

Genetic analysis of quantitative traits in medaka fish and humans

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About

0.1 Summary

Japanese courage: a genetic analysis of complex traits in medaka fish and humans

This thesis primarily explores how an individual's genes interact with the genes of their social companions to create differences in behaviour, using the Japanese medaka fish as a model organism. Chapter 1 sets out the introduction to the diverse topics covered in this thesis.

Chapter 2 describes several genomic characteristics of the Medaka Inbred Kiyosu-Karlsruhe (MIKK) panel, which comprises 80 inbred lines of medaka that were bred from a wild population residing in Kiyosu, southern Japan. In this chapter I plot the inbreeding trajectory of the MIKK panel, and analyse its evolutionary relationship with other previously established inbred medaka strains; degree of homozygosity; rate of linkage disequilibrium decay; repeat content; and structural variation, all which relate to its utility for the genetic mapping of complex traits.

In Chapter 3, I use a custom behavioural assay to characterise and classify bold-shy behaviours in 5 previously established inbred medaka lines. Here I describe the assay, assess its robustness against confounding factors, and apply a hidden markov model (HMM) to classify the fishes' behaviours across a spectrum of boldness-shyness based on their distance and angle of travel between time points. I describe how the different lines differ in their behaviours over the course of the assay (a direct genetic effect) and how the behaviour of a single "reference" line (*iCab*) differs in the presence of different lines (a social genetic effect).

In Chapter 4, I explain how I applied this behavioural assay to the MIKK panel in order to identify lines that diverge in both their own bold-shy behaviours (the direct genetic effect) and the extent to which they transmit those behaviours onto their tank partners (the social genetic effect). I then describe how we used those divergent lines as the parental lines in a multi-way F2 cross in an attempt to isolate the genetic variants that are associated with both direct and social genetic effects.

In Chapter 5 I describe the bioinformatic processes and genetic association models used to map the variants associated with differences in the period of somite development, based on a separate F2 cross between the southern Japanese *iCab* strain, and the northern Japanese *Kaga* strain.

Finally, in Chapter 6, I compare and rank all complex traits in the GWAS Catalog based on the extent to which their associated alleles vary across global human populations, using the Fixation Index (*Fst*) as a metric and the 1000 Genomes dataset as a sample of global genetic variation. In this chapter I set out the bioinformatic pipelines used to process the data, present the distributions of *Fst* for trait-associated alleles across the genome, and use the Kolmogorov-Smirnov test to compare the distributions of *Fst* across different traits.

Altogether, this thesis describes some of the genomic characteristics of both medaka fish and humans, and how those variations relate to differences in complex traits, with a particular focus on the genetic causes of adaptive behaviours and the transmission of those behaviours onto one's social companions.

Chapter 1

Introduction

1.1 A brief history of genetics

Humankind has long sought to understand the basis of biological variation. What gives rise to the wondrous variety of life forms on Earth? Why do individuals of a particular species differ from one another? How do children inherit traits that are similar to those of their parents, yet on the whole remain distinct from both their parents and their siblings? And are the traits we care about – our health, our intelligence, our ability to thrive in a changing world – pre-determined from birth, or continuously pliable throughout our lives?

1.1.1 Ancient Greece

Around 500 BC, the Ancient Grecian Pythagoras applied his understanding of triangles to this question, proposing the theory known as “spermism”. He posited that hereditary information was passed down from parent to child via male sperm, with the female only providing the nutrients that would allow it to grow, and, like the theorem that bears his name, that these two sides of the “triangle” the length of the third side: the characteristics of the child (Mukherjee 2016).

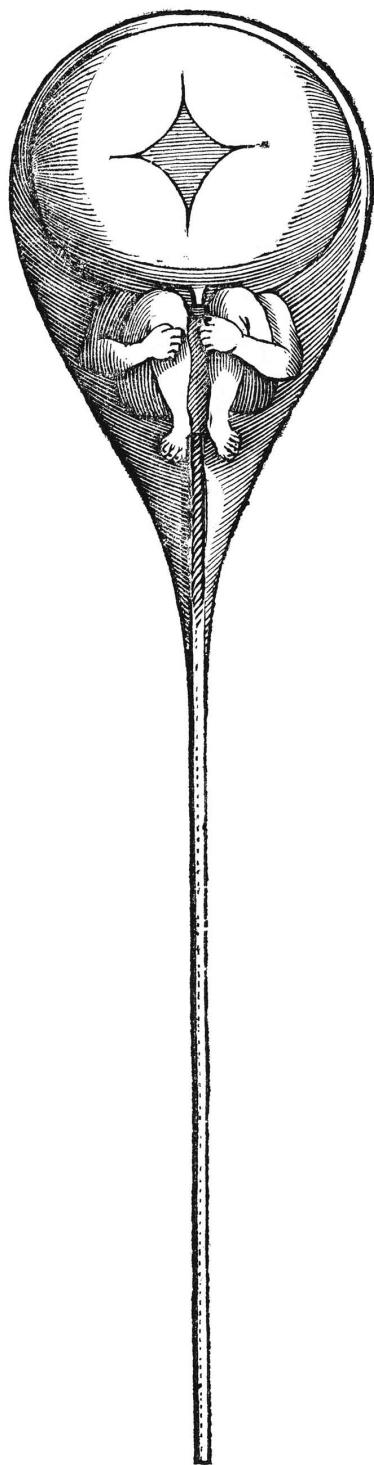
Over a century later, in 380 BC, Plato extended this metaphor in *The Republic* to argue that this principle could be applied to perfect humanity, by breeding perfect combinations of parents.

Aristotle joined the discussion with his treatise *Generation of Animals*, where he noted cases where human skin colour and other traits could skip generations, and thus hereditary information must not only be transmitted through sperm. He suggested an idea of “movement” – the transmission of information – from

the father's sperm, which sculpts the mother's menstrual blood in the same way a carpenter carves a piece of wood.(Mukherjee 2016)

1.1.2 Medieval times

In medieval times, the prevailing theory was that a tiny human – a homunculus – sat within the sperm, waiting to be inflated upon its introduction to a woman's uterus. However, this would require a homunculus to sit within another homunculus, *ad infinitum*, like Matryoshka dolls, all the way back to the Biblical first man, Adam. Even the inventor of the microscope, Nicolaas Hartsoeker, thought he saw one in a sperm he was studying.



1.1.3 Charles Darwin and Gregor Mendel

In 1831, a young Charles Darwin boarded the HMS *Beagle* to embark on an expedition to collect specimens from South America. After collecting a huge number of fossils from the along the eastern coast and shipping them back to England, the *Beagle* spent 5 weeks touring through the 18 volcanic islands of the Galàpagos, where Darwin collected

1.1.4 Breeding programs in agriculture

Chapter 2

Genomic variations in the MIKK panel

This project was carried out in collaboration with Felix Loosli's group at the Karlsruhe Institute of Technology (KIT), and Joachim Wittbrodt's group in the Centre for Organismal Studies (COS) at the University of Heidelberg.

This chapter sets out my contributions to the the following pair of papers published in the journal *Genome Biology*, on both of which I am joint-first author:

- Fitzgerald et al. (2022)
- Leger et al. (2022)

2.1 The Medaka Inbred Kiyosu-Karlsruhe (MIKK) panel

Biological traits are the product of an interaction between an organism's genes and its environment, often described as the relationship between "nature and nurture".(Plomin and Asbury 2005) This is especially true for complex traits such as behaviour, which I investigate in Chapters 3 and 4.

It is unfeasible to explore the relationship between genes and environment experimentally in humans due to the insufficient ability to manipulate either set of variables. Researchers accordingly resort to using model organisms, with which it is possible to control for both. The genetics of model organisms may be controlled to a degree by establishing inbred strains through the repeated mating of siblings over successive generations. Eventually, as the individuals within each line inherit the same haplotype from their related parents,

they become almost genetically identical to one another, with the added benefit that their genotypes can be replicated across time in subsequent generations. This utility has led to the establishment of “panels” of inbred strains for several model organisms including the thale cress (*Arabidopsis thaliana*),(Bergelson and Roux 2010) common bean (*Phaseolus vulgaris L*),(Johnson and Gepts 1999) tomato (*Lycopersicon esculentum*),(Saliba-Colombani et al. 2000) maize (*Zea mays*),(Limami et al. 2002) nematode (*Caenorhabditis elegans*),(Evans et al. 2021) fruit fly (*Drosophila melanogaster*) (Mackay and Huang 2018), and mouse (*Mus musculus*) (Saul et al. 2019).

Although the mouse is an appropriate model for humans due to their orthologous mammalian organ systems and cell types, inbred strains of this organism descend from individuals that had already been domesticated, and therefore do not represent the genetic variation present in wild populations. Furthermore, the large panels of inbred mice such as the Collaborative Cross (CC),(Threadgill et al. 2011) Diversity Outcross (DO)(Svenson et al. 2012) and B6-by-D2 (BXD)(Peirce et al. 2004) are derived from only a small number of individuals. As gene-environment studies seek to ultimately understand their effects on traits “in the wild” (such as with humans), there is accordingly a need for a panel of inbred vertebrates that represents the genetic variation present in natural populations.

The medaka fish (*Oryzias latipes*) has been studied as a model organism in Japan for over a century,(Wittbrodt, Shima, and Schartl 2002) and is gaining recognition elsewhere as a powerful genetic model for vertebrates.(Spivakov et al. 2014) In addition to possessing a number of desirable traits that are characteristic of model organisms (including their small-size, short reproduction time, and high fertility), medaka are also – uniquely among vertebrates – resilient to inbreeding from the wild.

Since 2010, the Birney Group at EMBL-EBI, in collaboration with the Wittbrodt Group at COS, University of Heidelberg and the Loosli Group at the Karlsruhe Institute of Technology (KIT), have been working to establish the world’s first panel of vertebrate inbred strains – now known as the Medaka Inbred Kiyosu-Karlsruhe Panel (**MIKK panel**). The MIKK Panel was bred from a wild population caught near Kiyosu in Southern Japan, and now comprises 80 inbred, near-isogenic “lines”.(Fitzgerald et al. 2022)

The MIKK Panel was created to map genetic variants associated with quantitative traits at a high resolution, and to explore the interactions between those variants and any environmental variables of interest. The purpose of the companion papers Fitzgerald et al. (2022) and Leger et al. (2022) was to introduce the MIKK panel to the scientific community, and describe the genetic characteristics of the MIKK panel that would make it a useful resource for other researchers who wish to explore the genetics of quantitative traits in vertebrates. My contributions to these papers involved visualising the inbreeding trajectory of the panel (Chapter 2.2.2), exploring the evolutionary history of the MIKK panel’s founding population (Chapter 2.2.3), measuring the levels of homozygos-

ity across the panel (Chapter 2.2.4), assessing its allele-frequency distribution and rate of linkage disequilibrium (LD) decay (Chapter 2.2.5), and characterising the structural variants present in a smaller sample of lines using Oxford Nanopore long-read sequencing data (Chapter 2.3).

2.2 Genomic characterisation of the MIKK panel

2.2.1 MIKK panel DNA sequence dataset

For the preparation of Fitzgerald et al. (2022), 79 of the 80 extant MIKK panel lines – together with several wild Kiyosu samples and individuals from the established *iCab* medaka strain – had their DNA sequenced from brain samples using Illumina short-read sequencing technology. Tomas Fitzgerald from the Birney Group at EMBL-EBI then aligned these sequences to the *HdrR* medaka reference and called variants to produce the **MIKK Illumina call set** in the form of a .vcf file containing single nucleotide polymorphism (SNP) and small insertion-deletion (INDEL) calls for each line. To avoid allele frequency biases introduced by the 16 pairs/triplets of “sibling lines” (see 2.2.2), I removed each pair’s arbitrarily-labelled second sibling line from the variant call set, leaving 63 MIKK panel lines (**MIKK non-sibling call set**), and used only those calls for the analyses in Chapters 2.2.4 and 2.2.5.

For the preparation of Leger et al. (2022), 12 MIKK panel lines had their DNA sequenced from brain samples using Oxford Nanopore Technologies (ONT) long-read sequencing technology. Adrien Leger from the Birney Group at EMBL-EBI then aligned these sequences to the *HdrR* medaka reference, and called variants to produce the **MIKK ONT call set** in the form of a .vcf file containing structural variants calls for each line with tags for insertions (INS), deletions (DEL), duplications (SUP), inversions (INV) and translocations (TRA). The work described below used these variant call sets as the primary datasets.

2.2.2 Assessing the inbreeding trajectory of the MIKK panel

The MIKK panel was bred from a wild population of medaka found in the Kiyosu area near Toyohashi, Aichi Prefecture, in southern Japan.(Spivakov et al. 2014) From this wild population, the Loosli Group at KIT set up random crosses of single mating pairs to create 115 ‘founder families’. For each founder family, they then set up between two and five single full-sibling-pair inbreeding crosses, which resulted in 253 F1 lines. Lines derived from the same founder family are referred to as ‘sibling lines’. Over the course of the next eight generations of inbreeding, they used only one mating pair per line. I generated **Fig. 2.1A** and **B** from the

inbreeding data provided by the Loosli Group. **Fig. 2.1A** shows the number of lines that survived over the course of the first 14 generations of the inbreeding program, and the various causes for the termination of other lines. **Fig. 2.1B** shows the average fecundity levels of the surviving lines at generation F16. In addition, the Birney Group at EMBL-EBI generated morphometric data for the MIKK panel lines to demonstrate the distribution of physical phenotypes across the MIKK panel. I used this data on relative eye diameters to generate **Fig. 2.1C**.

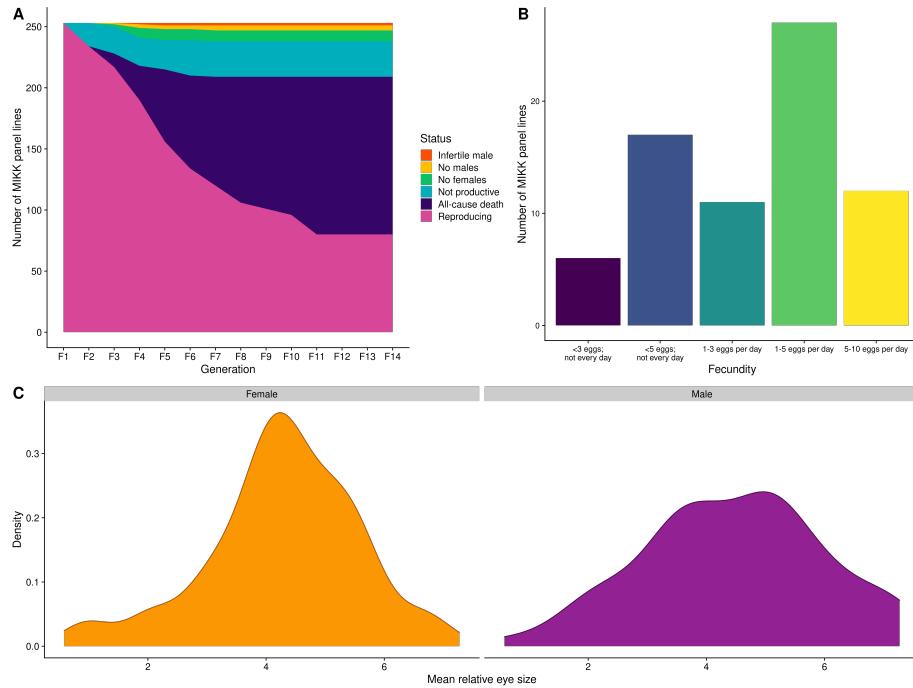


Figure 2.1: Inbreeding, fecundity and eye size in the MIKK panel lines. **A:** Status of all MIKK panel lines during the first 14 generations of inbreeding, showing cause of death for non-extant lines. **B:** Average fecundity of MIKK panel lines in generation F16, as measured during peak egg production in July 2020. **C:** Distribution of mean relative eye size for female and male medaka across all MIKK panel lines.

2.2.3 Introgression with northern Japanese and Korean medaka populations

To explore the evolutionary history of the MIKK panel's founding population, we sought to determine whether there was evidence of introgression between that southern Japanese population, and northern Japanese and

Korean medaka populations. To this end, I used the 50-fish multiple alignment from Ensembl release 102 to obtain the aligned genome sequences for the established medaka inbred lines *HdrR* (southern Japan), *HNI* (northern Japan), and *HSOK* (Korea), as well as the most recent common ancestor of all three strains. (“Index of /Pub/Release-102/Emf/Ensembl-Compara/Multiple_alignments/50_fish.epo/” n.d.) Using the phylogenetic tree provided with the dataset, and the *ape* R package,(Paradis and Schliep 2019) I identified the most recent common ancestor of those three strains. For each locus with a non-missing base for *HdrR*, I assigned the allele in that ancestral sequence as the ‘ancestral’ allele, and the alternative allele as the ‘derived’ allele, and then combined that dataset with the MIKK Illumina call set and variant calls for the southern Japanese *iCab* strain (see 2.2.1).

I then carried out an ABBA BABA analysis to calculate a modified ‘admixture proportion’ statistic \hat{f}_d (S. H. Martin, Davey, and Jiggins 2015) as a measure of the proportion of shared genome in 500-kb sliding windows between the MIKK panel and either *iCab*, *HNI*, or *HSOK* (**Fig. 2.2**), using the scripts provided by the first author of S. H. Martin, Davey, and Jiggins (2015) on their GitHub page.(martin [2016] 2022)

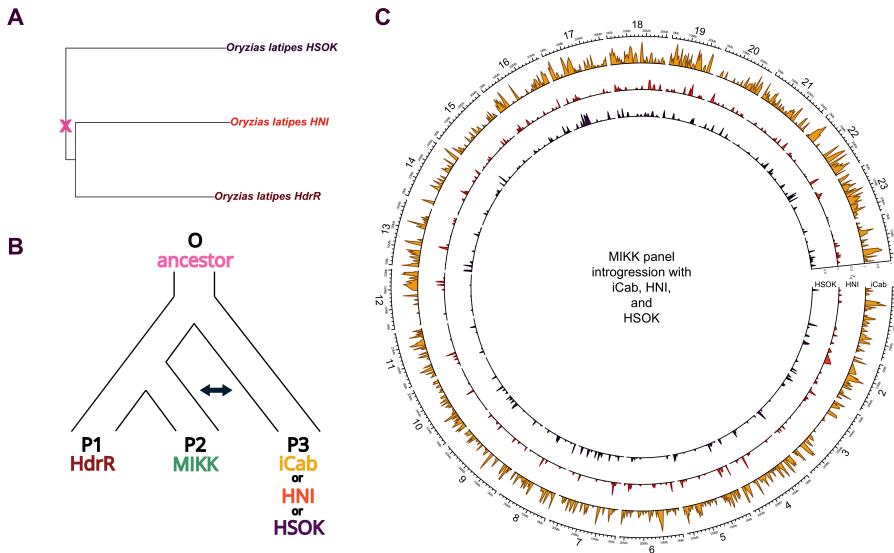


Figure 2.2: **Figure 2:** ABBA-BABA analysis. **A.** Phylogenetic tree generated from the Ensembl release 102 50-fish multiple alignment, showing only the medaka lines used in the ABBA-BABA analysis. **B.** Schema of the comparisons carried out in the ABBA-BABA analysis. **C.** Circos plot comparing introgression (\hat{f}_d) between the MIKK panel and either *iCab* (yellow), *HNI* (orange), or *HSOK* (purple), calculated within 500-kb sliding windows using a minimum of 250 SNPs per window.

Based on the genome-wide mean \hat{f}_d , the MIKK panel shares approximately 25% of its genome with *iCab*, 9% with *HNI*, and 12% with *HSOK*. These results provide evidence that the MIKK panel's originating population has more recently introgressed with medaka from Korea than with medaka from northern Japan. This supports the findings in Spivakov et al. (2014), where the authors found little evidence of significant interbreeding between southern and northern Japanese medaka since the populations diverged. Although the proportional difference between *HNI* and *HSOK* is small, this further supports the general finding that northern and southern Japanese medaka strains show low levels of interbreeding that may be a result of geographical isolation or genome divergence.(Katsumura et al. 2019)

2.2.4 Nucleotide diversity

As a means of assessing genetic diversity in the MIKK panel, I calculated nucleotide diversity ($\hat{\pi}$) within 500-kb non-overlapping windows across the genome of the 63 lines in the MIKK non-sibling call set (see 2.2.1), and compared this to the nucleotide diversity in 7 wild medaka from the same Kiyosu population from which the MIKK panel was derived. Mean and median nucleotide diversity in both the MIKK panel and wild Kiyosu medaka were close to 0, and slightly higher in the MIKK panel (mean: MIKK = 0.0038, wild = 0.0037; median: MIKK = 0.0033, wild = 0.0031). The patterns of varying nucleotide diversity across the genome are shared between the MIKK panel and wild Kiyosu medaka, where regions with high levels of repeat content tend to have higher nucleotide diversity ($r = 0.386$, $p < 0.001$) (Fig. 2.3). I also calculated $\hat{\pi}$ for each line individually, and as expected, levels of $\hat{\pi}$ around the (XX/XY) sex determination region of 1:~16-17 Mb are elevated in all lines relative to the consistently low levels found in most other chromosomes.

The higher level of $\hat{\pi}$ observed within specific regions on several chromosomes – such as chromosomes 2, 11, and 18 – correspond closely to the regions we identified as containing large (>250 kb) inversions that appear to be shared across at least some of the MIKK panel (Fig. 2.4). These regions are also enriched for large deletions and duplications.(Leger et al. 2022) Inversions cause permanent heterozygosity (Hoffmann, Sgr'o, and Weeks 2004), and duplications and deletions may have increased the density of called SNPs in these regions (Fredman et al. 2004), so the observed depressions in homozygosity at these loci may be the result of such large structural variants that are present in the MIKK panel's genomes.

Overall, this analysis confirms that the MIKK panel shows similar levels of homozygosity compared to classical laboratory inbred medaka strains, and possesses a strong increase in isogenic genotypes compared to wild medaka from the original wild population.

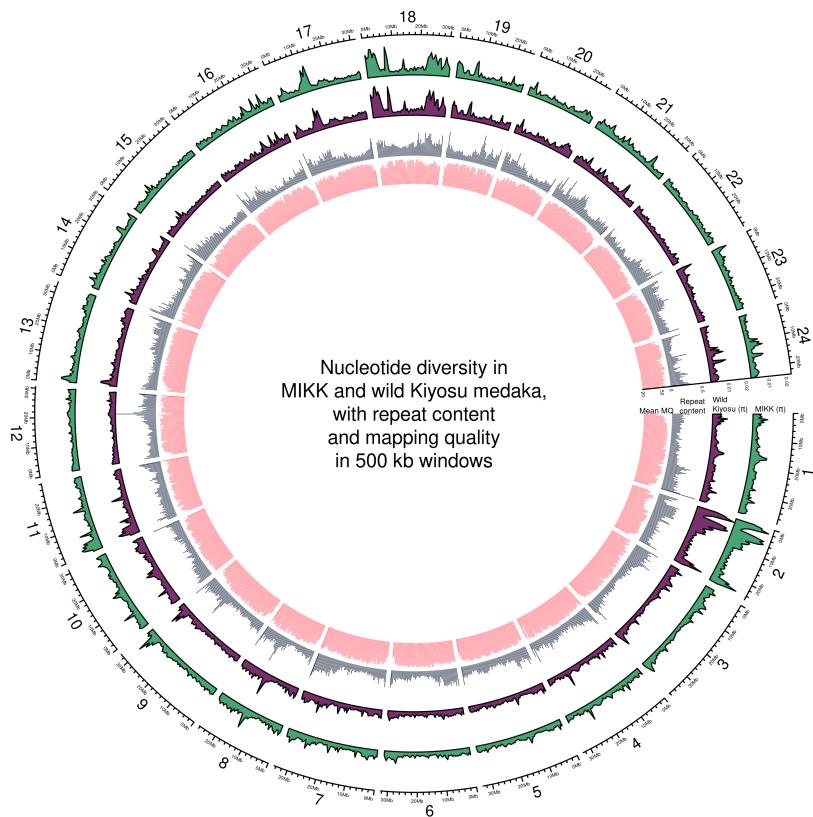


Figure 2.3: Circos plot with nucleotide diversity ($\hat{\pi}$) calculated within 500-kb non-overlapping windows for 63 non-sibling lines from the MIKK panel (green) and 7 wild Kiyosu medaka samples from the same originating population (purple); proportion of sequence classified as repeats by RepeatMasker (blue); and mean mapping quality (pink).

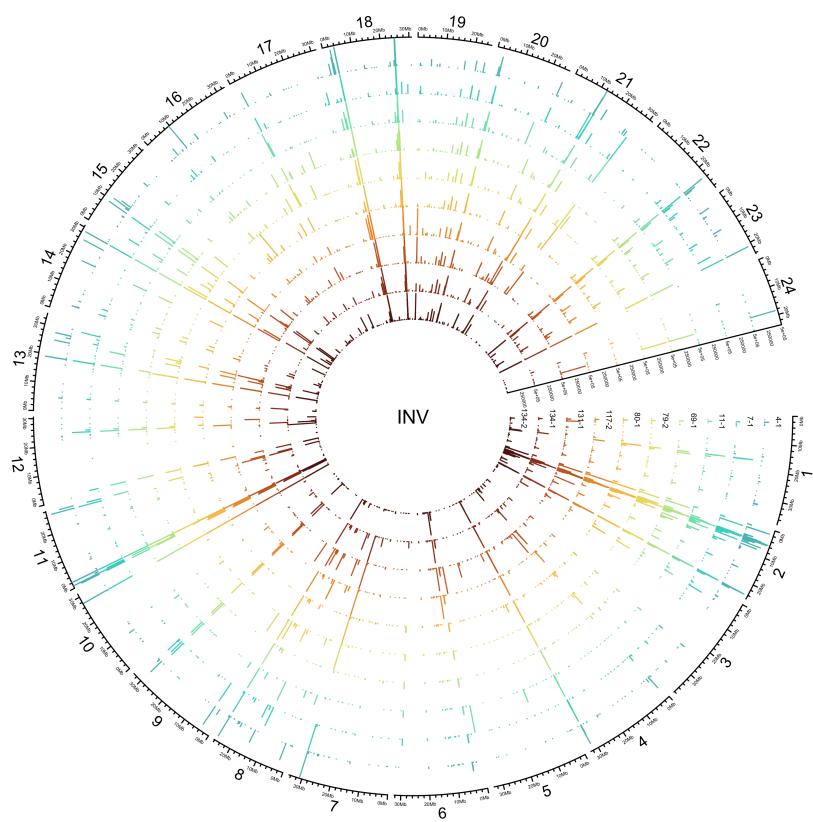


Figure 2.4: Inversions identified in 9 MIKK panel lines using a combination of Oxford Nanopore Technologies long-read and Illumina short-read sequences (see Chapter 2.3 below).

2.2.5 LD decay

I analysed the MIKK panel's allele frequency distribution and linkage disequilibrium (LD) structure to assess their likely effects on genetic mapping. To remove allele-frequency biases introduced by the presence of sibling lines in the MIKK panel, I used only the MIKK non-sibling call set (see Chapter 2.2.1).

To assess how accurately one may be able to map genetic variants using the MIKK panel relative to a human dataset, I compared the MIKK panel's minor allele frequency (MAF) distribution and LD structure against that of the 2,504 humans in the 1KG Phase 3 release. ("A Global Reference for Human Genetic Variation" 2015) To prepare the "**1KG call set**", I first downloaded the .vcf files for each autosome from the project's FTP site (<ftp://ftp.1000genomes.ebi.ac.uk/vol1/ftp/release/20130502/>), then merged them into a single VCF using GATK.(McKenna et al. 2010) I then used PLINK(Chang et al. 2015; Purcell and Chang, n.d.) to calculate the minor allele frequencies for all non-missing, biallelic SNPs in both the MIKK non-sibling and IKG call sets (N SNPs = 16,395,558 and 81,042,381 respectively) (**Fig. 2.5A**). As expected, the 1KG and MIKK panel calls are similarly enriched for low-frequency variants, albeit to a lesser extent in the MIKK panel, which is likely due to its smaller sample size.

To determine the rate of LD decay in the MIKK panel and compare it to that in the 1KG sample, for both the MIKK non-sibling and 1KG call sets, I used PLINK to compute r^2 on each autosome for all pairs of non-missing, biallelic SNPs with MAF > 0.10 within 10 kb of one another (for 1KG and the MIKK panel respectively ~ 5.5M and ~ 3M SNPs, with a total number of pairwise r^2 observations of 204,152,922 and 146,785,673). I then grouped the r^2 observations for each pair of SNPs based on their distance from one another into non-overlapping bins of 100 bp in length, and calculated the mean r^2 in each of those bins to generate **Fig. 2.5B** using the mean r^2 and left boundary of each bin.

Based on the 1KG calls under these parameters, LD decays in humans to a mean r^2 of around 0.2-0.35 at a distance of 10 kb, whereas the MIKK panel reaches this level within 1 kb, with a mean r^2 of 0.3-0.4 at a distance of ~100 bp. This implies that when a causal variant is present in at least two lines in the MIKK panel, one may be able to map causal variants at a higher resolution than in humans. We note that LD decays faster in chromosome 2 of the MIKK panel relative to the other chromosomes. This suggests that it has a much higher recombination rate, which is consistent with the linkage map described in Naruse et al. (2000), showing a higher genetic distance per Mb for this chromosome. This higher recombination rate in chromosome 2 may in turn be caused by its relatively high proportion of repeat content (**Fig. 2.6**).

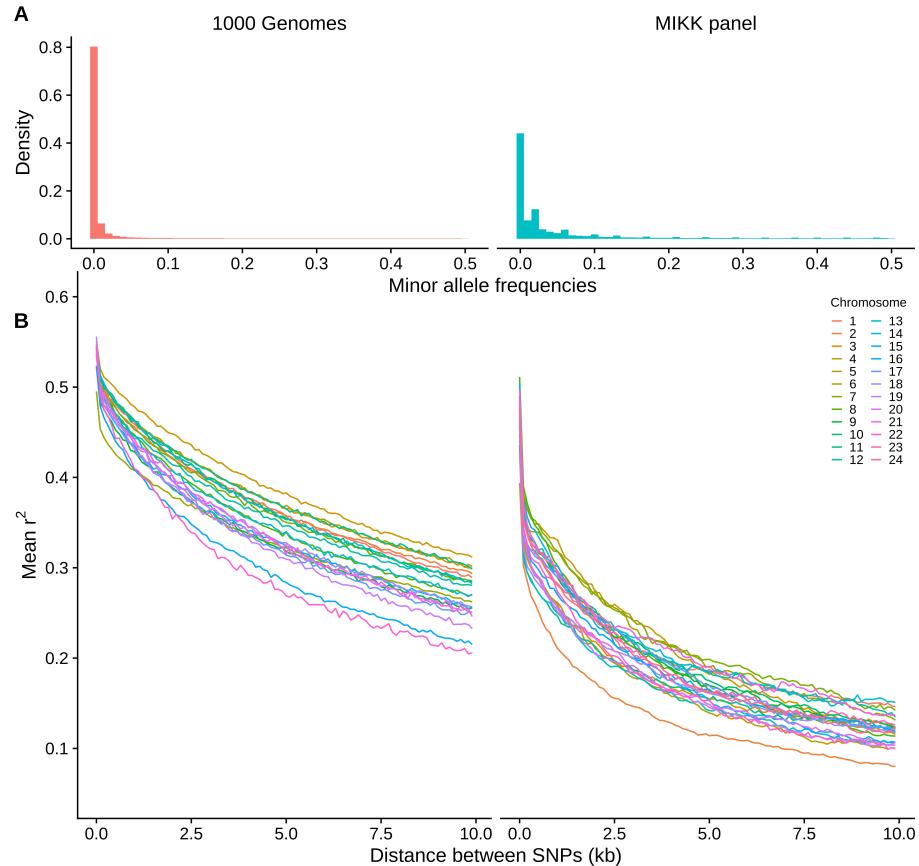


Figure 2.5: Minor allele frequency distributions and LD decay for biallelic, non-missing SNPs in the 1000 Genomes Phase 3 variant calls ($N = 2,504$) (1KG), and the MIKK panel Illumina-based calls excluding one of each pair of sibling lines ($N = 63$), across all autosomes (1KG: chrs 1-22; MIKK: chrs 1-24). **A:** Histogram of allele frequencies in the 1KG and MIKK panel calls. **B:** LD decay for each autosome, calculated by taking the mean r^2 of pairs of SNPs with MAF > 0.1 within non-overlapping 100 bp windows of distance from one another, up to a maximum of 10 kb. LD decays faster on chromosome 2 for the MIKK panel due to its higher recombination rate.

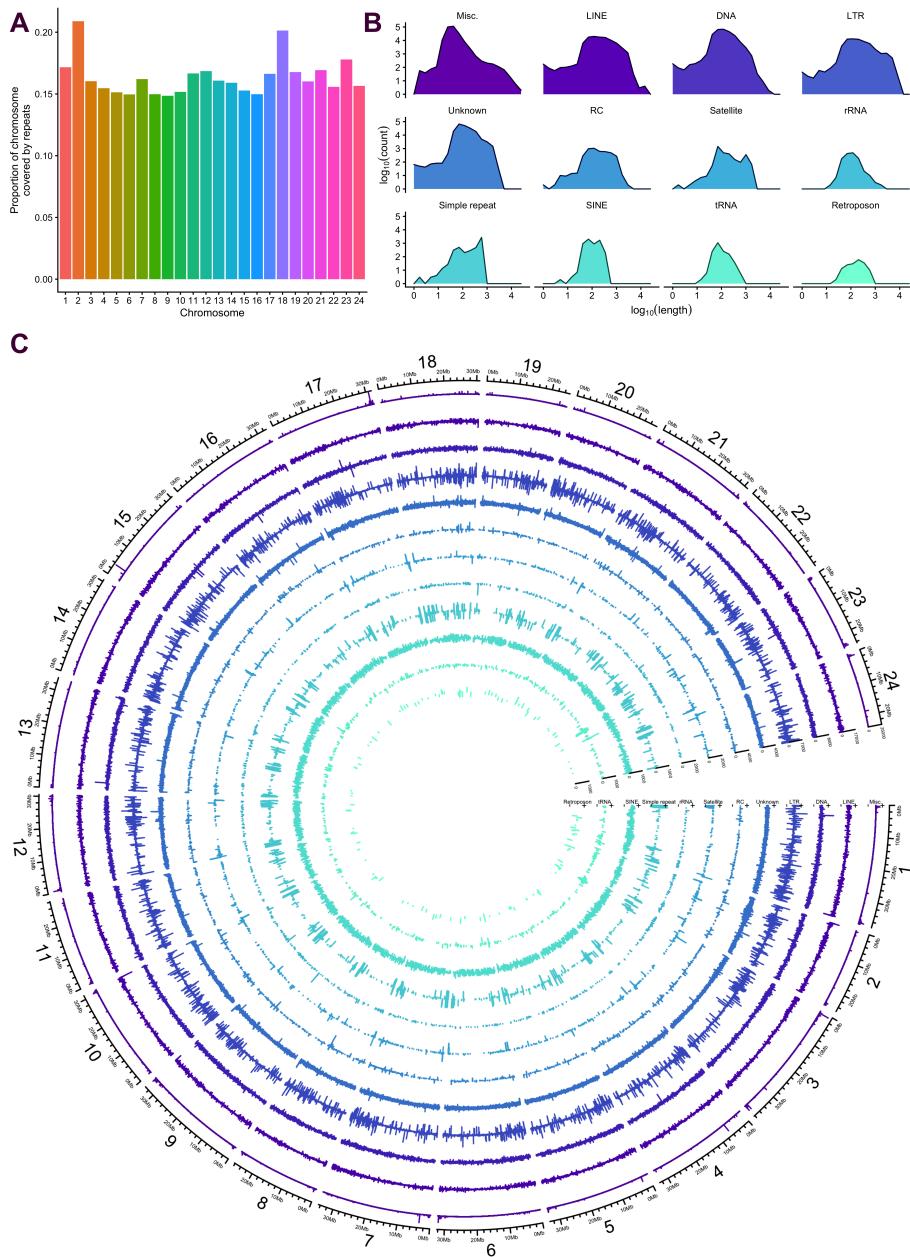


Figure 2.6: Repeat content in the *HdrR* genome based on RepeatMasker results obtained by Jack Monahan. **A.** Proportion of repeat content per chromosome. **B.** \log_{10} of repeat lengths and counts per repeat class. “Misc” includes all repeats assigned to their own specific class, for example “(GAG) n ” or “(GATCCA) n ”. **C.** Circos plot showing repeat length (radial axes) by locus (angular axis) and repeat class (track).

2.3 Structural variation in the MIKK panel

As an alternative to the variation pangenome approach described in Leger et al. (2022), I explored the structural variants (SVs) present in 9 of the MIKK panel lines in a reference-anchored manner, similar to many human studies. Differences in SVs between panel lines is another important class of genetic variation that could cause or contribute to significant phenotypic differences. Here we used ONT data obtained for 9 of the 12 selected lines allowing us to characterise larger SVs in the MIKK panel and to create a more extensive picture of genomic rearrangements compared to available medaka reference genomes. Adrien Leger from the Birney Group at EMBL-EBI first called structural variants using only the ONT long reads, producing a set of structural variants classified into five types: deletions (DEL), insertions (INS), translocations (TRA), duplications (DUP) and inversions (INV). I then “polished” the called DEL and INS variants with Illumina short reads to improve their accuracy. The polishing process filtered out 7.4% of DEL and 12.8% of INS variants, and adjusted the breakpoints (i.e. start and end positions) for 75-77% of DEL and INS variants in each sample by a mean of 23 bp for the start position, and 33 bp for the end position. This process produced a total of 143,326 filtered SVs.

The 9 “polished” samples contained a mean per-sample count of approximately 37K DEL variants (12% singletons), 29.5K INS variants (14%), 3.5K TRA variants (9%), 2.5K DUP (7%) and 600 INV (7%) (**Fig. 2.7D**). DEL variants were up to 494 kb in length, with 90% of unique DEL variants shorter than 3.8 kb. INS variants were only up to 13.8 kb in length, with 90% of unique INS variants shorter than 2 kb. DUP and INV variants tended to be longer, with a mean length of 19 and 70.5 kb respectively (**Fig. 2.7A**). **Fig. 2.7E** shows the per-sample distribution of DEL variants across the genome. Most large DEL variants over 250 kb in length were common among the MIKK panel lines. A number of large DEL variants appear to have accumulated within the 0-10 Mb region of chromosome 2, which is enriched for repeats in the *HdrR* reference genome (**Fig. 2.6**).

SVs were generally enriched in regions covered by repeats. While only 16% of bases in the *HdrR* reference were classified as repeats (irrespective of strand), those bases overlapped with 72% of DEL, 63% of DUP, 81% of INV and 35% of TRA variant regions. However, repeat bases only overlapped with 21% of INS variants. We also assessed each SV’s probability of being loss-of-function (pLI)(Lek et al. 2016) by calculating the logarithm of odds (LOD) for the pLI scores of all genes overlapping the variant (**Fig. 2.7B,C**). 30,357 out of 134,088 DEL, INS, DUP and INV variants overlapped at least one gene, and 9% of those had a score greater than 10, indicating a high probability that the SV would cause a loss of function. Two INS variants on chr2 had an outlying LOD score of 57 as a result of overlapping medaka gene ENSORLG00000003411, which has a pLI score of 1 – the highest intolerance to variants causing a loss of function. This gene is homologous with human genes *SCN1A*, *SCN2A* and

SCN3A, which encode sodium channels and have been associated with neuronal and sleep disorders. We did not find evidence that longer SVs tended to have a higher probability of causing a loss of function (**Fig. 2.7B**).

We compared these polished INS and DEL calls with the high-quality graph-based alternative paths and large-scale deletions, respectively (see section titled *Novel genetic sequences and large-scale insertions and deletions in the MIKK panel* in Leger et al. (2022)). We found that 2 of the 19 regions covered by graph-based alternative paths, and 4 of the 16 regions covered by graph-based deletions, had no SVs that overlapped those regions at all, which suggests they would have been missed entirely when using a reference-anchored approach alone.

With the exception of one alternative path on chromosome 20, the alternative paths were not captured by INS variants, which only covered up to 63% of the bases in each region, and in many cases substantially less. On the other hand, for 8 of the 16 graph-based deletions, the DEL variants covered at least 85% of the bases in those regions. The other 8 graph-based deletions were either not at all covered by DEL variants, or only slightly. This indicates that the reference-based approach is better at detecting large-scale deletions than alternative paths (“insertions”), but still misses around half of such variants relative to the graph-based approach.

2.4 Conclusions

Taken together, these analyses show that the MIKK panel is highly homozygous, with LD characteristics that will favour high-resolution genetic mapping relative to humans. In the future, the SV analysis performed on a subset of the MIKK panel will be expanded across the entire panel, which will permit the inclusion of both large- and small-scale variants in genetic linkage studies. I proceeded to use the MIKK panel to analyse bold/shy behaviours, as I describe in Chapter 4, with a view to carrying out an F2-cross linkage study to identify genetic variants associated with differences in the behaviours of an individual, and the extent to which they transmit those behaviours to their social companions. However, before carrying out this study, we first ran a “pilot” study on 5 previously-established inbred lines to validate our behavioural assay. This is the subject of the following chapter.

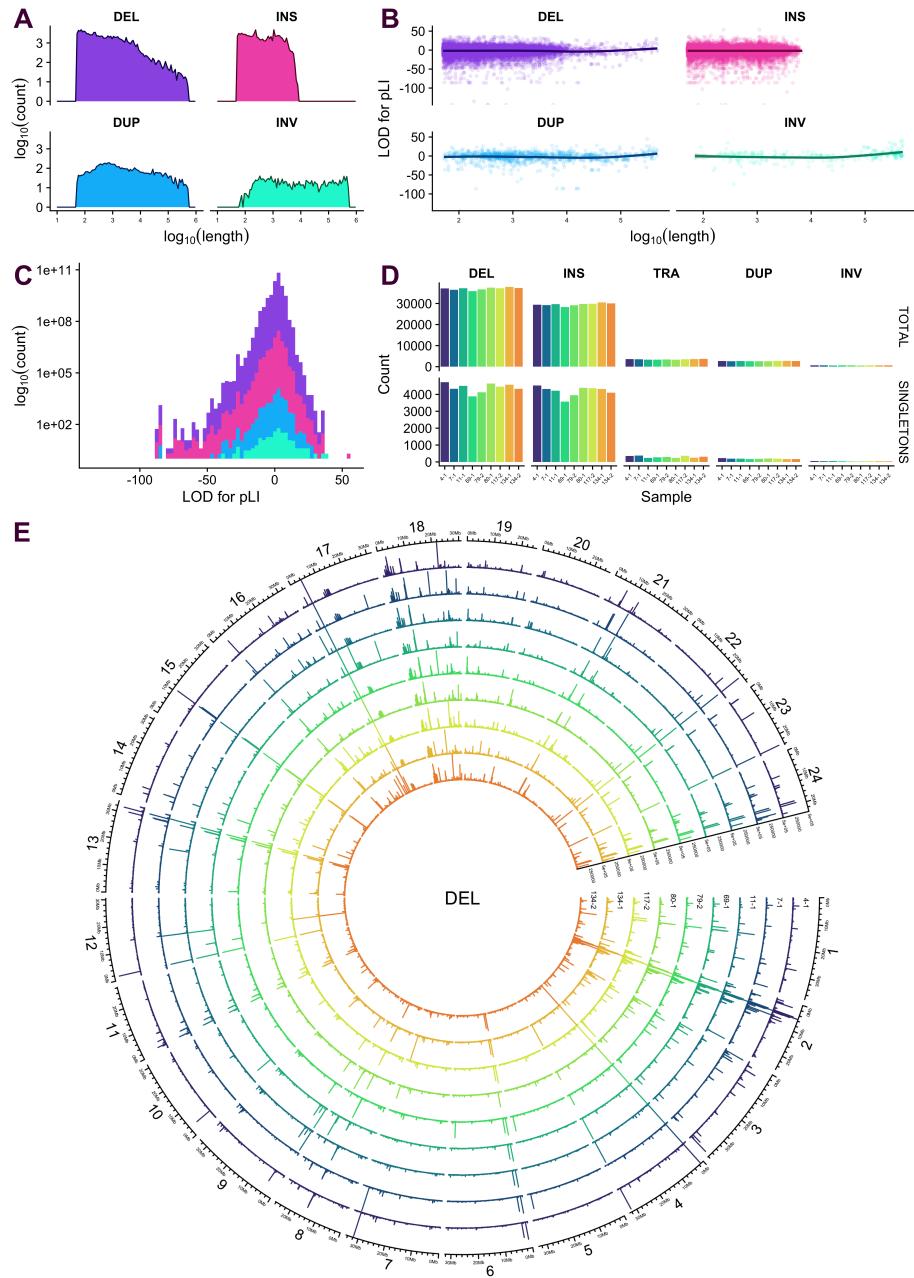


Figure 2.7: Polished SVs in 9 MIKK panel lines sequenced with ONT. DEL: deletion; INS: insertion; TRA: translocation; DUP: duplication; INV: inversion.

A. Aggregate \log_{10} counts and lengths of distinct SVs by type, excluding TRA.

B. pLI LOD scores in distinct SVs by SV type.

C. Histogram of LOD scores by SV type.

D. Total and singleton counts of SV types per sample.

E. Circos plot showing per-sample distribution and lengths of DEL variants across the genome.

Chapter 3

Classification of bold/shy behaviours in 5 inbred medaka lines

3.1 Introduction

Humankind has long sought to understand what causes differences between the minds of individuals, and the behaviours they manifest. The origin of these differences resides in our genomes, as genetic differences between individuals are what set them on their unique developmental trajectories (Mitchell 2007). During the course of an organism's development, and ongoing throughout its lifespan, their genes interact with each other and the environment, leading to the creation of measurable traits, or phenotypes (Plomin and Asbury 2005). A core domain of biological inquiry concerns the extent to which an individual's value for a trait is determined by their genes (**G**), their environment (**E**), or an interaction between the two (**GxE**), commonly referred to as the interplay between 'nature and nurture' (Galton and Okamoto 1874; Plomin and Asbury 2005).

Experimental investigations of GxE in humans are hampered by the difficulties in sufficiently controlling for either genes or environment. To explore this fundamental question, researchers accordingly turned to model organisms, including the nematode (*Caenorhabditis elegans*) (Snoek et al. 2019), fruit fly (*Drosophila melanogaster*) (Schneider, Atallah, and Levine 2017), mouse (*Mus musculus*) (Baud et al. 2017), and teleost species such as zebrafish (*Danio rerio*) (Raterman et al. 2020) and medaka (*Oryzias latipes*). Medaka is an established model organism which has been studied in Japan for over a century (Wittbrodt, Shima, and Schartl 2002). In addition to possessing many favourable traits

including ease of handling, a rapid reproduction cycle, a short lifespan, and a well-annotated genome, medaka has a trait that is singular among vertebrates – they have a high tolerance to inbreeding from the wild, allowing one to establish near-isogenic inbred strains with relative ease (Fitzgerald et al. 2022; Kirchmaier et al. 2015).

Inbred strains permit experimental quantification of complex trait parameters with sufficient replication under controlled assay conditions. By comparing individuals from different strains, one can measure the strength of genetic effects on a trait of interest. Furthermore, the low degree of genetic variance between individuals of an inbred strain allows one to measure the strength of environmental effects on a given trait by controlled variation of the environment.

3.2 Boldness-shyness

Behaviour is a complex trait that is affected by both genes and environment, and for social animals such as humans and medaka, one's social environment is considered likely to constitute a large component of the environmental effect (Ruzzante and Doyle 1990; Young 2008). Apart from social aspects, an organism must face many “hostile forces of nature” throughout its life (Buss 1991; Darwin 1859), such as food shortages, predation, harsh climate, and diseases. Adaptive behaviours allow individuals to navigate such dangers and maximise the likelihood of their survival at both the individual and population level (Lima and Dill 1990).

Boldness-shyness is thought to be a fundamental axis of behavioural variation in many species, with an obvious causal relationship to an individual's likelihood of survival, and consequently with natural selection at the population level (Sloan Wilson et al. 1994). It represents an evolutionary trade-off between acquiring benefits (in terms of food or mates) and avoiding harms (in terms of predators or conspecific competitors), with each situation accompanied by its own optimal degree of risk (Lima and Dill 1990). It is both heritable (Svartberg 2002; Culum Brown, Burgess, and Braithwaite 2007), and subject to change following different life experiences or under different environmental conditions (Culum Brown, Burgess, and Braithwaite 2007). Boldness-shyness has been studied extensively with fish. Shy individuals tend to react to novelty by reducing their activity and becoming more vigilant, whereas bold individuals show higher levels of activity and exploratory behaviour (C. Brown, Jones, and Braithwaite 2007). One assay commonly used to measure this behavioural domain is referred to as the ‘open field’ assay, where fishes are observed while swimming freely in an experimental setting (C. Brown, Jones, and Braithwaite 2007; Laland, Krause, and Brown 2011; Lucon-Xiccato et al. 2022, 2020; Lucon-Xiccato and Bisazza 2017; Matsunaga and Watanabe 2010). Another is the ‘novel object’ assay, where a novel object is introduced to the fishes’ environment to simulate a threat (C. Brown, Jones, and Braithwaite 2007; Schjolden, Stoshus, and Winberg 2005;

Wilson et al. 1993; Dominic Wright, Butlin, and Carlberg 2006; D. Wright et al. 2003). Where both assays were performed on the same fish, the behaviours exhibited were found to be correlated across assays, indicating that both were measuring the same boldness-shyness axis (C. Brown, Jones, and Braithwaite 2007). [there is also an aspect of habituation in both parts of the test that should be mentioned]

3.3 Social genetic effects

The specific environmental factor is the so-called indirect or social genetic effect, which describes the indirect interactions between an individual's genes and the genes of their companions (Baud et al. 2017). Social genetic effects have been shown to exert influence on various traits in mice including anxiety, wound healing, immune function, and body weight (Baud et al. 2017), and various traits related to development and survival in many species of livestock (Ellen et al. 2014). However, in those studies the social interactions were maintained throughout development, and it is unclear whether social genetic effects can still exert influence on adaptive behaviours during discrete, time-limited interactions.

Taking advantage of the rich genetic resources offered by medaka we established an OFT to examine the performance of isogenic inbred strains for an inter-strain comparative analysis of the boldness-shyness behaviour of medaka. We used a combined open-field and novel-object assay involving assaying pairs for fish, to determine: a) whether there were consistent differences in bold-shy behaviours exhibited by 5 established inbred strains of medaka fish (*iCab*, *HdrR*, and *HO5* from southern Japan, and *Kaga* and *HNI* from northern Japan); and b) whether there were consistent differences in bold-shy behaviours exhibited by a given strain (*iCab*) dependent on the strain that it was partnered with. The former was intended to measure the effect of an individual's own genes on its behaviour (a direct genetic effect), and the latter to measure the effect of the genes of the focal fish's tank partner on the behaviour of the focal fish (social genetic effect). Our experimental design allowed us to assess both direct and indirect effects on behaviour simultaneously, and to infer the degree to which variation in bold-shy behaviours is attributable to the differences in an individual's own genetics, the differences in the genetics of their social companions, and stochastic variation. A schema for the experimental plan is shown in **Figure 3.1**.

[Wrap up the findings in one or two sentences: We find inter-strain differences that are statistically significant Social genetic effects that influence behaviour of a strain depending on the partner (or genetic configuration of the test pair, not sure whether this sounds ok)]

To detect

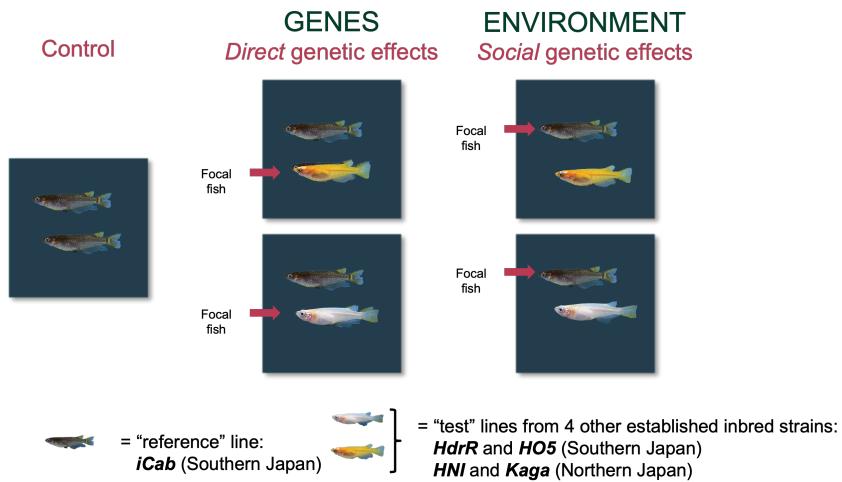


Figure 3.1: Schema for experimental plan. *iCab-iCab* pairings are the control condition. To explore direct genetic effects on behaviour, we compare the behaviours of test fishes from different lines, and infer that the differences between lines are caused by the differences in their genetics (direct genetic effects). To explore social genetic effects, we use the same data but turn our focus to the reference fish, and infer that the differences we observe between their behaviours are caused by the differences in their social environments, which are in turn driven by the different genetics in the test fish lines (social genetic effects).

3.4 Results

3.4.1 Data collection

Our behavioural assay is 20 minutes long, comprising two consecutively-run 10-minute components: a) an ‘open field’ component, where the fishes are introduced to the test tank and left to swim around freely; and b) a ‘novel object’ component, where a small black plastic cylinder is added to the tank at the beginning of the second 10-minute period, after which the fishes are again left to swim around freely. The assay is run on pairs of fish. Medaka is a seasonal breeder in which photoperiod has a strong effect on physiology and behaviour (L’opez-Olmeda et al. 2021). In this study we tested fish that were acclimated to summer conditions. To avoid confounding mating behaviours between males and females and associated aggressive interactions between males we used only female fish in all experiments. To increase the throughput of the assay, the test tank was divided into four quadrants with barriers, allowing us to run the assay on four pairs of fish simultaneously. Two test tanks situated side-by-side were used, allowing to run 8 concurrent assays. The experimental setup used is shown in Figure 3.2.

Between 11 and 16 June 2019, I assayed a total of 307 pairs of fish, comprising the following counts for each strain pairing: 68 *iCab/iCab*, 60 *iCab/HdrR*, 76 *iCab/HNI*, 47 *iCab/Kaga*, and 56 *iCab/HO5*. The locations of the lines’ originating populations are shown in Figure 3.3. The fish from the *iCab* strain was denoted as the “reference fish”, and was introduced to the test tank first. The “test fish” which was either another *iCab* fish (for the control condition), or a fish from one of the other four strains that were assayed in this experiment (*HdrR*, *HNI*, *Kaga*, *HO5*). The order in which the strains were assayed across the six days was randomly determined prior to the collection of the data. The test tanks were also rinsed between runs to remove any substances released by subjects during previous runs that could influence the behaviour of the subjects that followed.

3.4.2 Tracking

We split the videos by quadrant and assay component, and tracked the movement of the fishes with the open-access software package *idtrackerai* (Romero-Ferrero et al. 2019). Each individual fish was tracked across at least 85% of frames in each video, with 78% of videos tracked for over 99% of frames. The failure to track both fishes across all frames was usually caused by instances where a fish was situated behind the novel object or quadrant divider, rendering it invisible to the camera. A random selection of 20 videos was reviewed to search for instances of mislabeled fishes due to software errors. We found none, which is consistent with the reliability of the software as reported by its

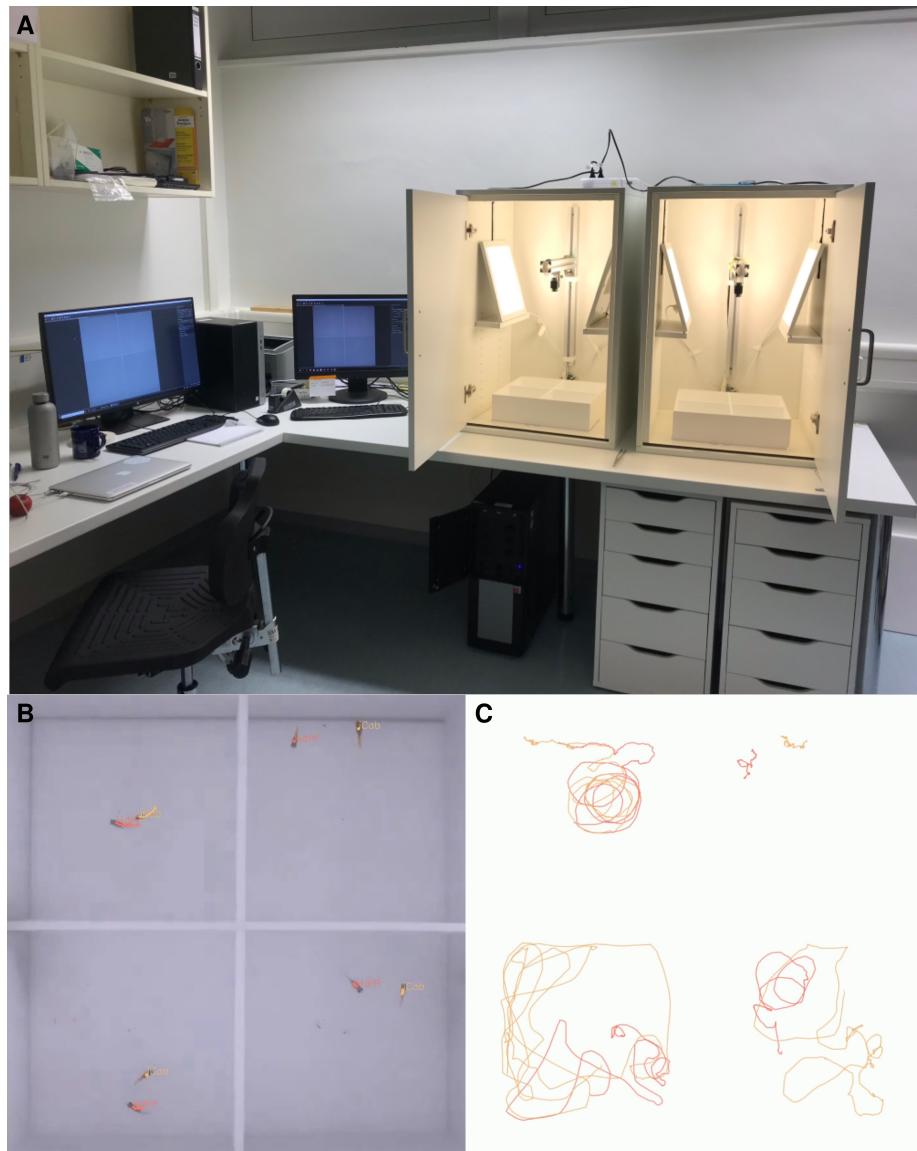


Figure 3.2: **A:** Experimental setup, with two test boxes side-by-side (denoted as “L” for left and “R” for right). Each test box contains one test tank, separated by removable barriers into quadrants, allowing for the simultaneous assay of four pairs of fish per test tank. The interior of the box is ambiently illuminated by LED lights, and a camera is suspended over the centre of each test tank to record the videos. **B:** Four pairs of fishes in a test tank with labelled quadrants (I, II, III, IV) and strains (*iCab* or *HdrR*). **C:** Paths of *iCab* reference fish and *HdrR* test fish from the video at panel (B) at 110 seconds.

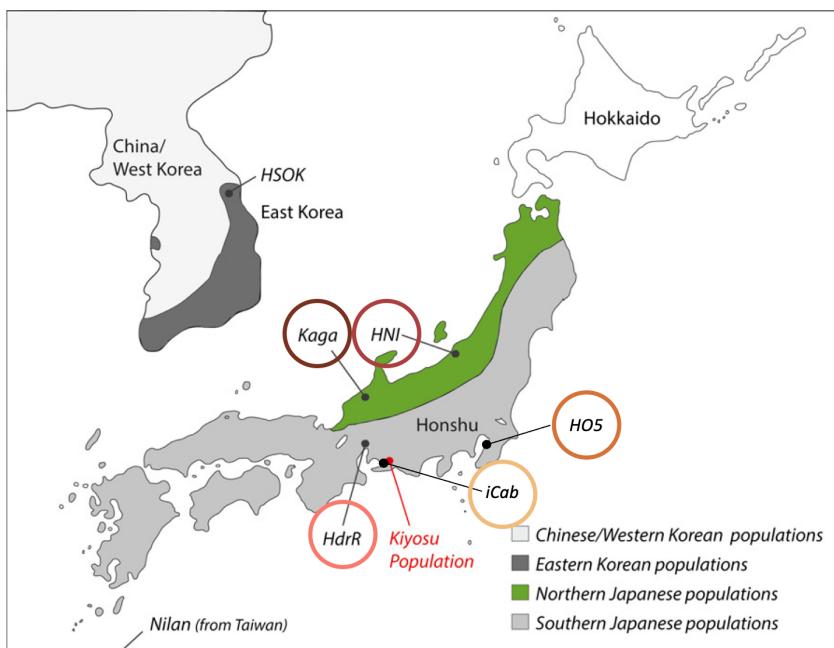


Figure 3.3: Image adapted from (Spivakov et al. 2014), showing the locations of the originating populations of the 5 inbred medaka lines used in this study.

authors. We therefore concluded that such instances would be absent or very rare and thus negligible.

To identify which fish was the reference or test fish, we could generally distinguish between the strains based on their colour, as *iCab* pigmentation is light-brown, *HO5* are light-brown with an orange hue, *HdrR* females are white, and *HNI* and *Kaga* are grey. Where the reference fish was indistinguishable in colour from the test fish, we identified the fish that was introduced to the test tank first, and followed it by eye through to the first frame of the assay. In cases of *iCab-iCab* pairings, we randomly assigned the individuals to either the “reference” or “test” fish.

We then used the coordinates of the fishes in each frame to calculate the distance and angle travelled by each fish between a fixed time interval, for example every 0.05 seconds. Distance was calculated between points B → C, and angle was calculated between points A → B → C. We used these distance and angle variables to train a HMM with the *hmmlearn* Python package (*Hmmlearn/Hmmlearn* [2014] 2022) in order to classify the movements as discrete behaviours or “modes of movement”.

3.4.3 Effect of covariates

We examined the effects of several covariates, including date of assay, time of assay, tank quadrant, and tank side. To achieve this, we calculated the mean speed of individuals in *iCab-iCab* pairings ($N = 136$) over the course of the entire 20-minute video (including both open field and novel object assays), and ran a multi-way ANOVA with all covariates (Figure 3.4). We found significant differences for date of assay and tank quadrant ($p = 0.0139$ and 0.0108), but not for time of assay or tank side. This may have been driven by a difference in the way the assay was performed on the first day of the experiment (11 June 2019), where we used a thick fabric sheet to cover the front of the box rather than the wooden doors shown in Figure 3.2, as they were only installed the following day. The greater level of external light and sound permeating through the fabric may have caused the fishes to exhibit slower movement on that first day, and when the data from that day is excluded, the p-values for date of assay and tank quadrant increase to 0.0477 and 0.0469 respectively.

3.4.4 Choice of time interval and number of HMM states

HMMs are well-suited for classifying the hidden states that generate stochastic, sequential observations. To determine the optimal parameters for the HMM’s classification of behaviours, we sought to reduce overfitting (which tends to favour using a lower number of HMM states) while maximising the ability to distinguish between strains based on the relative time they spent in each HMM state (which tends to favour a higher number of HMM states). We additionally

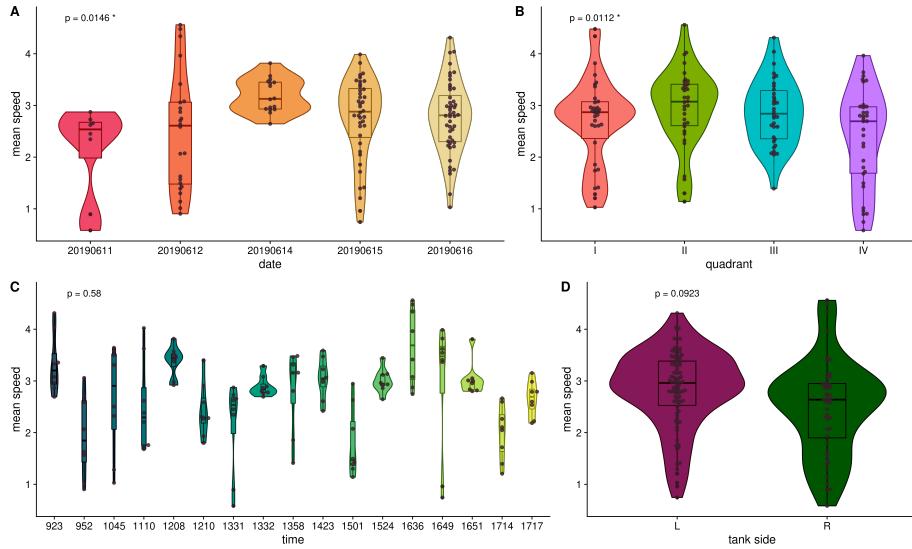


Figure 3.4: Effect of covariates on mean speed of iCab individuals when paired with another iCab over the course of the full video (including both open field and novel object assays). P -values were calculated from a multi-way ANOVA with all four covariates included as terms, and adjusted for false discovery rate.

considered the time interval between which the distance and angle of travel was measured.

Figure 3.5 sets out the comparison of HMM parameters on two measures designed to quantify, respectively, the level of overfitting ('mean concordance between cross-validated HMM states'), and the quantification of differences between strains ('summed Kruskal-Wallis statistic comparing frequency of time spent in each HMM state across medaka strains) (Methods).

Based on these results and a visualisation of the polar plots for each combination of state number and time interval, we excluded combinations with 15 or more states due to an asymmetry across states that would create difficulties for interpreting their biological meaning (Supplementary material). For the downstream analysis we selected the combination of 14 states with a 0.08-second interval between time points, because out of the remaining combinations it appeared to optimally balance the level of overfitting and detection of differences between strains.

The distances and angles of travel for the 14 states are shown in Figure 4, generated from 10,000 randomly-selected data points (i.e. movements). Each point represents the radial distance in $\log_{10}(\text{pixels})$ that a fish travelled from its previous location ($B \rightarrow C$), and the polar angle travelled from $A \rightarrow B \rightarrow C$, where $A \rightarrow B$ is always aligned vertically along the $0-180^\circ$ axis. For example, a

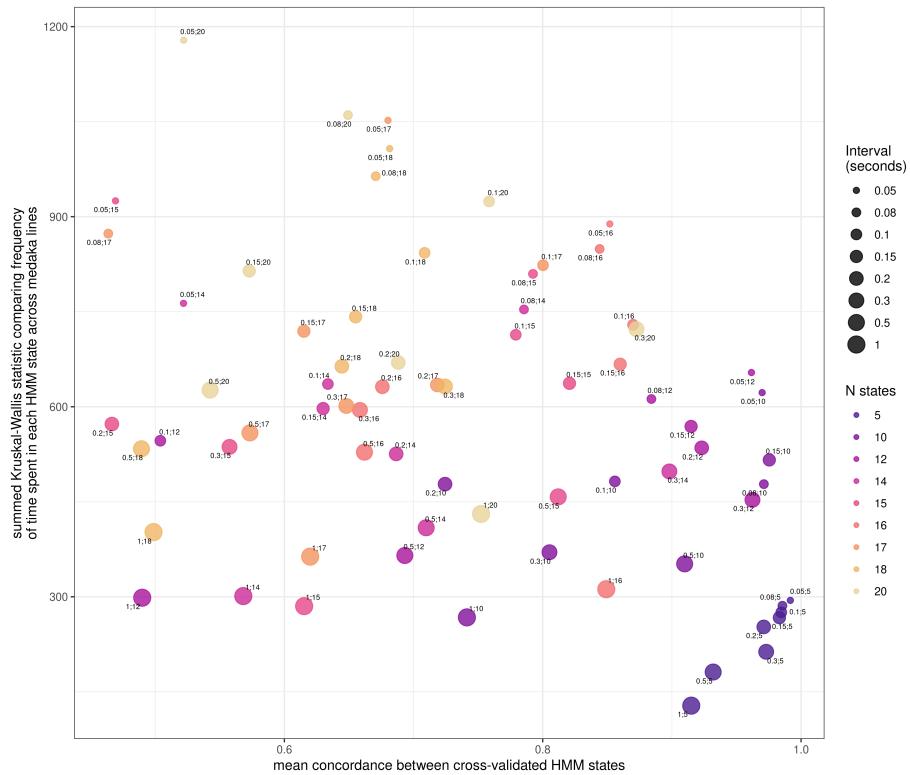


Figure 3.5: Comparison between HMM parameters. Horizontal axis: Mean concordance between states assigned by HMMs through a 2-fold cross-validation process. Vertical axis: Kruskal-Wallis statistic comparing strains based on the proportion of time spent in each HMM state, summed across all states. Size of points correspond to the interval, in seconds, between which the distance and angle of travel was calculated (Methods).

point at 45° far from the pole represents a fast, forward movement to the right, and a point at 260° close to the pole represents a slow, backward movement to the left.

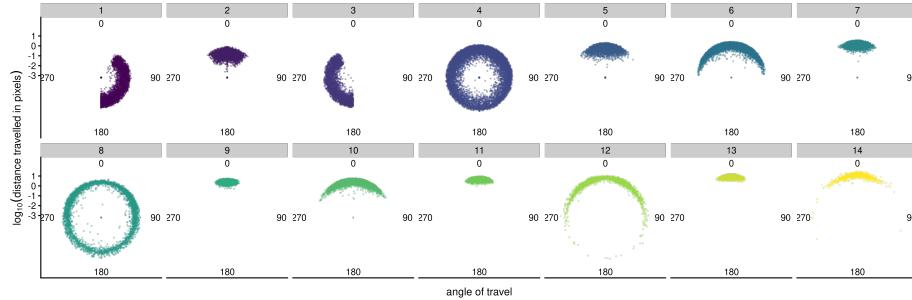


Figure 3.6: Classification of movements by the 14-state HMM, based on distance (in $\log_{10}(\text{pixels})$) and angle of travel between a time interval of 0.08 seconds from points $B \rightarrow C$ for distance, and points $A \rightarrow B \rightarrow C$ for angle. Each point represents the distance and angle at point C, and $A \rightarrow B$ is aligned vertically along the $0-180^\circ$ radial axis. The figure shows an illustrative 10,000 data points (movements), randomly selected from the full dataset. States are sorted in ascending order by mean distance.

We next sought to determine whether there was a difference in the proportion of time spent in each state between the 5 inbred strains (implying the presence of direct genetic effects), and between the *iCab* reference fishes depending on the inbred strains of their tank partner (implying the presence of social genetic effects).

3.4.5 Direct and social genetic effects on bold/shy behaviour

3.4.5.1 Direct genetic effects

To determine whether the test fish strains differed in the proportions of time they spent in each state, we ran separate multi-way ANOVAs for each combination of assay component (open field or novel object) and state (states 1 to 14):

Table 3.1: Significant differences in the proportion of time spent in each HMM state across test fish strains for the open field and novel object assay components.

Assay	State	Variance explained (%)	p-value (FDR-adjusted)
open field	1	26.62	3.60e-22
open field	2	21.94	6.18e-18
open field	3	28.21	4.45e-24
open field	4	17.73	2.12e-15
open field	5	7.48	2.78e-05
open field	6	5.60	2.48e-04
open field	7	5.46	3.11e-04
open field	8	5.79	1.08e-04
open field	9	7.36	8.96e-06
open field	10	3.78	1.06e-02
open field	13	4.66	3.42e-03
novel object	1	17.19	7.28e-14
novel object	2	14.28	2.92e-11
novel object	3	19.30	5.53e-16
novel object	4	13.12	1.26e-10
novel object	6	4.12	4.20e-03
novel object	7	8.93	1.84e-06
novel object	9	10.68	9.87e-08

$$frequency_{assaycomponent,state} = \beta_1(testfishstrain) + \beta_2(date) + \beta_3(time) + \beta_4(quadrant) + \beta_5(tankside)$$

The proportion of time each individual spent within a state was first inverse-normalised within each combination of assay and state, and the date of assay, time of assay, tank quadrant, and tank side were included as covariates. P-values were then adjusted for the False Discovery Rate (**FDR**).

The states that showed a significant difference across any of the variables included in the model are set out in **Table 3.1**. The test fish strains differed significantly in the proportion of time spent in a given state ($p < 0.05$, FDR-adjusted) for 11 out of 14 states in the open field assay ($4.45 \times 10^{-24} < p < 1.06 \times 10^{-2}$), and 7 out of 14 states for the novel object assay ($5.53 \times 10^{-16} < p < 4.2 \times 10^{-3}$), with the strain of the test fish explaining up to ~28% of the variance in the proportion of time spent in a given state. For some states, there was also a significant difference between quadrants, date of assay, and tank side (open field: $1.03 \times 10^{-9} < p < 1.18 \times 10^{-2}$; novel object: $1.75 \times 10^{-8} < p < 4.9 \times 10^{-2}$). Full tables for all states and variables are provided in the Supplementary Material.

Figure 3.7 depicts the time dependence of HMM states over the course of the video, and the regions of the test tank that were most frequently occupied by the

different strains. Figures A and H show the HMM states with panels coloured red to indicate the states that were found to significantly differ between test fish strains. **Figures 3.7B and E** show how each individual test fish, grouped by inbred strain, moved through HMM states throughout the course of the video, with each tile coloured by the state most frequently-occupied by the individual within 2-second intervals. Figures **3.7C and F** show the same data, recalculated as densities within each strain, with only the states that showed significant differences between strains in colour, and the remaining states consolidated and coloured grey. There is an especially clear difference between strains in the proportions of time spent in the slowest-moving states (i.e. states 1 to 3) at the beginning of each assay component, with an increase across all strains in the novel object assay, likely as a consequence of having less room to move, as well as the fear response that the novel object was designed to elicit. The differences are clearest when comparing the southern Japanese medaka strains (*iCab*, *HdrR*, and *HO5*) against the northern Japanese strains (*Kaga* and *HNI*). In addition, we note that *Kaga* tends to spend more time in the fast- and forward-moving state 13 at the beginning of the assay than at other times, which suggests that for that strain, such movements may be the manifestation of a stress response. **Figures 3.7D and G** show, as densities, the regions of the tank that were most frequently occupied by each strain. Although the northern Japanese strains *Kaga* and *HNI* were similarly fast-moving relative to the southern Japanese strains, in the open field assay component they appear to favour different regions of the tank – where *HNI* occupied the central regions of the tank with more frequency, *Kaga* tended to prefer swimming along the boundaries of the tank.

3.4.5.2 Social genetic effects

To determine whether the *iCab* reference fishes altered their behaviour depending on the inbred strain of their tank partner, we carried out the same analysis and model as above using only data from the *iCab* reference fishes. The states that showed a significant difference across any of the variables included in the model are set out in **Table 3.2**. The *iCab* reference fishes differed significantly in the proportion of time they spent in a given state depending on the strain of their tank partner ($p < 0.05$, FDR-adjusted) for 5 out of 14 states in the open field assay ($2.04 \times 10^{-6} < p < 2.11 \times 10^{-2}$), and 7 out of 14 states for the novel object assay ($4.76 \times 10^{-7} < p < 4.06 \times 10^{-2}$). The strain of the tank partner explained up to ~9% of the variance in the proportion of time the *iCab* reference spent in a given state. Full tables for all states and variables are provided in the Supplementary Material.

We observe that the proportions of time the *iCab* reference fishes spent in different states do differ based on the strains of their tank partner, and that their behavioural patterns tend to reflect those of the test fish strains they are paired with (**Figure 3.8**). Thus, the *iCab* reference fishes spend less time in the slower-moving states when in the presence of the faster-moving northern Japanese strains *Kaga* and *HNI*, which in turn shows that the test fishes are transmitting

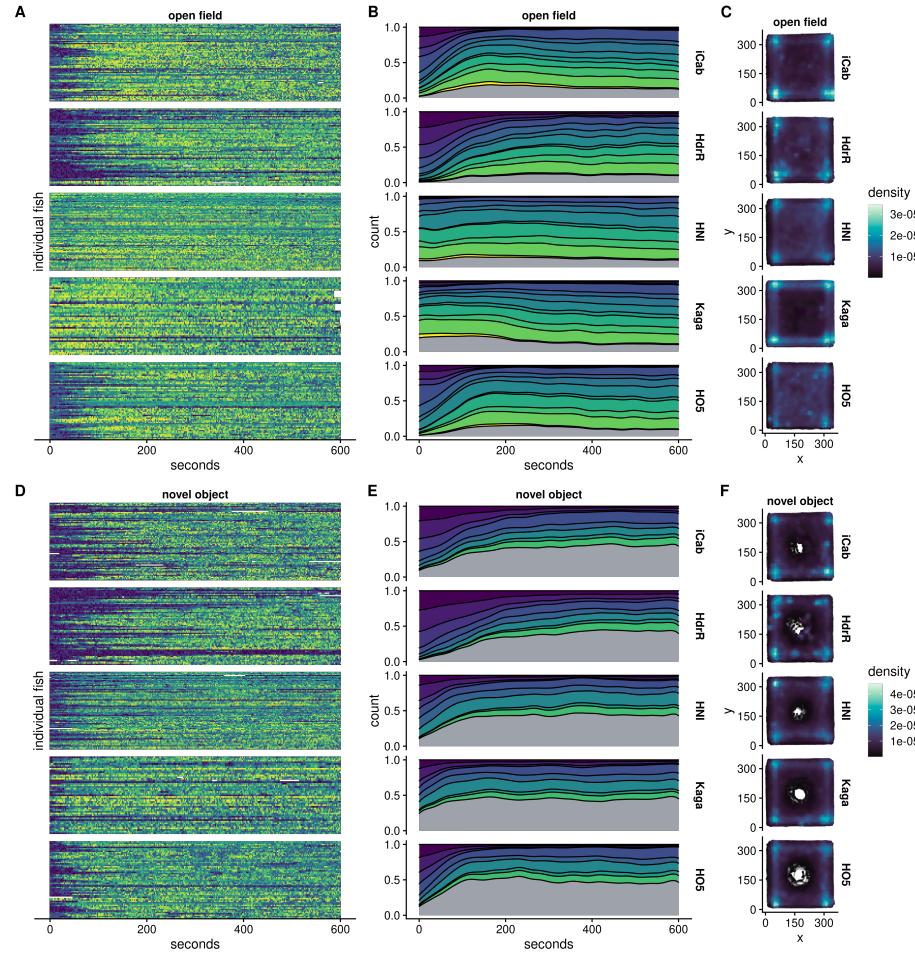


Figure 3.7: Differences between test fish strains in the HMM states they occupied during the open field (top) and novel object (bottom) assay components. **A and H:** 14 HMM states with panels coloured red to indicate significant differences between test fish strains in the proportion of time spent in those states during the separate assay components. **B and E:** Transitions between HMM states across time for each individual test fish, grouped by strain. Tiles are coloured by the state most frequently occupied by each fish within 2-second intervals. **C and F:** Densities within each strain for the occupation of states that significantly differed between strains (colour), with other states consolidated (grey). **D and G:** Densities of the test tank locations occupied by each strain, calculated within 900 grid points (30x30).

Table 3.2: Significant differences in the proportion of time spent in each HMM state by *iCab* reference fishes depending on the strain of their tank partner during the open field and novel object assay components.

Assay	State	Variance explained (%)	p-value (FDR-adjusted)
open field	1	8.52	5.88e-06
open field	2	9.09	2.04e-06
open field	3	7.97	1.77e-05
open field	5	3.92	4.29e-03
open field	12	2.97	2.11e-02
novel object	1	7.94	8.73e-06
novel object	2	9.38	4.76e-07
novel object	3	8.73	1.58e-06
novel object	6	4.76	1.23e-03
novel object	8	2.80	4.06e-02
novel object	10	3.81	8.43e-03

their behaviours to some degree to their *iCab* tank partners. The differences in the behaviours of *iCab* reference fishes based on the strain of their tank partners are not as large as those between the test fish strains. However, unlike what was observed with the test fishes, here there is a greater number of states that show significant differences during the novel object component of the assay compared to the open field component. This suggests that when movement is restricted, or when in the presence of a potential threat, the behaviour of the test fish tank partner has more of an influence on the *iCab* reference fish's behaviour than otherwise.

Finally, to develop a metric to quantify the degree to which the *iCab* reference fishes' behaviour is influenced by the strain of its tank partner, we calculated the proportions of time that the pairs of fish spent simultaneously occupying the same HMM state. **Figure 3.9** shows that when paired with the slowest-moving *HdrR* strain, the *iCab* reference fishes spent more time co-occupying the slow- and forward-moving state 2, whereas they tended to co-occupy the fast- and forward-moving state 11 when paired with the faster-moving northern *Kaga* and *HNI* strains. When paired with another *iCab*, they preferred to co-occupy the slow-moving and pan-directional state 4. For each combination of assay component and state, we then ran a Kruskal-Wallis test to determine whether there were differences in the frequencies of state co-occupancy under different strain pairings ($p < 0.05$, FDR-adjusted), and found significant differences for states 1 to 6 for the open field component ($1.1 \times 10^{-8} < p < 4.1 \times 10^{-2}$), and states 1 to 4 and 7 for the novel object component ($1.6 \times 10^{-6} < p < 2.5 \times 10^{-2}$). The heatmaps show that *iCab* tends to co-occupy state 4 at the highest frequency when paired with another *iCab*, which suggests that this pan-directional, slow-moving state is a more comfortable or natural state for *iCab* to occupy, particularly when under stress.

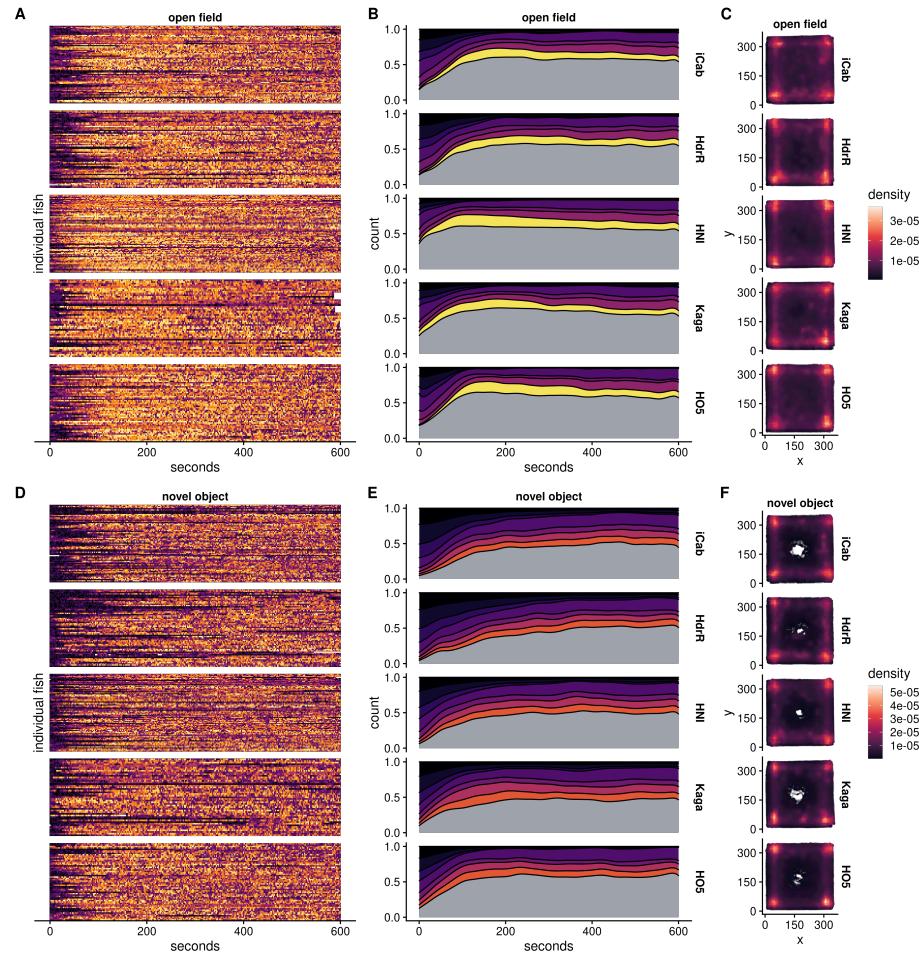


Figure 3.8: Differences between HMM states occupied by the reference fish when paired with different test fish strains during the open field (top) and novel object (bottom) assay components. **A and H:** 14 HMM states with panels coloured red to indicate significant differences between the reference fishes under different strain-pairings in the proportion of time spent in those states during the separate assay components. The HMM states are the same as those in **Figure 3.7**, but coloured with a different palette. **B and E:** Transitions between HMM states across time for each individual iCab reference fish, grouped by the strain of its tank partner. Tiles are coloured by the state most frequently occupied by each fish within 2-second intervals. **C and F:** Densities within each strain-pairing for the occupation of states that significantly differed between strain-pairings (colour), with other states consolidated (grey). **D and G:** Densities of the test tank locations occupied by the iCab reference fishes when paired with different strain, calculated within 900 grid points (30x30).

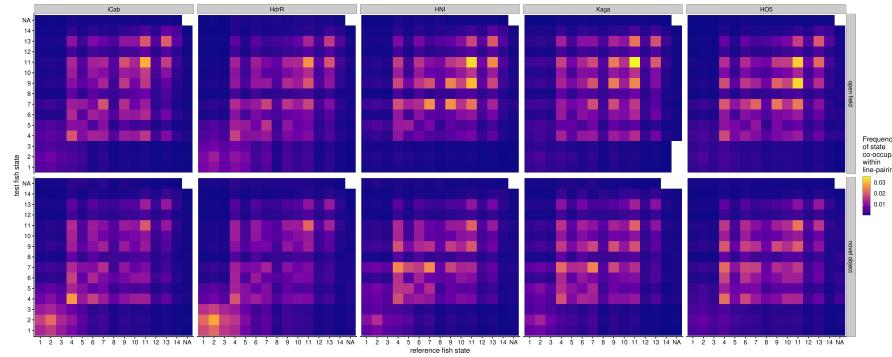


Figure 3.9: Frequency of HMM state co-occupancy between pairs of fish, calculated across all all videos per strain-pairing.

3.5 Discussion

In this chapter have described an assay for measuring bold-shy behaviours in medaka fish that can reliably detect differences: (a) between individuals from different inbred strains – allowing for the quantification of direct genetic effects on behaviour; and (b) between the behaviour of individuals when paired with tank partners from a different strain – allowing for the quantification of social genetic effects on behaviour.

I found that behaviours exhibited during the assay show minimal variance across the covariates of date of assay, time of assay, tank quadrant, and tank side. This creates confidence that the genetic effects that we observed – both direct and indirect – are not unduly affected by these variables.

I have shown that a Hidden Markov Model (HMM) allows an adequate classification of movements based on the direction and angle of travel within set time intervals. The HMM method has previously been used to classify maternal behaviour patterns in mice (Carola, Mirabeau, and Gross 2011), and I have extended the application here to bold-shy behaviours in medaka fish. In principle, this method can be expanded to include additional behavioural features such as proximity to the wall or other objects, inwards/outwards orientation, proximity to the tank partner, and other metrics related to leader-follower dynamics, a possibility that will be tested in future studies.

The HMM classification of behaviours also facilitated the ranking of behaviours by speed and angle of movement, which may be further interpreted in terms of biology and adaptation styles. However, even though the HMM classifies the slowest-moving states as separate modes of movement, one should be cautious when attributing biological meaning to their differences, because even when a fish is almost completely still, the fish object’s centroid (upon which the variables of distance and angle of travel are calculated) will tend to move by one or several

pixels through minor changes in the segmentation of the object, and are thus subject to greater noise than the faster-moving states.

I have found that inbred strains of medaka fish can be distinguished by the proportion of time they spend in certain states. The slowest states, capturing no or minimal movement, were the states that most clearly separated the strains, and these differences appeared most clearly at the beginning of the open field and novel object assays. This suggests that for southern Japanese strains such as *iCab*, *HdrR*, and *HO5*, the “freeze” reflex is caused by anxiety, which eventually dissipates over time indicating habituation. Similar observations showing initial anxiety as shown by freezing behaviour and subsequent habituation have been made in other studies using open field assays with *iCab* fish (Lucon-Xiccato et al. 2022).

On the other hand, the northern Japanese strains *Kaga* and *HNI* spent little time in the slow-moving states at the beginning of the video, which indicates either that their habituation sets in earlier, or that their stress and anxiety is expressed to a lesser degree as freezing behaviour. The former appears to be more likely for *Kaga*, as in the open field assay, it spends more time in the faster-moving states at the beginning of the video and then slows down thereafter, which suggests that its higher level of movement may be induced by stress. It is interesting then that once the novel object is introduced, *Kaga* tends to move slowly like the other strains. Obviously introduction to a novel environment and exposure to a potentially dangerous object elicits different behavioural patterns in this strain. Taken together with the overt thigmotaxis behaviour (i.e. moving along the sides of the tank during the open field assay component) relative to other strains, its behaviour may suggest an “escape-seeking” response. It will be interesting to carry out further experiments to determine under which fear-inducing conditions *Kaga* reacts with this more frantic style of movement rather than the freeze response that it displays in the novel object component in common with the other strains, and to explore its physiological basis.

With respect to social genetic effects, we have found that a fish’s behaviour is affected by the differential behaviour of its tank partner, although the effect is less powerful than the direct genetic effect on a fish’s own biology. These social genetic effects are detectable when observing the proportions of time the reference fishes spend in certain states over the course of the video, and can be quantified by measuring the frequency of state co-occupancy with their tank partners.

It is also interesting to find that *iCab* prefers to co-occupy the slow, pan-directional state 4 when paired with another individual from the same strain. As the strains are raised exclusively in the company of individuals from the same strain, that type of behaviour may represent a more comfortable – yet still cautious – mode of movement, or a type of mimicry that tends to occur when in the company of individuals that are more genetically or socially familiar.

In this study we only used one strain as the reference fish, but future experiments

can expand on this analysis by using different strains as the reference, thereby exploring how a strain's genetics influence the degree of their behavioural plasticity, and how the distinct behaviours of strains may interact in intriguing ways.

In summary we show that the OFT experimental setup in combination with the HMM analysis can reliably detect both direct and social genetic effects. This creates the opportunity to carry out a similar study on a larger panel of inbred strains, such as the MIKK panel (Fitzgerald et al. 2022), with a view to identifying the genetic variants associated with not only these differences in behaviour, but also the differences in the degree to which an individual transmits their behaviour onto their social companions. This in turn will shed light on longstanding biological questions concerning the direct and indirect influences on behaviour, their physiological bases, and their adaptive purposes. This is the subject of the following chapter.

Chapter 4

Genetic linkage study of bold/shy behaviours in the MIKK panel

The purpose of the study described in this chapter was to run the behavioural analysis described in Chapter 3 over the MIKK panel described in Chapter 2, identify the lines that diverged in both their behaviour, and the level of transmission of their behaviour onto their *iCab* reference tank partner, and then use them as the parental strains in an F2 cross to attempt to identify the genetic variants associated with those differences.

4.1 F2 cross

The F2 cross is a traditional method for mapping genetic variants associated with traits of interest. A schema for the method is presented in **Figure 4.1**. In essence, it involves starting with two inbred strains that diverge for the trait of interest (the ‘parental strains’, or F0 generation F0). One then crosses the parental strains to create a generation of F1 hybrid individuals who each possess, for every pair of their chromosomes, one chromosome from each of their parents. The individuals in this F1 generation are genetically identical to their parents with respect to their germline. Finally, one inter-crosses the F1 generation to create a set of F2 individuals that share unique combinations of the original F0 strains’ genotypes, and tend to display values for the trait of interest that span across the spectrum between the extreme values of their parents.

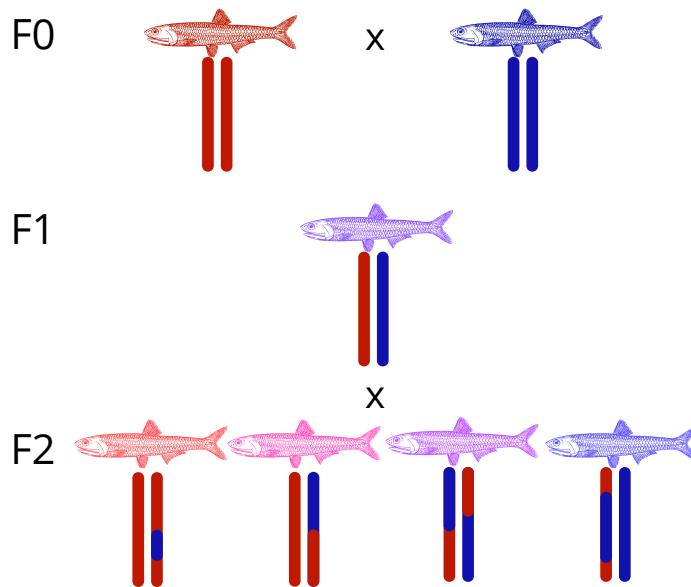


Figure 4.1: Schema of the F2-cross experimental setup. The F0 generation comprises two medaka strains that have extreme, opposing values for a trait of interest, represented by the colours red and blue. Below them is an illustrative single pair of chromosomes. The chromosomes within each pair are depicted as the same colour, as the strains are homozygous through successive generations of inbreeding. Their F1 offspring is heterozygous for each pair of their 24 chromosomes, and all F1 individuals are therefore almost genetically identical to one another (with the exception of somatic mutations and the regions of the genome that were not homozygous in the parental generations). The F1 individuals are then inter-crossed with one another to produce the F2 generation, which, due to recombination events during gamete formation, have unique combinations of the parental strains' genotypes, and tend to span the phenotypic spectrum between the extremes of their F0 parental strains, represented by their colours.

4.2 Data collection - F0 generation

In November 2019 I traveled to the fish facility managed by our collaborator, Felix Loosli at KIT in Karlsruhe, and over the course of 11 days from 11 to 21 November 2019, I ran the behavioural assay described in Chapter 3.4.1 another 206 times. I again used the *iCab* strain as the reference fish, and for the test fish I used either an individual from one of the MIKK panel lines, individuals captured from the same Kiyosu population as the MIKK panel but permitted to breed freely within a separate tank in the facility ('Kiyosu closed-capture', or 'Kiyosu CC'), or individuals from a related but different species of medaka from the Philippines, *Oryzias luzonensis*. I ensured that I performed at least 2 assay runs for each MIKK panel line that was available, generating a minimum of 8 test fish replicates per line. As there were four pairs of fish in the test tank during each run, the complete dataset comprises 824 videos of pairs of fish, which I further divided by assay component (open field and novel object) to create 1648 videos.

I again used the software *idtrackerai* (Romero-Ferrero et al. 2019) to track the movement of the fishes across frames of each video. After adjusting the software parameters for each video to maximise the number of frames that were successfully tracked, I was left with 1610 out of the 1648 videos (~97.7%) where both fishes were tracked over at least 85% of frames. Only these 1610 videos were used in the downstream analysis. The first question to address was whether the MIKK panel lines differed in their behaviours. I therefore computed each individual fish's mean speed (measured as the distance traveled in pixels per 0.05 seconds) over the course of the full 20-minute video, grouped them by line, and plotted the results presented in **Figure 4.2**.

4.3 Mean speed for all MIKK lines

This figure shows that there are clear differences between some MIKK panel lines at the extremes, and that the lines differ in the amount of within-line variance observed. This figure acted as a guide to determine which lines to select as the parental strains in the F2 cross. To identify genetic variants directly associated with bold-shy behaviours, I sought to select lines that showed either high or low levels of movement, and preferably low within-line variance.

4.4 HMM states

To examine these behaviours at a finer resolution, as for the pilot study described in 3, I again applied a hidden markov model (**HMM**) to classify the fishes' movements based on their distance and angle of travel between time intervals. I used the same method to select the best choice of time interval and

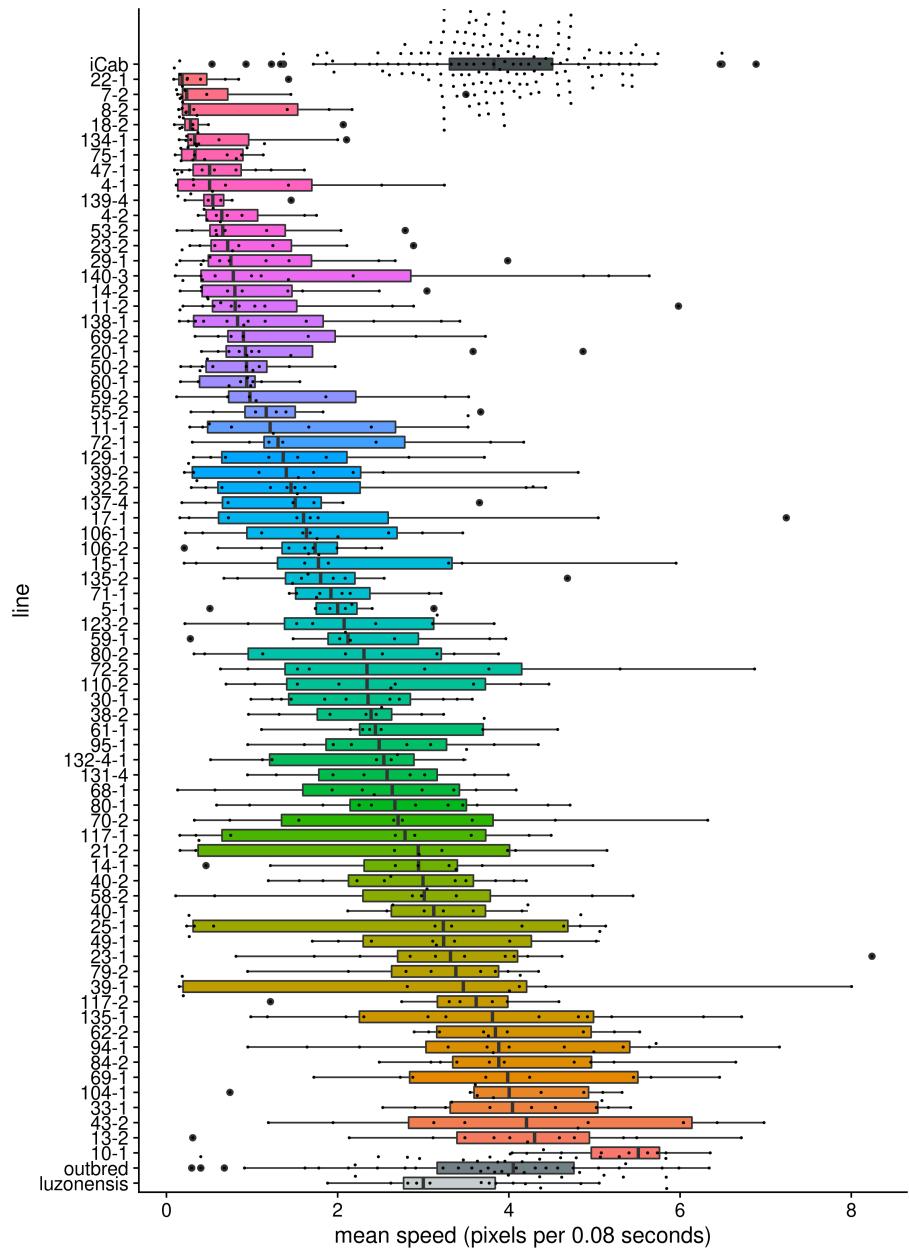


Figure 4.2: Mean speed of the MIKK panel and other strains over the course of the entire 20-minute video (measured as the distance traveled in pixels per 0.05 seconds). *iCab* fishes in the *iCab-iCab* control condition are at the top, the MIKK panel lines are sorted by their group median, and the Kiyosu closed capture and *O. luzonensis* fishes are at the bottom.

number of states (**Figure ??**). Here we observed the same phenomenon where the parameter combinations that performed the best showed an asymmetry between some states that would make interpretation difficult. For example, a time interval of 0.08 seconds combined with a state space of 17 caused state 4 to appear to get carved out of state 3 (**Figure 4.4**).

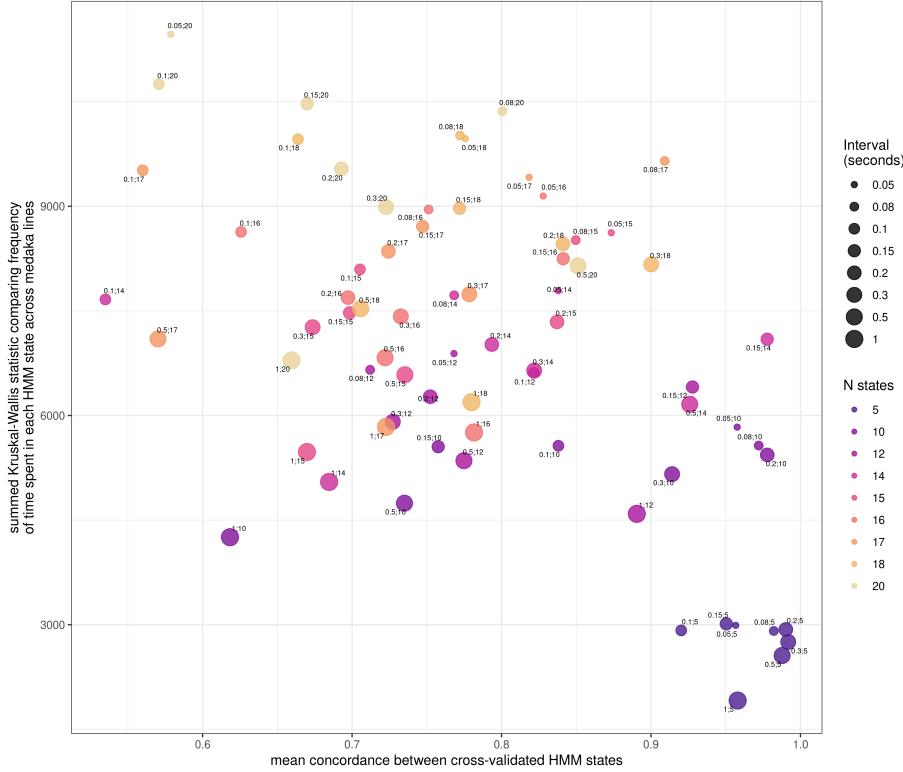


Figure 4.3: (ref:mikk-param-comp)

I therefore selected the best combination of parameters without this asymmetry, which in this case was a time interval of 0.05 seconds with a state space of 15 (**Figure 4.5**), and used these states for all downstream analysis.

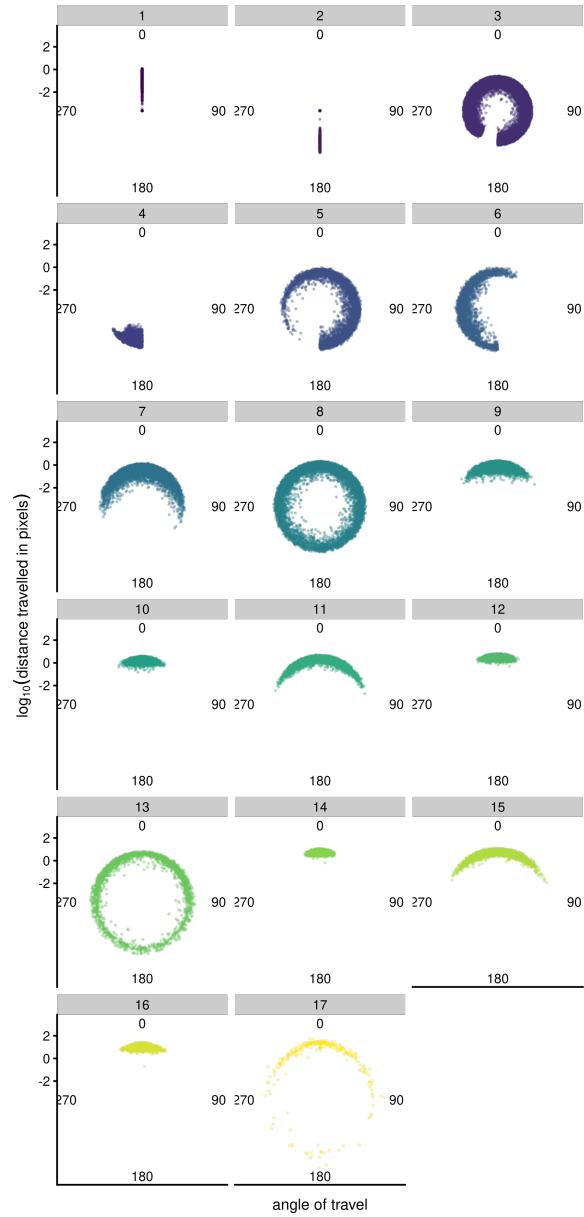


Figure 4.4: The best apparent combination of parameters (0.08 time interval with a 17-state space) created an asymmetry between states 3 and 4, which would cause difficulties in interpreting their biological relevance.

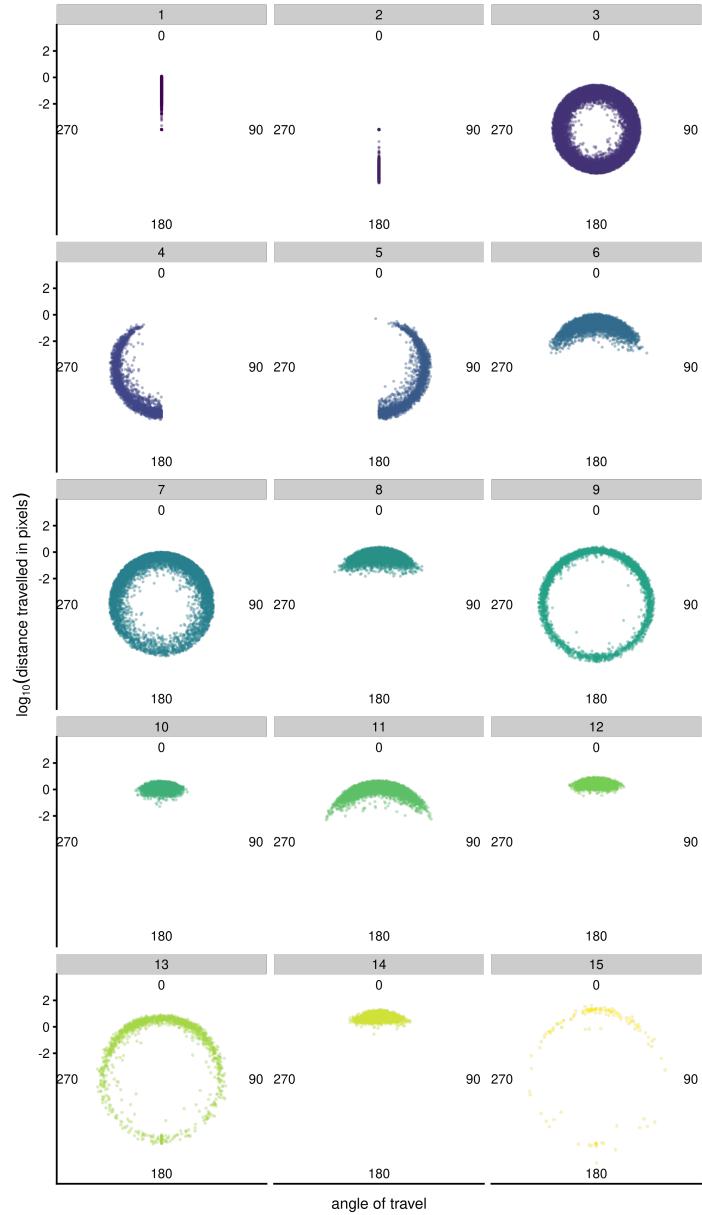


Figure 4.5: The HMM states used for the downstream analysis, with the model classified based on the distance of travel (\log_{10} pixels, radial axis) and angle of travel (angle). A straight forward movement would sit around 0° , a left movement around 270° , and a right movement around 90° .

Chapter 5

Genetic loci associated with somite development periodicity

5.1 Background

“The distinction between Mendelian loci and QTLs is artificial, as the same mapping techniques can be applied to both. In fact, the classification of genetic (and allelic) effects should be considered as a continuum. At one end of the spectrum is the dichotomous Mendelian trait with only two detectable and distinct phenotypes, which are governed by a single gene. At the other end are traits, such as growth, which are likely to be affected by many genes that each contribute a small portion to the overall phenotype.” (Members of the Complex Trait Consortium 2003)

Since it became possible to sequence the genotypes of individuals at scale, it has been an ongoing point of debate as to how best to model the effects that genetic variants have on a trait of interest.

Population structure and unequal relatedness among individuals in a given cohort can lead to false discoveries (Ewens and Spielman 1995; Members of the Complex Trait Consortium 2003). This is because individuals who share common ancestries will share both variants that do affect the trait of interest, and variants that do not, and these variants will be correlated with one other due to that shared ancestry. Therefore, if an association is found between the causal variants and a trait of interest, the non-causal variants that are correlated with the causal variants will also be found to be statistically associated with the trait.

How then does one control for population structure?

Three methods were formerly used (Zhang et al. 2010):

1. Structured association (Jonathan K. Pritchard, Stephens, and Donnelly 2000)
2. Genomic control (Devlin and Roeder 1999)
3. Family-based tests of association (Abecasis, Cardon, and Cookson 2000)

“Ronald fished introduced random effects models to study the correlations of trait values between relatives” (Fisher 1919).

5.2 Somite development

During the development of an embryo, somites are the earliest primitive segmental structures that form from the presomatic mesoderm (**PSM**) (Kim et al. 2011). They later differentiate into vertebrae, ribs, and skeletal muscles, thereby establishing the body’s anterior-posterior axis. Vertebral number is precisely defined for a given species (Gomez et al. 2008), but is the most variable physical trait across species (Kimura, Shinya, and Naruse 2012). For example, frogs have 6-10, humans have 33, and snakes can have more than 300 (Gomez et al. 2008; Kimura, Shinya, and Naruse 2012). **Figure 5.1** depicts a number of formed somites in a 9.5-day-old mouse embryo.

The number of vertebrae is determined by the periodicity of somite formation, which occurs rhythmically and sequentially. This periodic somite formation is controlled by a molecular oscillator, known as the ‘segmentation clock’, which drives periodic waves of gene expression in the NOTCH, FGF, and WNT pathways, forming a signalling gradient that regresses towards the tail in concert with axis elongation (Gomez et al. 2008). Over the course of elongation, the wave period increases (i.e. each somite takes longer to form), and the PSM progressively shrinks until it is exhausted, eventually terminating somite formation (Gomez et al. 2008).

It is not fully understood how the synchrony and phase waves of the segmentation clock are initially established (Falk et al. 2022). To explore this question, our collaborators Ali Seleit and Alexander Aulehla at EMBL-Heidelberg used a CRISPR-Cas9 knock-in approach (Seleit, Aulehla, and Paix 2021) to establish a medaka *Cab* strain with an endogenous, fluorescing reporter gene (Her7-Venus) for the oscillation signalling pathway. This method allows them to image somite formation and extract quantitative measures for segmentation clock dynamics.

In medaka, it is known that the southern Japanese *Cab* strain and the northern Japanese *Kaga* strain have divergent somite periodicity [WHERE?], where *Kaga*’s tends to be faster, and *Cab*’s slower. Accordingly, to identify genetic loci associated with these differences in clock dynamics, they set up an F2 cross



Figure 5.1: Image of a mouse embryo at day 9.5 from Gridley (2006), showing somites in darker colours.

experiment using the reporter-carrying *Cab* strain and the *Kaga* strain as the parental F0 strains. They inter-crossed the hybrid F1 generation to create a sample of 622 F2 individuals, imaged the developing embryos of these F2 samples, and used pyBOAT (Schmal, Mönke, and Granada 2022) to extract the oscillation features during somite development.

5.3 Phenotype

Figure ?? shows the period data generated by pyBOAT for this study.

5.4 Genetic sequencing data

Our collaborators extracted DNA from the F0, F1, and F2, and sequenced the F0 and F1 samples with the Illumina platform at high coverage (~30x). They sequenced the F2 samples at low coverage (~1x), which would be sufficient to map their genotypes back to the genotypes of their parental strains.

5.5 F0 homozygosity and F1 heterozygosity

Before proceeding to map the F2 sequences to the genotypes of the F0 generation, I first investigated the levels of homozygosity in the F0 *Cab* and *Kaga*

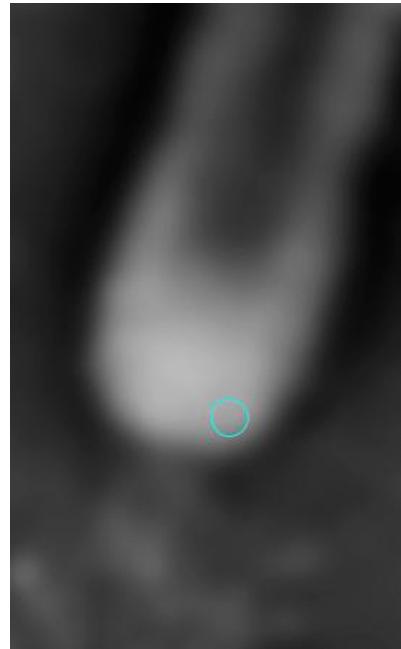


Figure 5.2: Screenshot of somite extension in an F2 individual captured by Ali Seleit during imaging. The blue circle represents the point tracked by pyBOAT over time, generating the quantitative phenotype data on period development used in this study.

strains, as this would have an effect on the resolution of our genetic mapping. That is to say, for regions where either parent is consistently heterozygous, it would be difficult to determine the parent from which a particular F2 individual derived its chromosomes at that locus. I therefore aligned the high-coverage sequencing data for the F0 *Cab* and *Kaga* lines to the medaka *HdrR* reference (Ensembl release 104, build ASM223467v1) using BWA-MEM2, sorted the aligned .sam files, marked duplicate reads, and merged the paired reads with picard (“Picard Toolkit” 2019), and indexed the .bam files with Samtools (Li et al. 2009).

To call variants, I followed the GATK best practices (to the extent they were applicable) with GATK’s HaplotypeCaller and GenotypeGVCFs tools, then merged all calls into a single .vcf file with picard. Finally, I extracted the biallelic calls for *Cab* and *Kaga* with bcftools (Danecek et al. 2021), counted the number of SNPs within non-overlapping, 5-kb bins, and calculated the proportion of SNPs that were homozygous. **Figure 5.3** is a circos plot generated with circlize (Gu et al. 2014) for the *Cab* F0 strain used in this experiment, featuring the proportion of homozygous SNPs per 5-kb bin (green), and the total number of SNPs in each bin (yellow).

To determine whether the low levels of observed homozygosity in *Kaga* was affected by its alignments to the southern Japanese *HdrR* reference, we also aligned the F0 samples to the northern Japanese *HNI* reference (**Figure 5.5**). This did not make differences to the levels of observed homozygosity in either sample, which gave us confidence that the low homozygosity observed in *Kaga* was not driven by reference bias.

5.6 F1 homozygosity

We next examined the level of heterozygosity in the F1 generation from the *Cab-Kaga* cross.

For the purpose of mapping the F2 sample sequences to the genomes of their parental strains, we selected only biallelic SNPs that were homozygous-divergent in the F0 generation (i.e. homozygous reference allele in *Cab* and homozygous alternative allele in *Kaga* or vice versa) *and* heterozygous in the F1 generation.

The number of SNPs that met these criteria per chromosome are set out in **Figure 5.7**.

5.7 F2 genotyping

To maximise the efficiency of our sequencing runs, we “shallow-sequenced” the F2 generation with the short-read Illumina platform at a depth of ~1x. We then aligned these sequences to the *HdrR* reference with BWA-MEM2, sorted

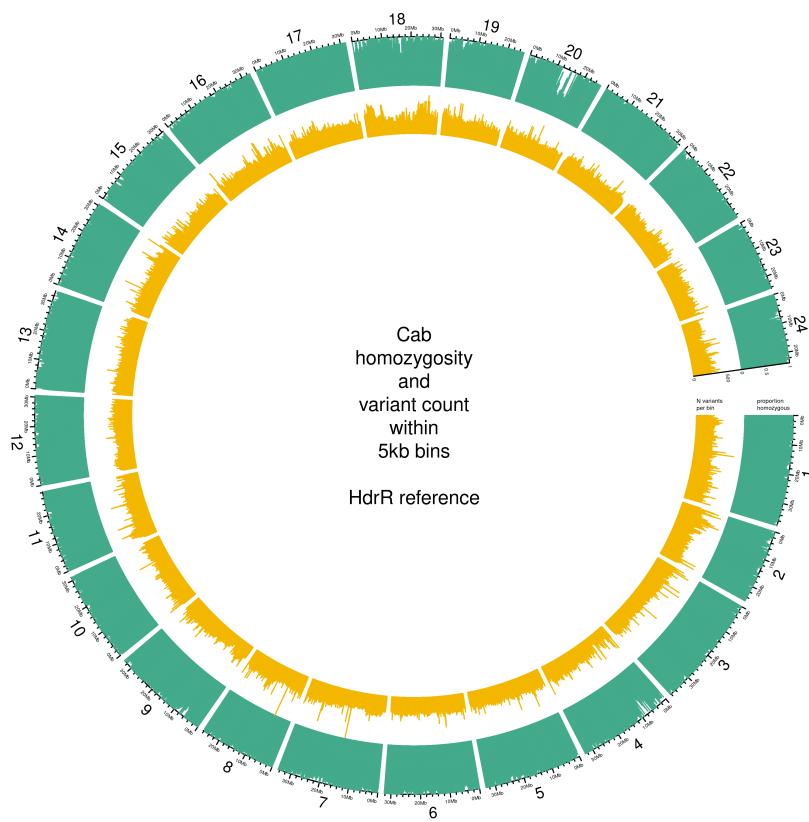


Figure 5.3: Proportion of homozygous SNPs within 5 kb bins in the *Cab* F0 generation genome (green), and number of SNPs in each bin (yellow).

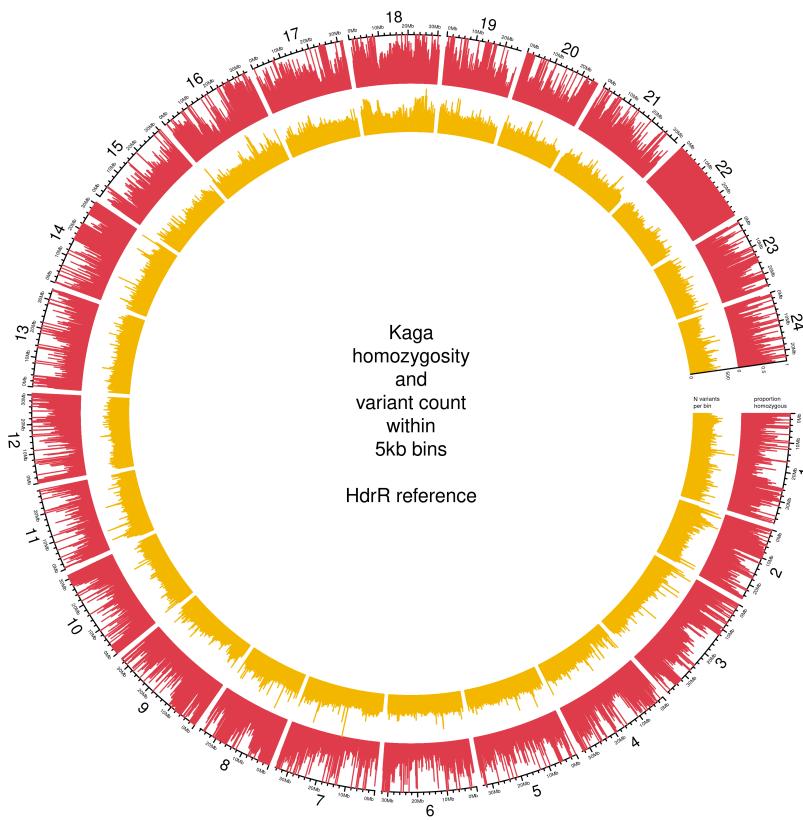


Figure 5.4: Proportion of homozygous SNPs within 5 kb bins in the *Kaga* F0 generation genome (red), and number of SNPs in each bin (yellow).

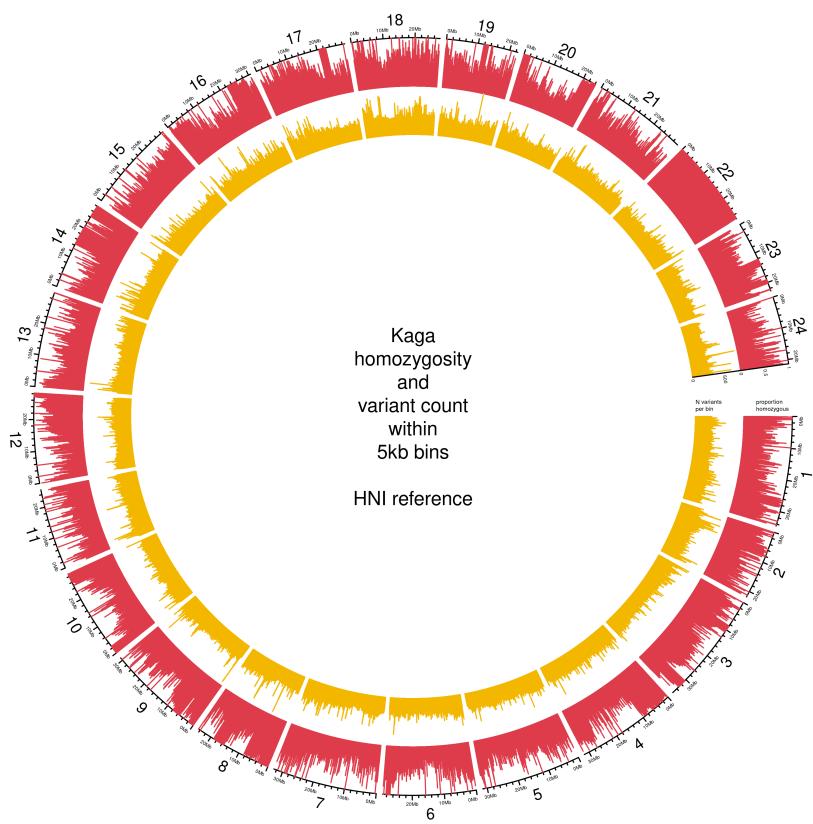


Figure 5.5: Proportion of homozygous SNPs within 5 kb bins in the *Kaga* F0 generation genome when aligned to the *HNI* reference (red), and number of SNPs in each bin (yellow).

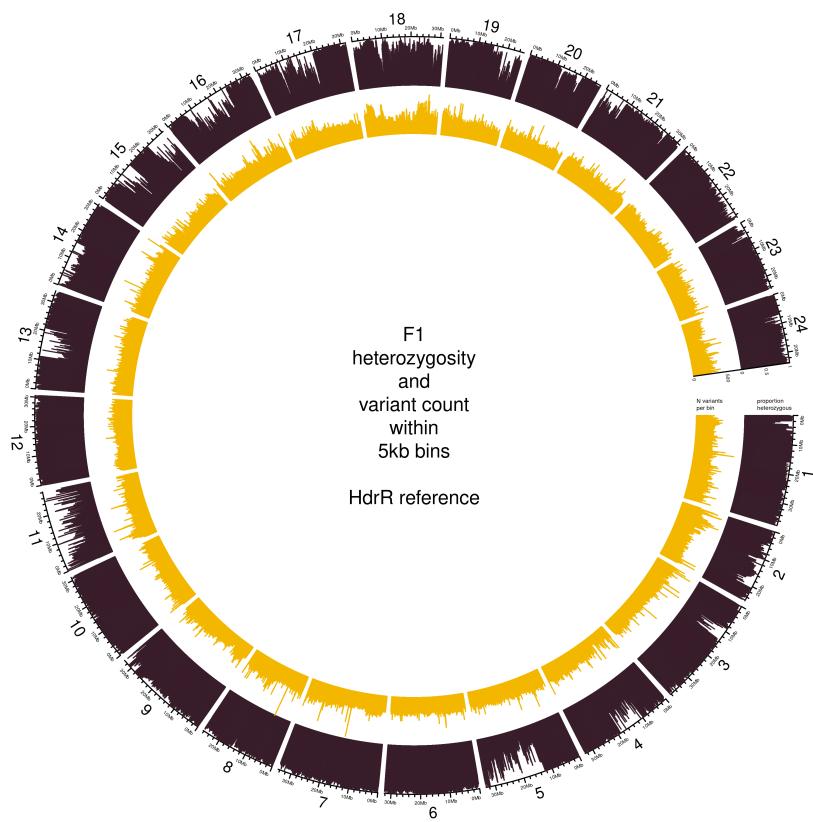


Figure 5.6: Proportion of heterozygous SNPs within 5 kb bins in the *Cab-Kaga* F1 cross (brown), and number of SNPs in each bin (yellow).

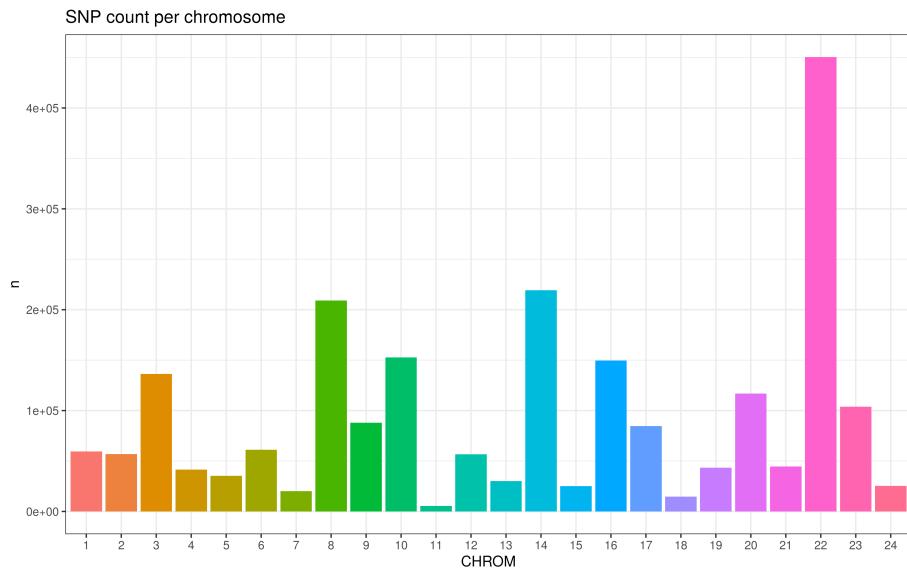


Figure 5.7: Number of SNPs per chromosome that were homozygous-divergent in the F0 *Cab* and *Kaga* generations, and heterozygous in the F1 generation.

the reads and marked duplicates with Picard, then indexed the resulting BAM files with samtools. Genotyping these shallow sequences with the same method as used for the high-coverage sequences for the F0 and F1 generation would be inappropriate. We therefore used a different method whereby we used *bam-readcount* to count the reads that supported either the *Cab* or the *Kaga* allele for all SNPs that met the criteria described above in section 5.6, summed the read counts within 5 kb blocks, and calculated the frequency of reads within each bin that supported the *Kaga* allele. This generated a value for each bin between 0 and 1, where 0 signified that all reads within that bin supported the *Cab* allele, and 1 signified that all reads within that bin supported the *Kaga* allele. Bins containing no reads were imputed with a value of 0.5.

We then used these values for all F2 individuals as the input to a Hidden Markov Model (HMM) with the software package *hmmlearn*, which we applied to classify each bin as one of three states, with state 0 corresponding to homozygous-*Cab*, 1 corresponding to heterozygous, and 2 corresponding to homozygous-*Kaga*. Across each chromosome of every sample, the output of the HMM was expected to produce a sequence of states. Based on previous biological knowledge that crossover events occur on average once per chromosome [CITE], I expected to observe the same state persisting for long stretches of the chromosome, only changing to another state between 0 and 3 times, and rarely more.

Figure @??fig:hmm-standard) shows how adjusting the HMM parameters changed the called genotypes for 10 F2 samples on chromosome 18. Allow-

ing the HMM to train itself for the transition probabilities and emission variances, the HMM produced an apparently noisy output (**Figure @??fig:hmm-standard)A**). Fixing the transition probabilities to make it very likely for a state to transition

I used these genotype-block calls to generate the recombination karyoplots shown in Figures 5.9 and 5.10.

Figure 5.11 shows the proportion of 5-kb bins called as either homozygous-*Cab*, heterozygous, or homozygous-*Kaga* within each F2 sample (points). The ordinary expectation for the ratios would be 0.25, 0.5, and 0.25 respectively. However, we observe a skew towards homozygous-*Cab* and away from homozygous *Kaga*. This may have been caused by the low homozygosity observed in *Kaga*.

5.8 Genome-wide linkage analysis

Finally, I used the called recombination blocks as pseudo-SNPs in a genetic linkage analysis. To detect associations between the pseudo-SNPs and the three phenotypes of interest, I used a mixed linear model (**MLM**) as implemented in GCTA (Yang et al. 2011). That paper describes the model as follows:

$$\mathbf{y} = \mathbf{X}\beta + \mathbf{W}\mathbf{u} + \epsilon \text{var}(\mathbf{y}) = \mathbf{V} = \mathbf{W}\mathbf{W}'\sigma_u^2 + \mathbf{I}\sigma_\epsilon^2$$

Where \mathbf{y} is a $n \times 1$ vector of phenotypes with n being the sample size, \mathbf{W} is a standardised genotype matrix, \mathbf{u} is a vector of SNP effects, and ϵ is a vector of residual effects. I additionally used the leave-one-chromosome-out implementation of GCTA's MLM, with excludes the chromosome on which the candidate SNP is located when calculating the GRM.

As described above in 5.3, the microscope used to image the embryos (either DB or AU) differed by several degrees in heat, which likely caused differences in the measurements observed. We accordingly experimented with including microscope as a covariate, either alone or together with the genotype for the reporter locus (either homozygous or heterozygous), or excluding it altogether. In an attempt to avoid complications resulting from its inclusion, we also tried inverse-normalising the period phenotype within each microscope group, transforming the phenotype to fit a normal distribution across both microscopes.

To set the significance threshold, we permuted the phenotype across samples using 10 different random seeds, together with all covariates when included, and ran a separate linkage model for each permutation. We then set the lowest p -value from all 10 permutation as the significance threshold for the non-permuted model. We additionally applied a Bonferroni correction to our p -values by dividing α (0.05) by the number of pseudo-SNPs in the model, and set this as a secondary threshold.

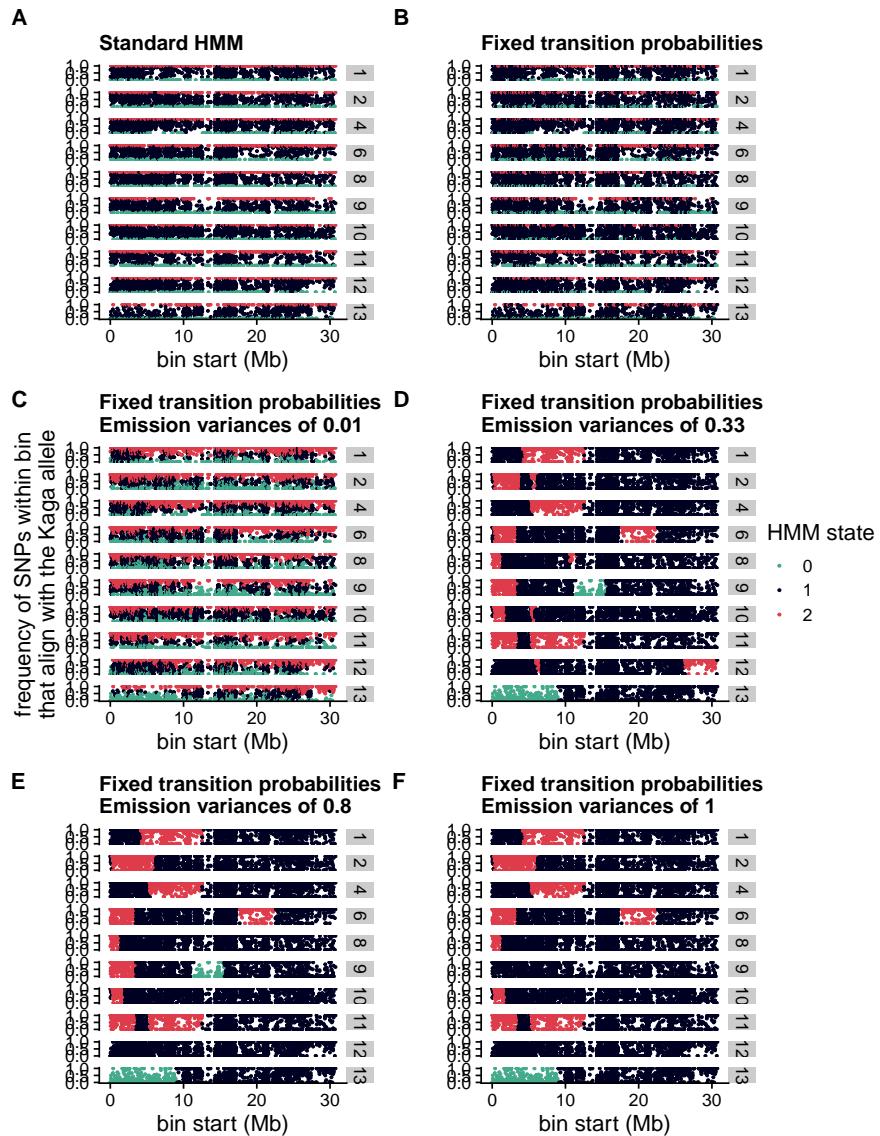


Figure 5.8: HMM states called for each bin across chr18 for 10 F2 samples. States 0, 1, and 2 correspond to homozygous *Cab*, heterozygous, and homozygous *Kaga*. Each point represents a 5-kb bin. Y-axis is the proportion of reads within each bin that align to the *Kaga* allele. X-axis is the bp location of the start of each bin. **A:** Standard HMM with all model parameters trained on the data. **B:** HMM with fixed transition probabilities of $0 \rightarrow 0/1 \rightarrow 1/2 \rightarrow 2 = 0.999$, $0 \rightarrow 1/2 \rightarrow 1 = 0.00066$, $0 \rightarrow 2/2 \rightarrow 0 = 0.000333$, $1 \rightarrow 0/1 \rightarrow 2 = 0.0005$. **C-F** retain those transition probabilities but with different fixed emission variances of 0.01 (**C**), 0.33 (**D**), 0.8 (**E**), and 1 (**F**).



Figure 5.9: (ref:karyo-wi-missing)

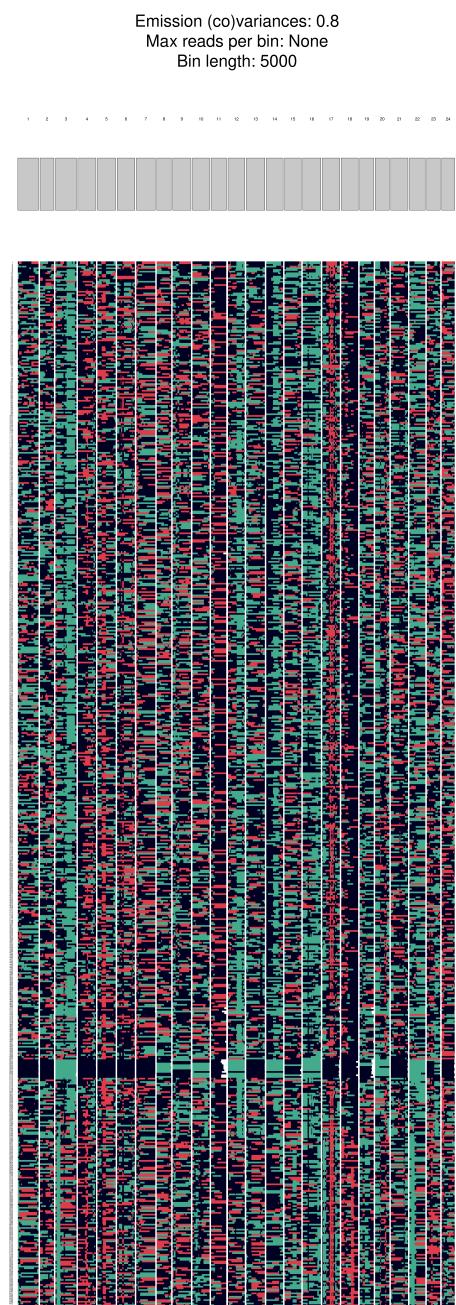


Figure 5.10: (ref:karyo-no-missing)

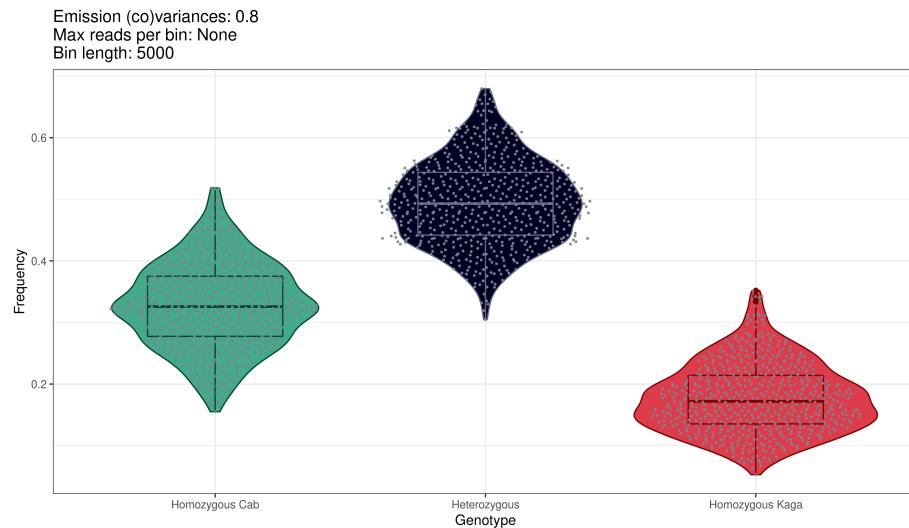


Figure 5.11: Proportions of 5-kb blocks called as either homozygous-*Cab*, heterozygous, or homozygous-*Kaga*.

5.8.1 Period intercept

Figure 5.12 is a Manhattan plot of the genetic linkage results for the period intercept phenotype, inverse-normalised across microscopes.

5.8.2 PSM area

We additionally

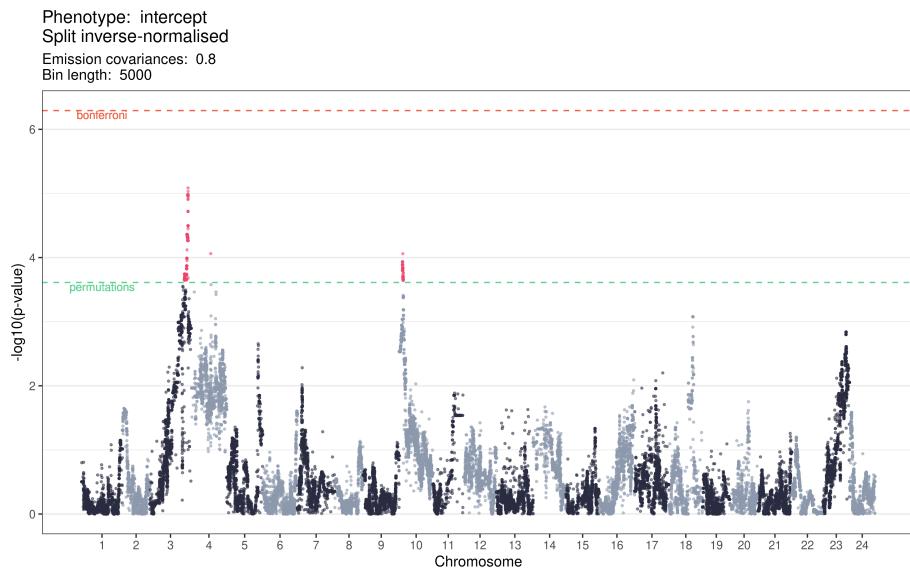


Figure 5.12: Manhattan plot of the genetic linkage results for the period intercept phenotype, inverse-normalised across microscopes. Pseudo-SNPs with p -values lower than the permutation significance threshold are highlighted in red.

Chapter 6

Variation in the frequency of trait-associated alleles across global human populations

6.1 Background

Humans have long sought to use genetic information to predict an individual's likely value for a given trait, in our own species and in other organisms (Chapter 1). As seen in previous chapters, an individual's phenotypic value at a given point in time is the product of complex interactions between their genome and their environment, beginning from embryonic development and continuing throughout their lifetimes. It is now clear that "complex" traits such as height, intelligence, and behaviour are highly polygenic, meaning that they are genetically influenced by hundreds or thousands of genetic variants, each exerting a small effect in one or the other direction along the trait's spectrum (Sellal and Barton 2019).

A richer understanding of the cumulative effect of genetic variants on any trait allows for the prediction of the value that an individual is most likely to have for that trait. Of all human traits, diseases are particularly salient; in 2018, the global healthcare industry was valued at US\$8 trillion, and predicted to increase to US\$12 trillion by 2022 ("The \$11.9 Trillion Global Healthcare Market: Key Opportunities & Strategies (2014-2022) - ResearchAndMarkets.com" 2019). This strong financial imperative complements the moral imperative to reduce suffering, together driving the question of how to use genetic information to improve human health.

Recent technological developments have made it possible to sequence human genomes at scale, and it is thought that by combining detailed genetic information with other environmental and phenotypic information (such as lifestyle or clinical factors), clinicians could move towards the practice of “precision medicine”, where interventions could be tailored to their patients’ unique risk profiles (Wray, Goddard, and Visscher 2007). The use of genetic information to predict individuals’ values for a trait of interest entails the construction of metrics known as “polygenic scores” (**PGS**). When the trait is a disease, PGS is commonly known as polygenic risk scores (**PRS**), or genetic risk profiling, but I use the term PGS to encompass both disease and non-disease traits.

6.1.1 Polygenic Scores (PGS) and Genome-Wide Association Studies (GWAS)

6.1.1.1 PGS

PGS using genetic information alone show modest yet reliable accuracy for the prediction of complex traits (Alicia R. Martin et al. 2019): the correlations between PGS and the trait value as measured by R^2 have reached 0.24 for height (Yengo et al. 2018), and 0.12-0.16 for educational attainment (Okbay et al. 2022). PGS also improve predictions beyond non-genetic clinical models for a variety of health-related traits, including breast cancer (Maas et al. 2016), prostate cancer (Schumacher et al. 2018), and type I diabetes (Sharp et al. 2019). The predictive accuracy of PGS scores can be further improved by combining genetic information with lifestyle and clinical factors, as seen with cardiovascular disease (Khera et al. 2018; Kullo et al. 2016; Natarajan et al. 2017; Paquette et al. 2017; Tikkannen et al. 2013; Sun et al. 2021).

6.1.1.2 GWAS

PGS are calculated for an individual by summing trait-associated alleles identified by genome-wide association studies (**GWAS**), as weighted by the alleles’ effect sizes (Duncan et al. 2019). GWAS aim to identify genetic variants associated with traits by comparing the allele frequencies of individuals who share similar ancestries, but differ in values for the trait in question (Uffelmann et al. 2021). As of 2021, over 5,700 GWAS have been performed for more than 3,330 traits (Uffelmann et al. 2021).

However, most GWAS have been performed with individuals of European ancestry, despite only constituting around 16% of the present global population. Although the proportion of participants in GWAS from a non-European background increased from 4% in 2009 to 16% in 2016 (Popejoy and Fullerton 2016)), as of 2019, 79% of all GWAS participants recorded in the GWAS Catalog were of European ancestry, and the proportion of non-European individuals has remained the same or reduced since late 2014 (Alicia R. Martin et al. 2019).

This bias extends to PGS studies, where as of 2019, only 67% of them included only participants of European ancestry, with another 19% including only East Asian ancestry participants, and only 3.8% with cohorts of African, Hispanic, or Indigenous ancestry (Duncan et al. 2019).

It is therefore unsurprising that PGS scores are far better at predicting disease risk in individuals of European ancestry than in those of non-European ancestry (Alicia R. Martin et al. 2017; Alicia R. Martin et al. 2019). Indeed, the predictive accuracy of PGS scores decays with genetic divergence of the GWAS “independent” or “test” sample, from the “discovery” or “training” sample, as established in both humans (Alicia R. Martin et al. 2017; Alicia R. Martin et al. 2019), and livestock (Clark et al. 2012; Habier et al. 2010; Pszczola et al. 2012).

Compared to PGS scores for those of European ancestry, PGS scores across multiple traits are ~64-78% less accurate for individuals of African ancestry, (Duncan et al. 2019; Alicia R. Martin et al. 2019), ~50% less accurate for individuals of East-Asian ancestry, and ~37% less accurate for individuals of South-Asian ancestry (Alicia R. Martin et al. 2019).

6.1.2 Contributors to PGS non-transferability

What explains this disparity in predictive value? A number of factors may be responsible, including:

1. The failure of GWAS to identify causal variants that either do not exist or are not identifiable within the “discovery” sample, for both technological and methodological reasons (Alicia R. Martin et al. 2019);
2. The sample populations may differ in linkage disequilibrium (**LD**) – the correlation structure of the genome – which would change the estimated effect sizes of the causal variants, even when the causal variants themselves are the same (Alicia R. Martin et al. 2019);
3. Allele frequencies of the causal variants, and the distribution of the effect sizes of the causal variants, may differ between populations (Alicia R. Martin et al. 2017; Scutari, Mackay, and Balding 2016); and
4. The environments and demographies of populations tend to differ. Such differences are often correlated with genetic divergence due to geography, making it difficult to determine whether the associations are driven by the differences between population in their genetics, or their environments (Alicia R. Martin et al. 2019; Kerminen et al. 2019).

The first three factors can degrade predictive performance even in the absence of biological and environmental differences. On the other hand, environmental

and demographic differences can drive forces of natural selection can in turn drive differences in causal genetic architecture (Alicia R. Martin et al. 2019).

I will discuss each of these factors in turn before addressing point (3) in this analysis.

6.1.2.1 Technological and methodological limitations of GWAS

The power to discover a causal variant through GWAS depends on the variant's effect size and frequency in the study population (Alicia R. Martin et al. 2019; Sham et al. 2000). That is to say, the stronger the variant's effect, or the more common it is, the more likely it is to be discovered. Rare variants tend to have stronger effect sizes (Watanabe et al. 2019), likely due to purifying selection (Park et al. 2011), and tend not to be shared across populations (Gravel et al. 2011; Consortium et al. 2015). This is particularly relevant for African populations, as they have a much greater level of genetic variance than other populations due to the human species having originated on that continent (Consortium et al. 2015). Therefore, if GWAS aren't performed on diverse populations, PGS can't take into account the rare variants present in non-European populations that are likely to exert stronger effects on the trait of interest. There are also several other issues that can affect the discoverability of causal variants through GWAS, including the technology used for genotyping, the selection of the cohort, and the necessary exclusion of genotypic outliers.

With respect to genotyping technologies, GWAS often use data from SNP microarrays. These do not sequence the whole genome, but rather a selection (from several hundred thousand to millions) of genetic markers intended to present *common* genetic variation (Porcu et al. 2013), which accordingly tend to neglect rare genetic variants (Uffelmann et al. 2021). To increase the density of genotypes, which would increase the likelihood of refining the association signal and identifying causal variants, researchers often "impute" variants that aren't sequenced directly (Porcu et al. 2013). The imputation process involves "phasing" the study genotypes onto the genotypes of a "reference panel" (McCarthy et al. 2016). However, if the reference panel does not sufficiently represent the population in the study sample, they are likely to miss or incorrectly impute those genotypes (Alicia R. Martin et al. 2019). Again, this is particularly problematic for African populations.

The lack of representation of rare variants in SNP microarrays can be overcome by using next-generation sequencing technologies such as whole-genome sequencing (**WGS**) and whole-exome sequencing (**WES**). (The former seeks to sequence the full genome, and the latter of only targets the coding regions of the genome.) These methods are more expensive than SNP microarrays, which hinders their widespread use at scale, and although their costs are continuing to decrease rapidly, there is a question as to whether they return a proportionate benefit in all use cases (Schwarze et al. 2018).

A second limitation is the selection of GWAS cohorts, which can introduce selection and collider biases (Uffelmann et al. 2021). For instance, the UK Biobank, which contains genetic and phenotypic data on 500,000 participants who volunteered for inclusion between 2006 and 2010, tend to be older, female, healthier, and wealthier than non-participants (Fry et al. 2017). This creates the possibility of confounding genetic associations with environmental factors, which I discuss further in 6.1.2.4 below.

A third limitation is the “quality control” step that is required during the GWAS process (Uffelmann et al. 2021). To avoid confounding from population stratification, which can lead to overestimated heritability and biased PGS, GWAS cohorts are filtered to include only those with similar ancestries – or relative genetic homogeneity – by clustering individuals through principal component analysis (**PCA**) of their genotypes, and excluding outliers. I elaborate on the issue of population stratification in section 6.1.2.4 below, but at present, a statistical model for GWAS that can include cohorts with diverse ancestries without the risk of serious confounding is yet to be developed (Jeremy J. Berg et al. 2019).

6.1.2.2 Differences in LD

Because GWAS SNP markers are often not the causal variants themselves, but merely in physical proximity to them, the estimated effect size of a SNP marker depends on the extent to which it is in LD with the causal variant (Mostafavi et al. 2020; Jonathan K. Pritchard and Przeworski 2001). To illustrate the problem, if a SNP has an LD r^2 with a causal variant of 0.8 in the discovery population and 0.6 in the target population, it would explain $25\% = (1 - 0.6/0.8)$ less trait variation in the target population, and would therefore be less predictive (Wang et al. 2020).

These differences in effect-size estimates may typically be small for most regions of the genome, but as PGS sum across all such effects, they aggregate these population differences (Alicia R. Martin et al. 2019; Jeremy J. Berg et al. 2019). Previous empirical and simulation studies have shown that accuracy of PGS scores decay with increased genetic differentiation (F_{ST} – described below in 6.1.3) and LD differences between populations (Habier et al. 2010; Pszczola et al. 2012; Scutari, Mackay, and Balding 2016; Wang et al. 2020). The issue may be addressed to a degree by using LD information from an external reference panel as a prior to infer the posterior mean effect size of a genetic variant – Vilhjálmsson et al. (2015) demonstrated through simulations that this could improve PGS predictive accuracy. Yet the most appropriate means of deal with differences between populations in LD remains an active area of research (Duncan et al. 2019).

6.1.2.3 Differences in allele frequencies

Causal variants can differ in both frequency and effect size between different ancestry groups, e.g. for lactase persistence (S'egurel and Bon 2017), or skin pigmentation (Adhikari et al. 2019). If a causal allele is rare in the GWAS discovery population, even if it is discovered (see 6.1.2.1), it is likely to have noisy effect size estimates, and therefore likely to inaccurately estimate its effect size in a different population where it exists at a higher frequency.

Differences in allele frequencies between populations can arise through random genetic drift, or be driven by selective pressures towards the trait optima for a given environment (Harpak and Przeworski 2021). However, evolutionary biologists have found that differences between populations in the mean values for traits tend to occur through small, coordinated shifts in their allele frequencies (Jeremy J. Berg et al. 2019; Edge and Coop 2019). In Chapter 6, I explore the differences in allele frequencies across populations for all polygenic traits in the GWAS Catalog, and confirm that with few exceptions – including skin pigmentation, and HIV viral load – the differences in allele frequencies between populations tends to be small.

6.1.2.4 Differences in environment

Genes continuously interact with each other (GxG, or “epistasis” (Gros, Le Nagard, and Tenaillon 2009)), the genes of one’s parents (“genetic nurture”, Kong et al. (2018)) or social companions (“social genetic effects”) (Domingue et al. 2018; Baud et al. 2017),¹ and the wider non-genetic environment (GxE).

The respective contributions of genetics and environment to traits with social value – such as intelligence – is highly contentious, especially when there are apparent differences between populations in the mean values for those traits. PGS measure the proportion of variance within a population that is explained by genetics. Because PRS summarises a *proportion* of the total variance, when studying a population that is subject to greater environmental variation, the variance attributable to genetic factors will proportionately reduce. The corollary being that when studying a population where the environment is held constant, the proportion of variance for that trait that is explained by genetic factors will approach 1. Therefore, increases in the amount of environmental variance that a population is exposed to will reduce the accuracy of PGS predictions when applied to that population.

Different environments are also often correlated with population structure (Jeremy J. Berg et al. 2019). For example, in East Asia, there is a greater proportion of individuals of East-Asian ancestry than there is of European ancestry, and *vice versa* in Europe. Those East-Asian individuals will therefore tend to share more of their genetic background with each other than with

¹As also explored in Chapters 3 and 4

Europeans, and that population structure will be correlated with the different environments that exist in East Asia compared to Europe. This makes it difficult to determine whether it is the differences in their environments or the differences in their genetics that is driving the discrepancies between the mean values for traits between those populations. These complexities are unlikely to be resolved in the near future, which makes it attractive to turn to model organisms to address more basic biological questions regarding GxE in relation to complex traits (Andersson and Georges 2004), as we have done with respect to behaviour in Chapters 3 and 4.

6.1.3 F_{ST}

The widely-used fixation index (F_{ST}) was introduced independently by Sewall Wright (S. Wright 1949) and Gustave Malécot (Mal'écot 1948) as a metric for measuring the genetic diversity between populations.² It quantifies the relative variance in allele frequency between groups compared to within groups, reflecting the combined effects of genetic drift, migration, mutation, and selection (Holsinger and Weir 2009). The metric ranges from 0 to 1, where loci with high F_{ST} values – that is, loci with a large relative between-group variance in allele frequencies – may have been subject to selection or different demographic processes (Holsinger and Weir 2009). The metric has customarily been used to identify regions of the genome have been subject to diversifying selection (Akey et al. 2002; Guo, Dey, and Holsinger 2009; Bruce S. Weir et al. 2005).

I first sought to explore the distribution of F_{ST} for SNPs across the human genome. As the reference for human genomic variation across diverse populations, I used the New York Genome Center high-coverage, phased .vcf files (“Index of /Vol1/Ftp/Data_collections/1000g_2504_high_coverage/Working/20201028_3202_phased/” n.d.) for the 2,504 individuals from 26 populations from across the globe, as described in the 1000 Genomes phase 3 release (Consortium et al. 2015). I then annotated those .vcf files with human SNP IDs from dbSNP release 9606 (Smigelski et al. 2000), and calculated F_{ST} for each of the ~69M SNPs in that dataset with PLINK 1.9 (Chang et al. 2015; Purcell and Chang, n.d.). Figure 6.1 shows the location and F_{ST} value for all SNPs in the 1000 Genomes dataset, and Figure 6.2 shows their distribution across the range of F_{ST} values.

Figure 6.1 shows that with very few exceptions, F_{ST} remains below 0.6, although specific regions do appear to be differentially selected, as indicated by the peaks on chromosomes 1, 2, and 17. Figure 6.2 makes it clear that the vast majority of SNPs have very low F_{ST} , with a genome-wide mean of 0.019. The question then is whether the SNPs that have a detectable effect on traits tend to have higher F_{ST} values – and therefore greater variation in allele frequencies between populations – than random SNPs with similar allele frequencies in European populations. If so, this would suggest that variation in allele frequencies might

²In Wright's notation, F refers to “fixation” of an allele, and ST refers to “subpopulations within the total population”.

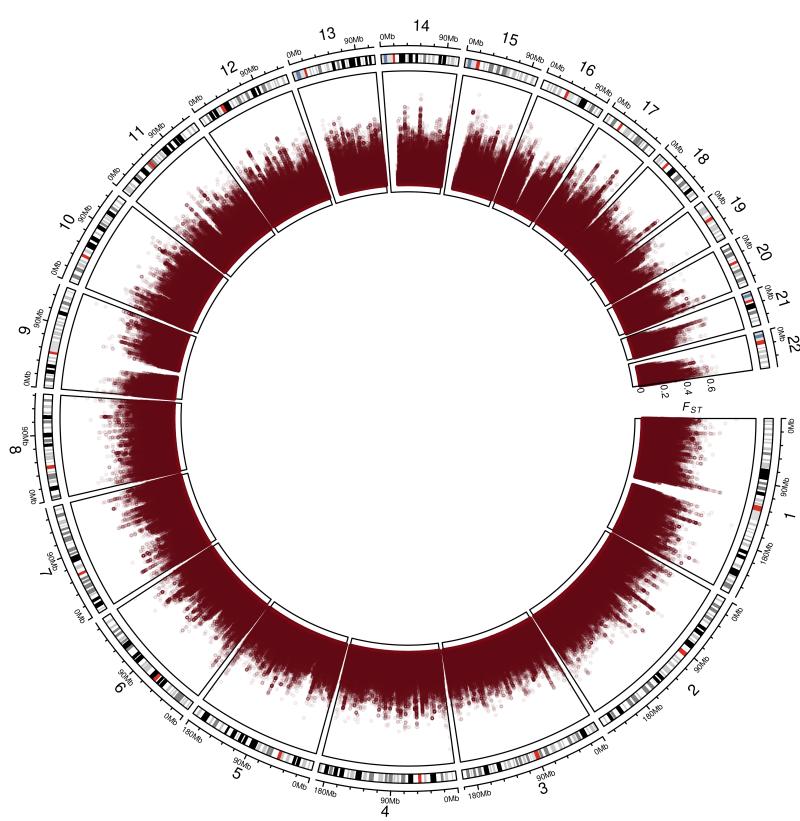


Figure 6.1: (ref:fst-circos)

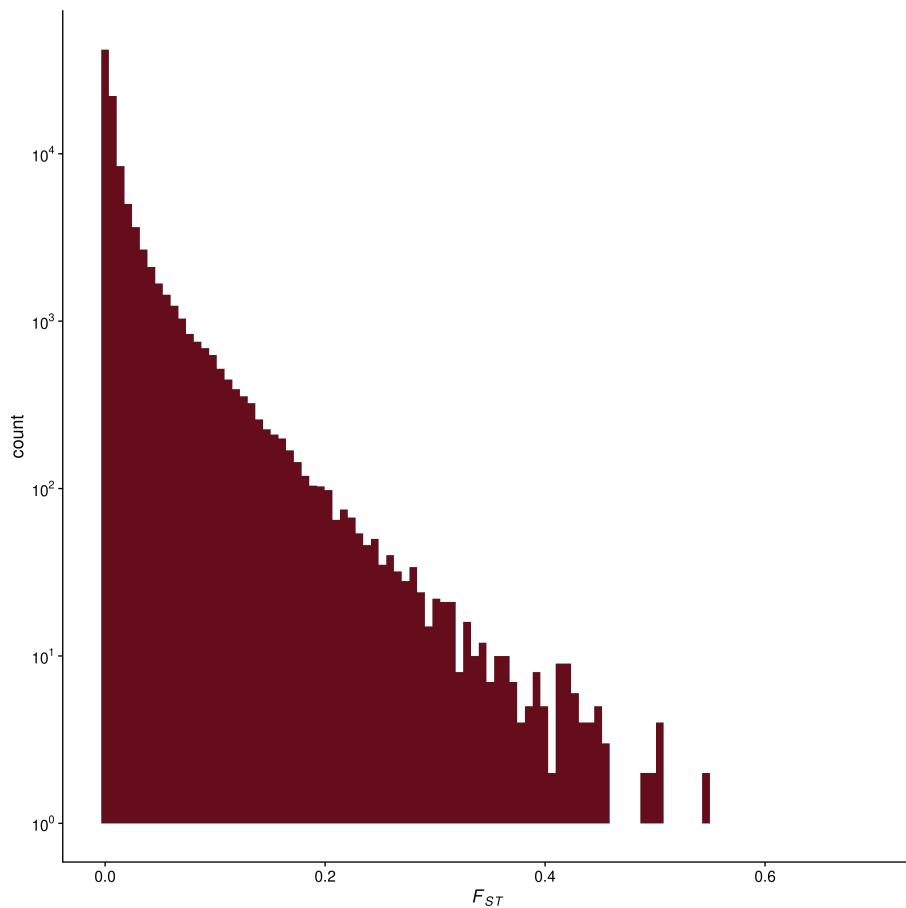


Figure 6.2: (ref:fst-histo)

contribute significantly to the non-transferability of PRS scores derived from European-focused GWAS.

6.2 Analysis

In this analysis I explore the distribution of F_{ST} scores for loci associated with 587 traits, a subset of the GWAS Catalog that passed our criteria for suitable polygenic traits (see section 6.2). Using high-coverage sequence data for 2,504 individuals from the 1000 Genomes Project phase 3 release, for each trait in the GWAS Catalog I calculated the distribution of F_{ST} across all approximately-unlinked SNPs associated with it (**trait SNPs**), and compared these F_{ST} distributions with the F_{ST} distributions of random-selected SNPs that were matched to the trait SNPs by their allele frequencies in European populations (**control SNPs**).

6.2.0.1 GWAS Catalog

I used the R package *gwasrapidd* (Magno and Maia 2020) to query all traits in the GWAS Catalog (MacArthur et al. 2017) as of 9 August 2021 ($N_{TRAITS} = 3,459$). For 541 of these traits, no matching variant IDs could be pulled out from the 1000 Genomes VCFs, leaving $N_{TRAITS} = 3,008$.

6.2.1 Linkage disequilibrium

To obtain the “trait SNP” dataset, for each trait, I sought to isolate the SNP closest to each of its true causal variants, and exclude the SNPs in LD with them. To this end, I used PLINK 1.9 (Chang et al. 2015; Purcell and Chang, n.d.) to “clump” the SNPs associated with each of the remaining 3,008 traits, using an “index” SNP p-value threshold of 10^{-8} (Panagiotou, Ioannidis, and Genome-Wide Significance Project 2012), r^2 threshold of 0.1 (Hill and Robertson 1968), and base window size of 1 Mb. This process revealed 2,045 traits with at least one index SNP that met the p-value threshold. The index SNPs for each trait formed the set of trait SNPs, and **Figure 6.3** shows the counts of unique SNP IDs associated with each trait before and after clumping. In order to target relatively polygenic traits, I further filtered out traits with fewer than 10 trait SNPs, leaving $N_{TRAITS} = 587$.

6.2.2 Control SNPs

To obtain the “control SNP” dataset, I assigned each trait SNP to one of 20 bins based on its minor allele frequency in European populations (as provided in the original 1000 Genomes .vcf files under the column header ‘INFO/AC_EUR’).

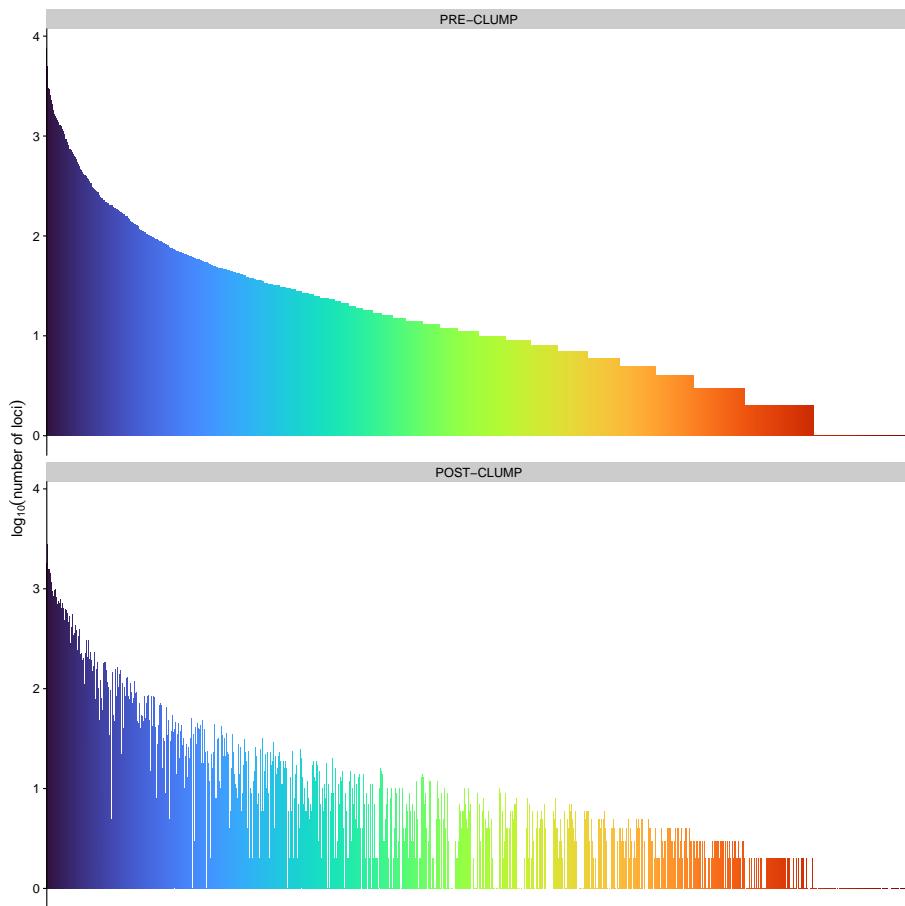


Figure 6.3: \log_{10} counts of associated SNPs for each trait before and after the clumping process, which involved: a) excluding all SNPs with a p -value greater than 10^{-8} ; and b) starting with the SNPs with the lowest p -values (“index” SNPs), excluding all other SNPs within a 1 Mb region of the index SNP with an LD r^2 of more than 0.1. [CHANGE COLOUR]

For example, if a trait SNP had a minor allele frequency of 0.08 in European populations, it was assigned to the (0.05, 0.1] bin. I did the same for all (unassociated) SNPs in the .vcf files, then paired each trait SNP with a random SNP from the .vcf file in the equivalent bin. These allele-frequency-paired random SNPs formed the set of “control SNPs”, which I used to infer the F_{ST} distribution of a random set of SNPs with the same allele frequencies as the trait SNPs, and against which I could compare the F_{ST} distribution of the trait SNPs.

6.2.3 F_{ST} and ranking traits by signed Kolmogorov-Smirnov D statistic

I then calculated F_{ST} for each of the trait SNPs and their matched control SNPs using the Weir and Cockerham method (B. S. Weir and Cockerham 1984), as implemented in the R package *pegas* (Paradis 2010). I then sought to rank all traits based on the directional difference in F_{ST} distributions between trait and control SNPs. The Kolmogorov-Smirnov (KS) test is an appropriate test to measure the differences between distributions (Conover 1999), but the p -values are strongly affected by the number of samples in each distribution (here, the number of loci in each trait), and it does not measure whether one distribution is overall higher or lower than the other distribution. These limitations made it impossible to use the KS test p -values to compare the directional distances between trait and control SNPs across traits that have very different numbers of SNPs. I accordingly formulated the following method for ranking the traits based on the directional distance of the F_{ST} distributions of the trait SNPs compared to the control SNPs:

First, I ran three KS tests for each trait t with $x_t = F_{ST,traitSNPs}$ and $y_t = F_{ST,controlSNPs}$:

1. two-sided (D_t) ;
2. one-sided “greater” (D_t^+) ; and
3. one-sided “less” (D_t^-).

I note that $D_t = \max(D_t^+, D_t^-)$, where D_t^+ is the greatest vertical distance attained by the eCDF of x_t over the eCDF of y_t , and D_t^- is the greatest vertical distance attained by the eCDF of y_t over the eCDF of x_t (Conover 1999; Durbin 1973). I then used a comparison of D_t^+ and D_t^- to formulate a “signed D statistic” (D_t^S), based on the logic that trait SNPs with a lower overall F_{ST} than control SNPs tend to have a higher D under the “greater” test than the “less” test, and vice versa.

Therefore, D_t^S :

$$\begin{aligned} D_t^- > D_t^+ : & -D_t \\ D_t^- = D_t^+ : & 0 \\ D_t^- < D_t^+ : & D_t \end{aligned}$$

In **Figure 6.4** I present the F_{ST} distributions of trait SNPs for an illustrative subset of 28 human traits, ranked by D_t^S when compared with their matched control SNPs. **Figure 6.4A** shows the densities of SNPs as a function of F_{ST} , and **Figure 6.4B and C** show their empirical Cumulative Distribution Functions (eCDFs). **Figure 6.4B** includes the eCDFs of control SNPs in grey. eCDF figures for all 587 traits that passed our filters (Methods) are provided in the Appendix A.1.

These results show that for most traits, especially those that are highly polygenic, the F_{ST} of their associated alleles tend to be low, and to differ little from their matched control SNPs. This suggests that the causal variants of polygenic traits are generally shared across global populations at similar frequencies. Wang et al. (2020) determined through simulations that differences in LD and allele frequencies between populations can explain 70-80% of the loss of PGS relative accuracy for traits like body mass index and type 2 diabetes. This builds on the work of others [CITE PAPERS CITED BY BERG AND COOP AND ELABORATE]. As most of these variants have been discovered in European populations, the poor transferability of PGS between populations does not appear to be primarily driven by differences in the allele frequencies of these discovered variants, but perhaps rather by as-yet undiscovered variants of larger effect sizes in non-European populations, as well as differences between these populations in LD structure and environment.

There is a question as to whether the higher distributions of F_{ST} observed for hair shape, eye colour, skin pigmentation, and HIV infection, are due to those variants being discovered in diverse populations, such as those in Africa. For instance, if the alleles were predominantly discovered through GWAS on African populations, which contain an outsized proportion of genetic variation, those alleles would be more likely to show lower frequencies in other populations, and consequently higher F_{ST} . To examine the number of individuals from different ancestries that were used in these studies, I generated Figure 6.5. This figure shows that GWAS performed for the more comprehensively-studied phenotypes such as body height, BMI, and educational attainment, included individuals from many diverse populations, whereas the GWAS on pigmentation-related traits tended to focus on European or Latin American populations, as well as those of African ancestry in some cases. As expected, the GWAS on HIV-related traits included a higher proportion of individuals of African ancestry, which may explain the higher levels of F_{ST} observed there. I note that the GWAS Catalog data did not allow me to determine whether different studies on the same trait used the same cohorts (e.g. from UK Biobank), which would have the effect of inflating the counts shown in Figure 6.5.

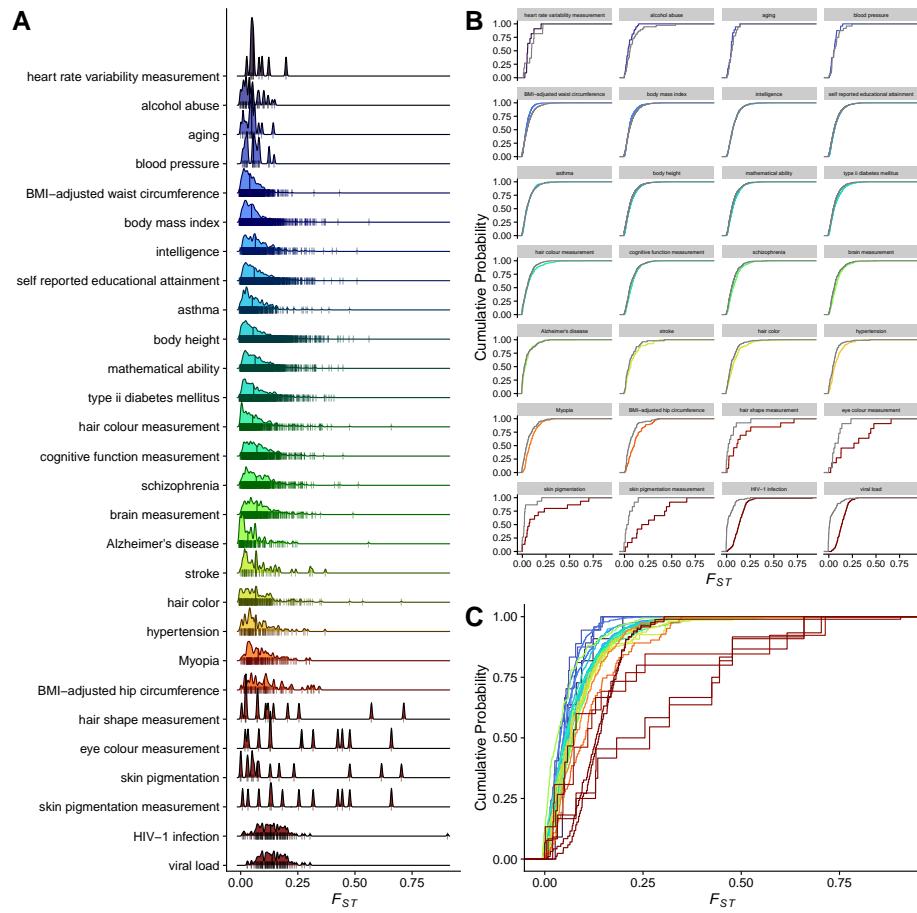


Figure 6.4: Distributions of F_{ST} across 28 illustrative human traits, ranked by signed-D (Kolmogorov-Smirnov test) comparing trait and control SNPs. **A.** F_{ST} density ridge plots with SNP markers. **B.** Empirical Cumulative Distribution Functions (eCDFs) of F_{ST} for trait-associated (colour) and random control (grey) SNPs, faceted by trait. **C.** Consolidated eCDFs of trait-associated SNPs from (B). eCDFs for all traits are included in the Appendix.

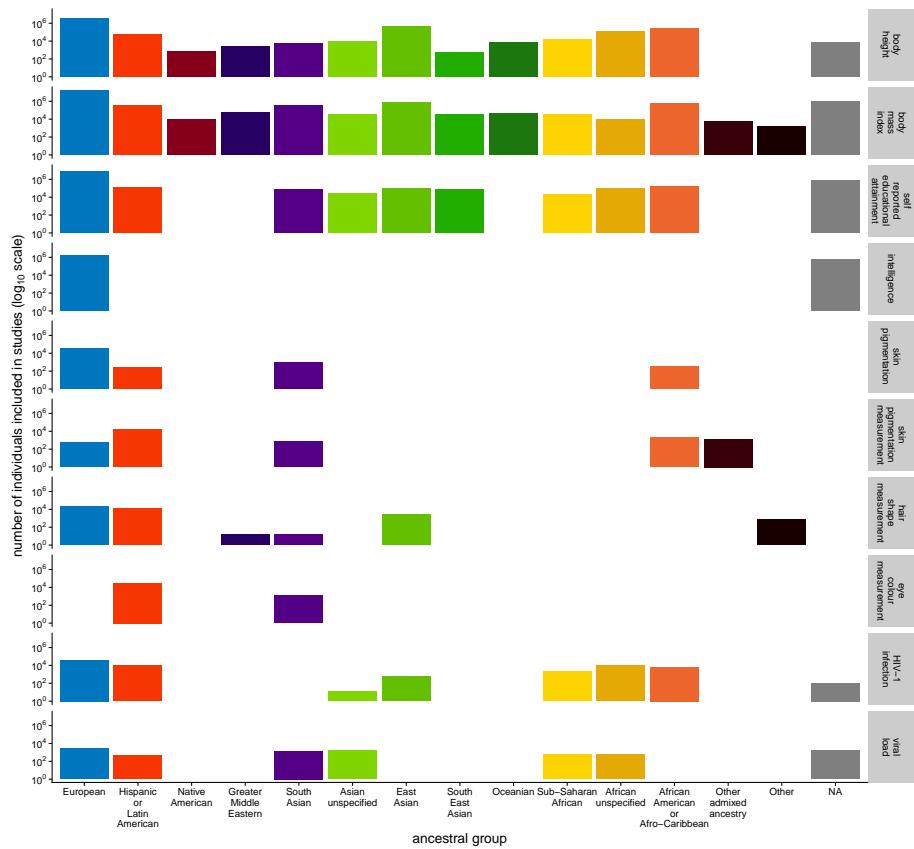


Figure 6.5: (ref:fst-n-indivs)

6.3 Implications

6.3.1 Limitation of F_{ST}

The first relevant limitation of F_{ST} is that it does not correspond to similarities or differences between populations in trait values. This is because F_{ST} does not take into account the effect size or the direction of effect of the trait-associated allele, so for highly-polygenic traits like the ones shown here, F_{ST} is almost entirely decoupled from the mean additive genetic value between populations (Jeremy J. Berg and Coop 2014a). This means that even when a trait's associated alleles have low F_{ST} , as we see for most traits here, it does not follow that the population mean values for that trait would be the same due to genetic similarities between those populations. As Kremer and Le Corre (2012) determined by through simulations, for highly polygenic traits, mean trait differences are driven by small, coordinated shifts in allele frequencies, which would not be detected by F_{ST} (Le Corre and Kremer 2012).

The second relevant limitation is that F_{ST} is not sufficiently powered to detect selection for polygenic traits (Jeremy J. Berg and Coop 2014b), which means that these results cannot be used to determine the extent to which alleles are under selection in a given population. This is apparent in our analysis, where in contrast with Racimo, Berg, and Pickrell (2018), height and BMI, which have been found to be under strong differential selection, appear similar to other polygenic traits.

6.3.2 The importance of environment, and a push for diversity in genetic studies

The obvious solution to this issue of non-transferability of PGS scores to diverse populations is to increase the representation of those populations in GWAS and PGS studies, as has been often proposed elsewhere (Alicia R. Martin et al. 2017; Alicia R. Martin et al. 2018; Bien et al. 2019; Alicia R. Martin et al. 2019; Sirugo, Williams, and Tishkoff 2019; Wojcik et al. 2019). [ELABORATE]

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Appendix A

eCDF of all polygenic traits
in the GWAS Catalog
ranked by D_t^S

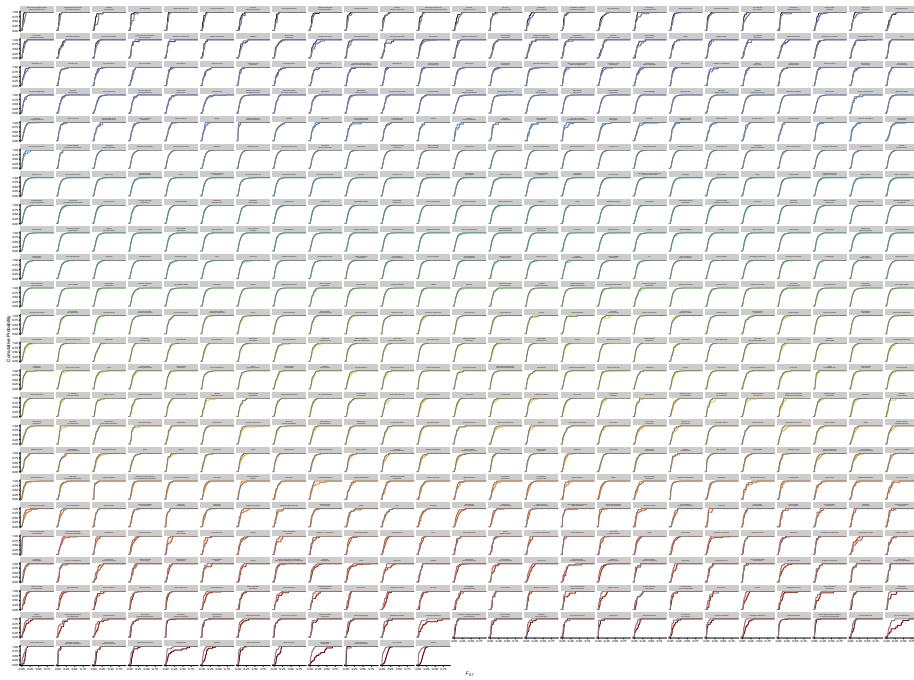


Figure A.1: 587 traits from the GWAS Catalog that passed our filters for polygenic traits, ranked by D_t^S .

Appendix B

HMM state time dependence for all MIKK panel lines

B.1 Direct genetic effects

B.1.1 Tile plot

B.1.2 Density plot

B.2 Social genetic effects

B.2.1 Tile plot

B.2.2 Density plot

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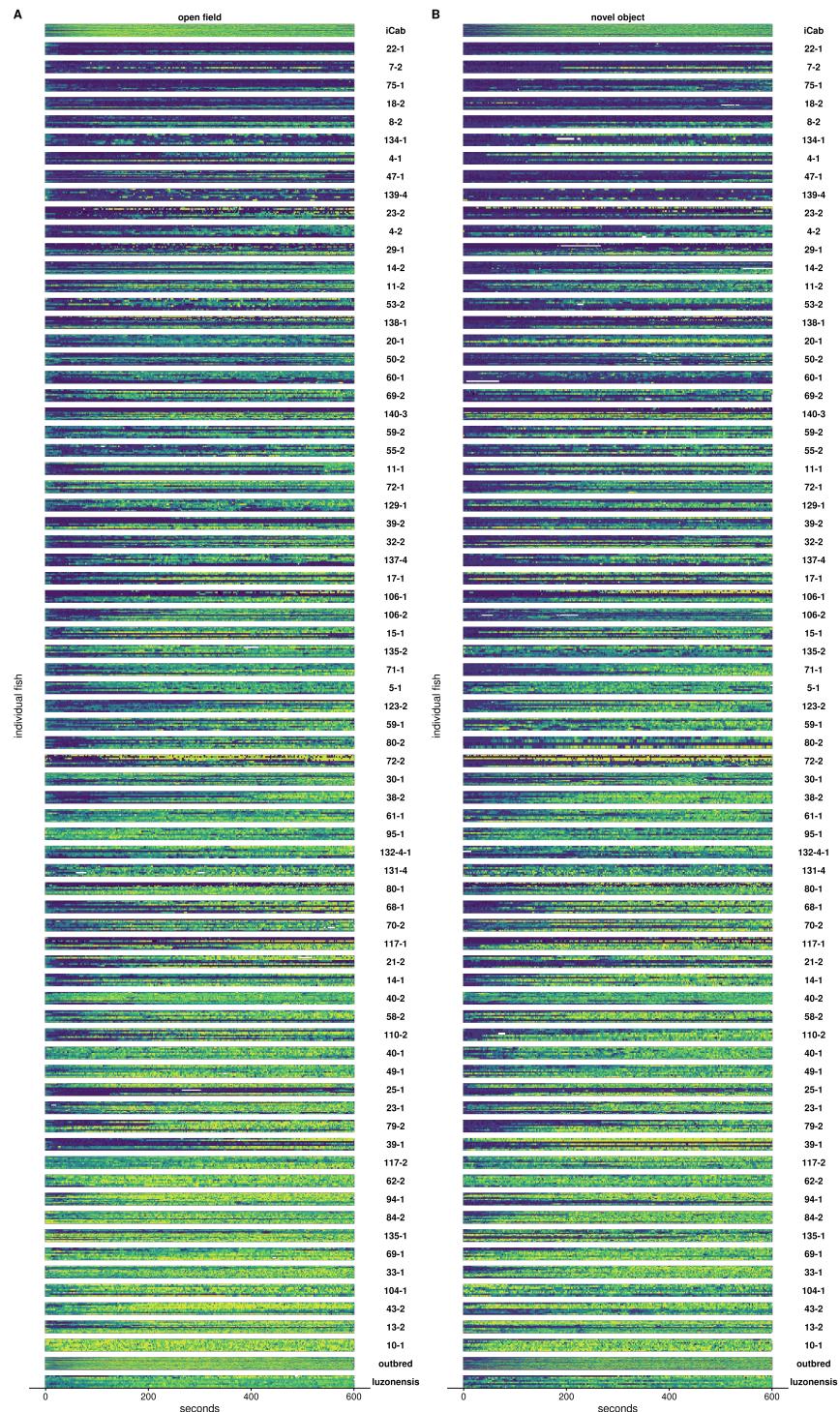


Figure B.1: Tile plot for all 1610 test fishes included in the MIKK panel behaviour analysis, ordered by each line's group median for individual mean speed over the course of the 20-minute video (open field and novel object combined). The order of lines is identical to that shown in **Figure 4.2**.

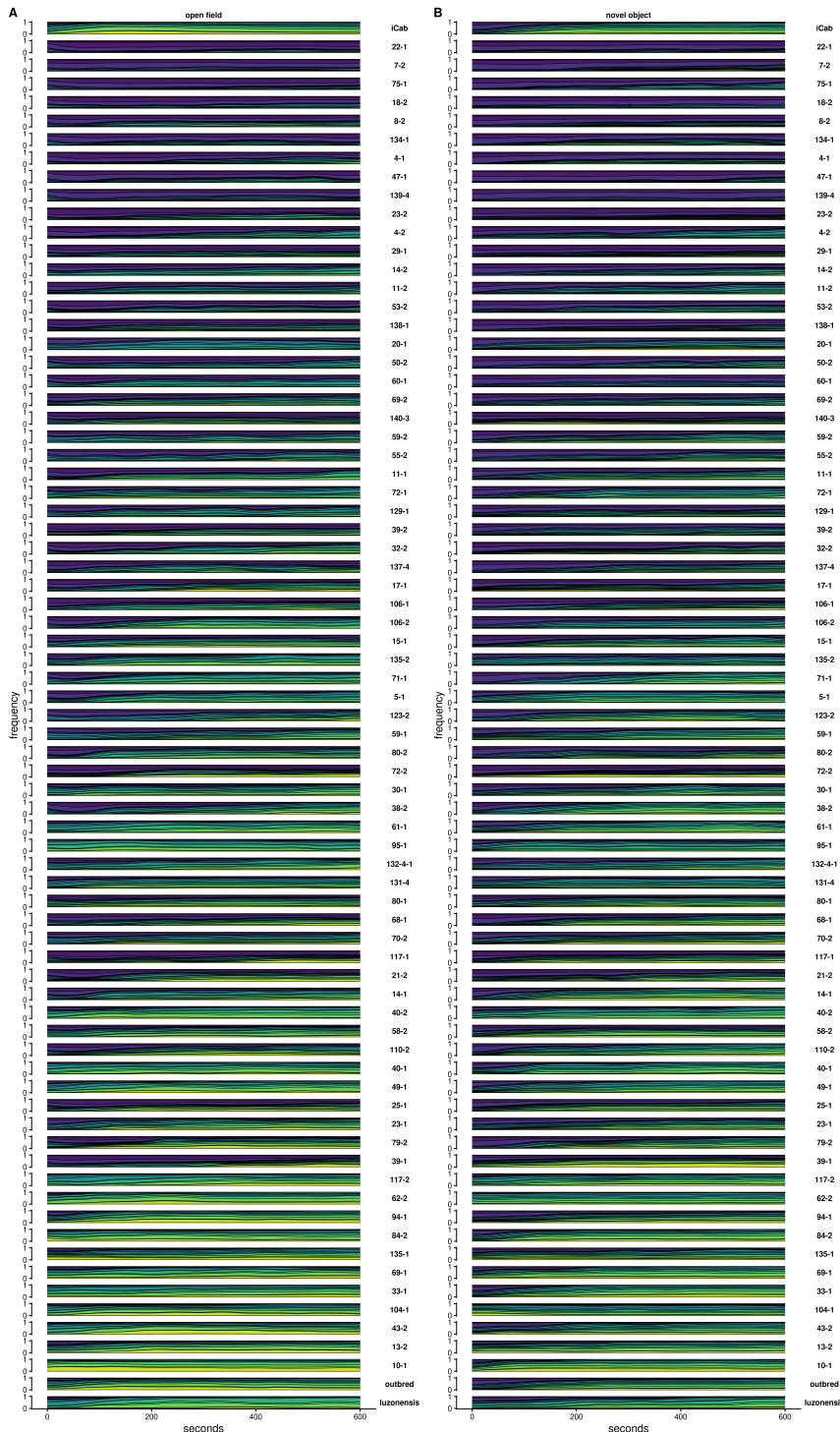


Figure B.2: Tile plot for all 1610 test fishes included in the MIKK panel behaviour analysis, ordered by each line's group median for individual mean speed over the course of the 20-minute video (open field and novel object combined). The order of lines is identical to that shown in **Figure 4.2**.

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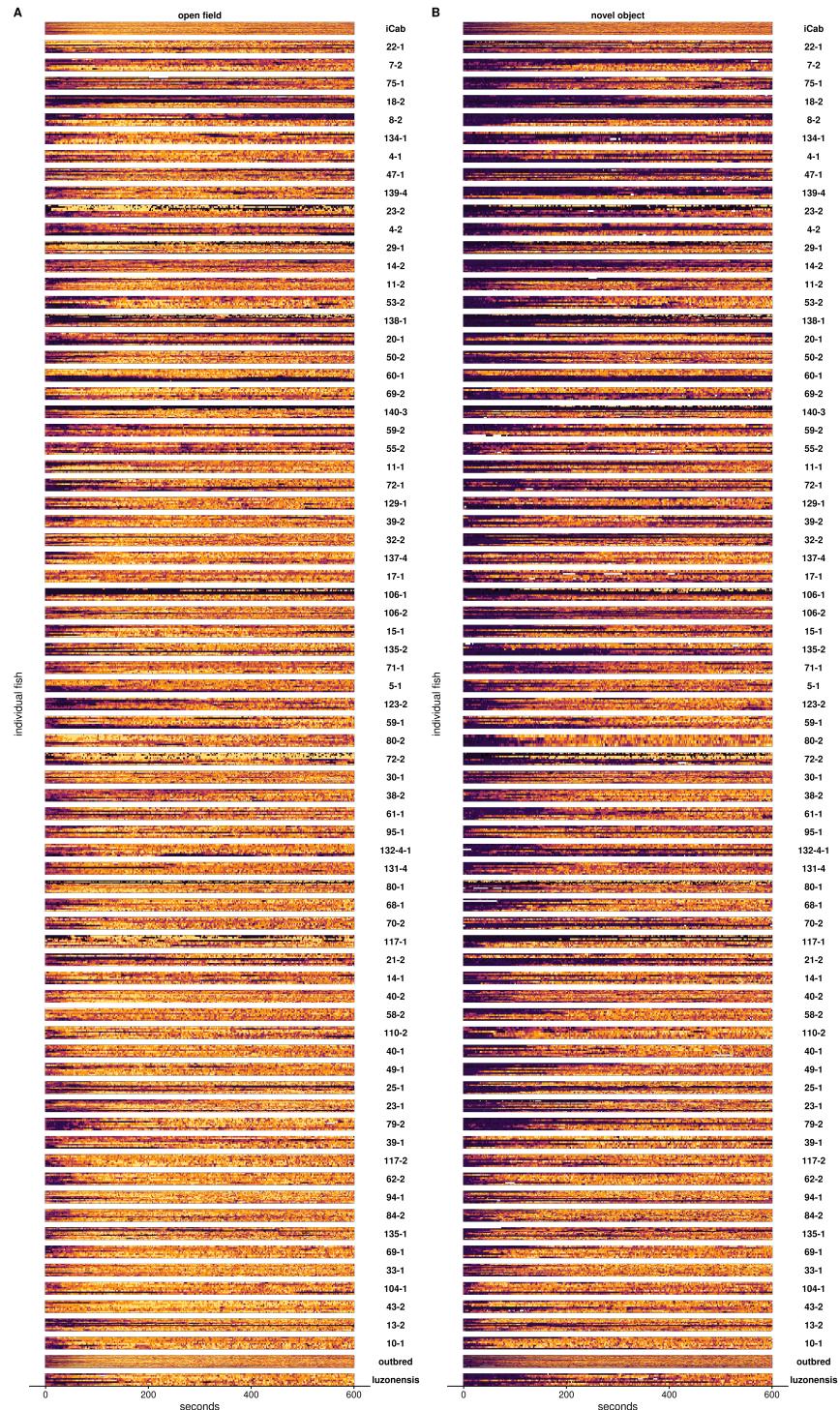


Figure B.3: Tile plot for all 1610 reference fishes included in the MIKK panel behaviour analysis, ordered by each line's group median for individual mean speed over the course of the 20-minute video (open field and novel object combined). The order of lines is identical to that shown in **Figure 4.2**.

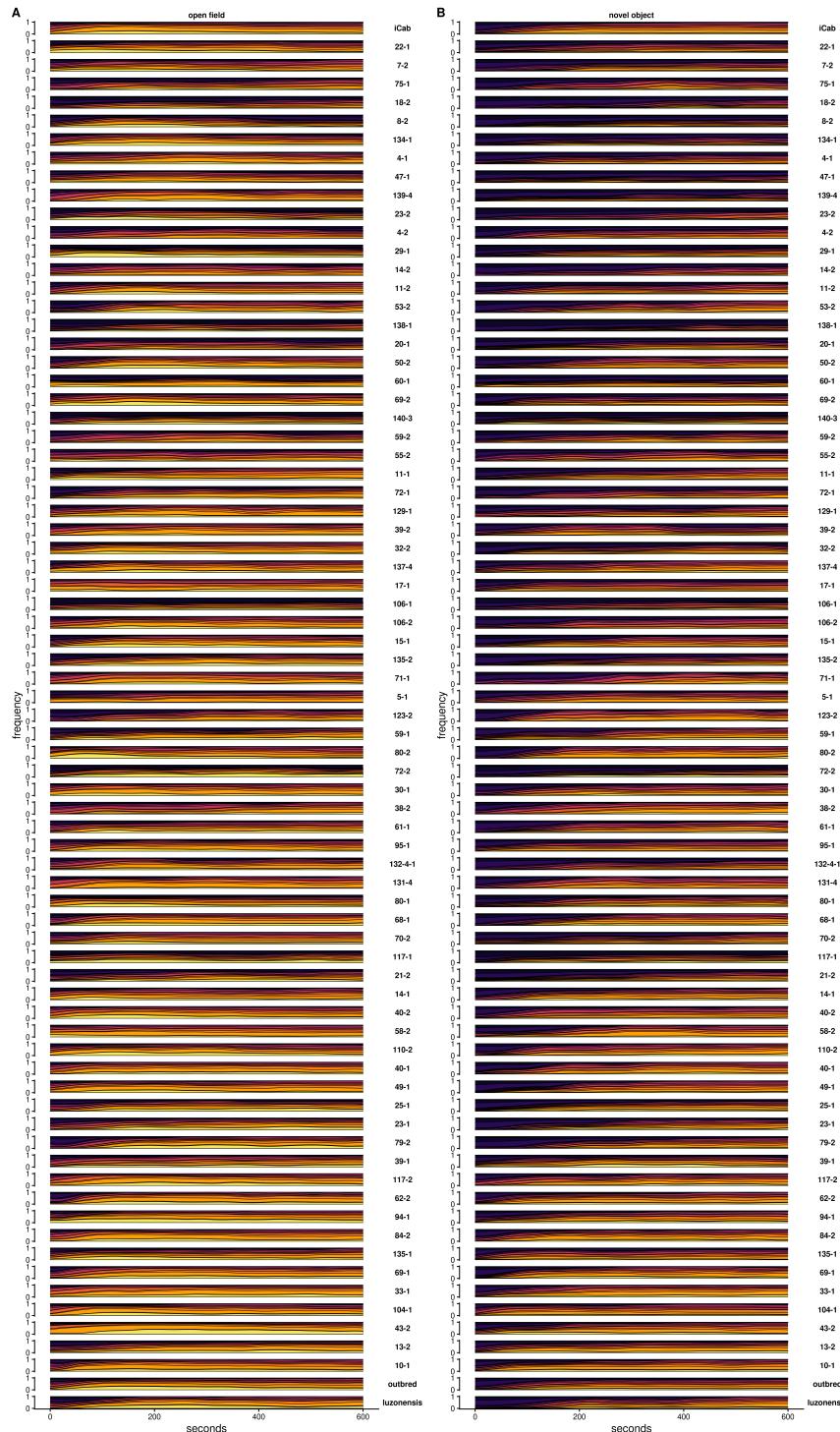


Figure B.4: Tile plot for all 1610 reference fishes included in the MIKK panel behaviour analysis, ordered by each line's group median for individual mean speed over the course of the 20-minute video (open field and novel object combined). The order of lines is identical to that shown in **Figure 4.2**.