

P1)

1- Do no harm: A robot may not injure a human being or, through inaction, allow a human being to come to harm.

2- Obey humans: A robot must obey the orders given to it by human beings, except where such orders would conflict with the first law(Do not harm).

3 - Self preservation; A robot must protect its own existence as long as such protection does not conflict with the first law(Do not harm) or the second law(obey humans).

Zeroth law: A robot may not harm humanity or, by inaction allow humanity to come to harm.

Mosab Mohamed B20-04

(2)

- P2) a) male (alexanderII).  
male (AlexanderIII).  
male (Vladimir).  
male (george).  
male (nicholasII).  
female (maria Alexandrovna).  
female (maria Fedorovna).  
female (olga).  
parent (alexanderII, alexanderIII).  
parent (alexanderII, Vladimir).  
parent (maria Alexandrovna, alexanderIII).  
parent (maria Alexandrovna, Vladimir).  
parent (alexanderIII, olga).  
parent (alexanderIII, nicholasII).  
parent (alexanderIII, george).  
parent (maria Fedorovna, olga).  
parent (maria Fedorovna, nicholasII).  
parent (maria Fedorovna, george).

- P2) a)
- $\text{father}(X, Y) :- \text{parent}(X, Y), \text{male}(X).$
  - $\text{mother}(X, Y) :- \text{parent}(X, Y), \text{female}(X).$
  - $\text{grandfather}(X, Y) :- \text{father}(X, Z), \text{parent}(Z, Y).$
  - $\text{grandmother}(X, Y) :- \text{mother}(X, Z), \text{parent}(Z, Y).$
  - $\text{brother}(X, Y) :- \text{parent}(Z, X), \text{parent}(Z, Y), \text{male}(X), X \neq Y.$
  - $\text{sister}(X, Y) :- \text{parent}(Z, X), \text{parent}(Z, Y), \text{female}(X), X \neq Y.$
  - $\text{uncle}(X, Y) :- \text{parent}(Z, Y), \text{brother}(X, Z).$
  - $\text{aunt}(X, Y) :- \text{parent}(Z, Y), \text{sister}(X, Z).$

b)

~~Alexander~~

Query: ?-  $\text{parent}(\text{alexanderII}, \text{alexanderIII}).$

Answer: true

Query: ?-  $\text{parent}(X, \text{nicolasII}).$

Answer:  $X = \text{alexanderIII}$

$X = \text{mariaFedorovna}$

Query: ?- ~~male~~ male( $X$ ), ( $\text{uncle}(-, X)$ ;  $\text{aunt}(-, X)$ ).

Answer:  $X = \text{george}$

$X = \text{nicolasII}$

Query: ?-  $\text{parent}(X, Y), \text{male}(X), \text{female}(Y).$

Answer:  $X = \text{alexanderIII}$   $Y = \text{olga}$

P3) GBEST: in this swarm all the particles are neighbors of each other. So, the position of the best overall particle in the swarm is used in the social term of the Velocity update equation. It is assumed that GBEST swarms converge fast, as all the particles are attracted ~~in~~ in the same time to the best part of the search space.

However, if the global optimum is not close to the best particle, it may be impossible to ~~make~~ the swarm to explore other areas; which means they will be trapped in local optima

LBEST: in this swarm, only a specific number of particles (neighbor count) can affect the Velocity of a given particle. The Swarm will converge slower but can locate the global optimum with a better chance

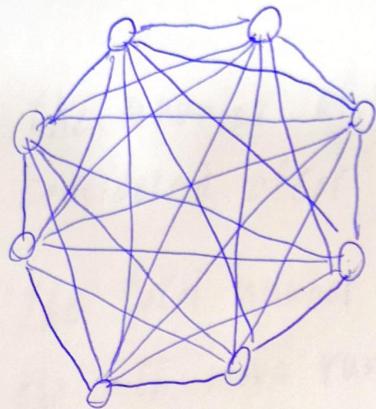
Mosab

Mohamed

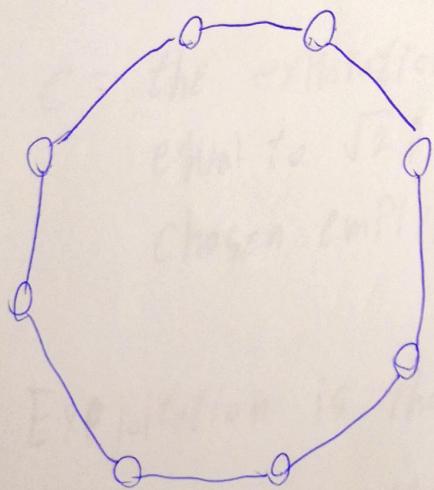
B20 - 04

⑤

P3) GBEST:



LBEST:



P4)

$$\text{formula : } \frac{w_i}{n_i} + c \sqrt{\frac{\ln N_i}{n_i}}$$

$w_i$  = the number of wins for the node  
considered after the  $i$ -th move

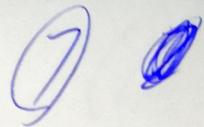
$N_i$  = the total number of simulations after  
the  $i$ -th move run by the parent node  
of the one considered

$n_i$  = the number of simulations for the node  
considered after the  $i$ -th move

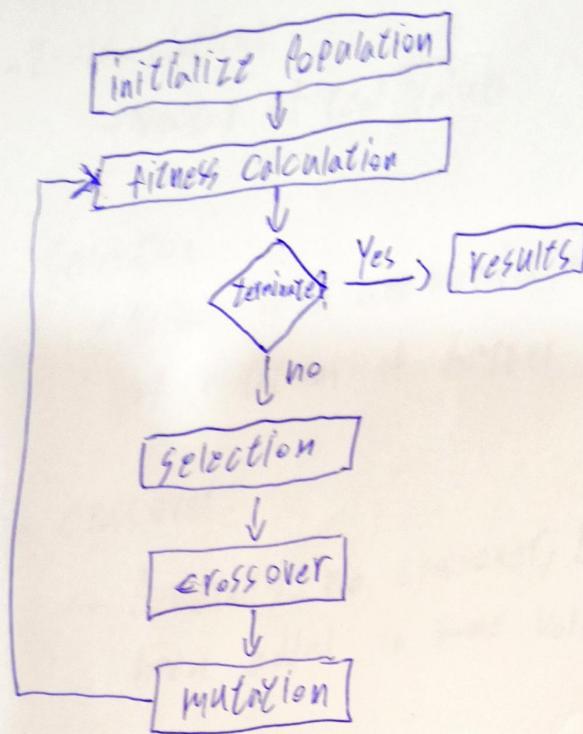
$c$  = the exploration parameter - in theory  
equal to  $\sqrt{2}$ ; in practice often  
chosen empirically

Exploitation is the first term

Exploration is the second term



P9) a)



pseudo-code:

- Create a random population consisting of chromosomes (data structure which encode a potential solution),
- until <done> based on stopping criteria (e.g. max generations or fitness wanted was achieved),
  - find fitness score for each member of the population.
  - select members to act upon using variation operators (could be done with various methods e.g. tournament)
  - apply variation operators:
    - crossover and/or mutation
  - replace some members with children from variation ops.
  - keep some members from previous population (elitism/inheritance)

## P5) b) 1-Representation:

- Vector of Real Values

## 2 - Selection:

- Replace with a member of a sample of mutations if better than parent

## 3 - Crossover:

- Generally no crossover, but it has been added in some variants

## 4 - Mutation

- Yes. add a small normally distributed parameter to a value

## Variants:

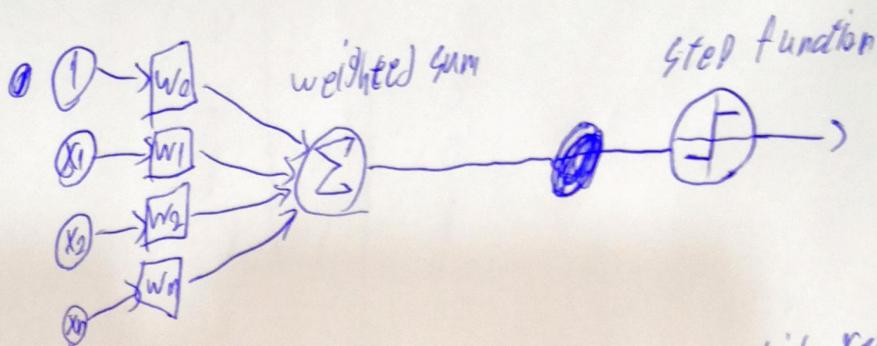
- $(\lambda+1)$ -ES = a mutant is tested against its parent and the fittest wins.

- $(1+\lambda)$ -ES =  $\lambda$  mutants are tested against their parents ~~with~~ the fittest wins. the parent wins if he's the fittest

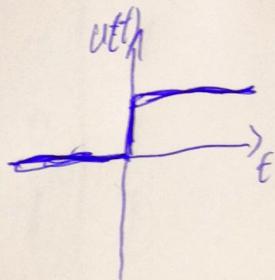
- $(1, N)$ -ES = same as  $(1-\lambda)$ -ES but the parent is never retained and only one mutant continues.

- $(\mu/\rho^+, \lambda)$ -ES = A population is used where a group of mutants is made for each and compete with the set of parents. This may have a crossover operation

P6)  output = step( $\sum w_i x_i$ ) where  $step(n) = \begin{cases} 1 & \text{if } n > 0 \\ 0 & \text{otherwise} \end{cases}$



activation function is a step function which returns 1 for inputs  $> 0$  and 0 otherwise



a)  AND :-  $y = step(bias + w_1 \cdot a + w_2 \cdot b)$   
 $bias = -1 \quad w_1 = 1 \quad w_2 = 1$   
 $y = step(-1 + a + b)$

b) OR :-  $y = step(bias + w_1 \cdot a + w_2 \cdot b)$   
 $bias = -1 \quad w_1 = 2 \quad w_2 = 2$   
 $y = step(-1 + 2a + 2b)$

c) NOT:-  $y = step(bias + w_1 \cdot a + w_2 \cdot b)$  ignored  
 $bias = 1 \quad w_1 = -1 \quad w_2 = 0$   
 $y = step(1 - a + 0 \cdot b)$

Mosab Mohamed

B20-04

10

P6) AND :-

a	b	output
0	0	0
0	1	0
1	0	0
1	1	1

OR :-

a	b	output
0	0	0
0	1	1
1	0	1
1	1	1

Note:-

a	b	output
0		1
1		0

	weight 1	weight 2	bias
AND	1	1	-1
OR	2	2	-1
NOT	-1	0	1