

## Wall-Follower-Reinforcement-Learning

This project uses Q Learning to create a wall follower robot using ROS and Python. ## To run:

```
roslaunch wall_flower wallfollow.launch  
roslaunch wall_flower move.py
```

### Youtube video:

[https://youtu.be/OW\\_JivZD3K4](https://youtu.be/OW_JivZD3K4)