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# GRAPH THEORY

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## 1 Graph

### 1.1 Basic Concepts

Graphs is a set of **Objects** and **Relations** between pairs of objects. A **Graph**  $G = (V, E)$ . Where:  $V$  is **Vertices/Nodes**, and  $E$  is **Edges**.

If we have two nodes  $u$  and  $v$ . And between  $u$  and  $v$ , there is a edge  $e$ . We can say that  $e$  **Connects**  $u$  and  $v$ .  $u$  and  $v$  are **End Points** of  $e$ .  $u(v)$  and  $e$  are **Incident**.  $u$  and  $v$  are **Adjacent** and **Neighbors**.

And it is often convenient to consider **Directed Edges(Arcs)**. They describe **asymmetric** relations. For example, there is a flight from A to B, but not the other way around, such a graph is called **Directed**.

We should notice that if we want to describe a graph, we can write likes:

Objects:A, B, C, D, Relations:{ {A, C}, {D, A}, {B, D}, {C, B} }

For directed graph:

Objects:A, B, C, D, Relations:{(A, C), (D, A), (B, D), (C, B)}

### 1.2 Vertex Degree

The **Degree** of a vertex is the number of its incident edges/neighbors. And the degree of a vertex  $v$  is denoted by  $deg(v)$ . The **degree of a graph** is the maximum degree of its vertices. If a vertex's degree is 0, we call it as **Isolated Vertex**. And a **Regular** graph is a graph where each vertex has the same degree(A regular graph of degree  $k$  is also called  $k$ -Regular).

The **Complement** of a graph  $G = (V, E)$  is a graph  $\overline{G} = (V, \overline{E})$ .

### 1.3 Paths

A **Walk** in a graph is sequence of edges, such that each edge(except for the first one) starts with a vertex where the previous edge ended. The **Length** of a walk is the number of edges in it.

A **Path** is a walk where all edges are distinct. And a **Simple Path** is a walk where all vertices are distinct.

A **Cycle** in a graph is a path whose first vertex is the same as the last one. In particular, all the edges in a Cycle are distinct. A **Simple Cycle** is a cycle where all vertices except for the first one are distinct(And there first vertex is taken twice).

### 1.4 Connectivity

A graph is called **Connected** if there is a path between every pair of its vertices. And a **Connected Component** of a graph  $G$  is a maximal connected sub-graph of  $G$ .

## 1.5 Directed Graphs

For directed graphs, the **In-degree** of a vertex  $v$  is the number of edges ending at  $v$ . And the **Out-degree** of a vertex  $v$  is the number of edges leaving  $v$ .

## 1.6 Weighted Graphs

A **Weighted Graph** associates a weight with every edge. The **Weight** of a path is the sum of weights of its edges. A **Shortest Path** between two vertices is a path of the minimum weight. And the **Distance** between two vertices is the length of a shortest path between them.

## 1.7 Type of Graphs

**Path Graphs.** The Path Graphs  $P_n$ ,  $n \geq 2$ , consists of  $n$  vertices  $v_1, \dots, v_n$  and  $n - 1$  edges  $\{v_1, v_2\}, \dots, \{v_{n-1}, v_n\}$ .

**Cycle Graph.** The Cycle Graph  $C_n$ ,  $n \geq 3$ , consists of  $n$  vertices  $v_1, \dots, v_n$  and  $n$  edges  $\{v_1, v_2\}, \dots, \{v_{n-1}, v_n\}, \{v_n, v_1\}$ .

**Complete Graph.** The Complete Graph(Clique)  $K_n$ ,  $n \geq 2$ , contains  $n$  vertices  $v_1, \dots, v_n$  and all edges between them ( $n(n - 1)/2$  edges)

## 1.8 Trees

A **tree** is a connected graph without cycles. Also, you can say a tree is a connected graph on  $n$  vertices with  $n - 1$  edges.

## 1.9 Bipartite Graphs

A graph  $G$  is **Bipartite** if its vertices can be partitioned into **two disjoint sets**  $L$  and  $R$  such that every edge in  $G$  connects a vertex in  $L$  to a vertex in  $R$ .  $L$  and  $R$  are called the **parts** of  $G$ .

And in a bipartite graph, if every vertex from part  $L$  can be connected to all vertices from part  $R$ . We call it is a

**Complete Bipartite Graph**  $K_{num(L), num(R)}$ .

For cycle graph, if even  $n$ ,  $C_n$  is always bipartite. And if odd  $n \geq 3$ ,  $C_n$  is not bipartite. The trees are always bipartite.

## 2 Cycles

### 2.1 Handshaking Lemma

Before a business meeting, some people shook hands. Then the number of people who made an odd number of handshakes is even. In graph terms: A graph has an even number of odd nodes.

**Lemma:** For any graph  $G(V, E)$ , the sum of degrees of all its nodes is twice the number of edges:

$$\sum_{v \in V} degree(v) = 2 \cdot |E|$$

Implies the handshaking lemma: if a graph had an odd number of odd nodes, then the sum of degrees would be also odd.

**Double Counting** technique:

- on one hand, the number of edges is equal to

the total degree of the left part. - on the other hand, it is equal to the total degree of the right part.

### 2.2 Lower Bound

Theorem: An undirected graph  $G(V, E)$  has at least  $|V| - |E|$  connected components. If a graph is connected, then  $|E| \geq |V| - 1$ . The theorem is useless for graphs with  $|E| \geq |V|$ .

### 2.3 Directed Acyclic Graphs

A **directed acyclic graph**, or simply a DAG, is a directed graph without cycles.

## 2.4 Topological Ordering

A **topological ordering** of a directed graph is an ordering of its vertices such that, for each edge  $(u, v)$ ,  $u$  comes before  $v$ . And every DAG has a topological ordering.

## 2.5 Strongly Connected Components

In a directed graph, nodes  $u, v$  are connected, if there is a path from  $u$  to  $v$  and a path from  $v$  to  $u$ . Nodes of any directed graph can be partitioned into subsets called **strongly connected components (SCCs)**. The nodes from the same SCC are connected, and nodes from different SCCs are not connected.

## 2.6 Eulerian Cycle

An **Eulerian cycle (or path)** visits every edge exactly once. The definition works for both directed and undirected graphs.

A connected undirected graph contains an Eulerian cycle, if and only if the degree of every node is even. And a strongly connected directed graph contains an Eulerian cycle, if and only if, for every nodes, its in-degree is equal to its out-degree.

## 2.7 Hamiltonian Cycle

A **Hamiltonian cycle** visits every node of a graph exactly once.

# 3 Graph Classes

## 3.1 Spanning Trees

A **Spanning Tree** of a graph  $G$ , is a subgraph of  $G$  which is a tree and contains all vertices of  $G$ . A **Minimum Spanning Tree** of a weighted graph  $G$  is a spanning tree of the smallest weight.

**Kruskal's Algorithm:** Start with an empty graph  $T$ , and repeat  $n - 1$  times: add to  $T$  an edge of the smallest weight which doesn't create a cycle  $T$ .

## 3.2 Bipartite Graphs

Theorem of Characterization: A graph is *Bipartite* if and only if it has no cycles of odd length.

## 3.3 Matchings

A **Matching** in a graph is a set of edges without common vertices. And a **Maximal Matching** is a matching which cannot be extended to a large matching. A **Maximum Matching** is a matching of the largest size.

**Hall's Theorem:** Let  $G = (V, E)$  be a graph, and  $SV$  be a subset of vertices. The **Neighborhood  $N(S)$**  of  $S$  is the set of all vertices connected to at least one vertex in  $S$ .