

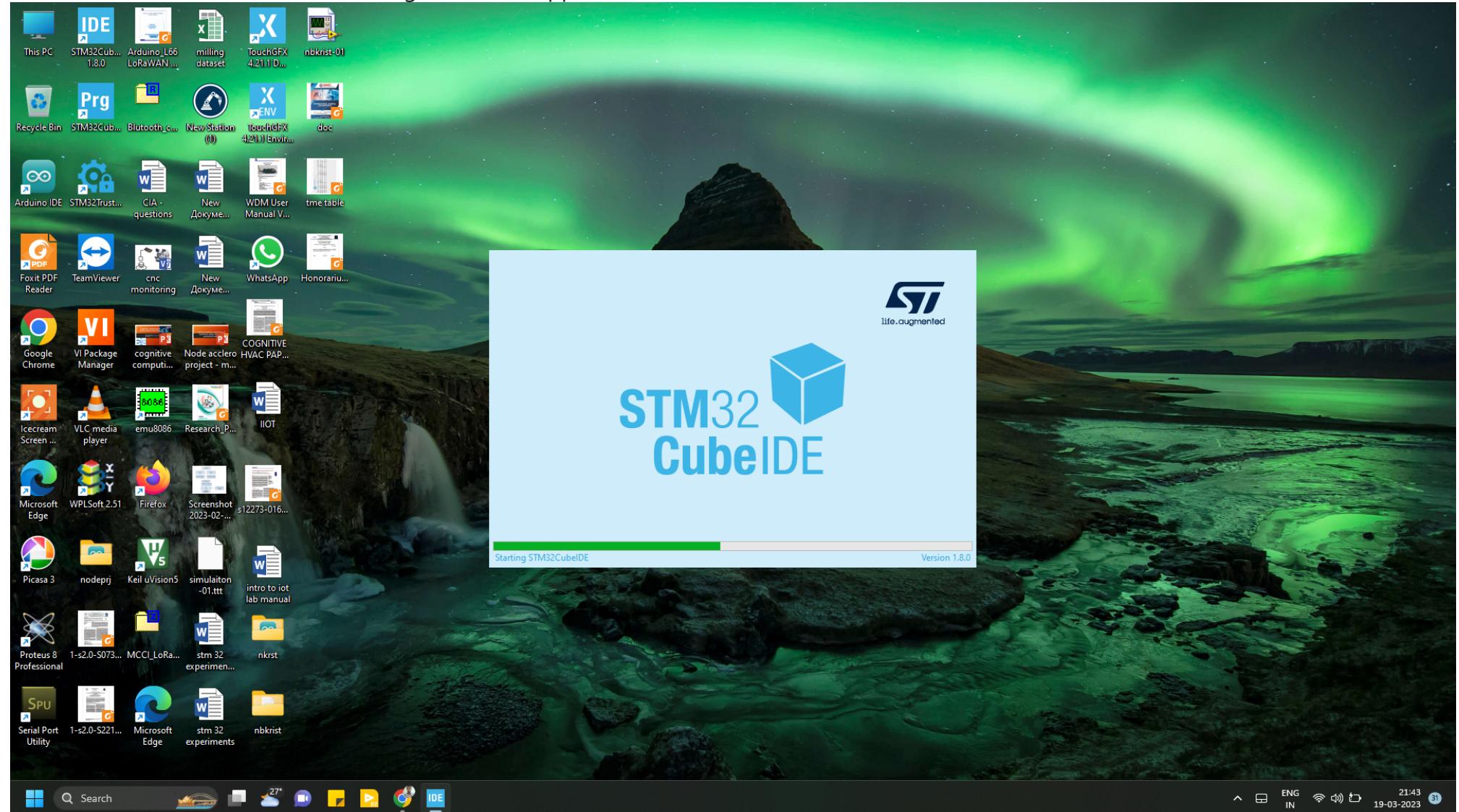
EXPERIMENT--02-INTEFACING-A-DIGITAL-INPUT-TO-ARM-DEVELOPMENT-BOARD

- ' Aim: To Interface a Digital Input (userpush button) to ARM development board and write a program to obtain the data and flash the led
- ' Components required: STM32 CUBE IDE, ARM IOT development board, STM programmer tool.
- ' Theory

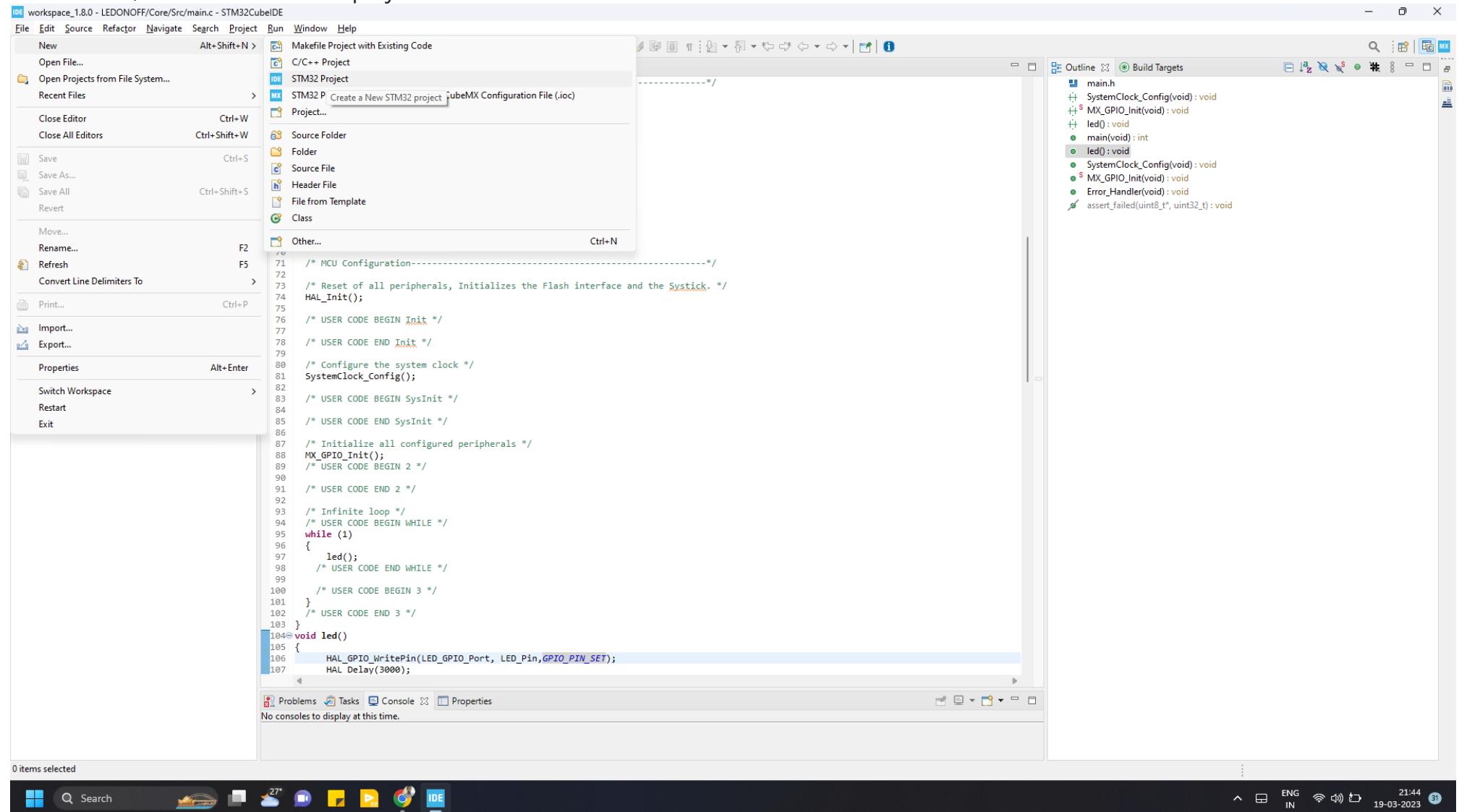
The full form of an ARM is an advanced reduced instruction set computer (RISC) machine, and it is a 32-bit processor architecture expanded by ARM holdings. The applications of an ARM processor include several microcontrollers as well as processors. The architecture of an ARM processor was licensed by many corporations for designing ARM processor-based SoC products and CPUs. This allows the corporations to manufacture their products using ARM architecture. Likewise, all main semiconductor companies will make ARM-based SOCs such as Samsung, Atmel, TI etc.

Procedure:

1. click on STM 32 CUBE IDE, the following screen will appear



2. click on FILE, click on new stm 32 project



IDE workspace_1.8.0 - LEDONOFF/Core/Src/main.c - STM32CubeIDE

File Edit Source Refactor Navigate Search Project Run Window Help

Project Explorer main.c

```
55/* Private user code -----*/
56 /* USER CODE BEGIN 0 */
57
58 /* USER CODE END 0 */
59
60 /**
61  * @brief  The application entry point.
62  * @retval int
63 */
64 int main(void)
65 {
66
67     /* USER CODE BEGIN 1 */
68
69     /* USER CODE END 1 */
70
71     /* MCU Configuration-----*/
72
73     /* Reset of all peripherals, Initializes the Flash interface and the Systick. */
74     HAL_Init();
75
76     /* USER CODE BEGIN Init */
77
78     /* USER CODE END Init */
79
80     /* Configure the system clock */
81     SystemClock_Config();
82
83     /* USER CODE BEGIN SysInit */
84
85     /* USER CODE END SysInit */
86
87     /* Initialize all configured peripherals */
88     MX_GPIO_Init();
89
90     /* USER CODE BEGIN 2 */
91
92     /* USER CODE END 2 */
93
94     /* Infinite loop */
95     /* USER CODE BEGIN WHILE */
96     while (1)
97     {
98         led();
99         /* USER CODE END WHILE */
100    }
101
102    /* USER CODE BEGIN 3 */
103 }
104 void led()
105 {
106     HAL_GPIO_WritePin(LED_GPIO_Port, LED_Pin, GPIO_PIN_SET);
107     HAL_Delay(3000);

```

Outline Build Targets

- main.h
- SystemClock_Config(void) : void
- MX_GPIO_Init(void) : void
- led() : void
- main(void) : int
- led() : void
- SystemClock_Config(void) : void
- MX_GPIO_Init(void) : void
- Error_Handler(void) : void
- assert_failed(uint8_t*, uint32_t) : void

Progress Information

Initializing STM32 Target Selector...

Cancel

Problems Tasks Console Properties

No consoles to display at this time.

0 items selected

Windows Start Task View File Explorer Task Scheduler Google Chrome IDE

ENG IN 21:44 19-03-2023 31

3. select the target to be programmed as shown below and click on next

IDE STM32 Project

Target Selection

Select STM32 target or STM32Cube example

MCU/MPU Selector | Board Selector | Example Selector | Cross Selector

MCU/MPU Filters

- Part Number: STM32G071RB
- Core: Check/Uncheck All
 - Arm Cortex-A7 + Arm Cortex-M4
 - Arm Cortex-M0
 - Arm Cortex-M0+
 - Arm Cortex-M3
 - Arm Cortex-M4
 - Arm Cortex-M4 + Arm Cortex-M0+
 - Arm Cortex-M7
 - Arm Cortex-M7 + Arm Cortex-M4
 - Arm Cortex-M33
- Series: Check/Uncheck All
 - STM32F0
 - STM32F1
 - STM32F2
 - STM32F3
 - STM32F4
 - STM32F7
 - STM32G0
 - STM32G4
 - STM32H7
 - STM32L0

Features

STM32G0 Series

STM32G071RB

Mainstream Arm Cortex-M0+ MCU with 128 Kbytes of Flash memory memory, 36 Kbytes RAM, 64 MHz CPU, 4x USART, timers, ADC, DAC, comm. I/F, 1.7-3.6V

ACTIVE Active
Product is in mass production

Unit Price for 10kU (US\$): 1.803

Boards: NUCLEO-G071RB - STM32G071B-DISCO

LQFP64

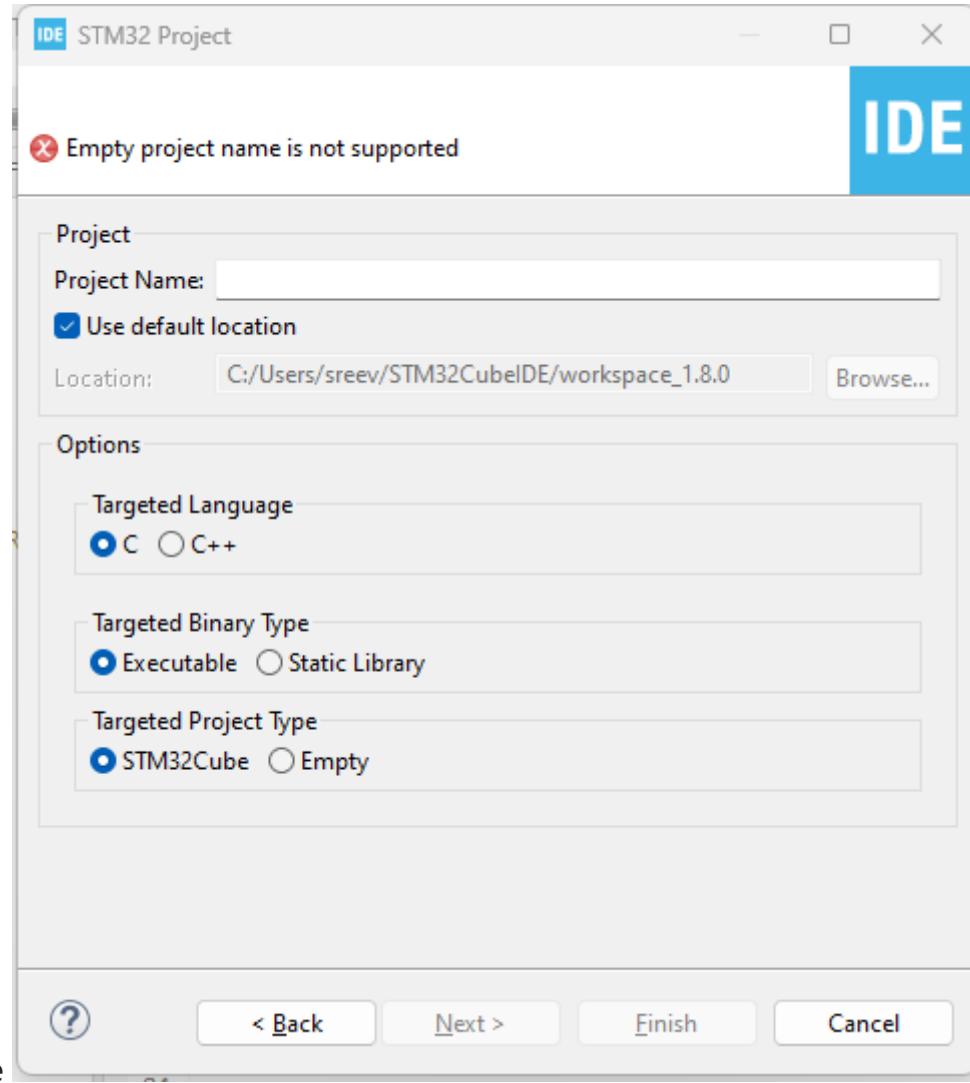
The STM32G071x8/xB mainstream microcontrollers are based on high-performance Arm® Cortex®-M0+ 32-bit RISC core operating at up to 64 MHz frequency. Offering a high level of integration, they are suitable for a wide range of applications in consumer, industrial and appliance domains and ready for the Internet of Things (IoT) solutions. The devices incorporate a memory protection unit (MPU), high-speed embedded memories (up to 128 Kbytes of Flash program memory with read protection, write protection, proprietary code protection, and securable area, and 36 Kbytes of SRAM), DMA and an extensive range of system functions, enhanced I/Os and peripherals. The devices offer standard communication interfaces (two I²Cs, two SPIs / one I²S, one HDMI CEC, and four USARTs), one 12-bit ADC (2.5 MSps) with up to 19 channels, one 12-bit DAC with two channels, two fast comparators, an internal voltage reference buffer, a low-power RTC, an advanced control PWM timer running at up to double the CPU frequency, five general-purpose 16-bit timers with one running at up to double the CPU frequency, a 32-bit general-purpose timer, two basic timers, two low-power 16-bit timers, two watchdog timers, and a SysTick timer. The STM32G071x8/xB devices provide a fully integrated USB Type-C Power Delivery controller. The devices operate within ambient temperatures from -40 to 125°C. They can operate with supply voltages from 1.7 V to 3.6 V. Optimized dynamic consumption combined with a comprehensive set of power-saving modes, low-power timers and low-power UART, allows the design of low-power applications.

MCUs/MPUs List: 2 items

	Part No	Reference	Marketing Status	Unit Price for 10kU (U...)	Board	Package	Flash	RAM	IO	Freq.
★	STM32G071RB	STM32G071...	Active	1.803	UFBGA64	128 kBytes	36 kBytes	60	64 MHz	
★	STM32G071RB	STM32G071...	Active	1.803	NUCLEO-G0...	LQFP64	128 kBytes	36 kBytes	60	64 MHz

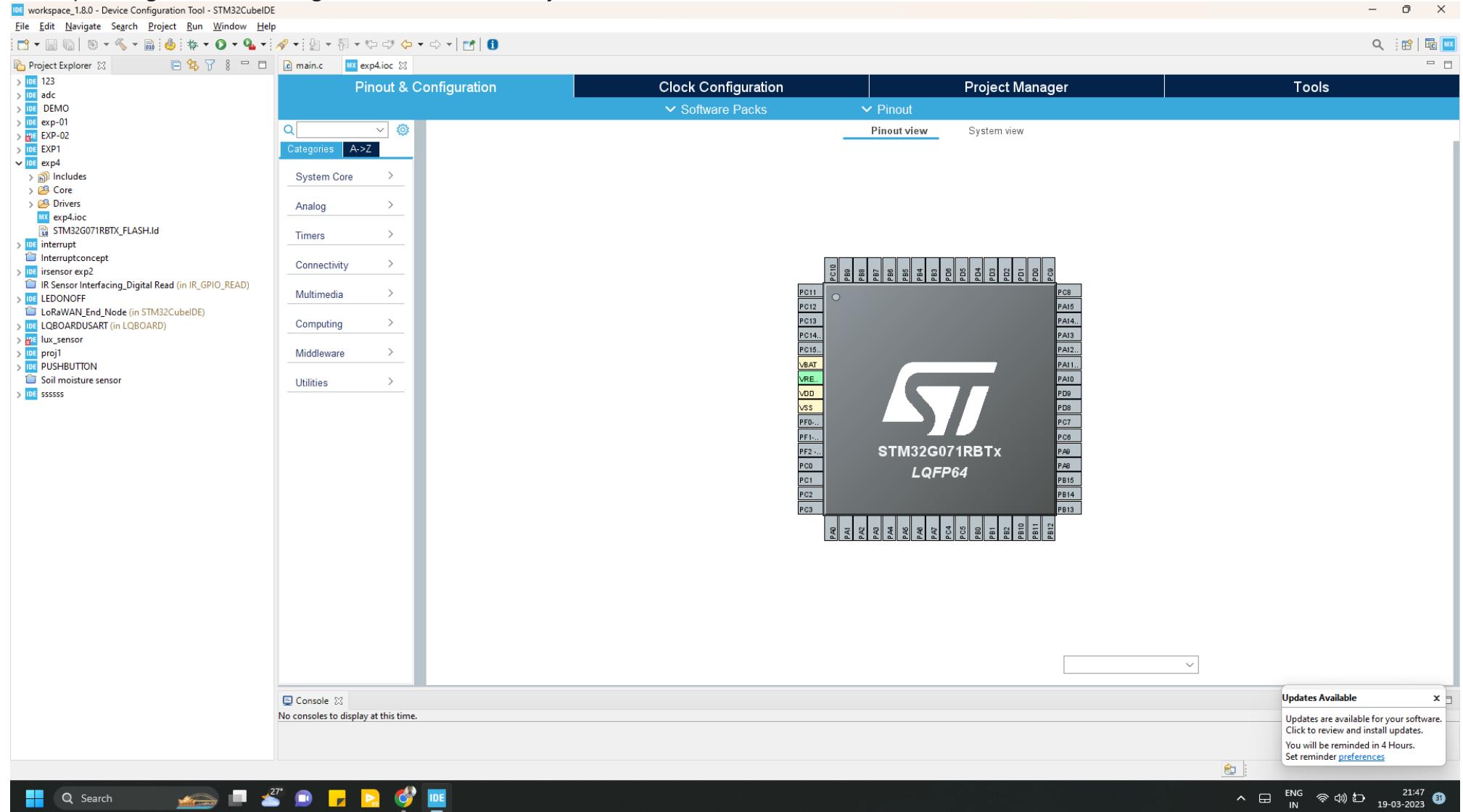
Display similar items

Next > | Back | Finish | Cancel | ? | Search | 27° | ENG IN | 21:45 | 19-03-2023 | IDE

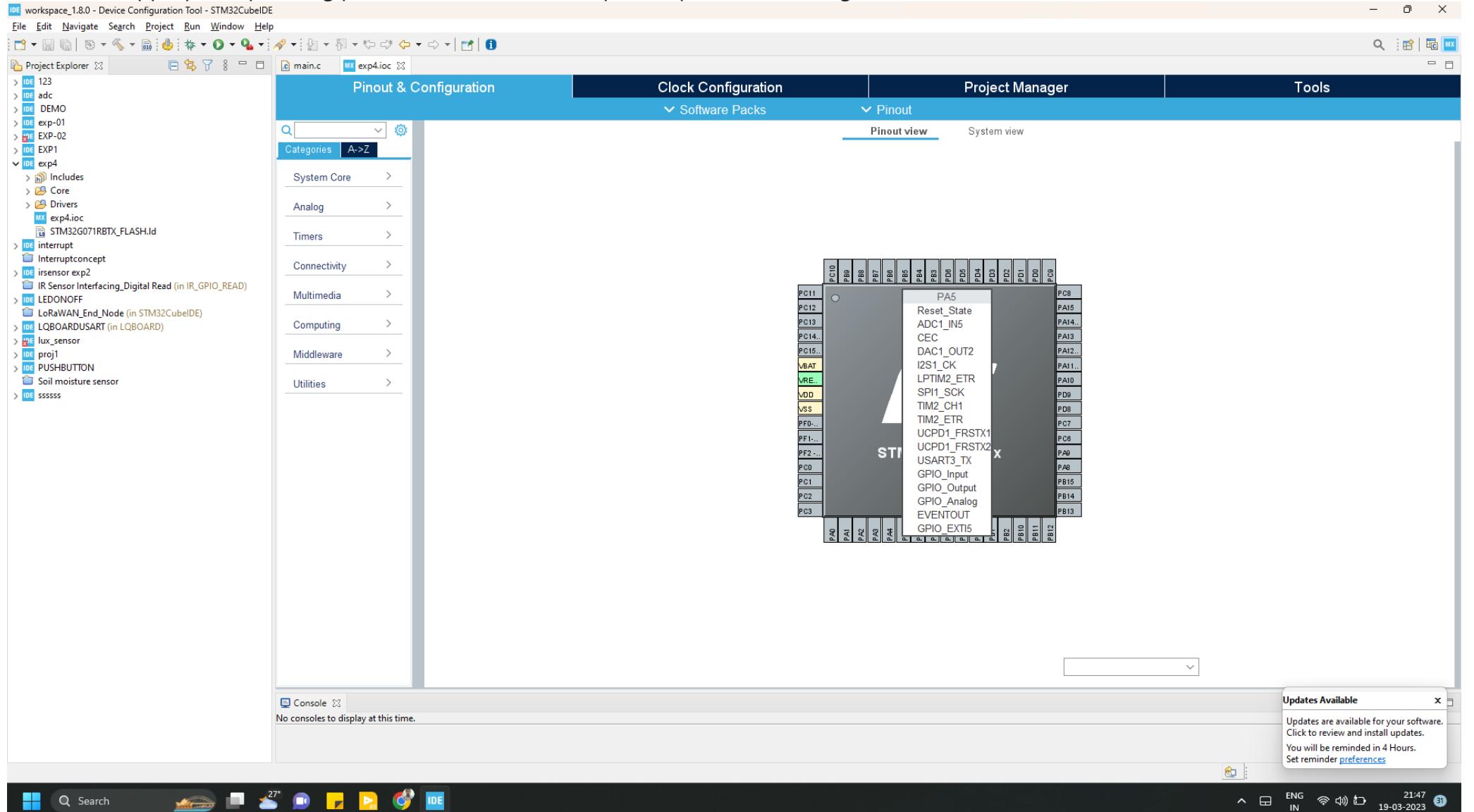


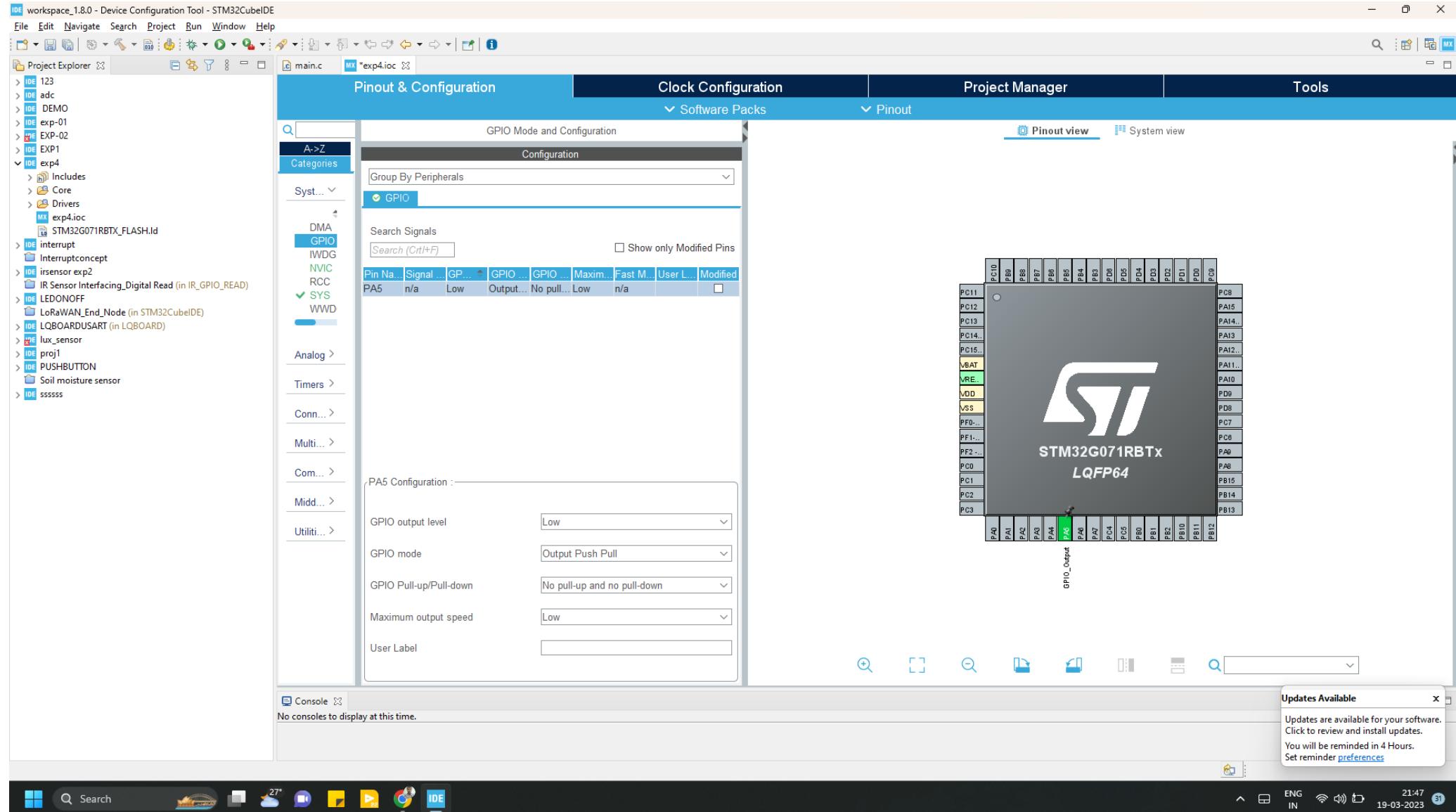
4.select the program name

5. corresponding ioc file will be generated automatically

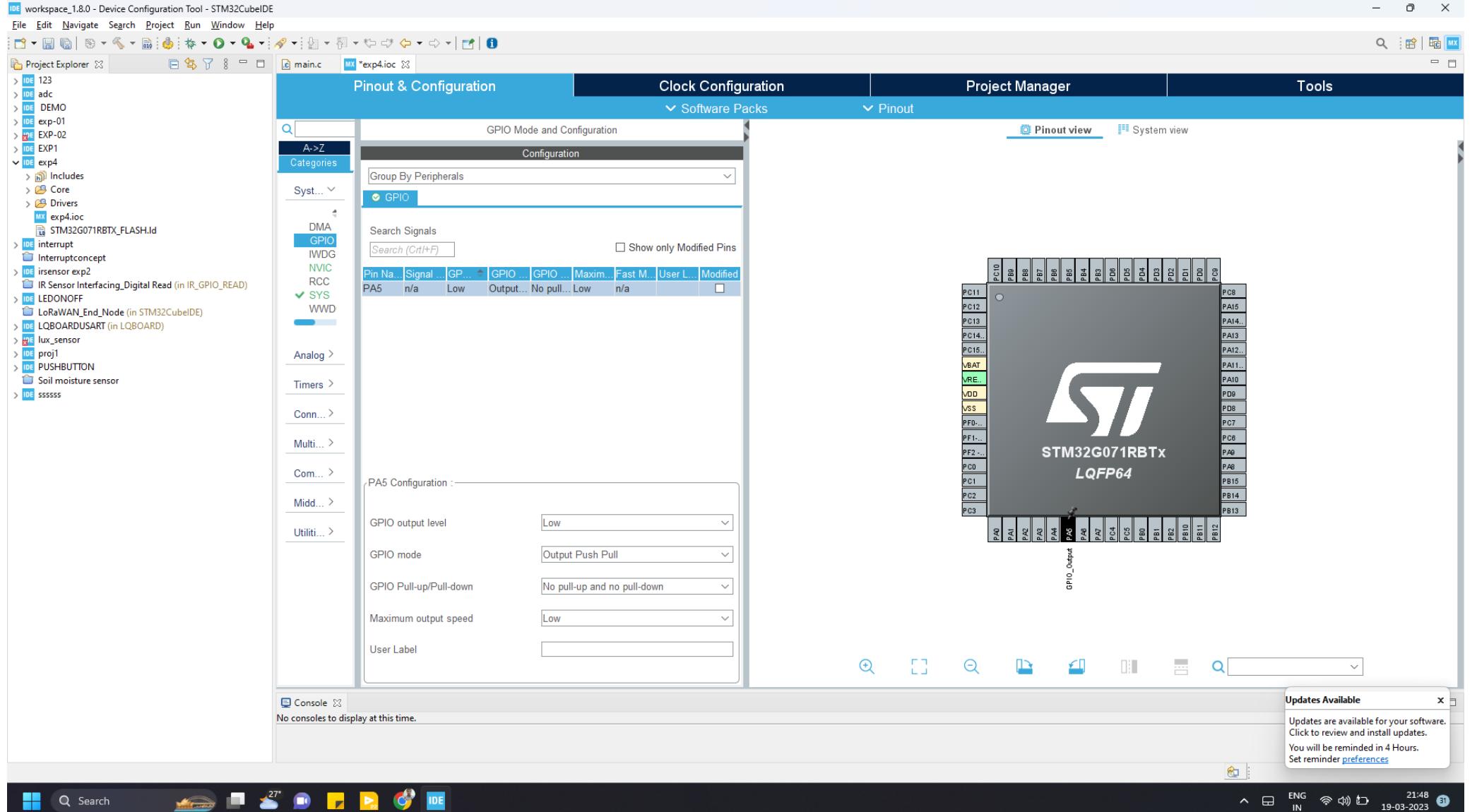


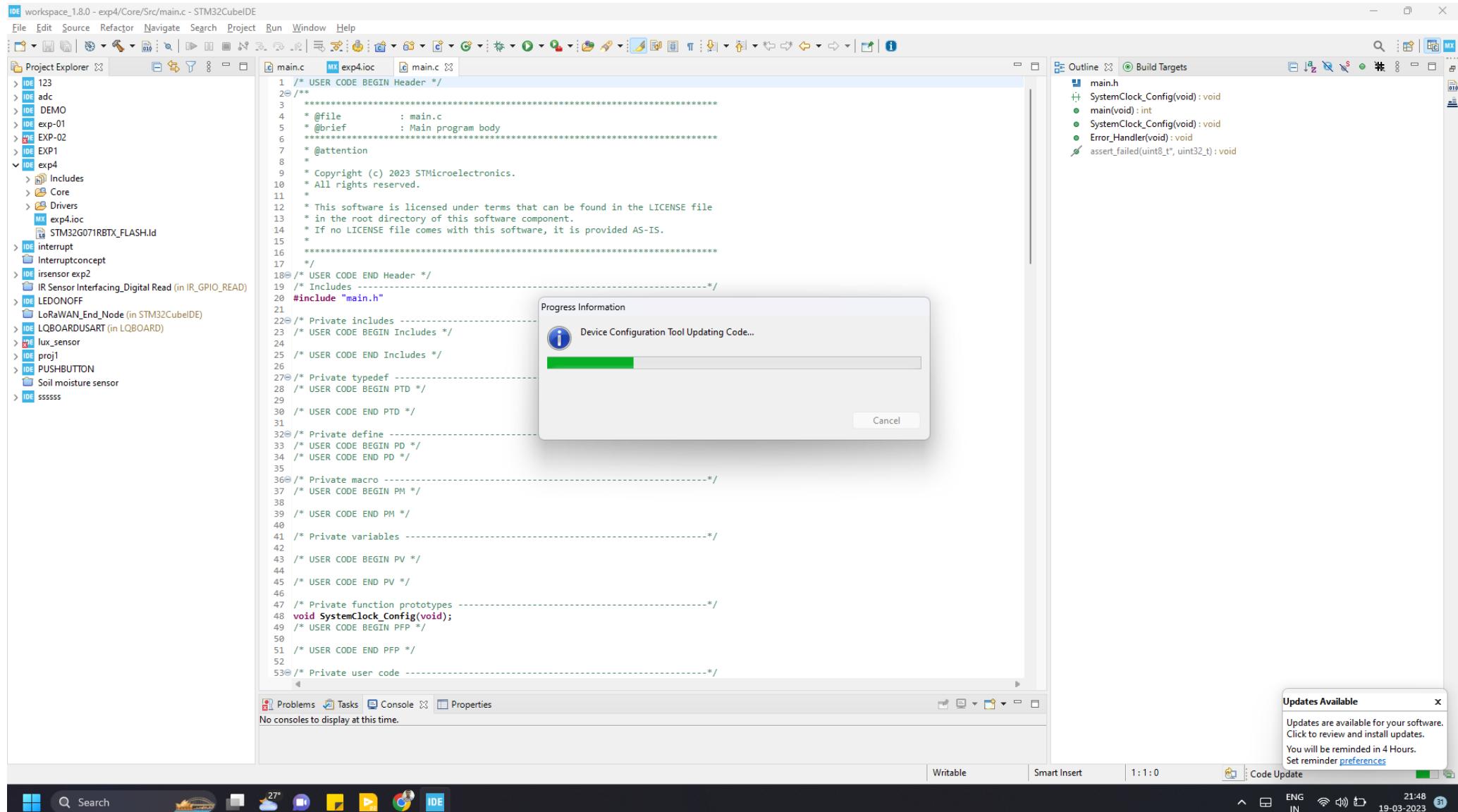
6.select the appropriate pins as gipo, in or out, USART or required options and configure





7.click on cntrl+S , automaticall C program will be generated





8. edit the program and as per required

IDE workspace_1.8.0 - exp4/Core/Src/main.c - STM32CubeIDE

File Edit Source Refactor Navigate Search Project Run Window Help

Project Explorer main.c MX exp4ioc main.c

```
1 /* USER CODE BEGIN Header */
2 /**
3  * @file      : main.c
4  * @brief     : Main program body
5  ******************************************************************************
6  * @attention
7  *
8  * Copyright (c) 2023 STMicroelectronics.
9  * All rights reserved.
10 *
11 * This software is licensed under terms that can be found in the LICENSE file
12 * in the root directory of this software component.
13 * If no LICENSE file comes with this software, it is provided AS-IS.
14 *
15 ******************************************************************************
16 */
17 /**
18 * @*/
19 /* Includes -----*/
20 #include "main.h"
21
22 /* Private includes -----*/
23 /* USER CODE BEGIN Includes */
24
25 /* USER CODE END Includes */
26
27 /* Private typedef -----*/
28 /* USER CODE BEGIN PTD */
29
30 /* USER CODE END PTD */
31
32 /* Private define -----*/
33 /* USER CODE BEGIN PD */
34 /* USER CODE END PD */
35
36 /* Private macro -----*/
37 /* USER CODE BEGIN PM */
38
39 /* USER CODE END PM */
40
41 /* Private variables -----*/
42
43 /* USER CODE BEGIN PV */
44
45 /* USER CODE END PV */
46
47 /* Private function prototypes -----*/
48 void SystemClock_Config(void);
49 static void MX_GPIO_Init(void);
50 /* USER CODE BEGIN PFP */
51
52 /* USER CODE END PFP */
53
```

Outline Build Targets

- main.h
- SystemClock_Config(void) : void
- MX_GPIO_Init(void) : void
- main(void) : int
- SystemClock_Config(void) : void
- MX_GPIO_Init(void) : void
- Error_Handler(void) : void
- assert_failed(uint8_t*, uint32_t) : void

Problems Tasks Console Properties

No consoles to display at this time.

Writable Smart Insert 1:1:0

Updates Available

Updates are available for your software. Click to review and install updates. You will be reminded in 4 Hours. Set reminder preferences

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9. use project and build all

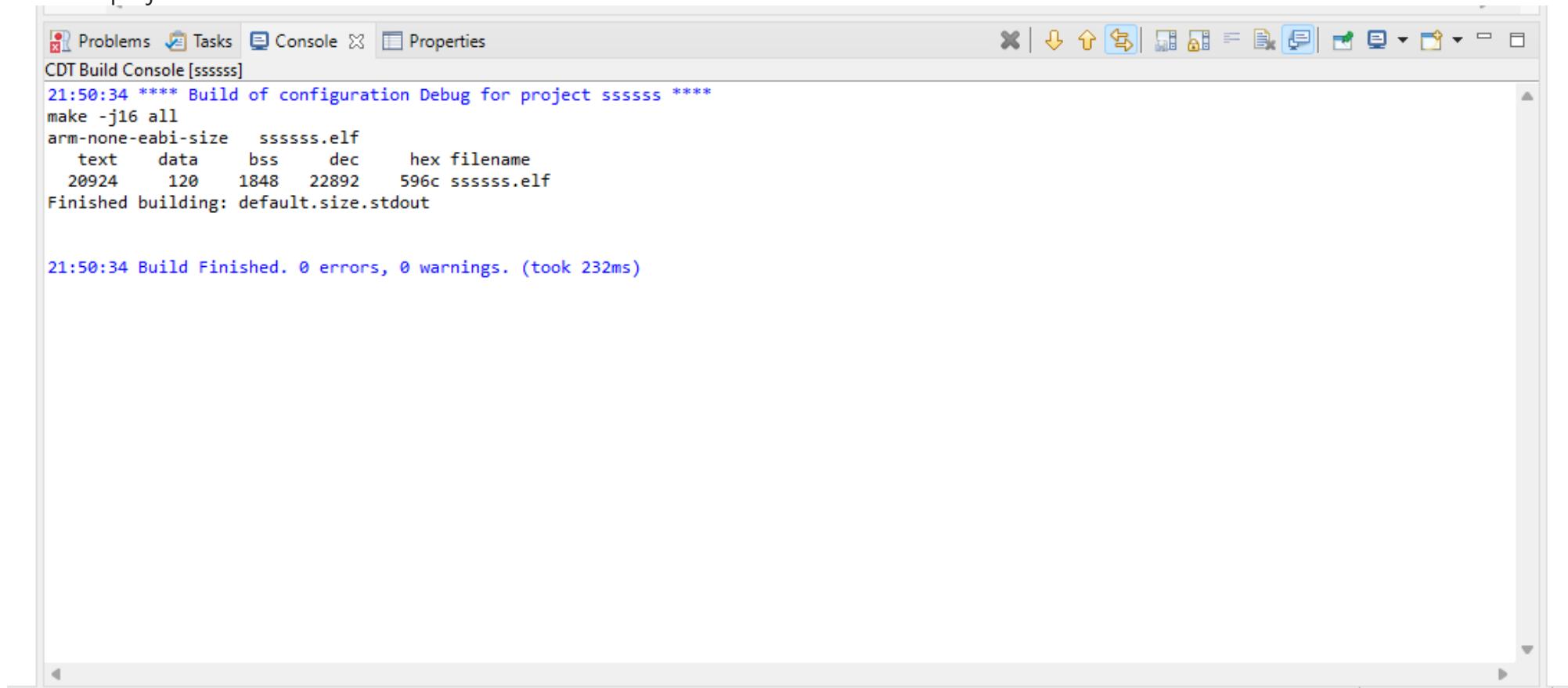
The screenshot shows the STM32CubeIDE interface with the following details:

- Project Explorer:** Shows various projects and files, including 123, adc, DEMO, exp-01, EXP-02, EXP-01, EXP-02, EXP1, exp4, interrupt, Interruptconcept, irsensor exp2, IR Sensor Interfacing_Digital Read (in IR_GPIO_READ), LEDONOFF, LoRaWAN_End_Node (in STM32CubeIDE), LQBOARDUSART (in LQBOARD), lux_sensor, proj1, PUSHBUTTON, Soil moisture sensor, and ssssss.
- Code Editor:** The main.c file is open, displaying C code for a STM32 project. The code includes comments for private includes, user code, and prototypes for SystemClock_Config and MX_GPIO_Init.
- Outline View:** Shows the structure of the main.h header file, including SystemClock_Config, MX_GPIO_Init, main, and Error_Handler.
- CDT Build Console:** Displays the build logs:

```
21:50:34 **** Build of configuration Debug for project ssssss ****
make -j16 all
arm-none-eabi-size ssssss.elf
    text     data     bss     dec   hex filename
 28924      120    1848   22892    596c ssssss.elf
Finished building: default.size.stdout

21:50:34 Build Finished. 0 errors, 0 warnings. (took 232ms)
```
- Bottom Status Bar:** Shows the workspace status (Building Workspace: 98%), system icons (Windows, search, taskbar), and system information (ENG IN, 21:50, 19-03-2023).

10. once the project is bulild

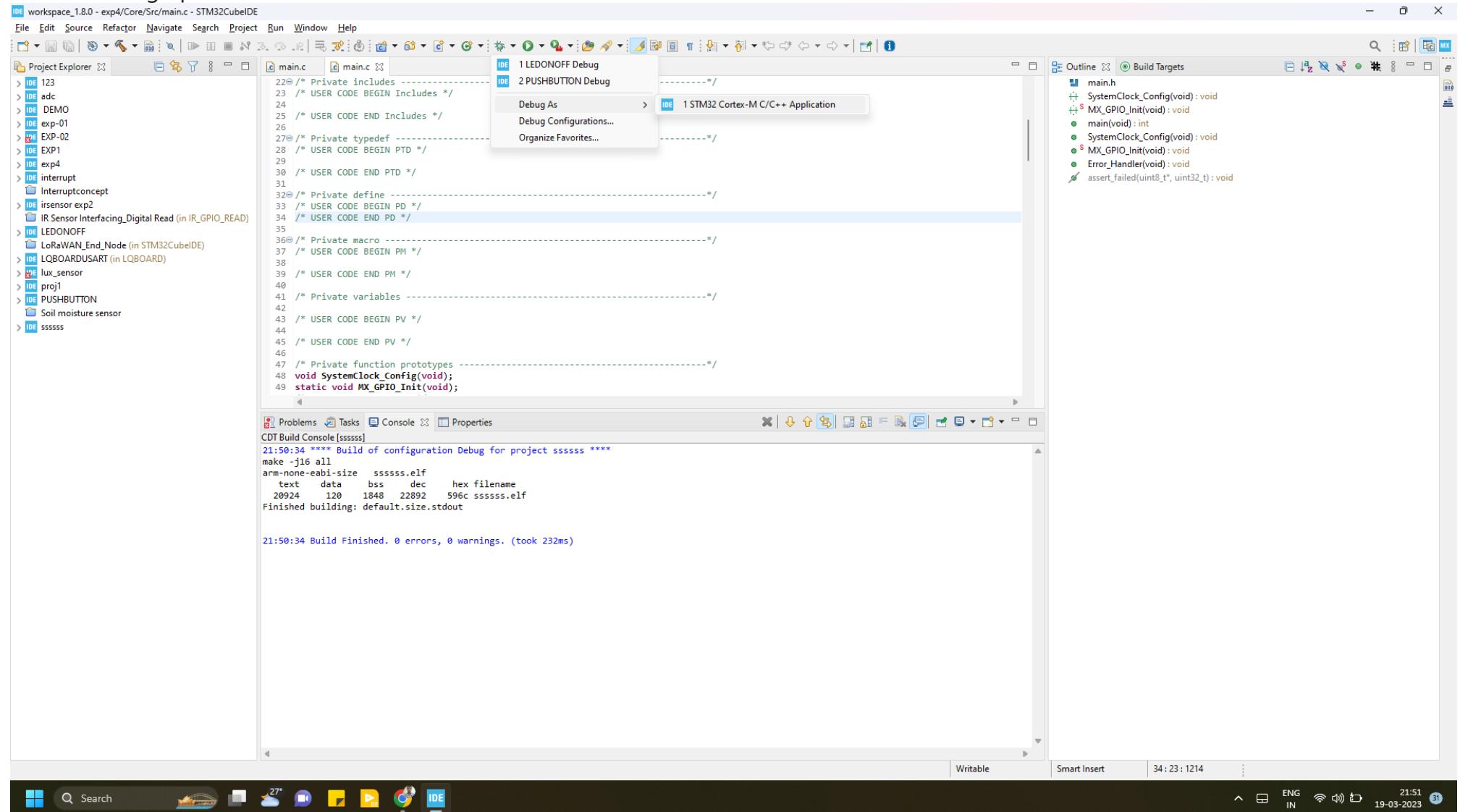


The screenshot shows the Eclipse CDT Build Console window. The title bar reads "CDT Build Console [ssssss]". The console output is as follows:

```
21:50:34 **** Build of configuration Debug for project ssssss ****
make -j16 all
arm-none-eabi-size    ssssss.elf
  text    data     bss     dec   hex filename
 20924      120    1848   22892   596c ssssss.elf
Finished building: default.size.stdout

21:50:34 Build Finished. 0 errors, 0 warnings. (took 232ms)
```

11. click on debug option



12. connect the ARM board to power supply and usb

13. check for execution of the output using run option

' STM 32 CUBE PROGRAM :

```
#include "main.h"
#include "stdio.h"
#include "stdbool.h"
bool vs;

void SystemClock_Config(void);
static void MX_GPIO_Init(void);

int main(void)
{
    HAL_Init();
    SystemClock_Config();

    MX_GPIO_Init();

    while (1)
    {
        vs = HAL_GPIO_ReadPin(GPIOC,GPIO_PIN_13);
        if(vs==0)
        {
            HAL_GPIO_WritePin(GPIOA, GPIO_PIN_5, GPIO_PIN_SET);
            HAL_Delay(50);
            HAL_GPIO_WritePin(GPIOA, GPIO_PIN_5, GPIO_PIN_RESET);
            HAL_Delay(50);
        }
        else
        {
            HAL_GPIO_WritePin(GPIOA, GPIO_PIN_5, GPIO_PIN_RESET);
        }
    }
}
```

```
}
```

```
void SystemClock_Config(void)
{
    RCC_OscInitTypeDef RCC_OscInitStruct = {0};
    RCC_ClkInitTypeDef RCC_ClkInitStruct = {0};

    HAL_PWREx_ControlVoltageScaling(PWR_REGULATOR_VOLTAGE_SCALE1);

    RCC_OscInitStruct.OscillatorType = RCC_OSCILLATORTYPE_HSI;
    RCC_OscInitStruct.HSISState = RCC_HSI_ON;
    RCC_OscInitStruct.HSIDiv = RCC_HSI_DIV1;
    RCC_OscInitStruct.HSICalibrationValue = RCC_HSICALIBRATION_DEFAULT;
    RCC_OscInitStruct.PLL.PLLState = RCC_PLL_NONE;
    if (HAL_RCC_OscConfig(&RCC_OscInitStruct) != HAL_OK)
    {
        Error_Handler();
    }

    RCC_ClkInitStruct.ClockType = RCC_CLOCKTYPE_HCLK|RCC_CLOCKTYPE_SYSCLK
                                |RCC_CLOCKTYPE_PCLK1;
    RCC_ClkInitStruct.SYSCLKSource = RCC_SYSCLKSOURCE_HSI;
    RCC_ClkInitStruct.AHBCLKDivider = RCC_SYSCLK_DIV1;
    RCC_ClkInitStruct.APB1CLKDivider = RCC_HCLK_DIV1;

    if (HAL_RCC_ClockConfig(&RCC_ClkInitStruct, FLASH_LATENCY_0) != HAL_OK)
    {
        Error_Handler();
    }
}

static void MX_GPIO_Init(void)
{
```

```
GPIO_InitTypeDef GPIO_InitStruct = {0};  
__HAL_RCC_GPIOC_CLK_ENABLE();  
__HAL_RCC_GPIOA_CLK_ENABLE();  
  
HAL_GPIO_WritePin(GPIOA, GPIO_PIN_5, GPIO_PIN_RESET);  
  
GPIO_InitStruct.Pin = GPIO_PIN_13;  
GPIO_InitStruct.Mode = GPIO_MODE_INPUT;  
GPIO_InitStruct.Pull = GPIO_PULLUP;  
HAL_GPIO_Init(GPIOC, &GPIO_InitStruct);  
  
GPIO_InitStruct.Pin = GPIO_PIN_5;  
GPIO_InitStruct.Mode = GPIO_MODE_OUTPUT_PP;  
GPIO_InitStruct.Pull = GPIO_NOPULL;  
GPIO_InitStruct.Speed = GPIO_SPEED_FREQ_LOW;  
HAL_GPIO_Init(GPIOA, &GPIO_InitStruct);  
  
}  
  
void Error_Handler(void)  
{  
    __disable_irq();  
    while (1)  
    {  
    }  
}  
  
#ifdef USE_FULL_ASSERT  
  
void assert_failed(uint8_t *file, uint32_t line)  
{  
  
}  
#endif
```

' Output :



Nucleo-G071RB\$AU2
NUCLEO-G071RB

Technical Details

Serial Transmission length 1 Meter.

USB Data Cable

Mobile USB Cable

N Cable

120.00 (Inclusive of all taxes)

Oct. 2022

Saastech

TECHNOLOGIES PVT. LTD.



Result :

Interfacing a digital Input (Pushbutton) with ARM microcontroller based IOT development is executed and the results are verified.

