# WiFiMCU Lua Reference Book



DoIT / LoBo

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# **Lua Basic Modules**

The Lua interpreter in WiFiMCU is based on Lua 5.1.4. The following modules are supported:

luaopen_base	Supported
luaopen_package	Supported
luaopen_string	Supported
luaopen_table	Supported
luaopen_math	Supported

'io' and 'debug' modules are not supported.

The functions description in supported modules can be found at: <a href="http://www.lua.org/manual/5.1/">http://www.lua.org/manual/5.1/</a>

# **MCU Module**

## **Function List**

mcu.ver()	Get the WiFiMCU firmware version
mcu.info()	Get the mxchipWNet library version, MAC address, WLAN driver version
mcu.reboot()	Reboot WiFiMCU
mcu.mem()	Get the memory status
mcu.chipid()	Get the stm32 chip ID (96 bits)
mcu.bootreason()	Get the WiFiMCU boot reason that caused its startup
mcu.getparams()	Get system parameters to lua table
mcu.sgetparams()	Print system parameters
mcu.setparams()	Set system parameters

## Constant

nil

## System parameters & Watchdog

## **System parameters**

There are a number of system parameters which can be modified to set the basic Lua system behavior. The parameters are saved in the parameter area of the WiFiMCU SPI Flash and are preserved between reboots/power cycles. The parameters are protected with CRC.

(default: 0 = IWDG; 1 = WWDG)

wdg\_tmo
 stack\_size
 inbuf\_size
 baud\_rate
 watchdog timeout in seconds miliseconds (default: 10000)
 size of the Lua thread stack in bytes (default: 20KB)
 size of the Lua input buffer in bytes (default: 256)
 baud rate of the Lua terminal (default: 115200)

parity parity used in Lua terminal (default: 'n', no parity)

init\_file name of the file which is executed on system start, if the name

is "", no file is executed. (default: "")

If some wrong parameters are set, and the system wont start, the parameters can be restored to the default values in **bootloader**, executing **3 -e** command.

## Watchdog

The system is protected by the watchdog. If the watchdog is not reloaded before the watchdog timeout expires, the system is RESET. The watchdog is automatically refreshed during the waiting for user input. If you have some long running Lua program, you have to reload the watchdog using *tmr.wdclr()* function before the watchgog timeout expires..

There are two types of watchdog in WiFiMCU Lua:

Watchdog type 0 is *STM32F411CE* **IWDG** timer (Independent Watchdog) which is set on system start and cannot be disabled. The IWDG is enabled even in STOP mode, so you cannot use STOP power save mode if this type of watchdog is used.

Watchdog type 1 is *STM32F411CE* **WWDG** timer (Window Watchdog). It does not run in STOP mode, so it is possible to use STOP power save mode with this watchdog type.

## mcu.ver()

#### Description

Get the WiFiMCU firmware version.

#### **Syntax**

nv,bd=mcu.ver()

#### **Parameters**

nil

#### **Returns**

```
nv: string type, WiFiMCU firmware version bd: string type, build date of the firmware
```

### **Examples**

```
> nv,bd=mcu.ver()
> print(nv,bd)
WiFiMCU 0.9.7 build 20151122
```

## mcu.info()

## Description

Get the mxchipWNet library version, MAC address, WLAN driver version.

**Syntax** libv,mac,drv=mcu.info()

Parameters nil

#### **Returns**

```
libv: mxchipWNet library version mac: MAC address of the module drv: WLAN driver version
```

### **Examples**

```
> libv,mac,drv=mcu.info()
> print(libv,mac,drv)
31620002.031 C8:93:46:50:21:4C wl0: Dec 29 2014 14:07:06 version 5.90.230.10
FWID 01-9bdaad4d
```

## mcu.reboot()

### Description

Reboot WiFiMCU immediately.

#### **Syntax**

mcu.reboot()

#### **Parameters**

nil

#### **Returns**

nil

### **Examples**

> mcu.reboot()

## mcu.mem()

### **Description**

Get the memory status.

**Syntax** fm,tas,mtas,fc=mcu.mem()

Parameters nil

#### Returns

fm: Total free space

tas: Total allocated space

mtas: Maximum total allocated space fc: Number of free chunks

### **Examples**

- > fm,tas,mtas,fc=mcu.mem()
- > print(fm,tas,mtas,fc)
- > 35600 50416 86016 25

## mcu.chipid()

### Description

Get the stm32 chip ID (96 bits).

## **Syntax**

chipid= mcu.chipid()

### **Parameters**

nil

#### **Returns**

chipid: the stm32 chip product ID

### **Examples**

- > chipid= mcu.chipid()
- > print(chipid)

0200C000FDFFFAE005DFF000

## mcu.bootreason()

### **Description**

Get the WiFiMCU boot reason that cause its startup.

#### **Syntax**

```
bootreason= mcu. bootreason()
```

#### **Parameters**

nil

#### **Returns**

bootreason: The boot reason should be one the followings:

"NONE": Fail to get the boot reason

"SOFT\_RST": Software reset "PWRON\_RST": Power on reset

"EXPIN RST": Pin reset

"WDG\_RST": Independent Watchdog reset
"WWDG RST": Window Watchdog reset

"LOWPWR RST": Low Power reset

"BOR\_RST": POR/PDR or BOR reset

### **Examples**

```
> mcu.bootreason()
SOFT_RST
```

## mcu.getparams()

#### **Description**

Get system parameters as Lua table.

### **Syntax**

```
param = mcu.getparams()
```

#### **Parameters**

nil

## **Returns**

param: Lua table containing the system parameters

```
> param= mcu.getparams()
> for k,v in pairs(param) do print("param: "..k.." = "..v) end
param: inbuf_size = 256
param: stack_size = 20480
param: baud_rate = 115200
param: crc = 0k
param: wdg_tmo = 10000
param: parity = NO_PARITY
param: init_file =
param: use_wwdg = 0
```

## mcu.sgetparams()

```
Description
   Print system parameters.
Syntax
   mcu.sgetparams()
Parameters
   nil
Returns
   nil, prints parameters
Examples
   > mcu.sgetparams()
      use wwdq = 0
      wdg tmo = 10000
    stack size = 20480
    inbuf size = 256
     init_file = ""
     baud rate = 115200
```

parity = 'n'

## mcu.setparams()

#### **Description**

CRC ok.

Set one or more system parameters.

## **Syntax**

mcu.setparams(paramtbl)

#### **Parameters**

```
paramtbl: Lua table containing one or more parameters

use_wwdg
wdg_tmo
stack_size
inbuf_size
init_file
baud_rate
parity

watchdog type, 0 or 1, default = 0 (hardware IWDG)
watchdog timeout in milisec, 2000~36000000, default = 10000
stack_size in bytes, 5000~31000, default = 20480
lua stack size in bytes, 128~1024, default = 256
name of the file executed on boot, default = "", no script executed
lua serial terminal baud rate, default = 115200
lua serial terminal parity, 'n' or 'e' or 'o', default = 'n'
```

Note: if watchdog type is changed, the system will reboot after watchdog timeout expires.

#### **Returns**

nil, prints status

```
> =mcu.setparams({stack_size=10240,use_wwdg=1,init_file="init.lua"})
updated: soft_wdg, RESET in 10 sec!
updated: stack_size
updated: init_file
New params saved.
```

# **GPIO Module**

# **Function List**

gpio.mode()	Define the GPIP Pin mode, set the pin to input output or interrupt mode
gpio.read()	Read the pin value
gpio.write()	Set the pin value
gpio.toggle()	Toggle the pin's output value

## Constant

gpio.INPUT	Input with an internal pull-up resistor
gpio.INPUT_PULL_UP	Input with an internal pull-up resistor
gpio.INPUT_PULL_DOWN	Input with an internal pull-down resistor
gpio.INPUT_INPUT_HIGH_IMPEDANCE_DOWN	Input high impedance down
gpio.OUTPUT	Output actively driven high and actively driven low
gpio.OUTPUT_PUSH_PULL	Output actively driven high and actively driven low
gpio.OUTPUT_OPEN_DRAIN_NO_PULL	Output actively driven low but is high-impedance when set high
gpio.OUTPUT_OPEN_DRAIN_PULL_UP	Output actively driven low and is pulled high with an internal resistor when set high
gpio.INT	Interrupt
gpio.HIGH	High voltage level
gpio.LOW	Low voltage level

## **GPIO Pin Table**

WiFiMCU Index	Alternate function	Discription
D0	GPIO/BOOT	WiFiMCU would enter into Bootloader Mode, if D0 goes to LOW
D1	GPIO/PWM/ADC	
D2	GPIO	
D3	GPIO/PWM	
D4	GPIO	
D5	GPIO	SWD Flash Programming Pin: swclk
D6	GPIO	SWD Flash Programming Pin: swdio
D7	GPIO/SPI5_MISO	
D8	GPIO/PWM/SPI5_MOSI	Uart1 rx pin: RX1
D9	GPIO/PWM	Uart1 tx pin: TX1
D10	GPIO/PWM	I2C interface: SCL
D11	GPIO/PWM	I2C interface: SDA
D12	GPIO/PWM	
D13	GPIO/PWM/ADC	
D14	GPIO/PWM	
D15	GPIO/PWM/ADC	
D16	GPIO/PWM/ADC/SPI5_CLK	
D17	GPIO/ADC	BLUE LED on WiFiMCU board

## gpio.mode()

#### **Description**

Define the GPIO Pin mode, set the pin to input output or interrupt mode.

## **Syntax**

```
gpio.mode(pin, mode)
gpio.mode(pin, gpio.INT, trigMode, func cb)
```

#### **Parameters**

```
pin: gpio ID, 0~17
mode: Should be one of the followings: gpio.INPUT
gpio.INPUT_PULL_UP gpio.INPUT_PULL_DOWN
gpio.INPUT_INPUT_HIGH_IMPEDANCE_DOWN gpio.OUTPUT
gpio.OUTPUT_PUSH_PULL gpio.OUTPUT_OPEN_DRAIN_NO_PULL
gpio.OUTPUT_OPEN_DRAIN_PULL_UP gpio.INT
trigMode: if mode is gpio.INT, trigMode should be:
'rising': Interrupt triggered at input signal's rising edge
'falling': Interrupt triggered at both rising and falling edge
```

func cb: if mode is gpio.INT, the interrupt call back function

Note: It's recommend that you DO NOT do too much time consuming operations in the func cb.

#### Returns nil

## **Examples**

```
>gpio.mode(0, gpio.OUTPUT)
>gpio.write(0, gpio.HIGH)
>gpio.mode(1,gpio.INPUT)
>print(gpio.read(1))
>0
```

## gpio.read()

## Description

Read the pin value.

Syntax value=gpio.read(pin)

### **Parameters**

```
pin: gpio ID, 0~17
```

#### **Returns**

```
value: 0 - low, 1 - high
```

#### **Examples**

```
> gpio.mode(0, gpio.INPUT)
> print(gpio.read(0))
> 0
```

## gpio.write()

### Description

Set the pin value.

#### **Syntax**

gpio.write(pin, value)

### **Parameters**

```
pin: gpio ID, 0~17
```

value: 0 or 1 or gpio.HIGH or gpio.LOW

#### Returns nil

```
> gpio.mode(0, gpio.OUTPUT)
> gpio.write(0,gpio.HIGH)
> gpio.write(0,0)
```

## gpio.toggle()

## Description

Toggle the pin's output value **Syntax** gpio.toggle(pin)

## **Parameters**

pin: gpio ID, 0~17

Returns nil

```
>gpio.mode(17, gpio.OUTPUT)
>gpio.toggle(17)
>gpio.toggle(17)
```

## **TIMER Module**

## **Function List**

tmr.start()	Start a timer with call back function
tmr.stop()	Stop a timer
tmr.stopall()	Stop all the timers
tmr.tick()	Get the current time tick of the MCU (ms) since startup
tmr.delayms()	Delay for a assigned time in millisecond
tmr.delayus()	Delay for a assigned time in microsecond
tmr.wdclr()	Clear the Independent watchdog counter

## **Constant**

nil

## tmr.start()

## Description

Start a timer with call back function.

## **Syntax**

tmr.start(tmrID, interval, func\_cb)

### **Parameters**

tmrID: timer ID,  $0\sim15$ . 16 timers are supported at present

interval: interval time for the timer func cb: Callback function for the timer

### Returns nil

```
> tmr.start(1,1000,function() print("tmr1 is called") end)
> tmr1 is called
tmr1 is called
tmr1 is called
```

## tmr.stop()

```
Description
        Stop a timer
Syntax
        tmr.stop(tmrID)
Parameters
        tmrID: timer ID, 0~15
Returns
        nil
Examples
        > tmr.start(1,1000,function() print("tmr1 is called") end)
        tmr1 is called
        tmr1 is called
        tmr1 is called
        tmr1 is called
        tmr1 is called
```

## tmr.stopall()

### Description

Stop all the timer.

### **Syntax**

tmr.stopall(tmrID)

#### **Parameters**

nil

## **Returns**

nil

## **Examples**

```
> tmr. stopall()
```

## tmr.tick()

#### **Description**

Get the current time tick of the MCU (ms) since startup.

Syntax tick=tmr.tick()

Parameters nil

Returns nil

```
>print(tmr.tick())
1072237
```

## tmr.delayms()

## **Description**

Delay for a assigned time in millisecond.

## **Syntax**

tmr.delayms(ms)

#### **Parameters**

ms: The delay time in millisecond

#### **Returns**

nil

### **Examples**

> tmr.delayms(1000)

## tmr.delayus()

### Description

Delay for a assigned time in microsecond.

#### **Syntax**

tmr.delayus(us)

#### **Parameters**

us: The delay time in microsecond

#### **Returns**

nil

### **Examples**

> tmr.delayus(1000)

## tmr.wdclr()

### Description

Clear the independent watchdog counter.

The default independent watchdog time is 10 senconds.

Note: This function should be called if some operations takes more than 10 seconds to complete

## **Syntax**

tmr. wdclr ()

#### Parameters nil

Returns nil

## **Examples**

> tmr.wdclr()

## WiFi Module

# **Function list**

wifi.startap()	Setup wifi in soft Access Point (AP) Mode, enable DHCP function
wifi.startsta()	Setup wifi in Station Mode (STA), begin to connect a AP
wifi.scan()	Scan APs
wifi.stop()	Close all the Wi-Fi connections, Both in station mode and soft ap mode
wifi.powersave()	Enable IEEE power save mode
wifi.ap.getip()	Get ip address in soft AP mode
wifi.ap.getipadv()	Get advanced net information in soft AP mode: DHCP mode, ip address, gateway, netmask, dns, MAC, broad cast address
wifi.ap.stop()	Close all the Wi-Fi connections in soft ap mode
wifi.sta.getip()	Get ip address in STA mode
wifi.sta.getipadv()	Get advanced net information in STA mode: DHCP mode, ip address, gateway, netmask, dns, MAC, broad cast address
wifi.sta.getlink()	Get the connected AP information in STA mode: Connect status, WiFi signal strength, ssid, bssid.
wifi.sta.stop()	Close all the Wi-Fi connections in STA mode
wifi.sta.ntptime()	Set RTC datetime from ntp server

## Constant

nil

## wifi.startap()

### Description

Setup wifi in soft Access Point (AP) Mode, enable DHCP function.

Syntax wifi.startap(cfg)

wifi.startap(cfg,func\_cb)

#### **Parameters**

cfg: lua table, contains the configurations for soft AP mode.

cfg.ssid: soft AP's ssid

cfg.pwd: soft AP's password. It will be an open WiFi if cfg.pwd is empty

```
cfg.ip: optional. The local ip address of the module, Default: "11.11.11.1"
```

cfg.netmask: optional. Default: "255.255.255.0" optional. Dafault: "11.11.11.1"

cfg.dnsSrv: optional. DNS server address. Default: "11.11.11.1" cfg.retry\_interval: optional. retry interval in micro seconds. Default: 1 sec

func\_cb: The callback function when the soft AP is setup successfully or the soft

AP is shut down.

#### **Returns** nil

### **Examples**

```
>cfg={}
>cfg.ssid="WiFiMCU_Wireless"; cfg.pwd=""
>wifi.startap(cfg)
```

## wifi.startsta()

### **Description**

Setup wifi in Station Mode (STA), begin to connect a AP.

## **Syntax**

```
wifi.startsta(cfg)
wifi.startsta(cfg, func cb)
```

#### **Parameters**

cfg: lua table, contains the configurations for soft AP mode.

cfg.ssid: AP's ssid

cfg.pwd: AP's password

cfg.dhcp: optional. Set dhcp function: 'enable' is to enable the dhcp function.

WiFiMCU will get ip automatically. 'disable' is to disable the dhcp

function. It's 'enable' in default.

cfg.ip: optional. The local ip address of the module. If cfg.dhcp is 'disable' this

parameter must be assigned.

cfg.netmask: optional. Netmask. If cfg.dhcp is 'disable' this parameter must be assigned. cfg.gateway: optional. Gateway. If cfg.dhcp is 'disable' this parameter must be assigned. cfg.dnsSrv: optional. DNS server address. If cfg.dhcp is 'disable' this parameter must be assigned.

cfg.retry\_interval: optional. retry interval in micro seconds. If cfg.dhcp is 'disable' this parameter must be assigned.

func\_cb: The callback function when WiFiMCU had connected to the AP successfully, or WiFiMCU is disconnected to from the AP.

#### Returns nil

```
>cfg={}
>cfg.ssid="Doit"; cfg.pwd="123456789"
>wifi.startsta(cfg)
```

## wifi.scan()

#### **Description**

Scan AP list and return a Lua table containing the results.

**Syntax** wifi.scan(fun cb(t))

#### **Parameters**

func\_cb(t): The callback function when scan is finished. 't' is a Lua table in which the keys are the APs' ssid and values are strings in format (" mac, signal strength, channel, authmode")

#### Returns nil

#### **Examples**

## wifi.stop()

### **Description**

Close all the Wi-Fi connections, Both in station mode and soft ap mode.

Syntax wifi.stop()

Parameters nil

Returns nil

**See also** wifi.ap.stop() wifi.sta.stop()

#### **Examples**

```
> wifi.stop()
```

## wifi.powersave()

#### **Description**

Enable IEEE power save mode.

#### **Syntax**

wifi. powersave ()

#### **Parameters**

nil

#### **Returns**

nil

```
> wifi. powersave ()
```

## wifi.ap.getip()

### Description

Get ip address in AP mode

#### **Syntax**

ip=wifi. ap.getip()

#### **Parameters**

nil

#### **Returns**

ip: The module ip in soft AP mode.

### **Examples**

```
> ip=wifi.ap.getip ()
> print(ip)
11.11.11.1
```

## wifi.ap.getipadv()

### **Description**

Get advanced net information in soft AP mode: DHCP mode, ip address, gate way, net mast, dns, MAC, broadcast address.

#### **Syntax**

dhcp,ip,gw,nm,dns,mac,bip =wifi. ap.getipadv()

#### Parameters nil

#### **Returns**

dhcp: DHCP mode. in soft AP mode, it will be always "DHCP Server"

ip: ip address.

gw: gateway address. nm: netmask.dns: dns address. mac: MAC address.

bip: broadcast ip address.

```
> dhcp,ip,gw,nm,dns,mac,bip =wifi.ap.getipadv()
> print(dhcp,ip,gw,nm,dns,mac,bip)

DHCP_Server 11.11.11.1 11.11.1 255.255.255.0 208.67.222.222 c89346501a62
255.255.255.255
```

## wifi.ap.stop()

### **Description**

Close all the Wi-Fi connections in soft ap mode.

Syntax wifi.ap.stop()

Parameters nil

Returns nil

**See also** wifi.stop() wifi.sta.stop()

## **Examples**

```
> wifi.ap.stop()
```

## wifi.sta.getip()

### Description

Get ip address in STA mode.

#### **Syntax**

```
ip=wifi. sta.getip()
```

#### **Parameters**

nil

### **Returns**

ip: The module ip in STA mode.

### **Examples**

```
> ip = wifi.sta.getip ()
> print(ip)
192.168.1.108
```

## wifi.sta.getipadv()

### **Description**

Get advanced net information in STA mode: DHCP mode, ip address, gateway, netmask, dns, MAC, broad cast address.

#### **Syntax**

```
dhcp,ip,gw,nm,dns,mac,bip =wifi. sta.getipadv()
```

#### Parameters nil

#### **Returns**

dhcp: DHCP mode. in STA mode, "DHCP Server" or "DHCP Client" or

DHCP Disable ip: ip address.

gw: gateway address.

nm: netmask.

dns: dns address. mac: MAC address.

bip: broadcast ip address.

## **Examples**

```
> dhcp,ip,gw,nm,dns,mac,bip = wifi.sta.getipadv()
```

> print(dhcp,ip,gw,nm,dns,mac,bip)

DHCP\_Client 192.168.1.108 192.168.1.1 255.255.255.0 192.168.1.1 c89346501a62 255.255.255

## wifi.sta.getlink()

## **Description**

Get the connected AP information in STA mode:Connect status, WiFi signal strength, ssid, bssid.

**Syntax** status, strength, ssid, bssid=wifi.sta.getlink()

**Parameters** nil

### **Returns**

status: The connecting status. if connected it's "connected" else it's "disconnected".

It will be nil for strength/ssid/bssid if it's "disconnected".

strength: The signal strength. ssid: The connected AP's ssid. bssid: The connected AP's bssid.

#### **Examples**

```
> status,strength,ssid,bssid=wifi.sta.getlink()
> print(status,strength,ssid,bssid)
```

connected 62 Doit BC:D1:77:32:E7:2E

## wifi.sta.stop()

### **Description**

Close all the Wi-Fi connections in STA mode.

Syntax wifi.sta.stop()

Parameters nil

Returns nil

**See also** wifi.stop() wifi.ap.stop()

## **Examples**

> wifi.sta.stop()

## wifi.sta.ntptime()

## Description

Set RTC datetime from ntp server.

#### **Syntax**

wifi.sta.ntptime()
wifi.sta.ntptime(timezone)
wifi.sta.ntptime(timezone,ntpserver)

#### **Parameters**

timezone: optional, use specified time zone offset from UTC (-12 - +14), default=0 optional, specify ntp server to use, default="time1.google.com"

### Returns

status: disconnected if no wifi connection detected

### **Examples**

> wifi.sta.ntptime(1)

## **Net Module**

## **Function list**

net.new()	Create a new socket, set the socket and transmission protocol
net.start()	Start the socket, set remote port, remote ip address, or local port according to the socket and transmission protocol
net.on()	Register the callback functions for socket events
net.send()	Send data
net.close()	Close socket
net.getip()	Get the ip address and port of the client socket.

## Constant

net.TCP	TCP protocol
net.UDP	UDP protocol
net. SERVER	Server type
net.CLIENT	Client type

## net.new()

## Description

Create a new socket, set the socket and protocol type.

Max 4 server and max 4 client can be setup in WiFiMCU.

If the socket type is Server, max number of 5 clients are allowed to connect.

**Syntax** skt=net.new(protocol,type)

#### **Parameters**

protocol: The transmission protocol, must be one of the two: net.TCP,

type: socket type, must be one of the two: net.SERVER, net.CLIENT

#### **Returns**

skt: the handle for this socket

### **Examples**

>skt = net.new(net.TCP,net.SERVER)

```
>skt2 = net.new(net.UDP,net.CLIENT)
```

## net.start()

### **Description**

Start the socket, set remote port, remote ip address, or local port according to the socket and transmission protocol.

#### **Syntax**

```
net.start(socket, localport)
net.start(socket, remoteport, "domain", [local port])
```

#### **Parameters**

socket: The socket handle returned from net.new()

localport: If the socket type is net.SERVER, It's the local binded port for this socket. remoteport: If the socket type is net.CLIENT, It's the remote server port.

"domain": If the socket type is net.CLIENT, it's the domain name string for remote server. The remote server's ip address can be used too.

local port: Optinal, if the socket type is net.CLIENT, [local port] set the local binded port for the socket. If ignored, a random port would be assigned.

#### Returns nil

## **Examples**

```
> skt = net.new(net.TCP,net.SERVER)
> skt2 = net.new(net.UDP,net.CLIENT)
> net.start(skt, 80)
> net.start(skt2,9000,'11.11.11.2', 8000)
```

## net.on()

#### **Description**

Register the callback functions for socket events.

**Syntax** net.on(socket,event,func cb)

#### **Parameters**

socket: The socket handle returned from net.new()

event: If the socket type is net.SERVER, event should be one of the following:

"accept" (TCP server socket only), "receive", "sent", "disconnect".

If the socket type is net.CLIENT, event should be one of the following:

"connect(TCP client socket only)", "receive", "sent", "disconnect", "dnsfound".

func cb: Callback function for different events. The function parameters diff from events.

"accept": TCP server socket only. If the tcp server accept a tcp client connection request, the function will be called. Function prototype is: func cb(clt, ip, port). "clt"

is the tcp client socket handle, "ip" is the client ip address, "port" is the client's port.

- "receive": If data arrived on the assigned socket, the function will be called. Function prototype is: func cb(clt, data). "clt" is the socket handle, "data" is the received data.
- "sent": When data had sent succeffuly on the assigned socket, the function will be called. Function prototype is: func cb(clt). "clt" is the socket handle.
- "disconnect": If the client socket is disconnected from server or some errors happened, the function will be called. Function prototype is: func\_cb(clt). "clt" is the socket handle.
- "connect": TCP Client socket only. When the client socket connects to the remote server successfully, the function will be called. Function prototype is: func\_cb(clt). "clt" is the socket handle.
- "dnsfound": TCP or UDP Client socket only. When the DNS operations has finished, the function will be called. Function prototype is: func\_cb(clt, ip). "clt" is the socket handle, "ip" is the ip address for the domain.

#### Returns nil

## **Examples**

```
> clt = net.new(net.TCP,net.CLIENT)
> net.on(clt,"dnsfound",function(clt,ip) print("dnsfound clt:"..clt.." ip:"..ip)
end)
> net.on(clt,"connect",function(clt) print("connect:clt:"..clt) end)
> net.on(clt,"disconnect",function(clt) print("disconnect:clt:"..clt) end)
> net.on(clt,"receive",function(clt,d) print("receive:clt:"..clt.."data:"..d)
end)
> net.start(clt,9003,"11.11.11.2")
```

## net.send()

#### **Description**

Send data.

### **Syntax**

net.send(socket, data, [func\_cb])

#### **Parameters**

```
socket: The socket handle returned from net.new() data: Data to be sent.
```

func\_cb: Optinal, "sent" eventcall back function. When data had sent succeffuly on the assigned socket, the function will be called. Function prototype is: func\_cb(clt). "clt" is the socket handle.

#### Returns nil

```
>net.send(clt,"hello")
```

## net.close()

#### **Description**

Close socket, release the resource of the socket.

### **Syntax**

net.close(socket)

#### **Parameters**

socket: The socket handle returned from net.new()

#### **Returns**

nil

## **Examples**

```
>skt = net.new(net.TCP,net.SERVER) >net.close(skt)
```

## net.getip()

### Description

Get the ip address and port of the client socket.

## **Syntax**

```
ip, port = net.getip(socket)
```

### **Parameters**

socket: The socket handle returned from net.new(). The socket handle should be a client socket.

#### **Returns**

ip: the ip address for the socket. port: the port for the socket.

```
>ip, port = net.getip(clt)
```

# **File Module**

The file system is based on spi flash embeded in WiFiMCU. The total storage capacity is  ${\sim}1550\mbox{K}$ 

## **Function list**

file.format()	Format file system, all stored data will be lost after format
file.open()	Open or create a file
file.close()	Close an opened file
file.write()	Write data to an opened file
file.writeline()	Write data to an opened file, with a '\n' added at the tailed of data
file.read()	Read data from an opened file
file.readline()	Read a line data from an opened file
file.list()	Get the file name and size list in file system
file.slist()	Print the file name and size list on terminal
file.remove()	Remove file
file.seek()	Set the position of file pointer
file.flush()	Clear file buffer
file.rename()	Rename the file
file.info()	Get the file system storage status
file.state()	Get the opened file's name and size
file.compile()	Compile a Lua scripts file to lc file.
file.recv()	Receive the file using Ymodem protocol
file.send()	Send the file using Ymodem protocol
dofile()	Run a file

## Constant

nil

## file.format()

#### **Description**

Format file system, all stored data will be lost after format. It's recommended not to do anythings while formatting.

### **Syntax**

file.format()

#### Parameters nil

#### Returns nil

If formatting is done successfully, "format done" will be printed, else "format error" will be printed.

### **Examples**

```
>file.format()
format done
```

## file.open()

#### **Description**

Open or create a file.

### **Syntax**

```
ret = file.open(filename,mode)
```

#### **Parameters**

filename: filename string to be created or opened. Directories are not supported yet. mode: open type:

```
"r": read mode (the default parameter)
```

"r+": update mode, all previous data is preserved

"w": write mode

"w+": update mode, all previous data is erased

"a": append mode

"a+": append update mode, previous data is preserved, writing is only

allowed at the end of file

#### **Returns**

ret: true if succeed, else nil.

```
>file.open("test.lua","w+")
>file.write("This is a test") >file.close()
```

## file.close()

#### Description

Close an opened file.

## **Syntax**

file.close()

#### **Parameters**

nil

#### **Returns**

nil

### **Examples**

```
>file.open("test.lua","w+")
>file.write("This is a test")
>file.close()
```

## file.write()

### Description

Write data to an opened file.

**Syntax** ret=file.write(data)

#### **Parameters**

data: The data to be wrote.

#### **Returns**

ret: true if succeed, else nil.

### **Examples**

```
>file.open("test.lua","w+")
>file.write("This is a test")
>file.close()
```

## file.writeline()

### **Description**

Write data to an opened file, with a '\n' added at the tailed of data.

**Syntax** ret=file.writeline(data)

#### **Parameters**

data: The data to be wrote. A char '\n' will be added at the end of data.

#### **Returns**

ret: true if succeed, else nil.

```
>file.open("test.lua","w+")
```

```
>file.writeline("This is a test")
>file.close()
```

## file.read()

## Description

Read data from an opened file.

### **Syntax**

```
ret=file.read()
ret=file.read(num)
ret=file.read(endchar)
```

### **Parameters**

if the parameter is nil, read all byte in file.

num: if a number is assigned, read the num bytes from file, or all rest data in case of end of file.

endchar: read until endchar or EOF is reached.

#### **Returns**

ret: the file data if succeed, else nil.

### **Examples**

```
>file.open("test.lua","r")
>data=file.read()
>file.close()
>print(data)
This is a test
>file.open("test.lua","r")
>data=file.read(10)
>file.close()
>print(data)
This is a
>file.open("test.lua","r")
>data=file.read('e')
>file.close()
>print(data)
This is a
```

## file.readline()

### **Description**

Read a line data from an opened file.

Syntax ret=file.readline ()

Parameters nil

## Returns

ret: the file data if succeed, else nil.

## **Examples**

```
>file.open ("test.lua","w+")
>file.writeline("this is a test")
>file.close()
>file.open("test.lua","r")
>data=file.readline()
>print(data)
This is a test
>file.close()
```

## file.list()

## **Description**

Get the file name and size list in file system.

**Syntax** ft=file.list()

Parameters nil

#### **Returns**

ft: a Lua table, in which the filename is the key, file size is the value.

## **Examples**

```
>for k,v in pairs(file.list()) do print("name:"..k.." size(bytes):"..v) end
name:test.lua size(bytes):15
```

# file.slist()

## **Description**

Print the file name and size list on terminal.

Syntax file.slist()

Parameters nil

Returns nil

**Examples** 

```
>file.slist()
test.lua size:15
```

# file.remove()

## **Description**

Remove file.

### **Syntax**

file.remove(filename)

```
Parameters
```

filename: filename string to be removed.

#### Returns

nil

## **Examples**

```
>file.remove("test.lua")
```

## file.seek()

## Description

Set the position of file pointer.

## **Syntax**

fi = file.seek(whence, offset)

#### **Parameters**

whence: should be one of the following:

```
"set": base is position 0 (beginning of the file);
"cur": base is current position;(default value)
"end": base is end of file;
```

offset: default 0.

#### **Returns**

fi: the file pointer final position if succeed, else nil.

## **Examples**

```
>file.open ("test.lua","r")
>file.seek("set",10)
>data=file.read()
>file.close()
>print(data)
test
```

## file.flush()

## **Description**

Clear file buffer.

## **Syntax**

ret = file.flush()

### Parameters nil

### **Returns**

ret: true if succeed, else nil.

```
>file.open ("test.lua","r")
>file.flush ()
```

```
>file.close()
```

## file.rename()

## Description

Rename the file.

## **Syntax**

ret=file.rename(oldname,newname)

#### **Parameters**

oldname: File name to be changed.

newname: New file name.

#### **Returns**

ret: true if succeed, else nil.

## **Examples**

```
> file.slist()
test.lua size:14
>file.rename('test.lua',' testNew.lua')
>file.slist()
testNew.lua size:14
```

# file.info()

## **Description**

Get the file system storage status.

## **Syntax**

last,used,total = file.info()

### Parameters nil

#### **Returns**

last: free storage left in bytes. used: used storage in bytes.

total: all allocated storage for file system in bytes.

## **Examples**

```
> last,used,total = file.info()
> print(last,used,total)
1140500 2750 1143250
```

## file.state()

## Description

Get the opened file's name and size

### **Syntax**

```
fn,sz = file.state()
```

#### Parameters nil

#### **Returns**

```
fn: filename.sz: file size in bytes.
```

### **Examples**

```
>file.open("testNew.lua","r")
>fn,sz = file.state()
>file.close()
>print(fn,sz)
testNew.lua 14
```

## file.compile()

## Description

Compile a Lua scripts file to lc file. The lc file will be named as the same name as the Lua file.

Syntax file.compile('filename.lua')

#### **Parameters**

filename.lua: file name of the Lua scripts.

Returns nil.

## **Examples**

```
>file.open("test.lua","w+")
>file.write("print('Hello world!')")
>file.close()
>file.compile("test.lua")
>file.slist()
test.lua size:21 test.lc size:100
```

# file.recv()

## Description

Receive the file over serial line using ymodem protocol.

```
Syntax file.recv(["filename"])
```

#### **Parameters**

filename: optional; if specified, the file is saved with that name, otherwise, file name from the sender is used

Returns nil. After receive, the directory content is printed

### **Examples**

> file.recv()

Start Ymodem file transfer...

CCCCCCCCCCCCC

Starting ymodem transfer. Press Ctrl+C to cancel.

Transferring test.lua...

100% 12 KB 12 KB/sec 00:00:01 0 Errors

Received successfully, 12389

oledtest.lua size: 1178 init.lua size: 1337 test.lua size: 12389

> file.recv("new\_test.lua")

Start Ymodem file transfer...

Starting ymodem transfer. Press Ctrl+C to cancel.

Transferring test.lua...

100% 12 KB 12 KB/sec 00:00:01 0 Errors

Received successfully, 12389

oledtest.lua size: 1178
init.lua size: 1337
test.lua size: 12389
new\_test.lua size: 12389

## file.send()

## **Description**

Send the file over serial line using ymodem protocol.

Syntax file.recv("filename",["newfilename"])

### **Parameters**

Filename: name of the file to send

newfilename: optional; if specified, the file is sent with that name, othewise, the

original file name is used

**Returns** nil. After receive, the directory content is printed

```
Examples
```

```
> file.send("test.lua")
Start Ymodem file transfer...
CCCCCCC
Starting ymodem transfer. Press Ctrl+C to cancel.
Transferring test.lua...
 100%
          12 KB
                    12 KB/sec
                                 00:00:01
                                               0 Errors
File sent successfuly.
> file.send("test.lua","old-test.lua")
sending "test.lua" as "old-test.lua"
Start Ymodem file transfer...
CCCCCC
Starting ymodem transfer. Press Ctrl+C to cancel.
Transferring old-test.lua...
 100%
          12 KB
                    12 KB/sec
                                 00:00:01
                                               0 Errors
File sent successfuly.
```

# dofile()

## **Description**

Run a file. The file can be either a Lua scripts or a lc format file.

## **Syntax**

dofile('filename.lua')
dofile('filename.lc')

#### **Parameters**

filename.lua: Lua scripts file. filename.lc: a lc file

Returns nil.

## **Examples**

>dofile("test.lua")
Hello world!
>dofile("test.lc")
Hello world!

# **PWM Module**

## **Function list**

pwm.start()	Start pwm function at assigned gpio pin
pwm.stop()	Stop pwm

## **Constant**

nil

## Pin Table

Plaese refer: "GPIO Table" for detail.

## pwm.start()

## **Description**

Start pwm function at assigned gpio pin.

## **Syntax**

pwm.start(pin, freq, duty)

## **Parameters**

```
pin: gpio pin ID. There are 11 PWM ports supported in WiFiMCU: D1, D3, D4, D9, D10, D11, D12, D13, D14, D15, D16. freq: PWM output frequency in Hz, 0<freq<10KHz duty: Duty of PWM output, must be 0<=duty <=100
```

Returns nil.

```
>i=1;pin=1;
>tmr.start(1,1000,function() i=i+10;if i>=100 then i=1 end
pwm.start(pin,10000,i)
end)
>
```

# pwm.stop()

## Description

Stop pwm.

Syntax pwm.stop(pin)

## **Parameters**

pin: gpio pin ID. There are 11 PWM ports supported in WiFiMCU: D1, D3, D4, D9, D10, D11, D12, D13, D14, D15, D16.

Returns nil.

## **Examples**

>pwm.stop(1)

# **ADC Module**

## **Function list**

adc.read()	Read the ADC result at assigned pin
adc.readmv()	Read the ADC result in mV at assigned pin

## Constant

nil

## Pin Table

Plaese refer: "GPIO Table" for detail.

# adc.read()

## Description

Read the ADC result at assigned pin.

## **Syntax**

data= adc.read(pin)

## **Parameters**

pin: gpio pin ID.

There are 5 ADC ports supported in WiFiMCU: D1, D13, D15, D16, D17.

## Returns

data: if succeed, data between 0~4095 is returned, else nil.

Note that: 0 presents 0V, 4095 presents 3.3V.

```
>=adc.read(1)
0
>=adc.read(1)
4095
```

# adc.readmv()

## Description

Read the ADC result in mV (mili volts) at assigned pin.

#### **Syntax**

```
data= adc.readmv(pin)
```

## **Parameters**

```
pin: gpio pin ID.

There are 5 ADC ports supported in WiFiMCU: D1, D13, D15, D16, D17.
```

#### **Returns**

data: if succeed, data between 0~3300 is returned, else nil.

```
>=adc.readmv(1)
1
>=adc.readmv(1)
3300
```

# **UART Module**

Only one hardware UART is supported in WiFiMCU. The GPIO pin is D8(RX1), D9(TX1). One software emulated UART is also supported on any GPIO pins.

## **Function list**

uart.setup()	Setup uart parameters: buadrate, databits, parity, stopbits.
uart.on()	Register the callback functions for uart events
uart.send()	Send data via uart
uart.recv()	Get received bytes as string
uart.recvstat()	Get number of received bytes and error status.

## Constant

null

Software emulated UART is full duplex, supported baud rates 1200~115200. At 115200 bd, the sender must be configured for **2** stop bits!

Warning: hardware UART shares Rx pin with hardware SPI5. You can't use both at the same time.

## uart.setup()

## **Description**

Setup uart parameters: buadrate, databits, parity, stopbits.

## **Syntax**

uart.setup(id, baud, parity, databits, stopbits [,txpin, rxpin])

#### **Parameters**

id: uart ID: 1=hardware UART; 2=software emulated UART

baud: baudrate, such as: 4800, 9600, 115200. parity: 'n': no parity, 'o': odd parity, 'e': even parity.

databits: data bits:  $5\sim9$  stopbits: stop bits,  $1\sim2$ 

txpin: only for software UART: Tx output pin; gpio ID,  $0\sim17$  rxpin: only for software UART: Rx input pin; gpio ID,  $0\sim17$ 

#### Returns nil

## **Examples**

```
>uart.setup(1,9600, 'n', 8, 1)
>uart.setup(2,38400, 'n', 8, 2, 3, 4)
```

## uart.on()

## **Description**

Register the callback functions for uart events.

### **Syntax**

uart.on(id, event ,func cb)

#### **Parameters**

id: uart ID: 1=hardware UART; 2=software emulated UART.

event: always "data".

func cb: Callback function for the event. When data arrived, the function will

be called. Function prototype is: func cb(len, data)

**len** is number of bytes received; **data** is the data received.

#### Returns nil

### **Examples**

```
>uart.on(1, 'data',function(len, t) print(len, " "..t) uart.send(1,t) end)
```

## uart.send()

## **Description**

Send data via uart.

#### **Syntax**

```
uart.send(id, string1,[num],...[stringn])
```

## **Parameters**

```
id: uart ID: 1=hardware UART; 2=software emulated UART.
```

string1: string to send.

[num]: Optional, number (character code) to send.

[stringn]: Optional, the nth string to send.

### Returns nil

```
>uart.send(1,'hello wifimcu')
>uart.send(1,'hello wifimcu','hi',string.char(0x32,0x35))
>uart.send(1,string.char(0x01,0x02,0x03), 0x42)
```

## uart.recvstat()

## **Description**

Check receive status.

## **Syntax**

uart.recvstat(id)

#### **Parameters**

id: uart ID: 1=hardware UART; 2=software emulated UART.

#### **Returns**

len: number of bytes received.

err: number of errors (frame errors + parity errors)

## **Examples**

```
>uart.recvstat(2)
>uart.recvstat(1)
        0
40
```

## uart.recv()

## **Description**

Get received bytes as string.

## **Syntax**

uart.recv(id, [len])

#### **Parameters**

id: uart ID: 1=hardware UART; 2=software emulated UART. len:

Optional: number of bytes to get; default: all bytes

## **Returns**

string of received bytes; "[nil]" if nothing is received recstr:

```
>uart.recv(2)
Received via software uart
>uart.recvstat(1)
>uart.recv(1, 16)
Received via har
>uart.recvstat(1)
>uart.recv(1)
dware uart
```

# **Bit Module**

# **Function List**

bit.bnot	Bitwise negation
bit.band	Bitwise AND
bit.bor	Bitwise OR
bit.bxor	Bitwise XOR
bit.lshift	Logical left shift a number
bit.rshift	Logical right shift a number
bit.arshift	Arithmetic right shift a number
bit.bit	Generate a number with a 1 bit (used for mask generation)
bit.set	Set bits in a number
bit.clear	Clear bits in a number
bit.isset	Test if a given bit is set
bit.isclear	Test if a given bit is cleared

## Constant

nil

# bit.bnot()

## Description

Bitwise negation.

**Syntax** num=bit.bnot(val)

## **Parameters**

val: the number to negation, value is 32 bit width.

## **Returns**

num: the bitwise negated value of the number.

```
>print("result: "..bit.bnot(0x00000000))
result: -1
```

## bit.band()

## **Description**

Bitwise AND.

#### **Syntax**

num= bit.band(val1, val2, ... valn)

#### **Parameters**

val1: the first number to AND val1: the second number to AND

valn: the nth number to AND

## **Returns**

num: the bitwise AND of all the arguments.

### Examples

```
> print("result: "..bit.band(0xffffffff, 0x000000ff, 0x000000f))
result: 15
```

# bit.bor()

## **Description**

Bitwise OR.

#### **Syntax**

num= bit.bor(val1, val2, ... valn)

#### **Parameters**

val1: the first number to OR val1: the second number to OR

valn: the nth number to OR

### **Returns**

num: the bitwise OR of all the arguments.

## **Examples**

```
> print("result: "..bit.bor(0x00000000, 0x0000000ff, 0x0000000f)) result: 255
```

## bit.bxor()

## **Description**

Bitwise XOR.

### **Syntax**

num= bit.bxor(val1, val2, ... valn)

### **Parameters**

val1: the first number to XOR val1: the second number to XOR

valn: the nth number to XOR

#### **Returns**

num: the bitwise XOR of all the arguments.

### **Examples**

```
> print("result: "..bit.bxor(0x00000000, 0x0000000ff, 0x0000000f))
result: 240
```

# bit.lshift()

## Description

Logical left shift a number.

## **Syntax**

```
num= bit.lshift(val, shift)
```

#### **Parameters**

val: the value to shift shift: positions to shift

#### **Returns**

num: the number shifted left.

## **Examples**

```
> print("result: "..bit.lshift(0x00000001,8))
result: 256
```

## bit.rshift()

## **Description**

Logical right shift a number.

#### **Syntax**

```
num= bit.rshift(val, shift)
```

### **Parameters**

val: the value to shift shift: positions to shift

#### Returns

num: the number shifted right.

## **Examples**

```
> print("result: "..bit.rshift(0x00000080,1))
result: 64
```

# bit.arshift()

## Description

Arithmetic right shift a number.

## **Syntax**

```
num= bit.arshift(val, shift)
```

#### **Parameters**

val: the value to shift shift: positions to shift

#### **Returns**

num: the number arithmetically shifted right.

### **Examples**

```
> print("result: "..bit.arshift(0x00000080,1))
result: 64
```

## bit.bit()

## **Description**

Generate a number with a 1 bit (used for mask generation).

### **Syntax**

```
num = bit.bit(pos)
```

#### **Parameters**

pos: position of the bit that will be set to 1.

#### Returns

num: the number that only one bit is set to 1 and 0 for the rests.

### **Examples**

```
> print("result: "..bit.bit(8))
result: 256
```

# bit.set()

#### **Description**

Set bits in a number.

### **Syntax**

```
num= bit.set(val, pos1,pos2,...,posn)
```

#### **Parameters**

val: the base number.

pos1: first position to be set. pos2: second position to be set. posn: nth position to be set.

#### **Returns**

num: the number with the bit(s) set in the given position(s)...

```
> print("result: "..bit.set(0x00000000, 0, 1, 2, 3))
result: 15
```

## bit.clear()

## Description

Clear bits in a number.

## **Syntax**

```
num= bit.clear (val, pos1,pos2,...,posn)
```

#### **Parameters**

val: the base number.

pos1: first position to be cleared. pos2: second position to be cleared. posn: nth position to be cleared.

#### **Returns**

num: the number with the bit(s) cleared in the given position(s).

## **Examples**

```
> print("result: "..bit.clear(0x0000000f, 0, 1, 2, 3))
result: 0
```

# bit.isset()

## Description

Test if a given bit is set.

## **Syntax**

```
res= bit.iset (val, pos)
```

#### **Parameters**

val: the value number to be test pos: bit position.

#### Returns

res: true if the bit at the given position is 1, false otherwise.

#### **Examples**

```
>=bit.isset(0x0000000f, 1) true >=bit.isset(0x0000000f, 5) false
```

## bit.isclear()

## **Description**

Test if a given bit is cleared.

## **Syntax**

```
res= bit.isclear (val, pos)
```

#### **Parameters**

val: the value number to be test

```
pos: bit position.
```

## Returns

res: true if the bit at the given position is 0, false otherwise.

```
>=bit.isclear(0x0000000f, 1)
false
>=bit. isclear (0x0000000f, 5)
true
```

# **Sensor Module**

## **Function List**

sensor.dht11.init	Init DHT11/22, Assign the GPIO Pin for DHT11/22.
sensor.dht11.get	Get the DHT11/22 temperature and humility values
sensor.ds18b20.init	Init DS18B20, Assign the GPIO Pin for 1-wire.
sensor.ds18b20.gettemp	Start temperature measurement and get the temperature
sensor.ds18b20.search	Search for DS18B20 1-wire devices
sensor.ds18b20.setres	Set DS18B20 resolution (9,10,11,12 bit)
sensor.ds18b20.getres	Get current DS18B20 resolution (9,10,11,12 bit)
sensor.ds18b20.getrom	Get DS18B20 ROM values (returns 8 element table)
sensor.ow.init	Init 1-wire device, Assign the GPIO Pin for 1-wire.
sensor.ow.search	Search for 1-wire devices

## Constant

```
\begin{array}{lll} sensor.ds18b20.DS18B20\_RES9 & DS18B20\ 9\ bit\ resolution\\ sensor.ds18b20.DS18B20\_RES10 & DS18B20\ 9\ bit\ resolution\\ sensor.ds18b20.DS18B20\_RES11 & DS18B20\ 9\ bit\ resolution\\ sensor.ds18b20.DS18B20\ RES12 & DS18B20\ 9\ bit\ resolution\\ \end{array}
```

## sensor.dht11.init()

## Description

Init DHT11 sensor. Assign the GPIO Pin for dht11.

## **Syntax**

res = sensor.dht11.init(pin,type)

## **Parameters**

pin: gpio ID,  $0\sim17$ .

type: optional, DHT type: 0=DHT11; 1=DHT22 (default: DHT11)

#### Returns

res: true if dht11/22 initialization successful, nil otherwise.

```
>=sensor.dht11.init(7)
true
```

## sensor.dht11.get()

### **Description**

Get the DHT11/DHT22 temperature and humility value.

### **Syntax**

temp, hum, stat = sensor.dht11.get()

#### Parameters nil

#### **Returns**

temp: temperature measured by DHT (deg for DHT11; 1/10 deg for DHT22).

hum: humidity measured by DHT (% for DHT11; 1/10 % for DHT22).

stat: conversion status (0=OK; 1=read err; 2=csum err; 3=check err; 4=not init)

## **Examples**

```
> =sensor.dht11.get()
26 65 0
```

## sensor.ds18b20.init()

## **Description**

Init ds18b20 sensor. Assign the GPIO Pin for 1-wire.

### **Syntax**

res = sensor.ds18b20.init(pin)

#### **Parameters**

pin: gpio ID,  $0\sim17$ .

### **Returns**

res: true if ds18b20 initialization successfully, false otherwise.

## **Examples**

```
>=sensor.ds18b20.init(7)
true
```

## sensor.ds18b20.search()

## **Description**

Search for DS18B20 1-wire devices.

#### **Syntax**

res = sensor.ds18b20.search()

#### **Parameters**

nil

#### **Returns**

res: Number of found DS18B20 devises.

## **Examples**

```
>=sensor.ds18b20.search()
1
```

## sensor.ds18b20.gettemp()

## **Description**

Start temperature measurement and get the temperature.

### Syntax

tmp, n = sensor.ds18b20.gettemp(dev)

#### **Parameters**

dev: ds18b20 device number, 1~num of detected devices with sensor.ds18b20.search()

#### **Returns**

tmp: temperature

n: duration of the measurement in msec (depends on current ds18b20 resolution)

## **Examples**

```
> = sensor.ds18b20.gettemp(1)
22.1875 591
```

## sensor.ds18b20.setres()

## **Description**

Set DS18B20 resolution (9,10,11,12 bit).

#### Svntax

sensor.ds18b20.setres(dev, res)

## **Parameters**

dev: ds18b20 device number,  $1\sim$ num of detected devices with sensor.ds18b20.search() res: resolution  $(9,10,11,12\ bit)$ 

#### **Returns**

nil

## **Examples**

```
> = sensor.ds18b20.setres(1,10)
```

## sensor.ds18b20.getres()

## **Description**

Get DS18B20 current resolution.

## **Syntax**

Res = sensor.ds18b20.getres(dev)

## **Parameters**

dev: ds18b20 device number, 1~num of detected devices with sensor.ds18b20.search()

#### **Returns**

res: resolution (9,10,11,12 bit)

## **Examples**

```
> = sensor.ds18b20.getres(1)
10
```

## sensor.ds18b20.getrom()

## **Description**

Get DS18B20 ROM values (returns 8 element table).

### Syntax

rom = sensor.ds18b20.getrom(dev)

#### **Parameters**

dev: ds18b20 device number, 1~num of detected devices with sensor.ds18b20.search()

#### Returns

rom: Table with 8 ROM values

## **Examples**

```
> rom=sensor.ds18b20.getrom(1); for i=1,9,1 do print(dsrom[i]) end
40
142
106
200
0
0
110
```

## sensor.ow.init()

## **Description**

Init 1-wire device. Assign the GPIO Pin for 1-wire.

### **Syntax**

```
res = sensor.ow.init(pin)
```

#### **Parameters**

```
pin: gpio ID, 0\sim17.
```

#### Returns

res: true if 1-wire initialization successfully, false otherwise.

```
>=sensor.ow.init(7)
true
```

# sensor.ow.search()

## **Description**

Search for any 1-wire devices.

#### **Syntax**

res = sensor.ow.search()

## **Parameters**

nil

## **Returns**

res: Number of found 1-wire devises.

```
>=sensor.ds18b20.search()
1
```

# **SPI Module**

## **Function List**

spi.setup	Init spi, assign GPIO pins
spi.write	Write data via spi interface, data can be multi numbers, string or lua table
spi.read	Read data from spi interface
spi.deinit	Deinitializes the SPI, free gpio pins

## Constant

spi.BITS_8	8 Bits data length
spi.BITS_16	16 Bits data length

Warning: UART shares Rx pin with hardware SPI5. You can't use both at the same time.

## spi.setup()

## **Description**

Initialize SPI. SPI module works in MASTER mode.

### **Syntax**

spi.setup(id, config)

#### **Parameters**

id: 0 for software SPI; 2 for hardware SPI5 config: Lua table with spi configuration parameters:

**mode**=spi mode 0,1,2,3

**speed**=spi\_speed spi clock frequency in kHz;

100~5000 for software spi (>5000 selects max possible speed)

400~50000 for hardware spi

**cs**=pin gpio ID, 0~17

**rw**=flag optional; 1 reads from MOSI while writing; 1 no read while write

The following parameters are only for software SPI:
sck=pin gpio ID, 0~17 used for SCK
mosi=pin gpio ID, 0~17 used for MOSI

**miso**=pin optional; gpio ID, 0~17 used for MISO

#### **Returns**

0 is succes; error code if not

## **Examples**

```
-- hardware SPI5
>res = spi.setup(2,{mode=3, cs=12, speed=15000})
-- software SPI
>res = spi.setup(0,{mode=3, cs=12, speed=1000,sck=2, mosi=4})
```

## spi.write()

### **Description**

Write data via spi interface. Data can be multi numbers, string or lua table

## **Syntax**

```
ret = spi.write(id, databits, data1, [data2],...,[datan])
```

### **Parameters**

```
    id: 0 for software SPI; 2 for hardware SPI5
    databits: write databits. spi. BITS_8 or spi. BITS_16.
    data1: should be 0<data1< 255 in spi. BITS_8 mode or 0<data2<65535 in spi. BITS_16 mode.</li>
    data2: optional.
    datan: optional.
```

#### **Returns**

ret: The number of data written.

#### **Examples**

```
>res = spi.setup(0,{mode=3, cs=12, speed=1000,sck=2, mosi=4})
>ret = spi.write(0, 0xAA)
```

## spi.read()

#### **Description**

Read data via spi interface.

## **Syntax**

```
ret = spi.read(id, databits, num)
```

#### **Parameters**

```
id: 0 for software SPI; 2 for hardware SPI5 databits: write databits. spi. BITS_8 or spi. BITS_16. num: the number of data to read.
```

#### **Returns**

ret: the Lua table of read data.

```
> ret = spi.read(0, 2)
```

```
> print(ret[1]); print(ret[2])
```

# spi.deinit()

## **Description**

Deinitializes the SPI, free gpio pins.

## **Syntax**

ret = spi.deinit(id)

## **Parameters**

id: 0 for software SPI; 2 for hardware SPI5

## **Returns**

ret: 0 on success; err code if error

## **Examples**

> ret = spi.deinit(2)

# **12C** Module

# **Function List**

i2c.setup	Init i2c, assign GPIO pin
i2c.start	Send start condition
i2c.stop	Send stop condition
i2c.address	Send i2c device address and set transmission direction
i2c.write	Write data via i2c interface, data can be multi numbers, string or lua table
i2c.read	Read data from i2c interface

## Constant

nil

# i2c.setup()

## Description

Init i2c, assign GPIO pin.

## **Syntax**

i2c.setup(id, pinSDA, pinSCL)

#### **Parameters**

id: i2c id, should be 0. pinSDA: GPIO Pin 0~17 pinSCL: GPIO Pin 0~17

#### Returns nil

## **Examples**

>i2c.setup(0, 1, 2)

## i2c.start()

## **Description**

Send start condition

## **Syntax**

i2c.start(id)

### **Parameters**

nil

### **Returns**

nil

## **Examples**

>i2c.start(0)

# i2c.stop()

## **Description**

Send stop condition

## **Syntax**

i2c.stop(id)

#### **Parameters**

id: i2c id, should be 0.

### **Returns**

nil

## **Examples**

>i2c.stop(0)

# i2c.address()

## Description

Send i2c device address and set transmission direction.

## **Syntax**

ack = i2c.address(id, dev\_id, mode)

## **Parameters**

id: i2c id, should be 0. dev\_id: device id address.mode: transmission direction. Should ether 'r' or 'w'.

### **Returns**

ack: if slave device acknowledge success, return true, else return nil.

## **Examples**

> i2c.address(0, 0x3C)

## i2c.write()

## **Description**

Write data via i2c interface, data can be multi numbers, string or lua table

### **Syntax**

```
ret = i2c.write(id, data1, [data2],...,[datan] )
```

## **Parameters**

id: should be 0.

data1: should be 0<data1 < 255.

data2: optional. datan: optional.

## **Returns**

ret: The number of data wrote.

## **Examples**

```
> ret = i2c.write(0, 0x00)
```

# i2c.read()

## Description

Read data from i2c interface

#### **Syntax**

```
ret = i2c.read(id, num)
```

#### **Parameters**

id: should be 0.

num: the number of data ready to read.

## Returns

ret: the string of read data.

```
> ret = i2c.read(0, 1)
> print(ret)
```

# **RTC Module**

# **Function List**

rtc.getasc	Get text representation of current date&time from RTC	
rtc.get	Get Lua Table with second, minute, hour, weekday, date, month, year from RTC	
rtc.getstrf	Get formated string representing the current datetime	
rtc.set	Set RTC second, minute, hour, weekday, date, month, year	
rtc.standby	Put CPU to standby or stop mode for specified number of seconds	
rtc.standbyUntil	Put CPU to stabdby or stop mode until specified time	

# rtc.getasc()

## Description

Get text representation of current date&time from RTC

## **Syntax**

strtime = rtc.getasc()

#### **Parameters**

nil

#### **Returns**

string: Current date & time

## **Examples**

```
> =rtc.getasc()
Wed Nov 4 15:56:06 2015
```

# rtc.getstrf()

## Description

Get formated string representing the current datetime from RTC

## **Syntax**

strtime = rtc.getstrf(format)

## **Parameters**

Forma	t: format string, default: "%Y-%m-%d %H:%M:%S"	
fmt	Replaced by	Example
%a	Abbreviated weekday name *	Thu
%A	Full weekday name *	Thursday
%b	Abbreviated month name *	Aug
%B	Full month name *	August
%c	Date and time representation *	Thu Aug 23 14:55:02 2001
%C	Year divided by 100 and truncated to integer (00-99)	20
%d	Day of the month, zero-padded (01-31)	23
%D	Short MM/DD/YY date, equivalent to %m/%d/%y	08/23/01
%e	Day of the month, space-padded (1-31)	23
%F	Short YYYY-MM-DD date, equivalent to %Y-%m-%d	2001-08-23
%g	Week-based year, last two digits (00-99)	01
%G	Week-based year	2001
%h	Abbreviated month name * (same as %b)	Aug
%Н	Hour in 24h format (00-23)	14
%I	Hour in 12h format (01-12)	02
%j	Day of the year (001-366)	235
%m	Month as a decimal number (01-12)	08
% <b>M</b>	Minute (00-59)	55
%n	New-line character ('\n')	
%p	AM or PM designation	PM
%r	12-hour clock time *	02:55:02 pm
%R	24-hour HH:MM time, equivalent to %H:%M	14:55
%S	Second (00-61)	02
%t	Horizontal-tab character ('\t')	
%T	ISO 8601 time format (HH:MM:SS), equivalent to %H:%M:%S	14:55:02
%u	ISO 8601 weekday as number with Monday as 1 (1-7)	4

%x	Date representation *	08/23/01
%X	Time representation *	14:55:02
%y	Year, last two digits (00-99)	01
%Y	Year	2001
%%	A % sign	%

#### **Returns**

string: Formated current date & time

### **Examples**

```
> =rtc.getstrf("%c")
Sun Nov 22 18:12:02 2015
> =rtc.getstrf("%H:%M:%S Date: %m/%d")
18:14:25 Date: 11/22
```

## rtc.get()

## **Description**

Get second, minute, hour, weekday, date, month, year from RTC

#### Syntax

```
curtime = rtc.get()
```

### **Parameters**

nil

#### **Returns**

Curtime: Lua table with current second, minute, hour, weekday, date, month, year

## **Examples**

```
> ct=rtc.get()
> for i=1,7,1 do print(ct[i]); end
11
59
17
0
22
11
2015
```

## rtc.set()

## **Description**

Set RTC second, minute, hour, weekday, date, month, year

## **Syntax**

```
res=rtc.set(timetbl)
Parameters
     timetbl: Lua table with second, minute, hour, weekday, date, month, year
Returns
     res: 1 if date&time are set or 0 if error
```

## **Examples**

```
> =rtc.set(53,57,15,3,4,11,15)
0K
```

## rtc.standby()

### **Description**

Put CPU to power save mode for specified number of seconds Note: in STANDBY mode, CPU is RESET on wakeup.

### **Syntax**

rtc.standby(mode, numsec)

#### **Parameters**

```
power save mode (0 for standby; 1 for stop)
numsec: number of seconds to staj in standby
```

#### **Returns**

nil, after wake up CPU resets

```
> rtc.standby(0,5)
Going to STANDBY MODE...
Wake up in 5 second(s)
(RESET)
WiFiMCU Lua starting...(Free memory 65544 bytes)
Current Time: Wed Nov 4 16:11:47 2015
[ Ver. 0.9.6_lobo_0.1 WiFiMCU Team, modified by LoBo @2015 ]
Executing init.lua...
> rtc.standby(1,5)
Going to STOP MODE...
Wake up in 5 second(s)
Back from power save mode.
```

## rtc.standbyUntil()

## Description

```
Put CPU to powersave mode until specified time
Note: in STANDBY mode, CPU is RESET on wakeup.
```

### **Syntax**

```
rtc.standbyUntil(mode, time)
```

#### **Parameters**

```
mode: power save mode (0 for standby; 1 for stop) time: Lua table with hour, minute, second to wake up at
```

#### Returns

nil, after wake up CPU resets

Back from power save mode.

```
> rtc.standbyUntil(0, {16,16,5})
Going to STANDBY MODE...
Wake up at 16:16:05

(RESET)
WiFiMCU Lua starting...(Free memory 65544 bytes)
Current Time: Wed Nov 4 16:16:05 2015

[ Ver. 0.9.6_lobo_0.1 WiFiMCU Team, modified by LoBo @2015 ]

Executing init.lua...
> rtc.standbyUntil(1, {16,16,5})
Going to STOP MODE...
Wake up at 16:16:05
```

# **OLED Module**

# **Function List**

oled.init	Initialize the oled display,
oled.clear	Clear the screen
oled.write	Write strings and or numbers to display
oled.writechar	Write one character to display
oled.fontsize	Select the font size
oled.charspace	Define the space between characters
oled.inverse	Select normal or inverted write
oled.fixedwidth	Set fixed width or proportional character printing

The module supports operations with small  $(0.96" \sim 1.3")$  oled displays based on SSD1306 controller, using the 4-wire SPI interface.

# oled.init()

# **Description**

Initialize the oled display and clear the screen. You must initialize the SPI interface first.

#### **Syntax**

res = oled.init(spi id, DCpin)

#### **Parameters**

spi\_id: id of the SPI interface to be used for oled DCpin: gpio ID, 0~17 used for DC control

### **Returns**

res: 0 on success, error code on error

```
-- hardware spi

>spi.setup(2,{mode=3, cs=12, speed=15000})

>res = oled.init(2,14)

-- software spi

>spi.setup(0,{mode=3, cs=12, mosi=9, sck=16, speed=500})

>oled.init(0,14)
```

# oled.clear()

```
Description
```

Clear screen.

**Syntax** 

oled.clear()

### **Parameters**

nil

#### **Returns**

nil

# **Examples**

> oled.clear()

# oled.write()

# Description

Write strings and or numbers to display.

oled.write(x, y, ndec, data1, [data2], ... [datan])

## **Parameters**

```
x position (column; 0\sim127)
y positoin (row; 0\sim7)
```

ndec: number of decimal places if number data is float; 0 to print integer)

data1: number or string to write to the display

data2: optional datan: optional

## Returns

nil

# **Examples**

```
>oled.write(0,0,0,"WiFiMCU")
>t=2.3456
>oled.write(8,2,1,"Temp=", t)
```

# oled.writechar()

# **Description**

Write single character to display.

# **Syntax**

oled.write(x, y, char)

### **Parameters**

x: x position (column; 0~127) y: y position (row; 0~7)

char: character code

#### **Returns**

nil

# **Examples**

>oled.writechar(16,5,0x42)

# oled.fontsize()

# Description

Set the font size (height). At the moment can be only 8 or 16

# **Syntax**

oled.fontsize(size)

#### **Parameters**

size: new font size (8 or 16)

#### **Returns**

nil

# **Examples**

>oled.fontsize(16)

# oled.charspace()

# Description

Set additional space between characters in pixels.

#### **Syntax**

oled.crarspace(chr\_spc)

#### **Parameters**

chr spc: new intercharacter space (0~8)

## **Returns**

nil

### **Examples**

>oled.charspace(1)

# oled.inverse()

```
Description
```

Set normal (light on dark) or inverse (dark on light) display.

#### **Syntax**

oled.inverse(flag)

## **Parameters**

flag: o for normal, 1 for inverse

# **Returns**

nil

# **Examples**

>oled.inverse(1)

# oled.fixedwidth()

# **Description**

Set fixed width or proportional character printing.

# **Syntax**

oled.fixedwidth(flag)

### **Parameters**

flag: 0 to print proportional character, 1 for fixed width

# Returns

nil

ММММ

```
>oled.fixedwidth(1)
>oled.write(0,0,0,"IIII\r\nMMMM")
IIII
MMMM
>oled.fixedwidth(0)
>oled.write(0,0,0,"IIII\r\nMMMM")
IIII
```

# **LCD Module**

# **Function List**

lcd.init	Initialize the display
lcd.clear	Clear the screen
lcd.write	Write strings and or numbers to display
lcd.on	Turn display on
lcd.off	Turn display off
lcd.setfont	Set the font used for write function
lcd.getfontsize	Get current font size in pixels
lcd.fixedwidth	Set fixed width or proportional character printing
lcd.setrot	Set text rotation (angle)
lcd.setorient	Set display orientation, default PORTRAIT
lcd.setwrap	Set line wrap for lcd.write() function
lcd.setcolor	Set foreground and background colors
lcd.settransp	Set transparency for character printing
lcd.invert	Set inverted/normal colors
lcd.putpixel	Puts pixel on screen
lcd.line	Draw line
lcd.rect	Draw rectangle
lcd.triangle	Draw triangle
lcd.circle	Draw circle
lcd.image	Show image from file

# Constant

lcd.PORTRAIT	Default orientation
lcd.PORTRAIT_FLIP	Orientation flipped portrait
lcd.LANDSCAPE	Orientation landscape
lcd.LANDSCAPE_FLIP	Orientation flipped landscape
lcd.CENTER	Center text (write function)
lcd.RIGHT	Right allign text (write function)
lcd.FONT_SMALL	small font (8x12)
lcd.FONT_BIG	Big font (16x16)
lcd.FONT_7SEG	7 segment vector font (digits,'-','.',':','deg' only
lcd.FONT_8X8	Default font (8x8)
lcd.BLACK	Colors
lcd.NAVY	

lcd.DARKGREEN	
lcd.DARKCYAN	
lcd.MAROON	
lcd.PURPLE	
lcd.OLIVE	
lcd.LIGHTGREY	
lcd.DARKGREY	
lcd.BLUE	
lcd.GREEN	
lcd.CYNAN	
lcd.RED	
lcd.MAGENTA	
lcd.YELLOW	
lcd.WHITE	
lcd.ORANGE	
lcd.GREENYELLOW	
lcd.PINK	

The module supports operations with TFT SPI displays. At the moment, only displays based on ST7735 controller, using the 4-wire SPI interface are supported.

Using hardware SPI is recommended, the speed much higher.

# lcd.init()

# Description

Initialize the oled display and clear the screen. You must initialize the SPI interface first.

# **Syntax**

res = lcd.init(spi id, DCpin, type [,orient])

# **Parameters**

spi id: id of the SPI interface to be used for oled

DCpin: gpio ID, 0~17 used for DC (data/command) control type: display type, 0,1,2 (probably 1 will work best)
Orient: optional, display orientation (default: PORTRAIT)

## **Returns**

res: 0 on success, error code on error

```
-- hardware spi with 50 MHz clock
>spi.setup(2,{mode=3, cs=12, speed=50000})
>res = lcd.init(2,14,1,lcd.LANDSCAPE)
-- software spi with ~5 Mhz clock
>spi.setup(0,{mode=3, cs=12, mosi=9, sck=16, speed=5000})
> res = lcd.init(0,14,1,PORTRAIT FLIP)
```

# lcd.clear()

# Description

Clear screen to default or specified color.

## **Syntax**

lcd.clear([color])

### **Parameters**

color optional; fill the screen with color (default: BLACK)

### **Returns**

nil

# **Examples**

```
> lcd.clear(lcd.BLUE)
```

> lcd.clear()

# Icd.off()

# **Description**

Turns the display of, preserve power. Back light has to be turned off separately.

# **Syntax**

lcd.off()

## **Parameters**

nil

#### **Returns**

nil

# **Examples**

> lcd.off()

# lcd.on()

# **Description**

Turns the display on.

```
Syntax
```

lcd.on()

### **Parameters**

nil

#### **Returns**

nil

# **Examples**

> lcd.on()

# Icd.invert()

# Description

Set inverted/normal colors.

## **Syntax**

lcd.invert(inv)

#### **Parameters**

inv 0: inverted colors off; 1: inverted colors on

#### **Returns**

nil

# **Examples**

> lcd.invert(0)

# lcd.setorient()

# **Description**

Set display orientation.

### **Syntax**

lcd.setorient(orient)

# **Parameters**

orient one of display orientation constants PORTRAIT, PORTRAIT\_FLIP, LANSCAPE, LANDSCAPE\_FLIP

## **Returns**

nil

- > lcd.orient(lcd.LANDCSAPE)
- > lcd.orient(PORTRAIT\_FLIP)

# lcd.setrot()

# Description

Set text rotation (angle) for lcd.write() function.

## **Syntax**

lcd.setrot(rot)

# **Parameters**

rot rotation angle  $(0\sim360)$ 

#### **Returns**

nil

# **Examples**

```
> lcd.rot(90)
```

> lcd.write("Ratated text")

# lcd.settransp()

# **Description**

Set transparency when writing the text. If transparency is on, only text foreground color is shown.

### **Syntax**

lcd.settransp(transp)

#### **Parameters**

transp 0: transparency off; 1: transparency on

### **Returns**

nil

### **Examples**

> lcd.settransp(1)

# lcd.setwrap()

# Description

Set line wrapping writing the text. If wrapping is on, text will wrap to new line, otherwise it will be clipped.

### **Syntax**

lcd.setwrap(wrap)

#### **Parameters**

wrap 0: line wrap off; 1: line wrap on

#### **Returns**

nil

## **Examples**

> lcd.setwrap(1)

# lcd.setcolor()

# **Description**

Set the color used when writing characters or drawing on display.

## **Syntax**

lcd.setcolor(color[,bgcolor])

#### **Parameters**

color foreground color for text and drawing bgcolor optional; background color for writing text

### **Returns**

nil

# **Examples**

- > lcd.setcolor(lcd.YELLOW)
- > lcd.setcolor(lcd.ORANGE, lcd.DARKGREEN)

# lcd.setfont()

# Description

Set the font used when writing the text to display. Four fonts are available: FONT\_8x8 (default 8x8), FONT\_SMALL (8x12), FONT\_BIG (16x16) and FONT 7SEG.



7-segment font is the vector font for which any size can be set (distance between bars and the bar width). Only characters **0**,**1**,**2**,**3**,**4**,**5**,**6**,**7**,**8**,.,-,:,/ are available. Character '/' draws the degree sign.

#### **Syntax**

lcd.setfont(font [,size, width])

#### **Parameters**

```
font one of the available fonts size optional; only for FONT_7SEG, distance between bars (default: 12; min=6; max=40) width optional; only for FONT_7SEG, bar width (default: 2; min=1; max=12 or size/2)
```

#### **Returns**

nil

## **Examples**

```
> lcd.setfont(lcd.FONT_BIG)
> lcd.setfont(lcd.FONT_7SEG, 20, 4)
```

# Icd.getfontsize()

# **Description**

Get current font size in pixels. Useful if  $FONT\_7SEG$  is used to get actual character width and height.

# **Syntax**

lcd.getfontsize()

## **Parameters**

nil

#### **Returns**

```
xsize width of the font character in pixels ysize height of the font character in pixels
```

# **Examples**

```
> lcd.getfontsize()
8 12
```

# lcd.putpixel()

# **Description**

Draws pixel on display at coordinates (x,y) using foreground or given color

#### Syntax

lcd.putpixel(x, y [, color])

### **Parameters**

```
x, y coordinates of pixel color optional: pixel color (default: current foreground color)
```

### **Returns**

nil

# **Examples**

```
> lcd.putpixel(10,10)
```

> lcd.putpixel(20,40,lcd.GREEN)

# Icd.line()

# **Description**

Draws line from (x1,y1) to (x2,y2) using foreground or given color

## **Syntax**

```
lcd.line(x1, y1, x2, y2 [,color])
```

### **Parameters**

```
x1,y1 coordinates of line start point x1,y1 coordinates of line end point
```

color optional: line color (default: current foreground color)

### **Returns**

nil

## **Examples**

```
> lcd.line(0,0,127,159)
```

> lcd.line(20,40,80,10,lcd.ORANGE)

# lcd.rect()

# Description

Draws rectangle at (x,y) w pixels wide, h pixels high, with given color. If the fill color is given, fills the rectangle.

### **Syntax**

```
lcd.rect(x, y, w, h, color [,fillcolor])
```

#### **Parameters**

x, y coordinates of the upper left corner of the rectangle width of the rectangle

h height of the rectangle color rectangle outline color optional: rectangle fill color

### **Returns**

nil

### **Examples**

```
> lcd.rect(10,10,100,110,lcd.RED)
```

> lcd.rect(0,0,128,160,lcd.ORANGE,lcd.YELLOW)

# lcd.circle()

# **Description**

Draws circle with center at (x,y) and radius r, with given color. If the fill color is given, fills the circle.

## **Syntax**

lcd.circle(x, y, r, color [,fillcolor])

#### **Parameters**

x, y coordinates circle center r radius of the circle color circle outline color fillcolor optional: circle fill color

#### **Returns**

nil

## **Examples**

- > lcd.circle(64,80,20,lcd.RED)
- > lcd.circle(50,60,30,lcd.ORANGE,lcd.YELLOW)

# lcd.triangle()

# **Description**

Draws triangle between three given points, with given color. If the fill color is given, fills the triangle.

### **Syntax**

lcd.triangle(x1, y1, x2, y2, x3, y3, color [,fillcolor])

#### **Parameters**

x1, y1, x2, y2, x3, y3 coordinates of the 3 triangle points triangle outline color optional: triangle fill color

## Returns

nil

# **Examples**

- > lcd.triangle(50,20,80,100,20,100,lcd.RED)
- > lcd.triangle(50,20,80,100,20,100,lcd.RED, lcd.WHITE)

# lcd.write()

# **Description**

Write strings and or numbers to display. Rotation of the displayed text can be set with lcd.setrot() function.

Two special characters are allowed in strings:

' $\mathbf{r}$ ' CR (0x0D), clears the display to EOL

'\n' LF (ox0A), continues to the new line, x=0

## **Syntax**

```
lcd.write(x, y, data1, [data2, ... datan])
```

#### **Parameters**

## **Returns**

nil

## **Examples**

```
>lcd.setcolor(lcd.YELLOW)
>lcd.write(0,0,"WiFiMCU")
>t=2.3456
>lcd.write(8,16,"Temp=", {t,2})
```

# Icd.image()

# Description

Shows the image from file. The image file must be in raw 16bit format. Any image can be converted with *ImageConverter565.exe* which can be found in *binary* directory on GitHub.

Be careful to give the right image width and height.

#### **Syntax**

lcd.image(x, y, xsize, ysize, filename)

#### **Parameters**

x: x position of the image upper left cornery: y position of the image upper left corner

xsize: image xsize (width)
ysize; image ysize (height)
filename: name of the row image file

# **Returns**

nil

```
>lcd.rot(lcd.PORTRAIT)
>lcd.clear()
>lcd.image(0,0,128,96,"wifimcu_128x96.img")
>lcd.rot(lcd.LANDSCAPE)
>lcd.image(0,0,160,128,"wifimcu_160x128.raw")
```