AI6104 - MATHEMATICS FOR AI

Tutorial 6 - Matrix Calculus

Problem 1

Let A be an invertible $m \times m$ matrix whose elements are functions of a scalar parameter α . Prove that

$$\frac{\partial A^{-1}}{\partial \alpha} = -A^{-1} \frac{\partial A}{\partial \alpha} A^{-1}$$

Hint: by the definition of inversion, we have $A^{-1}A = I$.

Solution:

By the definition of inversion, we have

$$A^{-1}A = I$$



Then we differentiate on both sides,

$$\frac{\partial A^{-1}}{\partial \alpha} + A^{-1} \frac{\partial A}{\partial \alpha} A^{-1} = 0$$

which concludes the proof.

Problem 2

We will look at the backpropagation in one layer of a neural network (see Figure 1).

In neural networks, a layer f is a function of input X and weight W, where the output is Y = f(X, W). In this problem, we assume a linear layer, Y = f(X, W) = XW. If we consider the input X has N samples, and each sample, $x^{(i)}$, is a D-dimensional vector, then X is an $N \times D$ matrix. Similarly, we have corresponding N output vectors, and each $y^{(i)}$ is M-dimensional, which forms a $N \times M$ matrix Y. Thus, the weight matrix W has shape $D \times M$. Similar layers as described above are embedded into larger neural networks with loss, usually a scalar, L.

(a) During backpropagation, we want to know the gradient of loss with respect to the input X and weight W. Write down $\frac{\partial L}{\partial X}$ and $\frac{\partial L}{\partial W}$ using chain rule.

Solution:

$$\frac{\partial L}{\partial X} = \frac{\partial L}{\partial Y} \frac{\partial Y}{\partial X}, \quad \frac{\partial L}{\partial W} = \frac{\partial L}{\partial Y} \frac{\partial Y}{\partial W}$$

(b) According to part (a), discuss the difficulties of calculating $\frac{\partial L}{\partial X}$ and $\frac{\partial L}{\partial W}$ using the matrix multiplications explicitly.

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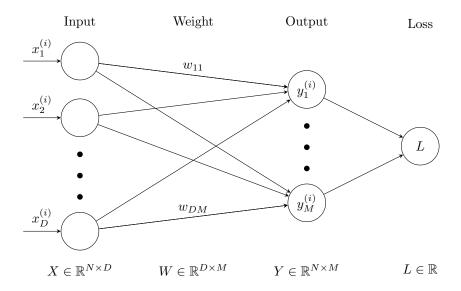


Figure 1: An illustration for Problem 2

Solution:

Calculating the $\frac{\partial L}{\partial X}$ using matrix multiplication directly needs $\frac{\partial Y}{\partial X}$, which is a Jacobian matrix. According to the settings above, this Jacobian matrix is of size $(N\times M)\times (N\times D)$. In a common deep learning setup, we might have N=64 and M=D=4096, which would result in $64\cdot 4096\cdot 64\cdot 4096\approx 6.8\times 10^{10}$ scalar values. Using 32-bit floating point, this Jacobian matrix will take 256 GB of memory to store.



Problem 3

Suppose a linear layer, Y = f(X, W), in a neural network has activation function A(Y). Calculate $\frac{\partial A}{\partial Y}$ for the following different activation functions.

- (a) **ReLU**: $R(Y) = \max\{0, Y\}$
- (b) **Sigmoid**: $S(Y) = \frac{1}{1+e^{-Y}}$
- (c) **Tanh**: $tanh(Y) = \frac{e^Y e^{-Y}}{e^Y + e^{-Y}}$

Solution:

(a)
$$R'(Y) = \begin{cases} 1, Y > 0 \\ 0, Y \le 0 \end{cases}$$

- (b) S'(Y) = S(Y)(1 S(Y))
- (c) $\tanh'(Y) = 1 \tanh^2(Y)$

Problem 4

This problem requires computing the gradients of a full neural network. In particular we are going to compute the gradients of a neural network with one hidden layer trained with

cross-entropy loss. The forward pass of single D-dimensional input sample x is as follows:

$$x = \text{input} \in \mathbb{R}^{D}$$

$$z = Wx \in \mathbb{R}^{M}$$

$$h = \text{ReLU}(z) \in \mathbb{R}^{M}$$

$$\theta = Uh \in \mathbb{R}^{C}$$

$$\hat{y} = \text{softmax}(\theta) \in \mathbb{R}^{C}$$

$$J = \text{CrossEntropy}(y, \hat{y}) \in \mathbb{R}$$

where W and U are weight matrices. y is the true label vector. The softmax activation of the j-th output unit is

$$\hat{y}_j = \operatorname{softmax}(\theta_j) = \frac{e^{\theta_j}}{\sum_j e^{\theta_j}}$$

The cross-entropy error function is

CrossEntropy
$$(y, \hat{y}) = -\sum_{j} y_j \log \hat{y}_j$$

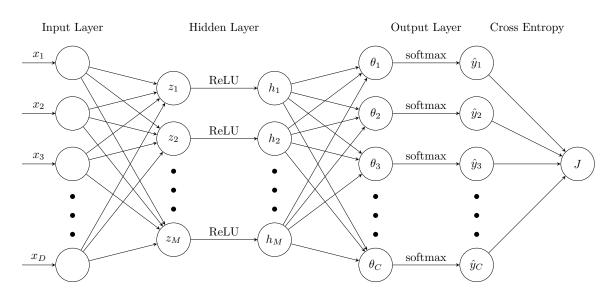


Figure 2: A neural network with one hidden layer

- (a) Calculate the gradient of cross entropy error with respect to the logits, i.e., $\frac{\partial J}{\partial \theta}$.
- (b) According to above information, compute all of the network's gradients, $\frac{\partial J}{\partial U}$, $\frac{\partial J}{\partial W}$, $\frac{\partial J}{\partial x}$. Hint: In practice, you may transpose your vectors to match the dimensions.

Solution:

(a) It is easy to show that

$$\frac{\partial J}{\partial \hat{y}} = -\frac{y}{\hat{y}}$$

For the gradient of softmax function, we look at a single entry first,

$$\frac{\partial \hat{y}_{j}}{\partial \theta_{k}} = \begin{cases} \frac{e^{\theta_{j}} \left(\sum_{k} e^{\theta_{k}} - e^{\theta_{j}}\right)}{\left(\sum_{k} e^{\theta_{k}}\right)^{2}}, & j = k \\ -\frac{e^{\theta_{j}} e^{\theta_{k}}}{\left(\sum_{k} e^{\theta_{k}}\right)^{2}}, & j \neq k \end{cases}$$
$$= \begin{cases} \hat{y}_{j} \left(1 - \hat{y}_{j}\right) \\ -\hat{y}_{i} \hat{y}_{k} \end{cases}$$

By chain rule, we can derive each entry of the gradient

$$\begin{split} \frac{\partial J}{\partial \theta_k} &= \sum_j \frac{\partial J}{\partial \hat{y}_j} \frac{\partial \hat{y}_j}{\partial \theta_k} \\ &= \frac{\partial J}{\partial \hat{y}_k} \frac{\partial \hat{y}_k}{\partial \theta_k} - \sum_{j \neq k} \frac{\partial J}{\partial \hat{y}_j} \frac{\partial \hat{y}_j}{\partial \theta_k} \\ &= -y_k \left(1 - \hat{y}_k \right) + \sum_{j \neq k} y_j \hat{y}_k \\ &= \hat{y}_k - y_k \end{split}$$



Therefore, the gradient can be written as

$$\frac{\partial J}{\partial \theta} = \hat{y} - y$$

(b) Recall that ReLU(x) = max(x, 0), which gives the gradient

$$ReLU' = \begin{cases} 1, & \text{if } x \ge 0 \\ 0, & \text{if otherwise} \end{cases} = sgn(ReLU(x))$$

where sgn(x) is the sign function. We then write down the chain rule for the gradients

$$\frac{\partial J}{\partial U} = \frac{\partial J}{\partial \theta} \frac{\partial \theta}{\partial U}$$

$$\frac{\partial J}{\partial W} = \frac{\partial J}{\partial z} \frac{\partial z}{\partial W}$$

$$= \frac{\partial J}{\partial \theta} \frac{\partial \theta}{\partial h} \frac{\partial h}{\partial z} \frac{\partial z}{\partial W}$$

$$\frac{\partial J}{\partial x} = \frac{\partial J}{\partial z} \frac{\partial z}{\partial x}$$

$$= \frac{\partial J}{\partial \theta} \frac{\partial \theta}{\partial h} \frac{\partial h}{\partial z} \frac{\partial z}{\partial x}$$

It is noticed that $\frac{\partial J}{\partial \theta}$ and $\frac{\partial J}{\partial z}$ are used multiple times, it is convenient to denote that

$$\delta_1 = \frac{\partial J}{\partial \theta} = (\hat{y} - y)^{\top}$$

and

$$\delta_2 = \frac{\partial J}{\partial z} = \frac{\partial J}{\partial \theta} \frac{\partial \theta}{\partial h} \frac{\partial h}{\partial z}$$
$$= \delta_1 \frac{\partial \theta}{\partial h} \frac{\partial h}{\partial z}$$
$$= \delta_1 U \circ \operatorname{sgn}(h)$$

where \circ denotes element-wise multiplication. Here we transpose the vectors to match the dimension. Now we can use δ_1 and δ_2 to compute our gradients. You may check the dimensions of all the terms in the gradients.

$$\frac{\partial J}{\partial U} = \delta_1^\top h^\top$$
$$\frac{\partial J}{\partial W} = \delta_2^\top x^\top$$
$$\frac{\partial J}{\partial x} = (\delta_2 W)^\top$$