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A6

Task 1:

a) See comments in code.

```
def QuadraticSpline(x, fx):  
  
    #calculate the number of segments & constants  
    nsegs = len(x)-1  
    nknts = len(x)  
  
    # create empty arr A and vec B of len 3 * the number of segments  
    # vec B must have 3 constants to define each quadratic section, and  
    # Arr A must have the same dimension as B to create a valid system to  
    solve  
  
    A = np.zeros((nsegs*3, nsegs*3))  
    b = np.zeros((nsegs*3, 1))  
  
    # fill in system for quadratic spline segments  
    for i in range(1, nknts-1):  
        #set up matrix  $ax^2 + bx + c$   
        A[2*i-2, 3*(i-1)] = x[i]**2  
        A[2*i-2, 3*(i-1)+1] = x[i]  
        A[2*i-2, 3*(i-1)+2] = 1  
        A[2*i-1, 3*(i-1)+3] = x[i]**2  
        A[2*i-1, 3*(i-1)+4] = x[i]  
        A[2*i-1, 3*(i-1)+5] = 1  
  
        b[2*i-2] = fx[i]  
        b[2*i-1] = fx[i]  
  
    #boundary condition for first  
    A[2*nsegs-2, 0] = x[0]**2  
    A[2*nsegs-2, 1] = x[0]  
    A[2*nsegs-2, 2] = 1  
    b[2*nsegs-2] = fx[0]  
  
    #boundary conditions for last  
    A[2*nsegs-2+1, -3] = x[-1]**2
```

```

A[2*nsegs-2+1, -2] = x[-1]
A[2*nsegs-2+1, -1] = 1
b[2*nsegs-2+1] = fx[-1]
#iterate through constants
for i in range(1, nknts-1):
    A[(2*nsegs-2)+2 + (i-1), 3*(i-1)] = 2*x[i]
    A[(2*nsegs-2)+2 + (i-1), 3*(i-1)+1] = 1
    A[(2*nsegs-2)+2 + (i-1), 3*(i-1)+3] = -2*x[i]
    A[(2*nsegs-2)+2 + (i-1), 3*(i-1)+4] = -1
    b[(2*nsegs-2)+2 + (i-1)] = 0

#set the initial conditions for the slope at the beginning and end
A[(2*nsegs-2)+ 2 + nsegs-1, 0] = 1
b[(2*nsegs-2) + 2 + nsegs-1] = 0
# use np.linalg to solve the matrix
coeffs = la.solve(A, b)

return coeffs #return

```

b) See code and Fig 1.

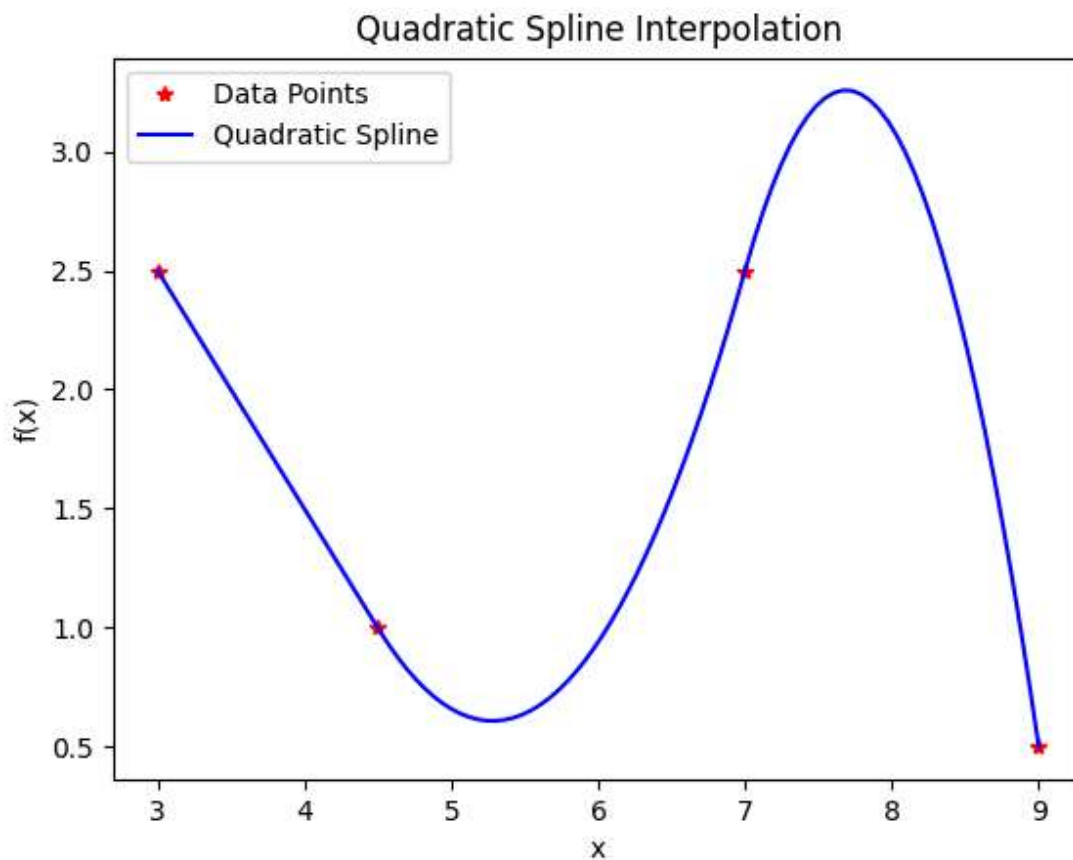


Figure 1. Quadratic Interpolation

Task 2:

```
task2
----- task2 -----
6th order polynomial coefficients: [ 3.60823545e+01 -5.34791997e+00  2.07156309e+01 -5.44323560e+00
 6.92663729e-01 -2.64776603e-02 -2.82361108e-04]
Cubic polynomial coefficients: [33.94597762 15.26824281  2.03046096  0.2674291 ]
Linear polynomial coefficients: [-27.00385455  53.70654545]
```

Task 3:

```
task3
----- task3 -----
Solution using CramerRule: [1. 1. 1.]
Solution using np.linalg.solve: [1. 1. 1.]
```

Task 4:

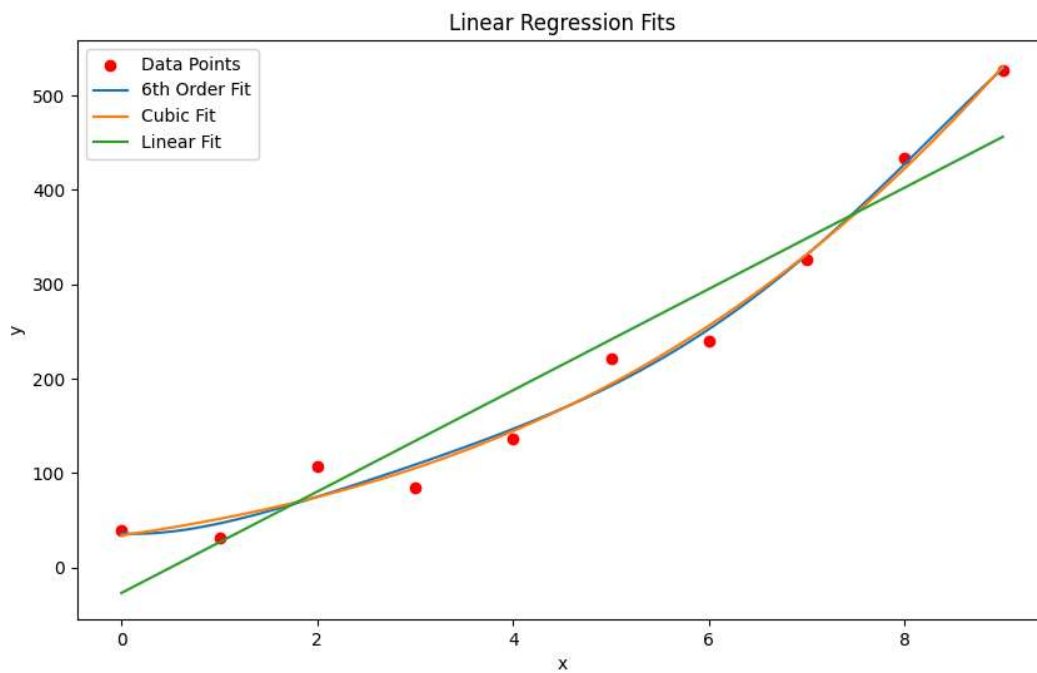


Figure 2. Linear Regressions