# Face Recognition with KNN in

# **MATLAB**

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**Abstract**-This paper mainly focus the recognize a person's identity is important mainly for security reason, but it could also be used to obtain quick access to medical, criminal, or any type of records. Solving this problem is important because it can protect everyone's personal information from being leaked.

**Index Terms**— MATLAB, Image Processing, Eigen Vector, Eigen Values, Euclidean Distance. Signal System, PCA, Image Recognition, Image Segmentation, KNN

#### 1.INTRODUCTION

The idea for this paper came up while through gate of the campus and FaceID in Macbook or smartphone, mainly paper is based upon MATLAB comprising image processing. I had read different algorithms based on image processing like Adam's algorithm, fisher face algorithm, Back Propagation Neural Network etc. But I will show the simplest way of implementing a face recognition system using MATLAB, Here no machine learning or Convolutional neural network (CNN) is required to recognize the faces. To keep the face recognition system as simple as possible, I used eigenvector based recognition system.

#### 2.REQUIREMENTS

SYSTEM: CentOS 7.5.1804 Core (RHEL 7.x) Kernel: x86\_64 Linux 3.10.0-862.eI7.x86\_64

Shell: bash 4.2.46

CPU: Intel Core2 Duo P8600 @ 2x

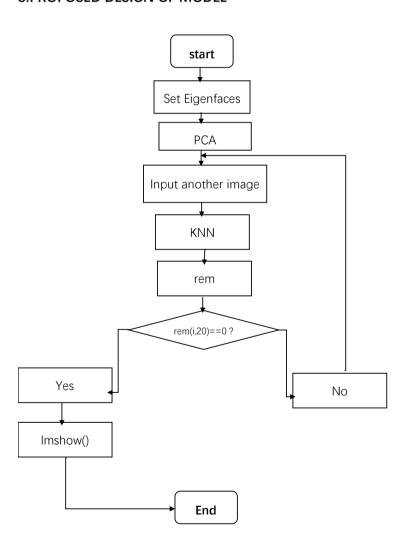
2.401GHz

RAM: 2358MiB / 3847MiB

GPU: Mesa DRI Mobile Intel® GM45

**Express Chipset** 

### 3.PROPOSED DESIGN OF MODEL



SOFTWARE: MATLAB R2018a

#### 4.IMPLEMENTATION

1. First obtain a set of people image. Each image is into a vector of size N and placed into the set.

$$S = \{\Psi_1, \Psi_2, \Psi_3, ..., \Psi_N\}$$
 (1)

2. After we have obtained our set, we will obtain mean image.

$$\Gamma = \frac{1}{N} \sum_{i=1}^{N} \Psi_i \tag{2}$$

3. Then we will find the difference  $\Delta$  between the input image and mean image.

$$\Delta_i = \Psi_i - \Gamma \tag{3}$$

4.We find N orthogonal unit vectors  $u_N$ , these unit vectors are descriptive the distribution  $\Delta$  (the difference in step 3). The k in  $u_N$  (k=1,2,3...,N)

$$\lambda_k = \frac{1}{N} \sum_{i=1}^{N} (u_k^T \Delta_i)^2 \qquad (4)$$

 $\lambda_k$ : Eigen value

When  $\lambda_k$  is at least, this  $u_k$  is pretty much guaranteed

And  $u_k$  also satisfies the flowing equation.

$$u_l^T u_k = \delta_{lk} = \begin{cases} 1 & if \ l = k \\ 0 & otherwise \end{cases}$$

5. Actually, to compute the  $u_k$  above is to compute the eigen-vectors of the following covariance matrix

$$C = \frac{1}{N} \sum_{i=1}^{N} \Delta_i \Delta_i^T = AA^T$$
 (5)

$$(A = \{\Delta_1, \Delta_2, \Delta_3, \dots, \Delta_N\})$$

But for an  $M \times M$  dimensional image, equation (5) is difficult to calculate, so we can use the other solution. If the number of image is less than the dimensions of image  $(N < M^2)$ , the number of vectors that matter is N - 1,not M, because the eigenvalues of the other eigen vectors are 0,

solve for the eigen vectors, it just to solve for an  $M \times M$  dimensional matrix L, The Mth row of L, the Nth column elements can be represented as

$$L_{mn} = \Delta_m \Delta_n^T \tag{6}$$

Once we know the  $\it N$  eigen vectors of the  $\it L$ , then the eigen vectors of covariance matrix are expressed as

$$u_l = \sum_{i=1}^{N} v_{ml} \, \Delta_m \, (l=1,2,...,N)$$
 (7)

6. Finally, we have to recognition, *l*th Eigenface that weights can form a vector

$$\Omega^T = [\omega_1, \omega_2, \dots, \omega_N] \tag{8}$$

According to the Euclidean distance

$$\varepsilon_k = \|\Omega - \Omega_k\|^2 \tag{9}$$

#### **5.RECOGNITION PROCEDURE**

A face image is transformed into its eigen image components. Now according KNN, we can realize face recognition.

# **6.MATLAB CODING**

function output value = load database(); persistent loaded; persistent numeric\_Image; if(isempty(loaded))  $all_{mages} = zeros(10304,400);$ for i=1:40 cd(strcat('s',num2str(i))); for j=1:10image\_Container = imread(strcat(num2str(j),'.pgm')); all Images(:,(i-1)\*10+j)=reshape(image\_Container,size(ima ge\_Container,1)\*size(image\_Container,2),1); end display('Doading Database'); cd ..

end
numeric\_Image = uint8(all\_Images);
end
loaded = 1;

output\_value = numeric\_lmage; loaded\_Image=load\_database(); random Index=round(400\*rand(1,1)); random Image=loaded Image(:,random In dex); rest\_of\_the\_images=loaded\_lmage(:,[1:rand om\_Index-1 random\_Index+1:end]); image Signature=20; white\_Image=uint8(ones(1,size(rest\_of\_the\_ images,2))); mean\_value=uint8(mean(rest\_of\_the\_image s,2)); mean Removed=rest of the imagesuint8(single(mean\_value)\*single(white\_lmag e)); L=single(mean\_Removed)'\*single(mean\_Re moved):%求协方差矩阵 [V,D]=eig(L);%求协方差矩阵的特征值 V=single(mean\_Removed)\*V; V=V(:,end:-1:end-(image Signature-1)); all\_image\_Signatire=zeros(size(rest\_of\_the\_i mages,2),image\_Signature); for i=1:size(rest of the images,2); all\_image\_Signatire(i,:)=single(mean\_Remov ed(:,i))'\*V; end subplot(121); imshow(reshape(random\_Image,112,92)); title('Looking for this Face', 'FontWeight', 'bold', 'Fontsize', 16, 'color' ,'red'); subplot(122); p=random\_lmage-mean\_value; s=single(p)'\*V; z=[];for i=1:size(rest\_of\_the\_images,2)

z=[];

for i=1:size(rest\_of\_the\_images,2)
 z=[z,norm(all\_image\_Signatire(i,:)-s,2)];

if(rem(i,20)==0),imshow(reshape(rest\_of\_the\_images(:,i),112,92)),end;

drawnow;

end

[a,i]=min(z);

subplot(122);

imshow(reshape(rest\_of\_the\_images(:,i),112,
92));

title('Recognition

Completed', 'FontWeight', 'bold', 'Fontsize', 16, 'color', 'red');

#### 7.TEXT RESULT









search this Image



Search this Image

Recognition Completed

#### 8.LIMITATION

- 1.Large amount of calculation
- 2.Sample imbalance problem
- 3.Consume a lot memory

# 9.APPLICATION

- 1.FaceID in PC and phone
- 2.Door lock for person

# 10.CONCLUSION

First we input a image and observed the Euclidean distance that can tells us how close the input image from the image on set. Then according that we know the face whether know.

# 11.REFERENCES

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ISSN 2229-5518

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