 2002). The subject’s head and the MR scan are coregistered in a common reference space using a set of anatomical landmarks (such as the alar wings of the nose, the tragus of the ear and the internal angles of both eyes), visible on both the subjects MRI and on his/her head. This allows a link between MR images and real anatomy and a three-dimensional (3-D) orientation by interactive visual navigation. The 3-D position of the landmarks can be measured with a digitizing pen using a radiofrequency-based, mechanical or optical tracking system. The optical-tracking system uses a camera to measure the 3-D locations of infra-red LEDs attached on the coil and on the subject’s head, giving the possibility of tracking simultaneously the 3-D orientation and the movement of the coil and of the subject’s head.

These systems allow real-time monitoring of coil position without restraining the subject’s head during a TMS experiment in order to preserve the effective stimulation sites on the cortical surface. Stereotaxic neuronavigation can be based on the subject’s structural (anatomical) MRI, on the functional MRI obtained in the same subject, and on the use of functional neuroimaging data from the literature (“probabilistic approach”; Paus et al., 1997) or from a brain “model” based on archives of the brains of healthy subjects (e.g., Talairach and Tournoux, 1988). Stereotaxy achieves greater accuracy, of the order of a few millimeters, compared with some centimeters for the non-navigated techniques (Sparing et al., 2008). Moreover, the trial-to-trial replacement variability is downgraded close to zero. The use of neuronavigation systems reduces the variability of the induced electric fields into the brain from one TMS pulse to another (Cincotta et al., 2010). Such systems are particularly useful to target cortical regions other than the motor cortex, such as the dorsolateral prefrontal cortex (Herwig et al., 2001b; Ahdab et al., 2010; Mylius et al., 2013).

10. Stimulation of nerve roots and peripheral nerve

Conduction across proximal segments of peripheral nerves, plexuses and nerve roots is commonly tested using H reflexes and F waves. This involves peripheral nerve stimulation, with transmission of nerve volleys centrally and then distally across the body segment under study. An alternative technique involves direct stimulation of proximal structures, and this may be preferable:

1. In corticospinal lesions, when measuring CMCT, as discussed above.
2. In peripheral nerve pathology, when looking for abnormalities of impulse conduction in motor axons in proximal segments in, e.g., nerve root lesions, multifocal motor neuropathy and acquired inflammatory polyneuropathies/radiculopathies. Here the responses to the peripheral stimuli may be combined with those to TMS.

The demonstration of conduction slowing or conduction block in proximal segments can be problematic with routine diagnostic testing, and a number of techniques have been developed to stimulate motor axons proximal to common sites of pathology. Such testing may be useful particularly in plexus lesions and in radiculopathies (either compressive or inflammatory) (e.g. Fisher, 2002; Alfonsi et al., 2003; Vucic et al., 2006; Incesu et al., 2013).

Unlike the situation with transcranial stimulation, recordings made using peripheral stimulation are best done at rest. Background contraction provides no advantages: the latency and waveform are not altered by background contraction, and the EMG of the contracting muscle would represent unwanted “noise” in such recordings. A comprehensive review of electromagnetic stimulation

of motor roots has been published recently, and includes a comparison with other stimulation methods (Matsumoto et al., 2013b).

Stimulation may be electrical or electromagnetic. With the former, the stimuli can be delivered through monopolar needle electrodes inserted close to the targeted structure (e.g., the sciatic nerve at the gluteal fold, plexus or a nerve root; Fisher, 2002; Vucic et al., 2006), or using the high-voltage stimulators developed for transcranial electrical stimulation (Fisher, 2002; Alfonsi et al., 2003). Electromagnetic stimulation has the advantage that it produces minor discomfort, and this can be important with relatively deep nerves, such as the femoral nerve (Bachasson et al., 2014), particularly in obese patients, or patients wearing a cast or those in whom cooperation is likely to be limited. For electrical stimulation, a Teflon-coated monopolar needle electrode is a convenient cathode, but description of this method is beyond the scope of the present document. As mentioned above, neighbors of the target muscle will be activated and will contribute to the CMAP, to a greater extent than with stimulation of the peripheral nerve more distally. Collision techniques may be necessary to eliminate this problem.

Thus, high-voltage or electromagnetic stimulation can be satisfactory alternatives to stimulation through a needle electrode for peripheral nerve abnormalities if latency is not critical and if the site of stimulation is not close to the site of pathology. Uncertainty about precisely where the stimulated axons are activated renders measures of conduction distance unreliable. With diffuse processes, the current required to activate axons will be elevated, and the site of lowest threshold may be some distance from the cathode.

11. Suggested check-list for a routine TMS clinical examination

- (1) Record age, height, current medication, and relevant clinical information and complete a check-list for safety (history of epilepsy, metal implants in the skull/scalp/head, cardiac pacemakers, spinal cord stimulators, pregnancy, etc. For a more extensive list of safety questions, see Rossi et al., 2009).
- (2) EMG electrode application: ensure a skin-electrode impedance of $<10\text{ k}\Omega$.
- (3) Supine position (with full muscle relaxation) or seated, with eyes open in a quiet environment (any sudden noise can modify TMS excitability measures).
- (4) Demonstrate a few stimuli in the air or to the examiner's wrist in order to familiarize the subject with stimulus.
- (5) Stimulate the scalp, scanning in search for the 'hot spot' with optimal coil orientation.
- (6) Define the corticomotor threshold for the MEP during relaxation and contraction (if required).
- (7) Collect and superimpose 2–3 reproducible MEPs during relaxation/contraction. Take the MEP with largest peak-to-peak amplitude for the MEP/CMAP ratio (usually 20–30% above the resting motor threshold intensity), and the MEP with shortest onset-latency for CMCT calculation.
- (8) Perform sustained contraction at about 20% of maximal force for CSP measurements; collect and superimpose 2–3 responses.
- (9) Collect CMAP of maximal amplitude during supramaximal electrical peripheral nerve stimulation and calculate the MEP/CMAP amplitude ratio.
- (10) Collect and superimpose 2–3 MEPs during spinal root stimulation.
- (11) Collect and superimpose the 'F-waves' during supramaximal nerve stimulation or record the response to "spinal" stimulation, to allow measurement of CMCT.
- (12) Repeat on the other side and note the interside differences of the measured parameters.

- (13) Specifically ask about and take note of any side-effect which the subject refers to the TMS procedure at the end of the session.

12. Paired-pulse stimulation

12.1. General principles of paired-pulse TMS studies

Paired-pulse TMS allows assessment of intra-cortical inhibition and facilitation. Several intracortical circuits can be tested and those discussed in this article are summarized in Table 5. It usually involves a conditioning stimulus (CS) followed by a test stimulus (TS), and the MEP amplitudes (usually peak-to-peak) or areas are compared to those produced by the TS alone as a reference (baseline/control) condition. Due to the trial-to-trial variability of MEP induced by TMS, at least 8–10 trials for each combination of CS/TS intensities and interstimulus interval (ISI) between CS and TS should be tested. The studies are usually done with the target muscle at rest. Contraction of the target muscle can strongly alter paired-pulse TMS findings. For example, contraction results in significant reduction of short interval intracortical inhibition (SICI) (Ridding et al., 1995b). Background EMG should be monitored and recorded to determine the state of muscle relaxation or level of muscle activity. In some paradigms, comprehensive examination involves testing a range of CS intensities to determine the thresholds for eliciting inhibition or facilitation. The TS intensity is set to allow observations of inhibition and facilitation, typically at amplitudes of 0.5–1 mV for hand muscles or 110–120% of resting MT. Using a test stimulus that produces MEP at the middle value of the Input–Output curve (S_{50}) is logically optimal and allows equal amounts of inhibition and facilitation (Kukke et al., 2014).

12.2. Short interval intracortical inhibition (SICI) and intracortical facilitation (ICF)

SICI is elicited when a subthreshold CS is followed by a suprathreshold TS at an ISI of 1–6 ms (Kujirai et al., 1993) (Fig. 12) and it is due to cortical inhibition (Nakamura et al., 1997). There are two phases of SICI, peaking at ISIs of $\sim 1\text{ ms}$ and 2.5 ms. SICI at 1 ms may partly be related to neuronal refractoriness but may also involve synaptic inhibition (Fisher et al., 2002; Hanajima et al., 2003; Roshan et al., 2003). SICI at 2.5 ms likely represents post-synaptic inhibition mediated by gamma-aminobutyric acid type A ($GABA_A$) receptors because drugs that enhance $GABA_A$ ergic neurotransmission increase SICI (Ziemann et al., 1996a; Di Lazzaro et al., 2007). SICI in reality reflects the balance between inhibition and facilitation. The relationship between the degree of SICI and CS intensity is a U-shaped curve (Chen et al., 1998; Ilic et al., 2002). At low CS intensities, increasing the CS intensity leads to greater SICI but further increase leads to reduction of inhibition and eventual facilitation, due to the recruitment of facilitatory circuits (Kujirai et al., 1993; Peurala et al., 2008). Therefore, SICI is a complex measure and the results from SICI studies should be interpreted carefully taking into account the different stimulus parameters. With SICI effects on I3 waves using posteriorly directed induced currents in the brain (see Section 2.2.4), the inhibition continues 20 ms or longer, which is compatible with $GABA_A$ inhibition in animals without any contamination by facilitation effects (Hanajima et al., 1998). This procedure has not been used widely because it is more complex than the usual method. There is a further issue: to standardize conditions, the intensity of the subthreshold CS is typically set as a percentage of MT. If there is a decrease in MT because cortical excitability is enhanced, the strength of the conditioning stimulus

Table 5
Summary paired-TMS methods.

Method	Cortical circuit								
	SICI	LICI	SICF	ICF	SIHI	LIHI	SAI	LAI	CBI
Conditioning/first stimulus	Sub-threshold TMS	Supra-threshold TMS	Supra-threshold TMS	Sub-threshold TMS	Supra-threshold TMS–contra M1	Supra-threshold TMS–contra M1	Median nerve ES	Median nerve ES	Sub-threshold TMS–contra cerebellum
Test stimulus/second stimulus to M1	Supra-threshold	Supra-threshold	Sub-threshold or threshold	Supra-threshold	Supra-threshold	Supra-threshold	Supra-threshold	Supra-threshold	Supra-threshold
Interstimulus interval (ms)	1–6	50–200	1.0–1.5, 2.3–3.0, 4.1–5.0	8–30	8–12	40–50	~20–25	~200	5–8
Proposed neurotransmitter/receptor	GABA _A DA	GABA _B	GLU GABA _A	GLU NE	Not known	GABA _B	ACh GABA _A	Not known	Not known

ACh = acetylcholine; CBI = cerebellar inhibition; contra = contralateral; DA = dopamine; ES = electrical stimulation; GABA = γ -aminobutyric acid; GLU = glutamate; ICF = intracortical facilitation; LAI = long latency afferent inhibition; LICI = long interval intracortical inhibition; LIHI = long latency interhemispheric inhibition; M1 = primary motor cortex; NE = norepinephrine; SAI = short latency afferent inhibition; SICF = short interval intracortical facilitation; SICI = short interval intracortical inhibition; SIHI = short latency interhemispheric inhibition.

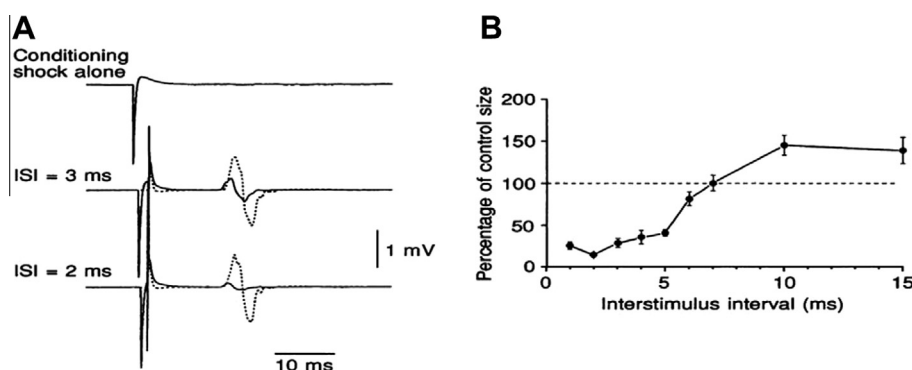


Fig. 12. EMG responses to TMS in relaxed first dorsal interosseous muscle are inhibited by a prior, subthreshold, magnetic conditioning stimulus (from Kujirai et al., 1993 – with permission). (A) Shows examples of EMG data from a single subject. The top trace shows absence of any responses to the conditioning stimulus given alone. The lower two records have two superimposed traces, the response to the test stimulus given alone, and the response to the test stimulus when given 3 ms (middle traces) or 2 ms (lower traces) after a conditioning stimulus. The larger of the two traces (dotted line) is the response to the test stimulus alone. It is dramatically suppressed at these two interstimulus intervals. Note the shorter latency of the conditioned response at an ISI = 3 ms. Each trace is the average of 10 sweeps. (B) Shows the mean (+SEM) time course of suppression in 10 subjects. At each interstimulus interval, the size of the conditioned responses is expressed as a percentage of the size of the control response. In both (A) and (B), the conditioning and test stimuli were given through the same figure-of-eight coil oriented so that electric current in the junction region flowed from anterior to posterior over the lateral part of the motor cortex.

evoking inhibition will be less, and vice versa. As noted in the preceding paragraph, the relationship between CS intensity and SICI is not linear, and is not easily predicted. These issues need to be considered when comparing data from patients with control data, difference in SICI between groups being due to a CS of different intensity rather than a pathological change. As recommended below, a range of CS intensities should be used in experimental studies, even though the procedure then becomes lengthy.

Intracortical facilitation (ICF) can be elicited with a similar protocol as SICI but at longer ISIs of 6–30 ms (Kujirai et al., 1993). It reflects a true facilitation rather than a rebound after SICI because it has a higher threshold than SICI and a different sensitivity to change in the CS current direction (Ziemann et al., 1996b). Excitatory glutamatergic circuits in M1 may be involved (Ziemann, 2004) and it has been suggested that this form of facilitation might result from the recruitment of additional cortical circuits separate from those more easily activated by single pulse stimulation (Di Lazzaro and Rothwell, 2014). However, the physiological basis of ICF is still poorly understood (Di Lazzaro et al., 2006).

12.3. Short interval intracortical facilitation (SICF)

SICF can be elicited by a suprathreshold first stimulus followed by a second stimulus, also suprathreshold (Tokimura et al., 1996) or at RMT level (Ziemann et al., 1998). SICF occurs at three distinct

phases with ISI at around 1.5, 2.9 and 4.5 ms (Ziemann et al., 1998; Chen and Garg, 2000) and is cortically mediated (Ziemann et al., 1998; Di Lazzaro et al., 1999b). It is likely due to the summation of different I-waves at corticospinal neurons (Ziemann and Rothwell, 2000; Ilic et al., 2002; Hanajima et al., 2002). The TMS intensity and ISI for eliciting SICF partly overlap with those for SICI. This may explain why SICI decreases at higher CS intensities (Peurala et al., 2008; Ni et al., 2013). A comprehensive testing protocol will initially evaluate the time course of SICF with a first stimulus that evokes an MEP of about 1 mV in a hand muscle and a second stimulus near the MT, at ISIs from 1 to 5 ms at steps of 0.2 ms. This identifies the optimal ISI for each SICF peak and trough for each individual. The SICF peaks and troughs may be tested further with a second stimulus at different intensities to identify the intensity required to evoke SICF. SICI should ideally be tested at the trough of SICF to reduce contamination by SICF. A range of CS intensities from about 0.5 active motor threshold (AMT) to about 1.4 AMT can be used to obtain SICI recruitment curve at specific ISIs. However, the testing protocol outlined above is lengthy and abbreviated protocols are needed in many experimental situations. For SICI, ISI 2.0 ms and CS intensity below AMT can generally avoid contamination with SICF. In some studies, the CS intensities may be adjusted to produce 50% of maximum inhibition to avoid floor or ceiling effects of subsequent intervention.

12.4. Long interval intracortical inhibition (LICI)

LICI refers to inhibition of a test MEP with a suprathreshold CS applied 50–200 ms prior to the TS (Valls-Solé et al., 1992; Wassermann et al., 1996; Sanger et al., 2001). LICI derives from cortical inhibition (Nakamura et al., 1997) likely mediated by GABA_B receptors (Werhahn et al., 1999; McDonnell et al., 2006; Müller-Dahlhaus et al., 2008). For comprehensive testing of LICI and a subsequent late disinhibition, a range of ISIs from 50 to 300 ms should be tested. The ISIs of particular interest may be tested further with different CS intensities. For abbreviated LICI testing, ISI of 100 or 150 ms may be used. Following LICI a phenomenon of Late Cortical Disinhibition – representing a very robust period of late facilitation – has been described (Cash et al., 2010; Caux-Dedestère et al., 2014).

12.5. Interhemispheric inhibition (IHI)

IHI is measured by delivering suprathreshold CS to M1 of one hemisphere followed by suprathreshold TS to M1 of the contralateral one. IHI is a cortical phenomenon (Di Lazzaro et al., 1999b) that is likely produced by interhemispheric excitatory pathways through the corpus callosum and synapse onto local inhibitory circuits in the target M1 (Ferbert et al., 1992; Wahl et al., 2007; Ni et al., 2009), although there might be some subcortical contribution (Gerloff et al., 1998). In certain restricted conditions, a homologous interhemispheric facilitation followed by the inhibition can be observed (Ugawa et al., 1993; Bäumer et al., 2006). IHI is most pronounced at ISI of ~10 ms and ~40–50 ms which are referred to as short and long latency IHI (SIHI and LIHI) (Chen et al., 2003; Ni et al., 2009). In addition to the interactions between the homologous M1s, IHI, particularly LIHI, represents a widespread inhibitory system projecting from various motor related cortical areas, including the dorsolateral prefrontal cortex, dorsal premotor cortex and somatosensory cortex, to the contralateral M1 (Ni et al., 2009). Pharmacological studies suggest that LIHI is mediated by post-synaptic GABA_B receptors (Irlbacher et al., 2007). Interhemispheric facilitation from the premotor cortex to M1 has also been demonstrated (Bäumer et al., 2006).

12.6. Paired-associative stimulation (PAS)

A further method to study cortical functional connections involves a TMS test stimulus preceded by conditioning electrical stimulation of peripheral nerve at different ISIs.

Marioenzi et al. (1991) first recorded MEPs from thumb flexor muscles, whilst a conditioning stimulation of median or ulnar nerve randomly preceded TMS of the opposite motor cortex (at ISIs of 10–48 ms). Conditioned MEPs compared to control MEPs were significantly attenuated at ISIs between 16 and 22 ms and were significantly increased at ISIs between 21.7 and 24.8 ms. Such effects were limited to median-innervated muscles and did not occur in ulnar-innervated muscles when the conditioning stimulus was on the median nerve. It has been theorized that the interval between muscle stretch and the onset of the transcortical, long latency electromyographic responses (LLRs) is divided into an afferent time (AT), taken at the peak of wave N20 of somatosensory evoked potentials, an efferent time (ET), calculated by means of CMCT, and a cortical interval (CI) for relaying the signal from somatosensory to motor cortex. Considering this theory, the afferent input from peripheral nerve stimulation changes the excitability of corticospinal neurons of the contralateral sensorimotor cortex during the CI (i.e., the MEP facilitation occurred with nerve stimulation-TMS intervals corresponding to the sum of AT + CI).

Given these basic assumptions, it was hypothesized that lasting excitability changes may be induced in the motor cortex by pairing

median nerve stimulation with TMS over the motor cortex, because the magnetic stimulation excites the pyramidal cell indirectly through the axons of excitatory interneurons and because somatosensory inputs converge on pyramidal cells located in the motor cortex. This approach prompted the development of the Paired Associative Stimulation method (PAS), a paradigm consisting of low-frequency repetitive stimulation of the median nerve (typically 90–200 stimuli) combined with time locked TMS over the contralateral motor cortex. PAS with the interval between the two associative stimuli set at ~25 ms (PAS25) led to a strong facilitation of MEPs, whereas inhibition occurred when the interval between peripheral and cortical stimulation was reduced to about 10–15 ms (Stefan et al., 2000; Wolters et al., 2003). This bidirectional PAS-induced plasticity is reminiscent of what is observed in experimental models of associative long-term synaptic plasticity, i.e., long-term potentiation, LTP, and long-term depression, LTD (Stefan et al., 2000, 2002; Wolters et al., 2003, 2005; Classen et al., 2004). In addition, PAS-induced excitability changes followed the rules of homeostatic plasticity (Pötter-Nerger et al., 2009). On motor corticospinal output, the effects of PAS are rapid (within 30 min), persistent (>30–60 min duration), reversible and topographically specific. By investigating the effects of PAS on somatosensory and auditory evoked potentials, it has been shown that similar effects are present in the somatosensory and auditory cortices as in the motor cortex. As a general rule, the interval separating two consecutive pairs of conditioning-test stimuli (PAS frequency) can affect the pattern of motor cortical excitability changes. Usually, PAS is delivered at a relatively low frequency (0.01–0.25 Hz) (Stefan et al., 2000; Ziemann, 2004; Müller et al., 2007), but some authors showed long-lasting changes in motor cortex excitability following PAS25 applied at 5 Hz (Quartarone et al., 2006).

Pharmacological studies have demonstrated the involvement of NMDA receptors in PAS25 (Stefan et al., 2002; Wolters et al., 2003). PAS25 does not change the SICI (Rosenkranz and Rothwell, 2006; Kujirai et al., 2006; Quartarone et al., 2006), suggesting that PAS does not influence inhibition mediated by the GABA_A receptor, whereas it increases the duration of the CSP recorded from a contracting muscle (Quartarone et al., 2003; Stefan et al., 2000, 2004), suggesting an influence on GABA_B receptor-mediated inhibitory circuits. LTP-like effects of PAS25 were also not associated with enhanced intracortical glutamatergic transmission as revealed by lack of ICF changes (Quartarone et al., 2006). In sum, PAS25 does not affect short-latency intracortical circuits (Ni et al., 2014), but, as demonstrated by Kujirai et al. (2006), those recruited at long latencies are facilitated by PAS. Because these elements would probably correspond to those involved in the generation of late I-waves, PAS-induced plasticity would be different from theta-burst induced plasticity, which is probably based on modulation of the first I-wave (Huang et al., 2005), discussed below.

12.7. Short latency (SAI) and long latency (LAI) afferent inhibition

Cutaneous or mixed afferent input from the hand can inhibit MEPs evoked in resting muscles by TMS of the motor cortex at remarkably short latencies with a reduction of cortical excitability which has been confirmed also by epidural spinal cord recordings (Tokimura et al., 2000).

SAI is elicited if median nerve stimulation precedes contralateral M1 TMS at ISIs around the latency of the N20 component of the somatosensory evoked potential, and is followed by a period of facilitation which is likely related to long latency transcortical responses (Marioenzi et al., 1991; Tokimura et al., 2000). Pharmacological studies showed that SAI involves cholinergic (Di Lazzaro et al., 2000) and GABA_Aergic (Di Lazzaro et al., 2005) circuits. SAI may be evoked with median nerve stimulation at the

wrist or with digit stimulation, usually of the index or the middle finger. The intensity of sensory stimulation may be adjusted to produce a motor twitch, or at two to three times sensory threshold (Ni et al., 2011a). Maximum inhibition occurs at ISIs of about N20 latency plus 2 ms, or between 20 and 22 ms for median nerve stimulation at the wrist and about 25 ms for digit stimulation (Mariorenzi et al., 1991; Bikmullina et al., 2009a; Ni et al., 2011a). LAI is elicited when median nerve stimulation is applied before TMS at ISI around 200 ms (Chen et al., 1999a).

12.8. Thalamo-cortical inhibition induced by cerebellar stimulation (CBI)

CBI refers to inhibition of M1 when preceded by stimulation over the contralateral cerebellar hemisphere, as seen in pioneering studies with cerebellar TES. It is thought to be mediated by activation of cerebellar Purkinje cells which inhibit M1 via a disynaptic pathway through relays in the deep cerebellar nuclei and in the ventro-lateral thalamus (Ugawa et al., 1991a, 1995b; Pinto and Chen, 2001; Groiss and Ugawa, 2012). This may be related to a potential of positive polarity recorded by scalp EEG in the contralateral central-frontal area from cerebellar stimulation (Amassian et al., 1992). Cerebellar stimulation can be performed with a double cone coil (Ugawa et al., 1995b; Werhahn et al., 1996) placed 3 cm lateral to theinion on a line joining theinion and the external auditory meatus. The intensity of cerebellar stimulation is set at 5% below the AMT (for stimulating the pyramidal tract over the cerebellum), while M1 stimulation is performed with a figure-of-eight coil adjusted to produce MEP of about 0.5 mV in hand muscles. CBI is maximum at ISIs of 5–8 ms (Amassian et al., 1992; Ugawa et al., 1995b).

12.9. Interactions between cortical circuits

Interactions between different cortical circuits can be tested with triple stimulation paradigms. For example, LICI inhibits SICI and this interaction is likely mediated by presynaptic GABA_A receptors (Sanger et al., 2001). Details of the method are described elsewhere (for a review see Ni et al., 2011b). Inputs from other cortical areas such as the premotor cortex, supplementary motor area and parietal cortices also modulate M1 excitability. Whether the effects are inhibitory or facilitatory to the M1 depends on the stimulation site, CS intensity and ISI. Neuro-navigation techniques may improve the accuracy identifying the target area outside the M1. Detailed description of these techniques are available elsewhere (Civardi et al., 2001; Koch et al., 2007; Bäumer et al., 2009; Arai et al., 2012).

13. TMS-EEG evoked cortical responses

TMS has been combined with different neuroimaging techniques (Siebner et al., 2009; Ziemann, 2011). For example, a promising tool has been introduced that permits the co-registration of the EEG activity – which has a temporal resolution of a few milliseconds and can be simultaneously sampled from a large number of scalp sites – during TMS (Fig. 13), thus providing the possibility to noninvasively probe the brain's cortical excitability and time-resolved connectivity (Ilmoniemi et al., 1997; Virtanen et al., 1999; Ilmoniemi and Kicic, 2010). This means that combined with EEG, TMS is developing towards a brain research method in which stimulation is navigated into a desired brain area and the concurrently recorded EEG scalp potentials are processed into source images of the TMS-evoked neuronal activation (Komssi et al., 2004). Needless to say, such an approach is quite promising also for clinical applications (Julkunen et al., 2013; Ragazzoni et al.,

2013; Frantseva et al., 2014; Napolitani et al., 2014; Sarasso et al., 2014).

The first published attempt to measure TMS-evoked brain responses was made in 1989 by Cracco et al. (1989); in their setup, one scalp electrode was used to record EEG responses to TMS at the homologous cortical area contra-lateral to the stimulation site and it was possible to record cortico-cortically mediated activity with an onset latency of 9–12 ms (for a review see Komssi and Kähkönen, 2006). However, this approach at that time was substantially hampered by severe technical limitations related to the coupling of a strong stimulation artefact to the recording system, known already from studies with electrical stimuli (Freeman, 1971). It was necessary to overcome this difficulty. One way to suppress the stimulus artifact was to use a sample-and-hold circuit able to block the EEG signal for several milliseconds immediately adjacent to the TMS pulse, as previously suggested by electrical stimulation experiments (Freeman, 1971). This method, avoiding saturation of the recording amplifiers by the magnetic stimuli, allowed for the first time the accurate recording of multichannel EEG activity in response to TMS. With this type of amplifier TMS-evoked brain EEG responses were successfully measured in 1997 (Ilmoniemi et al., 1997; Virtanen et al., 1999). The propagation of TMS-evoked brain activity was then traced between brain areas starting a few milliseconds post-stimulus. In the following years, TMS-EEG studies have started to describe the scalp topography and investigated the possible generator sources of the TMS-evoked EEG potentials (TEPs) in order to extend our understanding of the activation mechanisms of TMS. Moreover, they have confirmed the potential of TMS-EEG as a tool for basic neuro-physiological research and possibly for diagnostic purposes (for a review see Ferreri and Rossini, 2013).

The electric currents induced in the brain by TMS can depolarize cell membranes so that voltage-sensitive ion channels are opened and action potentials are initiated. Subsequent synaptic activation is directly reflected in the EEG (Ilmoniemi et al., 1997), which records a linear projection of the postsynaptic current distribution on the lead fields of its measurement channels. EEG is not very sensitive to action potentials because of their symmetric current distribution and short duration, so it is believed that postsynaptic currents generate most of the EEG signals. If the conductivity structure of the head is taken into account, the EEG signals can be used to locate and quantify these synaptic current distributions and to make inferences on local excitability and area-to-area functional connectivity in the nervous system (Komssi et al., 2002, 2004, 2007; Massimini et al., 2005; Ferreri et al., 2011). The initial TMS-evoked response, although difficult to measure uncontaminated by artifact (Veniero et al., 2009), appears to result from the activation of the target area whereas later deflections are partially due to activity triggered by axon-propagated signals. How the signals are transmitted strongly depends on the state of the simultaneous and/or in-series firing of distributed neuromodulatory neural network (Kähkönen et al., 2001; Massimini et al., 2005), and also on local activation at the time of stimulus delivery (Ilmoniemi and Kicic, 2010; Veniero et al., 2013).

Understanding the TMS-evoked activity that is elicited at sites distant from the TMS target can benefit from knowledge of the anatomical connectivity of the brain as seen by diffusion tensor imaging (DTI) studies with MRI (Ilmoniemi and Kicic, 2010; Niskanen et al., 2011; Peters et al., 2013). TEPs are generally highly reproducible, provided that the delivery and targeting of TMS is well controlled and stable from pulse to pulse and between experiments (Casarotto et al., 2010). Several components of the EEG response to single-pulse TMS in the motor cortex have been clearly identified (for review see Komssi and Kähkönen, 2006; Ilmoniemi and Kicic, 2010; Ferreri and Rossini, 2013). In particular, single-pulse TMS over M1 is able to evoke EEG activity lasting up to 300 ms composed at

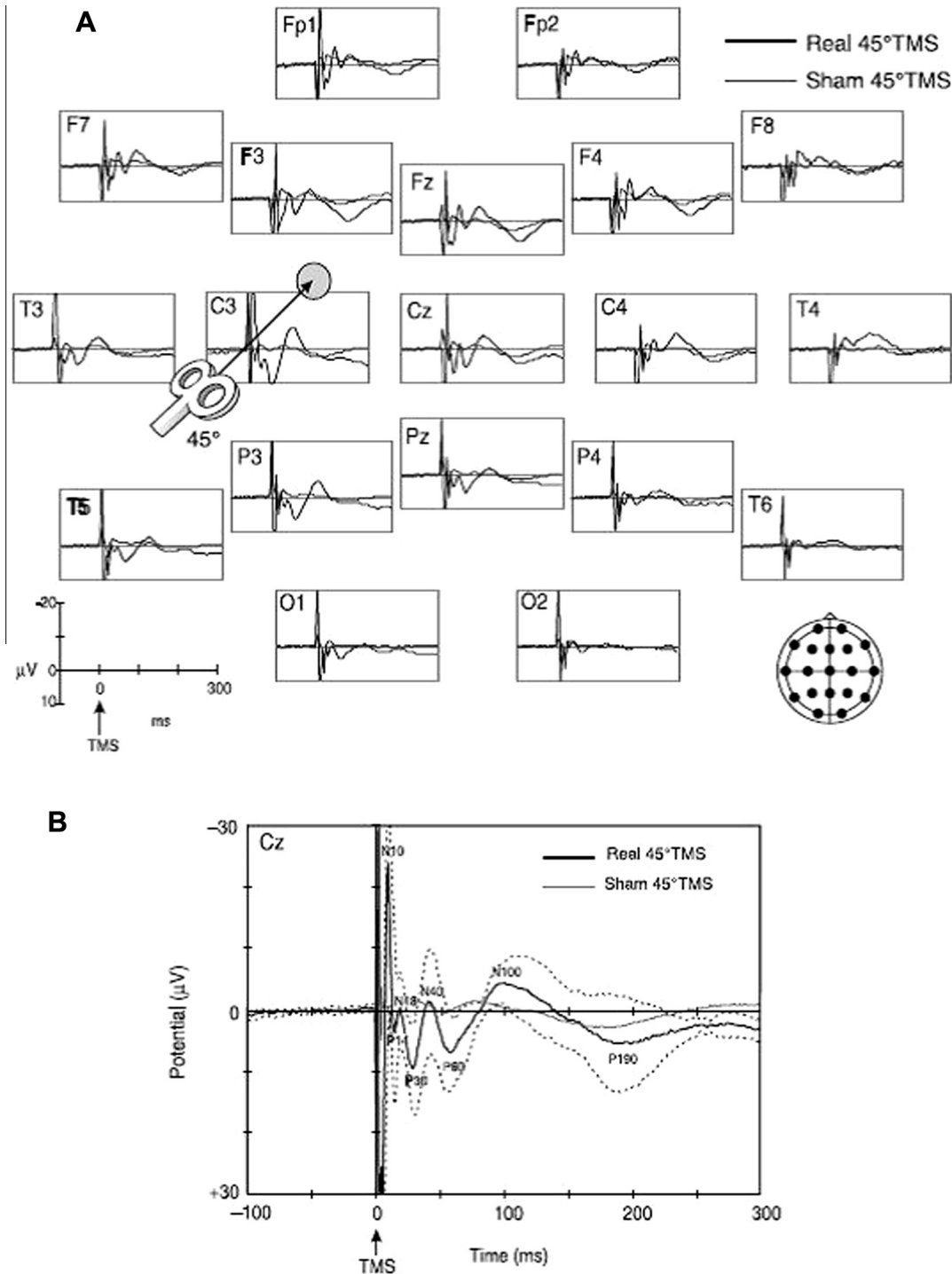


Fig. 13. TMS-EEG co-registration (Bonato et al., 2006 – with permission). (A) Grand average of the electroencephalographic (EEG) responses from 100 ms pre to 300 ms post-transcranial magnetic stimulation (TMS) at all scalp locations recorded during real-TMS and Sham-TMS. This figure refers to stimulation of the left primary motor cortex (MI) performed with the coil oriented 45° away from the midline and with the handle pointing backwards and laterally. The grey point indicates the site of stimulation (between F3 and C3), while the arrow indicates the orientation of the coil in respect to the stimulation site (45° to the sagittal plane). The electrode montage used for the experiment is shown at the bottom. Polarity of the waveforms is plotted with negative values upward in this and subsequent figures. The two Sham-TMS conditions (Sham 1-TMS and Sham 2-TMS) have been averaged. (B) Grand average of the EEG responses recorded at the vertex (Cz) during the real-TMS (thick solid line) and the Sham-TMS (thin solid line) conditions of the left MI performed with the coil oriented 45° away the midline and with the handle pointing backwards and laterally. Standard deviation of real TMS is also shown (dashed line). The onset of the TMS stimulus (at 0 ms) is labelled. Main features are marked in these sample waveforms for orientation. The two Sham-TMS conditions (Sham 1-TMS and Sham 2-TMS) have been averaged.

the vertex of a sequence of deflections of negative polarity peaking at approximately 7, 18, 44, 100, and 280 ms, alternating with positive polarity peaks at approximately 13, 30, 60 and 190 ms post-TMS (Ilmoniemi et al., 1997; Paus et al., 2001; Komssi et al., 2002, 2004, 2007; Nikulin et al., 2003; Kähkönen et al., 2004, 2005; Kähkönen

and Wilenius, 2007; Bonato et al., 2006; Daskalakis et al., 2008; Farzan et al., 2009; Lioumis et al., 2009; Mäki and Ilmoniemi, 2010a; Veniero et al., 2010; Ferreri et al., 2011, 2012; Premoli et al., 2014; Casula et al., 2014). However, these components are not invariable, the most reproducible being N7, P30, N44, P60,

N100 and P180 (Table 6; Fig. 13). In addition to some inter-individual differences, the responses depend on the exact coil location and orientation (Komssi et al., 2002), on the state of the cortex (Nikulin et al., 2003; Ferreri et al., 2014b; Kundu et al., 2014) and on the vigilance of the subject (Massimini et al., 2005, 2012). In addition to standard evoked responses, TMS may also trigger oscillatory activity or perturb ongoing rhythms (Paus et al., 2001; Fuggetta et al., 2005; Van Der Werf and Paus, 2006; Van Der Werf et al., 2006; Rosanova et al., 2009; Maki and Ilmoniemi, 2010b; Veniero et al., 2011; Thut et al., 2011; Vernet et al., 2013; Garcia Dominguez et al., 2014; Shafi et al., 2014), eliciting event-related EEG synchronization/desynchronization (Pfurtscheller and Lopes da Silva, 1999).

13.1. TMS–EEG in studying cortical excitability, connectivity and plasticity

The usual purpose of a topographic plot of TEPs is to detect both local and distant effects of TMS, i.e., to measure both local excitability of the stimulated patch of the cortex and the propagation of TMS-evoked activity in a broader cortical network. The overall response amplitudes are usually highest under the coil and diminish with increasing distance from the stimulation point. Locally, within one hemisphere, increased EEG activity can be seen in a number of neighboring electrodes, suggesting the spread of TMS-evoked activity to anatomically interconnected cortical areas (Ilmoniemi et al., 1997; Paus et al., 2001; Ferreri et al., 2011). An important feature of TEP topography is that even though only one cortical hemisphere is stimulated, bihemispheric EEG responses are evoked with different features. TMS-evoked activity propagates from the stimulation site ipsilaterally via association fibers and contralaterally via transcallosal fibers and to subcortical structures via projection fibers (Ilmoniemi et al., 1997; Komssi et al., 2002, 2004; Ilmoniemi and Kicic, 2010; Ferreri et al., 2011, 2012, 2014b). Therefore, EEG as a measurement of cortical activity after the TMS pulse makes possible to study cortico-cortical interactions by applying TMS to one area and observing responses in remote, but interconnected areas, or to study how the activity in one area affects the ongoing activity in other areas (Ilmoniemi and Kicic, 2010; Ferreri et al., 2014b). Post-synaptic effects of the inhibitory interneurons are considered to be represented as the TMS-evoked N44 and N100 components (Nikulin et al., 2003; Bender et al., 2005; Bonato et al., 2006; Ferreri et al., 2011, 2012; Premoli et al., 2014), as it has been seen shown that inhibitory processes in deeper cortical layers can produce surface-negative potentials preferentially (Caspers et al., 1980). An important challenge in interpreting TMS results comes from the fact that the effects of brain stimulation propagate from the target site ortho- and anti-dromically in the neuronal network (Ilmoniemi and Kicic, 2010) and similarly, the stimulated area is influenced by connected areas. Because area-to-area modulation is often inhibitory, corticospinal excitability (as reflected by the magnitude of the descending volley elicited by a given cortical stimulus) does not necessarily increase with the general level of cortical activity (Ilmoniemi and Kicic, 2010).

There is growing evidence, also from stimulation of cortical areas other than the M1, that the impact of TMS on the EEG response is not only determined by the properties of the stimulus alone, but also by the initial state of the activated brain region (Ferrarelli et al., 2008; Casarotto et al., 2011). This was preliminarily demonstrated by the analysis of the features of the EEG-based pre-stimulus spectral EEG profile to test the hypothesis that fluctuations in neuronal activity have a functional significance and may account for the variability in neuronal or behavioral responses to physically identical external stimuli, such as TMS (Ilmoniemi and Kicic, 2010). Besides assessment of the general state of the brain (Kähkönen et al., 2001; Massimini et al., 2005; for a review see Massimini et al., 2012), concurrent TMS and EEG have the potential to offer insights into how brain areas interact during sensory processing (Bikmullina et al., 2009b; Ferreri et al., 2012, 2014a), cognition (Bonnard et al., 2009; Miniussi and Thut, 2010) or motor control (Nikulin et al., 2003; Kičić et al., 2008; Ferreri et al., 2011). Several recent findings open up promising possibilities to use this technique to assess directly whether and where in the cortex LTP or LTD plasticity phenomena can be induced with several different paradigms (Esser et al., 2006; Huber et al., 2008; Veniero et al., 2013). Detection of the natural frequencies of TEPs with TMS–EEG may also have diagnostic potential and clinical applications, as it opens up possibilities to map the natural frequency of different cortical areas in various neuropsychiatric conditions such as depression, schizophrenia, epilepsy, dementia or disorders of consciousness (for review see Massimini et al., 2012; Daskalakis et al., 2012; Ferreri and Rossini, 2013; Kimiskidis et al., 2014). Since natural frequencies reflect relevant circuit properties, TMS-evoked EEG may radically extend the window opened by conventional MEP recordings (Maki and Ilmoniemi, 2010a). Whereas TMS-MEP is limited to motor areas, TMS–EEG can access any cortical region (primary and associative) both in healthy and diseased subjects, and may offer a straightforward and flexible way to detect and follow-up the state of corticothalamic circuits and cortico-cortical connections.

14. Repetitive TMS

Repetitive TMS (rTMS) was introduced in 1989 using consecutive stimuli with a progressively shorter interstimulus interval as short as 10 ms (Rossini and Caramia, 1992). It needs a specific set of stimulators able to overcome the recharging time to maintain the same stimulus output with extremely brief interstimulus intervals (i.e. 10 or 20 ms). rTMS has a modulatory effect on cortical excitability, which outlasts the stimulation period and can be used in a variety of ways both in motor and non-motor brain regions and with local and nonlocal effects on brain activity.

The majority of research which has studied the effects of rTMS on cortical activity has focused on the effects of stimulation in M1, as the cortical excitability of this brain region can be easily measured. There is relative consensus that stimulation frequencies below 1 Hz are mainly inhibitory, while repetition rates of 5 Hz

Table 6
TMS-evoked EEG potentials (modified and extended from Ferreri et al., 2011).

Component	TEPs after M1 stimulation					
	N7	P30	N44	P60	N100	P180
Latency	7.1 ± 2.5	28.8 ± 5.3	44.1 ± 5.8	62.6 ± 9.5	103.3 ± 19.3	189.7 ± 24.3
Proposed neurotransmitters/receptors involved	GLU/NMDAR	GABA _A	GABA _A /alpha1-subunit-GABA _A Rs	GABA _B ACh	GABA _B /GABA _B Rs	GABA _B

ACh = acetylcholine; GABA = γ -aminobutyric acid; GABA_ARs = GABA_A receptors; GABA_BRs = GABA_B receptors; GLU = glutamate; M1 = primary motor cortex; NMDAR = N-methyl-D-aspartate receptor; TEPs = TMS-evoked cortical potentials.

and beyond are mainly facilitatory at least regard to corticospinal motor output. Limited evidence as to the effect of rTMS in other brain regions has come from neuroimaging and EEG studies. These studies have been conducted predominantly in clinical groups where changes induced by stimulation may not necessarily reflect changes seen in healthy subjects. rTMS paradigms used to induce changes in cortical excitability include conventional rTMS techniques involving high (>3 Hz) and low (<1 Hz) frequency stimulation as well as newer patterned protocols such as theta burst stimulation (TBS) or quadripulse stimulation (QPS).

A substantial number of studies have explored the effects of conventional high and low frequency rTMS on cortical excitability, and there is an emerging body of research characterising the response to TBS.

14.1. High frequency rTMS

A large number of studies, especially in the early 2000s explored the effects of “high-frequency” rTMS on M1 cortical excitability (Pascual-Leone et al., 1994; see review by Fitzgerald et al. (2006)). A typical experiment would assess cortical excitability before and after the repeated application of brief, high-frequency stimulation trains, often with assessment of excitability during stimulation trials as well. These studies employed intensities of stimulation ranging from well below the resting MT to substantially above it (~150% of the resting MT). They also employed a diverse range of stimulus frequencies from 2 to 20 Hz or higher. Overall, this literature suggests that most high-frequency stimulation protocols produce an increase in cortical excitability, as measured by the size of induced MEPs within the rTMS stimulation train (Fitzgerald et al., 2006). The majority of studies also report increases in cortical excitability outlasting repeated stimulation trains although a number of studies (for example Peinemann et al., 2004), which used lower stimulus intensities, have reported no persistent post-TMS changes in cortical excitability.

There are also conflicting reports as to the effects of high-frequency rTMS on parameters of cortical inhibition (Fitzgerald et al., 2006; Jung et al., 2008). When cortical inhibition has been assessed with paired pulse TMS methods, the majority of studies have reported a decrease in SICI after high-frequency rTMS trains in healthy subjects (for example, Peinemann et al., 2000). However, the reverse (SICI increase) can be observed in pathological conditions, especially in patients with reduced SICI at baseline (Lefaucheur et al., 2006a). The CSP duration appears to be relatively increased during the stimulation train, but there is less consistency in reports on the after-effects of rTMS on CSP (Fitzgerald et al., 2006). A recent study found that greater effects on CSP duration were produced with a greater number of applied stimuli at high frequencies (i.e. 20 Hz) (de Jesus et al., 2014). Recently comments on non-linear effects of rTMS could potentially avoid the frequent assumption the more (intensity and number of stimuli) the better (Gamboa et al., 2010).

14.2. Low-frequency rTMS

In the majority of studies, low-frequency stimulation has been applied at 1 Hz, although a smaller number of studies have utilized frequencies between 0.1 and 0.9 Hz (Chen et al., 1997; Fitzgerald et al., 2006). Low frequency rTMS is often employed as a single, low-frequency stimulation train lasting 10–20 min. There have been some reports in which repeated briefer low-frequency stimulation trains were applied. Few effects of this form of low frequency stimulation have been reported within the stimulation trains but there is a moderately consistent effect of low-frequency stimulation on post-train cortical excitability, typically characterised by a reduction in MEP size (Fitzgerald et al., 2006). More

reliable effects on cortical excitability are induced with higher intensities of stimulation and where stimulation trains are repeated on more than one occasion.

The effects of low frequency rTMS on cortical inhibition are not consistent (Fitzgerald et al., 2006). A number of studies have reported no changes in SICI with 1 Hz stimulation (for example Gilio et al., 2003). A large number of studies have examined the effect of 1 Hz stimulation on the CSP with highly contradictory effects reported across studies (Fitzgerald et al., 2006). Recently, de Jesus et al. (2014) reported no effect of low frequency stimulation on intracortical excitability, including inhibition, in the motor cortex.

14.3. Patterned stimulation

The most well established patterned form of TMS is the application of theta burst stimulation (TBS) (Huang et al., 2005). Other approaches, including the use of quadripulse stimuli or the inhibitory effect of continuous theta burst (Rothkegel et al., 2010), have been less evaluated even if quite promising and, for certain aspects, more stable and reliable. These also include the application of repetitive pairs of TMS pulses and the combination of high and low frequency stimulation in a ‘priming stimulation’ paradigm (Hamada et al., 2013).

TBS involves TMS. TBS consists of TMS pulses delivered as a 3-pulse 50-Hz burst applied at 5 Hz (i.e., 50 Hz burst of 3 pulses delivered every 200 ms). Intermittent TMS (iTBS) involves 600 pulses delivered as 2-s trains of TBS repeated every 10 s (i.e. 2 s of TBS followed by an 8 s rest) for about 3 min. iTBS was initially considered as one of the most effective and reliable methods of producing LTP-like plasticity in the cortex (Huang et al., 2005). By contrast, continuous application of TBS trains for 40 s (cTBS) resulted in a LTD-like decrease in motor cortex excitability, as revealed by prolonged reduction of MEP size (Huang et al., 2005). Studies of both types of patterned stimuli have suggest that they produce lasting effects on cortical excitability that exceed those seen with standard rTMS protocols (Iezzi et al., 2011). Most studies which have explored the effect of iTBS have found that it produces an increase in cortical excitability that persists in some cases considerably longer than the effects seen with high frequency rTMS (Di Lazzaro et al., 2011). In contrast, cTBS has been shown to produce long-lasting reductions in cortical excitability, although these are seen with less consistency than the effects of iTBS. Few studies have explored the effect of TBS on cortical inhibition, and these have showed heterogeneous results (Suppa et al., 2008; McAllister et al., 2009; Doeltgen and Ridding, 2011). Recently, there has also been an increasing interest in exploring alternative stimulation parameters for the application of TBS, with stimulation bursts of 3 pulses applied at intervals of 33.3 ms (30 Hz), repeating every 200 ms (5 Hz) or every 167 ms (6 Hz) (Goldsworthy et al., 2012a; Wu et al., 2012). In addition, as TBS sessions are short, there is increasing interest in exploring whether providing multiple sessions with some time spacing between them can produce greater effects on cortical excitability than single sessions alone. The application of repeated cTBS sessions at 10 min intervals appears to produce greater reductions in cortical excitability than single sessions (Goldsworthy et al., 2012b). However, this effect was not seen with iTBS or TBS at a number of time intervals in a second study (Gamboa et al., 2010, 2011). It is also important to note that there are a number of significant variables that modulate the effects of TBS (and other forms of rTMS) on cortical excitability. For example, the effect of 1 Hz stimulation appears to be modulated by time of day and cortisol secretion (Clow et al., 2014). The effect of this type of stimulation is also dependent on the type of TMS coil, the cortical induced current direction and the stimulation intensity utilized (Lang et al., 2006; Talelli et al., 2007). In addition, the induction of

changes in cortical excitability appears to be substantially influenced by the induction of intrinsic cortical activity prior to or during the period of stimulation (Gentner et al., 2008). Finally, limited research has explored the reliability of induction of cortical excitability changes with TBS at different points in time: this appears to be better with iTBS (Hinder et al., 2014) than cTBS (Vernet et al., 2014). It is also worth noting that there may well be a variable response to TBS and other forms of non-invasive brain stimulation such that the expected change in cortical excitability will only be reproduced in a subset of subjects (Lopez-Alonso et al., 2014). Indeed, there is considerable intersubject variability in response to cTBS and iTBS (Hamada et al., 2013). Moreover, one must emphasize that, as for any other rTMS method, the resulting effect of a TBS protocol on cortical excitability and neural function of different areas is difficult to generalize from results obtained to the stimulation of the motor cortex in healthy subjects: TBS effects other than the “classical” iTBS/cTBS antagonism may be observed on non-motor function in patients by stimulating motor or extra-motor cortical regions (Grossheinrich et al., 2009; Borckardt et al., 2011; Lefaucheur et al., 2012). However, the promising effect of such short-duration stimulation protocols on synaptic plasticity should be really toned down at present, since it was recently demonstrated that TBS effects were highly variable between individuals, depending on differences in the interneuronal cortical networks that are preferentially recruited by the TMS pulse (Hamada et al., 2013).

Quadripulse stimulation (QPS) is another promising approach of patterned rTMS, which is thought to induce stable and reliable long-term effects (Hamada et al., 2008, 2009; Nakatani-Enomoto et al., 2012). QPS facilitates MEPs for interstimuli intervals (ISIs) of 1.5–10 ms and suppresses MEPs for ISIs of 30–100 ms. Its bidirectional effects on cortical excitability were confirmed by a neuroimaging study (Watanabe et al., 2014). The use of monophasic TMS pulses and the relatively long duration of the session (30 min) may explain its more stable effect. QPS should be a promising stimulation method for long lasting effect induction even though a few investigators have used it; more replication studies are needed.

14.4. General comments and practical considerations

Repetitive TMS is usually not a routine clinical tool; the interested Reader is referred for technical details to recent review publications (Rossi et al., 2009; Lefaucheur et al., 2014). Safety recommendations should be adhered to for the use of various forms of rTMS and patterned TMS (Rossi et al., 2009).

15. TMS in cognitive neuroscience

TMS has gained a stable and unique place among the non-invasive exploratory functional techniques for in vivo human brain investigation outside the classical motor cortex target. TMS can infer causality of a given cognitive/behavioral phenomenon, but this requires a number of “control” conditions including site (i.e., beside the “sham” stimulation of the target brain region, also the real stimulation of a non-target brain area), time and context specific effect on performance.

15.1. The “online interference” approach

The “online” concept is here developed in a wide sense, which includes both facilitation and depression of a given task performance. The unique feature of TMS in the field of cognitive neuroscience depends mainly on its ability to interact transiently with the stimulated brain area, modifying its activity and therefore

interrogating its function. Its functional impact is due to the ability to impinge on neuronal function transiently (Miniussi et al., 2013), modifying information processing dependent on the activity of the involved neurons (Silvanto et al., 2008; Siebner et al., 2009). Interference with TMS is therefore complementary to more traditional neuroimaging studies based on hemodynamic (fMRI) or metabolic (PET) approaches to cognitive challenges, irrespective of the neocortical region that is being targeted. TMS has been considered an advantageous alternative to classical lesion studies in patients not only because it can be applied in healthy controls but also for a number of additional reasons, given that the use of TMS follows the rule of inference. If cortical area A is involved in cognitive process B and is not involved in process C, the alteration of the activity of area A will result in altered performance in B and not C. Thus, for deductive reasoning, area A plays a causal role in the performance of B. Additionally, discrete lesions are either chronic processes, or have chronic consequences after acute presentation. The resulting behavioral effects thus reflect the specific information provided both by the lesion itself and by the plastic adaptive changes of the surviving brain areas. Moreover, TMS can be safely repeated in subjects on different occasions, eventually allowing an intra-lab or between-lab retest of a given experimental hypothesis. Finally, in some specific fields, as memory tasks requiring a two-stage cognitive process (i.e., encoding and later retrieval of items), TMS allows teasing apart the effects on one of these two tasks more easily than in the case of lesion studies (e.g. Rossi et al., 2001, 2004). Because information processing of higher brain functions is distributed along several parallel distributed networks involving “nodes” in many cortical areas, a single pulse is often inadequate to interact with the brain activity at a behaviorally relevant level. However, the first example of TMS outside the motor cortex used single pulses to transiently suppress visual perception by stimulating the occipital cortex about 80–100 ms after the presentation of the visual stimulus (Amassian et al., 1989). Single pulses can also produce a transient “neglect” of a sensory stimulus (Oliveri et al., 1999, 2000). In this context TMS may be used as a tool to investigate and understand the role and timing of the involvement of a target area in a specific performance (Walsh and Cowey, 2000), the contribution of different sites to different aspects of a cognitive function (Robertson et al., 2003), the relative timing of the contribution of two or more areas to task performance and the function of intracortical and transcallosal connectivity (Jahanshahi and Rothwell, 2000). In short, TMS can be used to investigate what information is processed in a given brain structure, and when this processing occurs. Therefore TMS is a technique that can be used to investigate brain–behavior relationships. In general, the possibility of understanding the location, timing (i.e. cognitive chronometry) (Walsh and Pascual-Leone, 2003) and functional relevance of the neuronal activity underlying cortical functions makes TMS an essential technique mainly in perception and cognitive research. Nevertheless several clinical applications are also possible.

15.2. Cognitive mapping

Similarly to the motor cortex non-motor areas can also be mapped; for example, one can produce phosphenes in different regions of the visual field with an accuracy of 1–2 degrees of visual angle by stimulating appropriate parts of the occipital cortex (Kammer, 1999; Merabet et al., 2003).

For clinical application, navigated TMS (navigated brain stimulation, NBS) (Ruohonen and Kahru, 2010) may allow an interference-based interrogation of a specific function. In this context it has been shown that presurgical mapping of the motor homunculus is sometimes used for localization when there are tumors that can distort brain architecture. There are some data to indicate that

such mapping can improve outcome (Krieg et al., 2014). NBS mapping has been used and approved by the FDA, and in this context it has been shown that NBS can be used for mapping speech-sensitive cortical areas as a valuable tool for in preoperative assessment (Picht et al., 2013). These methods are not standardized, and various language tasks can be used as well as various patterns of TMS stimulation (Tarapore et al., 2013; Rogić et al., 2014; Rösler et al., 2014). However, attention should be paid not to misinterpret the data. For example, true speech arrest of cortical origin should be different from the spreading of the induced electric field to the facial nerve, which may induce transient dysarthria (Stewart et al., 2001a).

15.3. Stimulation characteristics (frequency, intensity)

In the online application, the faster the rTMS frequency, the greater the disruption of the activity of the targeted brain region, and the greater the final behavioral effects will be (that is, unless single pulse TMS is applied at the optimal time, e.g., Amassian et al., 1989). However, with rTMS the potential risks will be greater and more prominent nonspecific behavior and attention effects will be observed, which can make the results more difficult to interpret (Rossi et al., 2009). Moreover, the effects induced by online stimulation are generally short-lived, lasting approximately a few hundred milliseconds to a few seconds. In this area, traditional methods of determining stimulation threshold have usually been used (Rossini et al., 1994). Nevertheless, in this field considering that often a non-motor area is under study, stimulation intensity is usually established as the lowest stimulation intensity that can successfully affect behavior when TMS is delivered over the area of interest, based on the literature and/or the researcher's previous experience (Stewart et al., 2001b; Sandrini et al., 2011).

15.4. TMS as a therapeutic tool

In contrast to online and short-lived rTMS effects, rTMS may be applied for several minutes with the aim of enhancing or inhibiting cortical reactivity and to modulate the hypo- or hyperfunction of a given brain network. This approach is called offline stimulation. TMS has been suggested to facilitate recovery from several cognitive deficits in post-stroke aphasia, neglect, Alzheimer and psychiatric patients (Miniussi et al., 2008; Miniussi and Rossini, 2011; Barr et al., 2013). All these applications need further confirmation to establish the exact boundaries of their practical utility in larger cohorts of patients and following the rules of Evidence Based Medicine in double-blind, placebo-controlled and cross-over trials. The principle underlying behind these applications is that inducing changes in cortical excitability leads to a recovery or reorganization of the functional network – including balancing the hemispheres when bihemispheric mutual control is normally present. Nevertheless, so far, further investigations are needed to determine efficacy, and whether TMS can be used to ameliorate deficits in the cognitive domain with long-lasting, clinically exploitable, effects. Moreover, an important aspect is that in some cases TMS cannot be considered the treatment by itself, but as an adjunct to other rehabilitative interventions to reduce the treatment time and potentiate the final effects.

16. Therapeutic applications of rTMS

In the next sections, several paradigmatic examples of clinical applications with rTMS for disease treatment are outlined. These are ones for which a recent evidence-based review (Lefaucheur et al., 2014) demonstrated level “A” efficacy.

17. rTMS in depression

Current State of rTMS Clinical Practice for Depression. To summarize the acute antidepressant effectiveness data, over 89 individual trials have been conducted, and 4 different large multisite trials have all found statistically and clinically significant effects of daily prefrontal rTMS for 3–6 weeks compared to sham in patients affected by major depression who did not respond to at least two antidepressant drugs. 12 meta-analyses confirm these trials. In some studies, however, non significant effects were reported. Two different devices currently have US Food and Drug (FDA) clearance for treating depression, with several others in some form of FDA pre-review.

Who should deliver TMS in Depression? Because it is a medical therapeutic treatment with a risk of seizure, rTMS should only be performed in a medical setting under the guidance and supervision of a licensed physician (Rossi et al., 2009); meanwhile, national regulations are determining these legal boundaries. When it is being used to treat acute depression it is suggested that the medical team should include a psychiatrist (Schlaepfer et al., 2010; Carpenter et al., 2012), and that the psychiatrists who use TMS should receive training in brain stimulation methods.

Unresolved Issues. Although the literature suggests that daily prefrontal rTMS has an antidepressant effect greater than sham TMS (placebo), and that the magnitude of this effect is at least as large as antidepressant drug treatments, many issues remain unresolved. For example, it is unclear how best to deliver rTMS to treat depression. Most, but not all (Klein et al., 1999), studies have used focal coils positioned over the left prefrontal cortex. It is still not known whether rTMS over one hemisphere is better than another, or whether there are better methods for placing the coil. For the most part, the coil has been positioned using a rule-based algorithm to find the prefrontal cortex, which was adopted in the early studies (George et al., 1995). However, this method was shown to be imprecise in the particular prefrontal regions stimulated directly underneath the coil, depending largely on the subject's head size (Herwig et al., 2001b). Many studies now employ a positioning system based on EEG coordinates, or placing the treatment coil at least 6 cm anterior to the thumb motor area, rather than the “standard” 5 cm (Johnson et al., 2013). It may be that 7 cm is even better (Beam et al., 2009). Two retrospective analyses of clinical trials where brain imaging was performed to document the coil location have independently confirmed that a coil position that is anterior and lateral is associated with a better clinical response (Herbsman et al., 2009; Johnson et al., 2013). Another group has performed a randomized controlled trial examining different prefrontal locations and a more anterior and lateral location did indeed produce a superior antidepressant response (Fitzgerald et al., 2009). These findings suggest that the location of the coil matters, even within broad boundaries of a specific lobe. It is not clear whether individualized location via neuronavigated methods will be needed for optimizing response, or whether general algorithms will suffice for a probabilistic positioning for most patients. Stimulation intensity and duration of series are other unresolved parameters in rTMS for depression. There is now increasing recognition that higher intensities of stimulation are needed to reach the prefrontal cortex, especially in elderly patients, where atrophy of the prefrontal cortex may outpace that of the motor cortex. Stimulation intensity is often based on MT even when a systematic study on the intensity (dose)/effect has not been carried out (Kozel et al., 2000; McConnell et al., 2001; Mosimann et al., 2002; Padberg et al., 2002). Data indicate that rTMS therapeutic effects likely develop over several weeks. Consequently, many of the initial trials, which lasted only 1–2 weeks, were probably too brief to generate maximum clinical antidepressant effects.

There is limited data on using rTMS as a maintenance treatment in depression (Nahas et al., 2000). Pilot findings suggest that rTMS might eventually be used as a maintenance tool in depression, and that one treatment per week might be a good first attempt at a maintenance schedule. Several groups have performed maintenance rTMS, but there have been no controlled clinical trials, and optimal ways of using rTMS to prevent relapse remain to be defined (Li et al., 2004; O'Reardon et al., 2005). Another interesting concept is the use of maintenance TMS following acute series or maintenance Electro Convulsive Therapy (ECT) in patients who require maintenance treatment above psychopharmacology, but for whom adverse cognitive effects, procedural side effects, fear of or intolerance of anesthesia, concurrent medication limitations, geographic distance or lifestyle infringements make ECT difficult or impossible.

18. rTMS in neuropathic pain

A large review was recently published (see Lefaucheur et al., 2014). The present section only concerns chronic neuropathic or non-neuropathic pain and not the use of rTMS to relieve provoked acute or experimental pain, which has also been reviewed elsewhere (Mylius et al., 2012). Because epidural stimulation of the motor cortex through surgically-implanted electrodes was used in the early nineties to treat drug-resistant neuropathic pain (Tsubokawa et al., 1991), rTMS therapy for pain relief was also targeted to the motor cortex (M1), or more precisely the precentral gyrus. Since the first report (Lefaucheur et al., 2001a), about 20 original placebo-controlled studies including at least 10 patients who received active low frequency (LF) or high frequency (HF) rTMS of M1 have been published to date, covering about 700 patients. Stimulation was always applied to the motor (precentral) cortex of the hemisphere contralateral to pain, usually the area corresponding homotopically to the painful zone. First, all studies consistently reported the absence of any significant analgesic effect of LF rTMS of M1 delivered contralateral to the pain side (Lefaucheur et al., 2001a, 2006b, 2008, 2014; André-Obadia et al., 2006; Saitoh et al., 2007). Conversely, HF rTMS delivered over the same target was found to produce significant pain-relieving effects (pain relief >30% in 46–62% of patients and >50% pain relief in 29%). These effects are optimal 2–4 days after a single rTMS session (Lefaucheur et al., 2001b). However, for a therapeutic application, repeated rTMS sessions are needed. Two studies clearly showed long-lasting pain relief following a 5-day protocol of 20 Hz rTMS of M1 in patients with post-stroke pain (Khedr et al., 2005), trigeminal neuropathic pain (Khedr et al., 2005), and phantom limb pain due to amputation (Ahmed et al., 2011). Finally, the largest study to date, by Hosomi et al. (2013), was based on a 10-day protocol of 5 Hz rTMS of M1 in a multicenter series of 64 patients with chronic neuropathic pain of various origins. They found modest but significant pain reduction following active vs. sham rTMS, but they used a rather low frequency of stimulation (5 Hz) and a limited number of pulses (500) per session.

Although an analgesic effect of rTMS of M1 has been demonstrated, there are still many open questions before rTMS can be used in the treatment of chronic pain in daily clinical practice. The two main issues are the design of a maintenance protocol for long-term therapy and the method of determining the optimal target within the precentral gyrus; in fact, the location of the best target over the precentral gyrus with respect to the clinical presentation remains challenging (Lefaucheur et al., 2004b, 2006b). Only a few studies have used neuronavigation in this context (Hirayama et al., 2006; Lefaucheur et al., 2012), and there are arguments to suggest that diffusion tensor fiber tracking, in particular, could be of interest for this purpose (Goto et al., 2008;

Ohn et al., 2012). Several rTMS target locations have been assessed for their ability to produce neuropathic pain relief, but M1 was found to be preferable to premotor or primary somatosensory cortical regions (Hirayama et al., 2006; Saitoh et al., 2006). However, stimulation of the dorsolateral prefrontal cortex (DLPFC) remains to be studied, according to the proven efficacy of this target in depression and the well-known relation between depression and chronic pain. Apart from being a therapeutic tool for neuropathic pain, rTMS can also be used as a method to select candidates for neurosurgically implanted cortical stimulation. It has been shown that a response to HF rTMS of M1 can predict a positive outcome after implantation (Lefaucheur et al., 2004a, 2011; André-Obadia et al., 2008, 2014; Hosomi et al., 2008). Therefore, it is good practice to perform rTMS tests before considering chronic cortical stimulation.

Regarding non-neuropathic pain conditions, sham-controlled results obtained in large series of patients and replicated by independent groups are lacking. In complex regional pain syndrome type 1, there are two sham-controlled studies showing a significant reduction of pain intensity following HF rTMS of M1, but outlasting stimulation for only a short time on average (Pleger et al., 2004; Picarelli et al., 2010). In fibromyalgia, two groups have reported prolonged effects of repeated HF rTMS sessions with a maintenance protocol, both on pain and quality of life, up to several months, but the target was the left M1 in one group (Mhalla et al., 2011) and the left DLPFC in the other group (Short et al., 2011). In migraine, HF rTMS of the left M1 (Misra et al., 2012, 2013) or the left DLPFC (Brighina et al., 2004) has also been assessed in sham-controlled studies showing a significant decrease in the frequency and intensity of migraine attacks. However, these promising results remain to be replicated by other groups (Conforto et al., 2014). It should also be noted that “conventional” rTMS protocols must be distinguished from devices delivering single or double TMS shocks over the occipital cortex during the aura of a migraine attack (Lipton et al., 2010). Despite rather debatable results, favorable recommendations have been recently issued on these devices for clinical application with FDA approval this year. Finally, one group showed that LF rTMS (1 Hz) delivered to the right secondary somatosensory cortex could provide pain relief in patients with visceral pain secondary to chronic pancreatitis (Fregni et al., 2005, 2011). Again, these results await replication in larger placebo-controlled studies.

Although rTMS represents a promising therapeutic tool in chronic pain, with proven efficacy, especially for M1 stimulation in neuropathic origin, further research is still needed to compare the respective value of various cortical targets, depending on the side and frequency of stimulation and the clinical presentation, with respect to the location and the respective sensory-discriminant and affective-emotional components of pain. A personalized approach should reduce the very high variability in rTMS analgesic response between individuals.

19. Conclusions and final remarks

This report aimed to provide the Reader with a comprehensive and updated knowledge on the basic mechanisms and practical applications of various forms of non-invasive, electromagnetic stimulation of the central and peripheral nervous systems and on the use of TMS as an adjunctive therapy of diseases resistant or only partly responding to drug treatments. An extended bibliography is also listed.

The same philosophy of the previous 1994 document has been implemented in the attempt to create a handout of value both for routine daily examinations and for building a research protocol. Other valuable reviews have been published in recent years on

several of the topics covered in this publication. This document will expand these offerings by taking advantage of a worldwide panel of experts covering all the various facets of the complex mosaic of non-invasive brain stimulation. We hope that reading this document will be as interesting and as much fun as it was for the authors to assemble it in its present form.

Conflict of interest

This work was not sponsored.

None of the authors have declared any conflict of interest.

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