# Practice Problem 10

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**Problem 1** — Assuming some Eps, which would require a higher value for MinPts: Identifying A&B as clusters, or identifying C&D as clusters?

#### Answer

 $C \ \& D$  would require a higher minimum points, as for any given radius, A & B have more points within it compared to C & D.

**Problem 2** — Using an Eps and MinPts that identifies C and D as clusters, what areas would be identified as noise? And how many total clusters would be found?

#### Answer

3

- (A, B, E)- would be considered one cluster as all the regions meet the threshold for a cluster.
- (C)- meets threshold for cluster.
- (D)- meets threshold for cluster.

F isn't part of a cluster, as the region isn't dense enough, so it'll be considered noise.

**Problem 3** — Using an Eps and MinPts that identifies A and B as clusters, what areas would be identified as noise? And how many total clusters would be found?

#### Answer

2

- (A)- meets threshold for cluster.
- (B)- meets threshold for cluster.
- C, D, E, F- All considered noise as the regions aren't dense enough for the points to be clustered.