Proof of Correctness

Total Correctness: Termination and Partial Correctness Partial Correctness: Loop invariants and induction

Loop Invariant: A property that holds before and after each iteration of a loop

Initialization: The loop invariant holds before the first iteration

Maintenance: If the loop invariant holds before an iteration, it holds after the iteration

Termination: When loop terminates, invariant gives useful property to show the algorithm is correct

Iterative: Usually loop invariants Recursive: Usually induction

Complexity

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a^{\log_b x} = x^{\log_b a}
\log_b x = \frac{\log_c x}{\log_c b}
\log_b M \cdot N = \log_b M + \log_b N
\log_b \frac{M}{N} = \log_b M - \log_b N
\log_b M^k = k \log_b M
Big Oh: f(n) is O(g(n)) if f(n) \leq cg(n) for n \geq n_0:
c, n_0 > 0
Big Omega: f(n) is \Omega(g(n)) if f(n) \ge cg(n) for n \ge n_0:
c, n_0 > 0
Big Theta: f(n) is \Theta(g(n)) if f(n) is O(g(n)) and f(n)
is \Omega(g(n))
Little Oh: Strict Big Oh
Little Omega: Strict Big Omega
\lim_{n\to\infty} \frac{f(n)}{g(n)}:
0 if f(n) is o(g(n)), \infty if f(n) is \omega(g(n))
<\infty if f(n) is O(g(n)), > 0 if f(n) is \Omega(g(n))
0 < \infty if f(n) is \Theta(g(n))
Growth Rates: 1 < \log(n) < \sqrt{n} < n < n \log(n) < n^2 <
n^c < 2^n < c^n < n! < n^n
Harmonic: \sum_{k=1}^{n} \frac{1}{k} \sim \ln n

Triangular: \sum_{k=1}^{n} k = \frac{n(n+1)}{2} \sim \frac{n^2}{2}

Squares: \sum_{k=1}^{n} k^2 \sim \frac{n^3}{3}
Geometric: \sum_{k=0}^{n} ar^k = \frac{a(r^{n+1}-1)}{r-1}
Stirling's Approximation: \log_2(n!) \sim n \log_2 n
Master's Theorem: T(n) = aT(\frac{n}{h}) + f(n), \epsilon > 0
f(n) = O(n^{\log_b(a) - \epsilon}) \to T(n) = \Theta(n^{\log_b a})
f(n) = \Theta(n^{\log_b a}) \to T(n) = \Theta(n^{\log_b a} \log n)
f(n) = \Omega(n^{\log_b(a)+\epsilon}) \wedge af(\frac{n}{b}) \leq cf(n) for some c < 1 \rightarrow
T(n) = \Theta(f(n))
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Divide and Conquer

Divide: Break problem into smaller subproblems Conquer/Combine: Solve subproblems recursively and combine

Recurrence Relation

A function defined in terms of itself Mirrors the recursive algorithm it represents Analysis of the running time of a divide and conquer algorithm generally involves solving a recurrence relation 1,2,3 Method

Merge Sort

$$\begin{array}{c|c|c} T(n) = 2T(\frac{n}{2}) + n - 1, \ T(1) = 0 \\ \hline \text{Level} & \text{Problem Size} & \text{Total Time} \\ \hline 0 & n & n \\ \hline 1 & \frac{n}{2} & 2\frac{n}{2} = n \\ 2 & \frac{n}{4} & 4\frac{n}{4} = n \\ \hline \vdots & \vdots & \vdots \\ k & \frac{n}{2^k} = 1 & 2^k \frac{n}{2^k} = n \\ \hline \rightarrow (\sum_{i=0}^{k-1} n) + 0 \cdot 2^{\log_2 n} \rightarrow \sum_{i=0}^{\log_2 n-1} n \rightarrow n \log_2 n \\ \text{or } \rightarrow \sum_{i=0}^k n \rightarrow \sum_{i=0}^{\log_2 n} n \rightarrow n \log_2 n \end{array}$$

Closest Pair

Dynamic Programming

Weighted Interval Scheduling

Memoization

Subset Sum/Knapsacks

Sequence Alignment

Bellman-Ford

Network Flow

Maximum Flow Problem

Ford-Fulkerson

Max Flow/Min Cut