Shubham Gupta

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EDUCATION

New York University

New York City, US

Master of Science in Computer Engineering — GPA: 3.75/4.0

May 2024

PES University

Bangalore, India

Bachelor of Technology in Computer Science and Engineering — GPA: 8.39/10.0

May 2022

PUBLICATIONS

- Lee, K., Gupta, S., Kim, S., Makwana, B., Chen, C., & Feng, C. (2023). SO-NeRF: Active View Planning for NeRF using Surrogate Objectives. arXiv preprint arXiv:2312.03266. [preprint] [code]
- Gupta, S., Uma, D., Hebbar, R. (2023). Analysis and Application of Multispectral Data for Water Segmentation Using Machine Learning. In: Tistarelli, M., Dubey, S.R., Singh, S.K., Jiang, X. (eds) Computer Vision and Machine Intelligence. Lecture Notes in Networks and Systems, vol 586. Springer, Singapore. https://doi.org/10.1007/978-981-19-7867-8_56 [preprint] [code] [publication] [slides]
- Gupta, S., Ravishankar, R. K., Gangaraju, M., Dwarkanath, P., & Subramanyam, N. (2022). WSSL: Weighted Self-supervised Learning Framework For Image-inpainting. arXiv preprint arXiv:2211.13856. [preprint] [code] [publication] [poster]

SCHOLARSHIPS AND AWARDS

- Granted Merit scholarship of \$16000 at New York University (2022-24).
- Granted Distinction Award Certificate in Semesters I, II, IV, V, VI, VII, and VIII at PES University.
- Granted the MRD scholarship(top 20% of the department) in Semesters V and VI at PES University.
- Secured 1st place at MIT Covid19 Challenge India: Track I as Team Collective (2020).
- Secured 3rd place at Prakalpa science exhibition at PES University for demonstration of Chladni patterns (2019).

EXPERIENCE

AI4CE Lab

May 2023 – Present

New York City, USA

Student Researcher— Advisor: Dr. Chen Feng

- Worked on optimizing camera trajectory by applying Active perception for Neural Radiance Fields. [ArXiv].
- Carried out large scale experiments on NYU HPC cluster for verifying hypothesis.

NYU Courant Institute

February 2023 – Present

Climate Modeling Research Assistant — Advisor: <u>Dr. Laure Zanna</u>

New York City, USA

- Co-wrote and reformatted content in *Machine Learning with Lorenz-96* to make climate modeling using machine learning more beginner friendly. [L96_demo]
- Maintaining and updating user experience for the M^2LInES website. [$\mathbf{M}^2\mathbf{LInES}$]

NYU Marron Institute

January 2023 – August 2023

Urban Transit Research Assistant — Advisor: Dr. Elif Ensari

New York City, USA

- Achieved an accuracy of 85% in classifying boundaries from Google Street View data for the IBX project.
- Experimented with Open Vocabulary Semantic Segmentation models: <u>X-Decoder</u> and <u>Grounded-SAM</u>, and ViT-Adapter to self annotate man-made boundaries from data.

NYU Robomaster

September 2022 – Present

Computer Vision Lead - Mentor: <u>Chris DiMauro</u>

New York City, USA

- Leading an interdisciplinary team of fifteen to train, optimize and deliver a detection and tracking solution.
- Secured 5th place in RoboMasters University League 2023, against twenty teams from USA, Singapore, and Japan.
- Cut YOLOv5 inference latency by 40% using **TensorRT** on Jetson and x86, deploying in Docker NGC containers.

Aruba, a Hewlett Packard Enterprise company

Software Development Intern - Manager: Sachin Sanap

Bangalore, India

- Developed SQL queries and SpringBoot APIs for customer device and app usage insights in production.
- Created a tool for developers to visualize customer statistics using **Grafana**, SQL, **Elasticsearch**, and **Python3**.

CBeyond Technologies LLP

November 2021 – June 2022

January 2022 – July 2022

Founder and CTO

Bangalore, India

- Founded a company to make Computer Vision based SaaS solutions available to the general public.
- FacePass: We aim to provide a face authentication system as an alternative to fingerprint system. Our solution will focus on having **zero contact points** to comply with covid restrictions.

Regional Remote Sensing Center - South, ISRO

August 2019 - April 2020

Research Intern — Advisor: **Dr. Hebbar R**

Bangalore, India

- Published work at the international conference of Computer Vision and Machine Intelligence (CVMI 2022).
- Demonstrated a Sentinel-2 data pipeline with **SnaPy** and **GDAL** for water body detection, **eliminating** manual annotation. Tested on DeeplabV3+ and a custom architecture for near real time water segmentation.

- Developed a model to monitor open water bodies from aerial drone images using **DeepLabv3+**.
- Won 1st place in one of the three internal hackathons and won 'L2' position for the final project demonstration.
- Recommended to work with scientists at RRSC-S, ISRO.

PROJECTS

SO-NeRF | [Website] | PyTorch, Python3, HPC, Blender, NerfStudio | Open-Source

2023

- Developed an active perception pipeline for Neural Radiance Fields that provides us with an optimal view trajectory prior to NeRF training.
- Our method shows a $\sim 80x$ speedup over the present day baseline in Active Perception for Neural Radiance Fields.

Cavemen: A prehistoric approach for Mapless Navigation | [Website] | Python3, Github, FAISS, Redis

2023

- End of Semester project for Robot Perception course where we demonstrate Dead Reckoning, Visual Bag of Words (VBoW), A* algorithm, and system design concepts.
- We achieve the fastest possible time to navigate to a target view in a maze without having prior knowledge of the map. Our solution visualizes the robot's location in **real-time**.
- Our solution is able to scale to maps of large size and generate VBoW of 18000 images under 3 minutes.

Compressed Sensing | [Website] | Python3, Numpy, Github, JupyterBook

2023

- End of Semester project for Image and Video Processing course where we demonstrate Compressed Sensing for MRI data using primal dual splitting algorithm to reduce scan lengths.
- We compare the performance and convergence on random and equidistant masks.

Leave Your Clothes Behind | [Website] | Python3, HPC, PyTorch, Blender, Pytorch3D

2023

- End of Semester project for the Deep Learning course where we demonstrate virtual try-ons for online shopping.
- We present a pipeline thay uses <u>SAM</u> to extract the clothes from a monocular handheld video and <u>COLMAP</u> to generate camera parameters. We then feed it to <u>NeRF2Mesh</u> to create a exportable mesh.

Talks

- Demonstrated how to use <u>Singularity and Anaconda</u> on NYU HPC clusters for machine learning and software development as the <u>Computer Vision Lead</u> at NYU Robomaster (2023).
- Hosted Android Study Jams as the Head of Android Development at Google Developer Student Club, PES University Chapter. The workshops introduced Android development using Kotlin and attracted over a 1000 unique views (2021).

Technical Skills

Languages: Python3, C++, Java, SQL, Javascript, Shell, Lucene, LATEX

Libraries: PyTorch, Pytorch3D, Onnx, TensorRT, OpenCV, Scikit-learn, Numpy, Pandas, Numba, PyRealSense2 Frameworks: ROS2, SpringBoot, Flutter, Hadoop, Elasticsearch, Jekyll, Hugo, Jenkins, Kubernetes, CUDA Applications: HPC, AWS, GCP, Docker, Grafana, QGIS, Github, Jira, Confluence, Firebase Postman, Blender Certifications: Associate Cloud Engineer, Architecting with Google Compute Engine, 30 Days of Google Cloud