Compiler Construction: Practical Introduction

Lecture 8
Program Optimization
Bootstrapping Compilers

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Program Optimization

Some general points

- Optimization can be performed on each stage of the program lifecycle: not only while compilation but while design, development and maintenance.
- Do we really need optimization?

 The best way to optimize a program is to design it correctly (then perhaps we do not need to optimize it ⊕)
- "Optimization-in-the-small" vs "optimization-in-the-large"

Program Optimization

- Finding places in programs which could be optimized (by some criteria) is very much empirical job; in the best case, there is just a set of techniques taken from experience.
- At the same time, there is a number of formal and/or constructive approaches for some kind of optimizations.

Today, we will be discussing what to optimize, but not how to do this...

Program Optimization

- While source code processing (lexical & syntax analysis)
 Big spectrum of optimization techniques.
- While semantic analysis (AST processing).

Sequential AST traversing.

Optimizations depend on the language semantics heavily.

While target code generation (machine-dependent optimizations)

Depend on the target architecture & on the instruction set.

While linking: global code optimizations.

Example: - C++ code bloat removing.

Common Subexpression Elimination (1)

```
long a = x*(1-\sin(y));
long b = x + y/z;
long c = y/z + 1 - \sin(y);
long tmp1 = 1-\sin(y);
long tmp2 = z/y;
long a = x*tmp1;
long b = x + tmp2;
long c = tmp2 + tmp1;
```

The place:

While AST analysis.

Limitations:

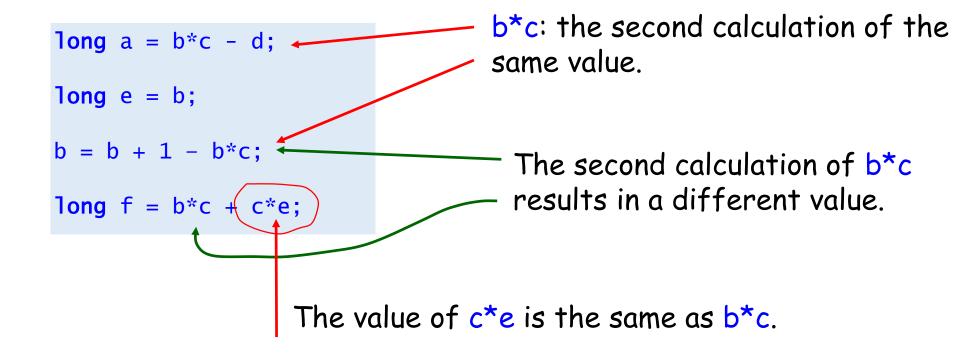
- 1. Factorized functions cannot issue side effects.
- 2. Operands of factorized expressions cannot modify their values.

Common Subexpression Elimination (2)

```
long a = x*(1-F(y));
long b = x + y/z;
...
z = <expression>;
long c = z/y + 1 - F(y);
Modifying value
```

Common Subexpression Elimination (3)

An expression may look different but still calculate the same value as some other expression => it can also get optimized.



Operation Strength Reduction (1)

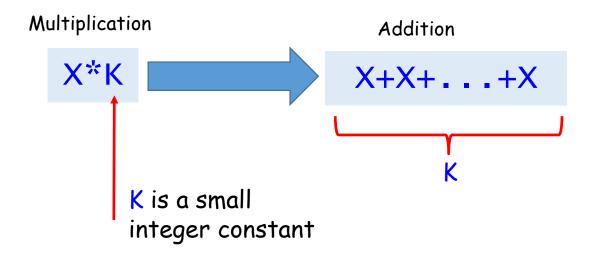
Actions: comparative performance

Multiplication/division on a power of two
Addition/subtraction
Multiplication
Division
Calculation of an integer power
Calculation of an arbitrary power

⇒ Replacing slower operations for faster ones (where possible)

For some target architectures it's **mandatory**: e.g., some RISCs just do not support multiplication!

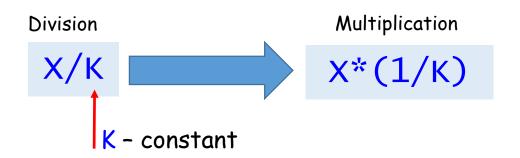
Operation Strength Reduction (2)



In general case it's impossible...

- At least one operand must be an integer constant.
- The constant should be relatively small; otherwise rounding errors will accumulate.

Operation Strength Reduction (3)



```
double x = c/b;
double y = (e+f)/b + d;
double z = b;
b = b+1;
...
z = sin(x)/z + e/b;
double tmp = (double)1/b;
double x = c*tmp;
double y = (e+f)*tmp + d;
double z = b;
b = b+1;
...
z = sin(x)/z + e/b;
```

Dead Code Elimination

```
double a;
...
a = (x+y)*sin(z);
...
a = x/y;
double a;
...
a = x/y;
```

If the value of a does not change between two assignments, then the first assignment can be removed.

Limitation: the action being removed cannot make side effects.

Constant propagation

If the value of a variable is known then the variable reference can be replaced for the value itself.

```
long a = 2;
long b = 3;
long c = a*b;
long t = (b+c)*a+x;
long a = 2;
long b = 3;
long c = 6; // a*b
...
long t = 18 + x; // (b+c)*a
```

Conditional Constant propagation

If the value in a loop condition is known in advance then the loop could be simplified.

Type conversion optimizations

Type conversion is a potentially costly

```
operation; therefore it's a good
double a, b;
                                     candidate for optimizations.
long i, j;
double c = a + i + b - j;
             ... a + (double)i + b - (double)j ...
double a, b;
long i, j;
double c = (a+b) + (i-j);
             ... a+b + (double)(i-j) ...
```

Code Hoisting

Access to array elements and function calls are also good candidates for optimizations...

```
for i:integer range 1..100 loop
    x(i) = y(i)+1/y(i);
    z(i) = y(i)**2;
end loop;
```

Address of y(i) gets calculated 300 times

Address of y(i) gets calculated 100 times

Loop Fusion (1)

Loops are main consumers of CPU time!

```
for i:integer range 1..100 loop
    x(i) = 0;
end loop;
for i:integer range 1..100 loop
    z(i) = y(i)**2;
end loop;
for i:integer range 1..100 loop
    x(i) = 0;
    z(i) = y(i)**2;
end loop;
```

Costs for loop organization are reduced

Loop Fusion (2)

```
for i:integer range 1..100 loop
    x(i) = 0;
end loop;
for i:integer range 1..200 loop
    z(i) = y(i)**2;
end loop;
for i:integer range 1..100 loop
   x(i) = 0;
    z(i) = y(i)**2;
end loop;
for i:integer range 101..200 loop
    z(i) = y(i)**2;
end loop;
```

(More general case)

Overall amount of iterations: 300

Overall amount of iterations: 200

Loop Unrolling (1)

```
for (int i=0; i<100; i++)
    x[i] = y[i]*z[i];
for (int i=0; i<100; i+=2)</pre>
    x[i] = y[i]*z[i];
    x[i+1] = y[i+1]*z[i+1];
```

Loop step = 1 Overall amount of iterations: 100

Loop step = 2 Overall amount of iterations: 50

Loop Unrolling (2)

```
-- Skip past blanks, loop is opened up for speed
while Source (Scan_Ptr) = ' ' loop
    if Source (Scan_Ptr + 1) /= ' ' then
        Scan_Ptr := Scan_Ptr + 1; exit;
    end if:
   if Source (Scan_Ptr + 2) /= ' ' then
        Scan_Ptr := Scan_Ptr + 2; exit;
    end if:
    if Source (Scan_Ptr + 3) /= ' ' then
        Scan_Ptr := Scan_Ptr + 3; exit;
    end if:
    if Source (Scan_Ptr + 4) /= ' ' then
        Scan_Ptr := Scan_Ptr + 4; exit;
    end if:
    if Source (Scan_Ptr + 5) /= ' ' then
        Scan_Ptr := Scan_Ptr + 5; exit;
    end if;
   if Source (Scan_Ptr + 6) /= ' ' then
        Scan_Ptr := Scan_Ptr + 6; exit;
    end if:
    if Source (Scan_Ptr + 7) /= ' ' then
        Scan_Ptr := Scan_Ptr + 7; exit;
    end if;
    Scan_Ptr := Scan_Ptr + 8;
end loop;
```

"Manual" loop unrolling

A real example: The scanner of the Ada GNAT compiler

Tail Recursion Elimination (1)

```
void f(int x)
{
    if ( x == 0 ) return;
        ... Some actions...
    f(x-1);
}
```

The idea:

If the recursive call is the very last operation in the function body then it can be replaced for the direct jump to the beginning of the body - perhaps with argument (re)initialization.

See more details in:

http://en.wikipedia.org/wiki/Tail_call

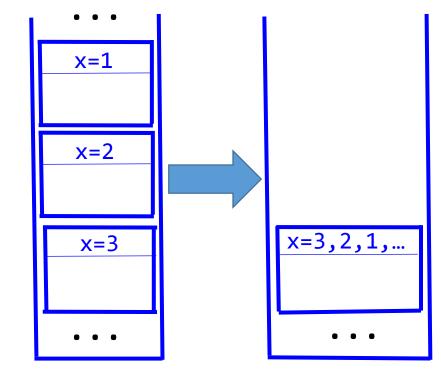
Tail Recursion Elimination (2)

Execution Stack

Stackframe for f's call with x = 1

Stackframe for f's call with x = 2

Stackframe for f's call with x = 3



The idea:

f(3);

If the recursive call is the very last operation in the function body then it can be replaced for the direct jump to the beginning of the body - perhaps with argument (re)initialization.

Tail Recursion Elimination (3)

```
long factorial(long n)
{
   if (n == 0) return 1;
   else return n*factorial(n-1);
}
```

This is **not** tail recursion. Why?

```
int fac_times(int n, int acc)
{
    if (n == 0) return acc;
    else return fac_times(n-1,acc*n);
}
int factorial(int n)
{
    return fac_times(n,1);
}
```

In many cases, a compiler for a higherlevel language "High" is written in a <u>lower</u> language "Low".

For example, the first compiler for the Fortran language was initially written in an assembly language...

The Interstron C++ compiler was initially written in C

However:

- The GNAT Ada compiler is written in Ada.
- The Eiffel compiler is written in Eiffel.
- The Scala compiler is written in Scala.
- Most C++ compilers are written in C++

The Interstron C++ compiler was later rewritten in C++

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Bootstrapping Technology

 The technology applies when the implementation & source languages are the same.

Advantages:

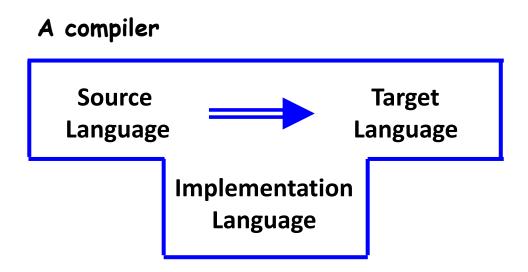
- More stable technology;
- Supports graduate language & compiler improvement;
- No dependency on any third-party tools;
- The code of the compiler is an excellent test for both language and compiler itself.

Disadvantages:

- A bit awkward technology; requires non-trivial management & powerful management tools (e.g., ant).

Bootstrapping Technology

- · Reference: Terence Parr.
- Graphical notation ("T Notation"):



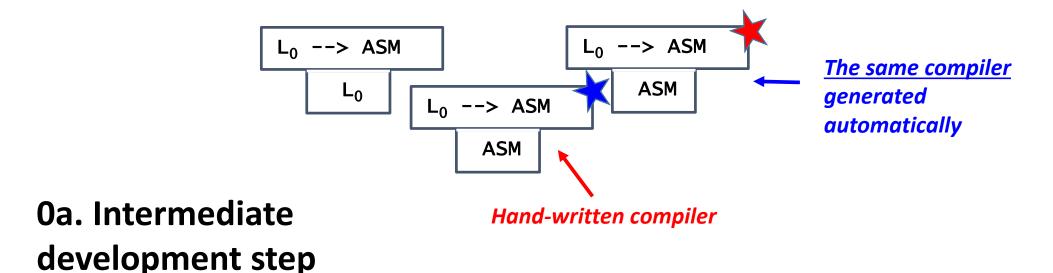


0. Initial development step

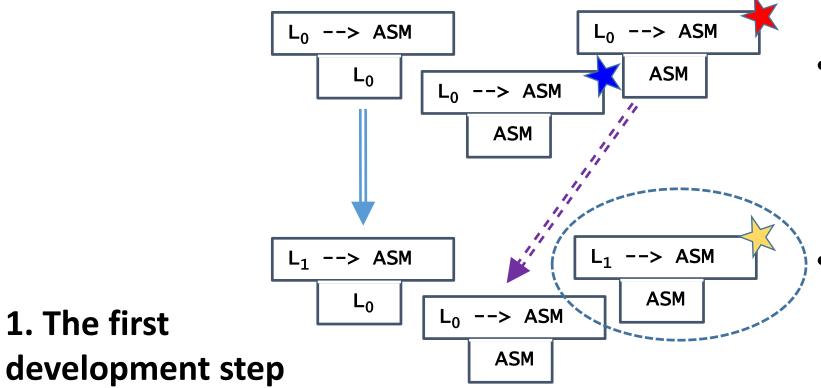
"ASM" can be any assembly language: - Intel x64

- .NET MSIL
- JVM bytecode
- etc.

- Define a very simple subset of the target L language: L₀
- Write the prototype compiler for L₀ in the same L₀ language
- Manually rewrite this prototype compiler in an assembly language



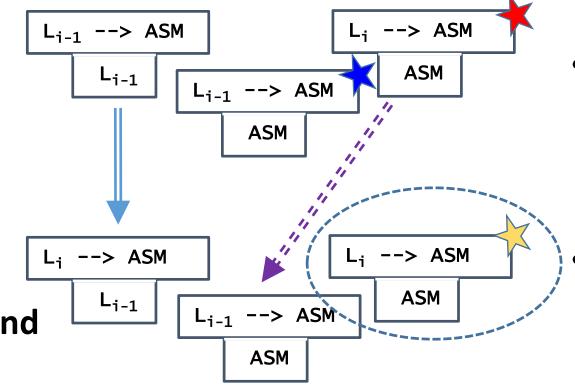
Apply the hand-written compiler to the initially written one



1. The first

- Extend the initial L_n compiler adding new features: get the L₁ compiler
 - Apply the previous version of the compiler to the newer one
- The result: the compiler for the next version of the language.

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2. The second and the following development steps

- Extend the current L_{i-1}
 compiler adding new
 features: get the L_i
 compiler
 - Apply the i-1_{th} version of the compiler to the i_{th} one
- The result: the compiler for the next version of the language.