

PoGaIN: Supplementary Material

Nicolas Bähler, Majed El Helou, Étienne Objois, Kaan Okumuş, and Sabine Süssstrunk, *Fellow, IEEE*.

I. MAXIMUM LIKELIHOOD DERIVATION

A. Poisson-Noise Modeling

Let us denote the observed noisy image as y and the ground-truth noise-free image as x . Then, the Poisson-Gaussian model takes the form of the following equation

$$y = \frac{1}{a}\alpha + \beta, \quad \alpha \sim \mathcal{P}(ax), \quad \beta \sim \mathcal{N}(0, b^2). \quad (1)$$

Using the linearity property of expectation, we can compute the expected value

$$\mathbb{E}[y] = \frac{1}{a}\mathbb{E}[\alpha] = \frac{1}{a}ax = x. \quad (2)$$

Further, the variance has the following expression

$$\mathbb{V}[y] = \mathbb{E}\left[\left(\frac{1}{a}\alpha + \beta\right)^2\right] - x^2 = \frac{1}{a^2}\mathbb{E}[\alpha^2] + b^2 - x^2. \quad (3)$$

Given that $\mathbb{E}[\alpha^2] = ax + a^2x^2$, we have

$$\mathbb{V}[y] = \frac{x}{a} + x^2 + b^2 - x^2 = \frac{x}{a} + b^2. \quad (4)$$

B. Likelihood Function of Single-Pixel Image

From the definition of the probability mass function (PMF) of a Poisson random variable α , we get

$$\mathbb{P}[\alpha = k] = \frac{e^{-ax}(ax)^k}{k!}, \quad k \geq 0. \quad (5)$$

From the relation between the probability density function (PDF) and the PMF of discrete random variable established with the Dirac delta function, i.e. $f_X(t) = \sum_{k \in \mathbb{Z}} \mathbb{P}[X = k]\delta(t - k)$, we can derive that

$$f_\alpha(t|a, x) = \sum_{k=0}^{\infty} \frac{e^{-ax}(ax)^k}{k!} \delta(t - k). \quad (6)$$

Let us define $\alpha' = \frac{1}{a}\alpha$. Then, the cumulative distribution function (CDF) of this random variable α' has the following form

$$F_{\alpha'}(t) = \mathbb{P}[\alpha' \leq t] = \mathbb{P}[\alpha \leq at] = F_\alpha(at). \quad (7)$$

By taking the derivative of Equation (7), the PDF of α' can be found

$$f_{\alpha'}(t) = \frac{dF_{\alpha'}(t)}{dt} = \frac{dF_\alpha(at)}{dt} = af_\alpha(at). \quad (8)$$

Hence, by combining Equations (6) and (8), the likelihood function of α' , which consists of the first part of the noise model, can be derived

$$\begin{aligned} f_{\alpha'}(t|a, x) &= a \sum_{k=0}^{\infty} \frac{e^{-ax}(ax)^k}{k!} \underbrace{\delta(at - k)}_{=\frac{1}{a}\delta(t - \frac{k}{a})} \\ &= \sum_{k=0}^{\infty} \frac{e^{-ax}(ax)^k}{k!} \delta(t - k/a). \end{aligned} \quad (9)$$

On the other hand, the likelihood function of a Gaussian random variable β with 0 mean is defined as

$$f_\beta(t|b) = \frac{1}{b\sqrt{2\pi}} e^{-t^2/2b^2}. \quad (10)$$

We then combine those equations and find the likelihood function of y . Since we know that α' and β are independent of each other, we have that

$$\begin{aligned} \mathcal{L}(y|a, b, x) &= (f_{\alpha'} * f_\beta)(y|a, b, x) \\ &= \sum_{k=0}^{\infty} \frac{(ax)^k}{k!b\sqrt{2\pi}} \exp\left(-ax - \frac{(y - k/a)^2}{2b^2}\right). \end{aligned} \quad (11)$$

C. Maximum Likelihood Solution for Single-Pixel Image

As derived, the maximum likelihood solution for a single-pixel image is the following

$$\begin{aligned} \hat{a}, \hat{b} &= \arg \max_{a, b} \mathcal{L}(y|a, b, x) \\ &= \arg \max_{a, b} \sum_{k=0}^{\infty} \frac{(ax)^k}{k!b\sqrt{2\pi}} \exp\left(-ax - \frac{(y - k/a)^2}{2b^2}\right). \end{aligned} \quad (12)$$

D. Likelihood Function of Multi-Pixel Image

We represent images as vectors of pixels, like y_n and x_n where $n \in \mathbb{N}$ is the index of single pixels. Hence, using this notation we obtain

$$\mathcal{L}(y_n|a, b, x_n) = \sum_{k=0}^{\infty} \frac{(ax_n)^k}{k!b\sqrt{2\pi}} \exp\left(-ax_n - \frac{(y_n - k/a)^2}{2b^2}\right). \quad (13)$$

Given x , i.e., the vector of all x_n , we can see that y_n and $y_{n'}$ are independent $\forall n \neq n'$. Therefore, we have

$$\begin{aligned} \mathcal{L}(y|a, b, x) &= \prod_n \sum_{k=0}^{\infty} \frac{(ax_n)^k}{k!b\sqrt{2\pi}} \\ &\quad \exp\left(-ax_n - \frac{(y_n - k/a)^2}{2b^2}\right). \end{aligned} \quad (14)$$