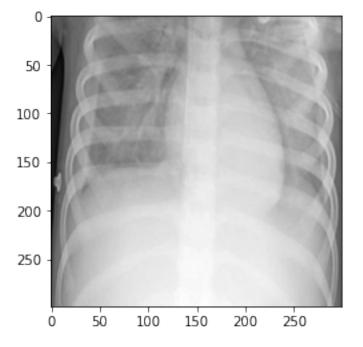
Experimento 4

```
[1]: import torch
     import torch.nn as nn
     import torchvision
     import torchvision.transforms as transform
     import torch.nn.functional as F
     import matplotlib.pyplot as plt
     import numpy as np
     import math
     device = torch.device('cuda:0' if torch.cuda.is_available() else 'cpu')
     #device='cpu'
     print(device)
     batch_size = 32
     img_transform = transform.Compose([transform.ToTensor(), transform.Normalize((0.))
      \rightarrow 5,),(0.5,))])
     data = torchvision.datasets.ImageFolder("C:/Users/matia/Desktop/AI_UTEC/
      →proyecto5/fotos",transform=img_transform)
     print(len(data))
     train_set,test_set=torch.utils.data.random_split(data,[14815,6350],_
      →generator=torch.Generator().manual_seed(0))
     val_set,test_set=torch.utils.data.random_split(test_set,[4233,2117],_
      →generator=torch.Generator().manual_seed(0))
     img, _ = train_set[0]
     print(img.shape)
     train_loader = torch.utils.data.DataLoader(dataset=train_set,_
      →batch_size=batch_size, shuffle=True)
     test_loader = torch.utils.data.DataLoader(dataset=test_set,__
      →batch_size=batch_size, shuffle=False)
```

```
val_loader = torch.utils.data.DataLoader(dataset=val_set, batch_size=batch_size,_
      ⇒shuffle=False)
    cuda:0
    21165
    torch.Size([3, 299, 299])
[2]: def show_img(img):
         plt.imshow(img.numpy()[0], cmap='gray')
[3]: print(len(train_set))
     print(len(test_set))
     print(len(val_set))
    14815
    2117
    4233
[4]: img, label = train_set[999]
     print(label)
     show_img(img)
```

3



```
[5]: #hyperparametros
num_classes = 4
learning_rate = 0.01
```

```
class CNN(nn.Module):
         def __init__(self, num_classes=4):
             super(CNN, self).__init__()
             self.layer1 = nn.Sequential(
                 nn.Conv2d(in_channels=3, out_channels=16, kernel_size=10,__
      ⇒stride=1,padding=0),
                 nn.ReLU(),nn.BatchNorm2d(16))
             self.layer2 = nn.Sequential(
                 nn.Conv2d(in_channels=16,out_channels=32, kernel_size=6, stride=1,_
      →padding=2),
                 nn.ReLU(),
                 nn.MaxPool2d(kernel_size=2, stride=2),nn.BatchNorm2d(32))
             self.layer3 = nn.Sequential(
                 nn.Conv2d(in_channels=32, out_channels=64, kernel_size=3, stride=1,_
      →padding=2),
                 nn.ReLU(),
                 nn.MaxPool2d(kernel_size=2, stride=2),nn.BatchNorm2d(64))
             self.layer4 = nn.Sequential(
                 nn.Conv2d(in_channels=64, out_channels=128, kernel_size=3, stride=1,_
      →padding=2),
                 nn.ReLU(),
                 nn.MaxPool2d(kernel_size=2, stride=2),nn.BatchNorm2d(128))
             self.fc = nn.Linear(37*37*128, num_classes)
         def forward(self, x):
             out = self.layer1(x)
             out = self.layer2(out)
             out = self.layer3(out)
             out = self.layer4(out)
             out = out.reshape(out.size(0), -1)
             out = self.fc(out)
             return out
[6]: model
                 = CNN(num_classes).to(device)
     loss_fn
                 = nn.CrossEntropyLoss()
     optimizer
                 = torch.optim.Adam(model.parameters(), lr = learning_rate)
     #loss_train = train(model, optimizer, loss_fn, num_epochs)
     #test(model)
     print([ e.shape for e in model.fc.parameters()])
     model.fc.weight
    [torch.Size([4, 175232]), torch.Size([4])]
```

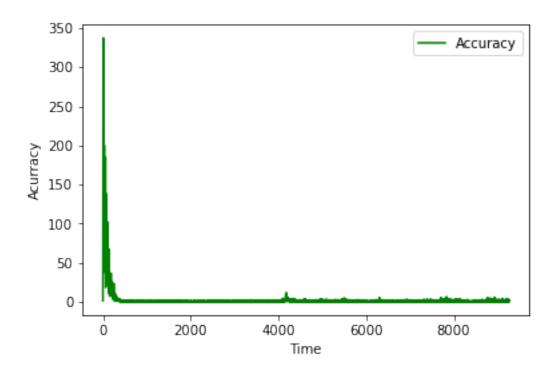
 $num_epochs = 20$

```
[6]: Parameter containing:
     tensor([[-0.0010, 0.0014, 0.0012, ..., -0.0020, -0.0016, -0.0003],
             [0.0003, -0.0015, 0.0016, \dots, -0.0008, -0.0013, -0.0018],
             [-0.0012, -0.0020, 0.0020, \dots, -0.0013, -0.0021, 0.0021],
             [-0.0023, -0.0016, -0.0015, \ldots, -0.0010, 0.0003, 0.0005]],
            device='cuda:0', requires_grad=True)
[7]: def train(model, optimizer, loos_fn, num_epochs):
         loss_vals = []
         running_loss =0.0
         # train the model
         total_step = len(train_loader)
         list_loss= []
         list_time = []
         j=0
         for epoch in range(num_epochs):
             for i, (images, labels) in enumerate(train_loader):
                 images = images.to(device)
                 labels = labels.to(device)
                 # forward
                 output = model(images)
                 loss = loss_fn(output, labels)
                 # change the params
                 optimizer.zero_grad()
                 loss.backward()
                 optimizer.step()
                 list_loss.append(loss.item())
                 list_time.append(j)
                 j+=1
                 #print(i, end=", ")
                 if (i+1) \% 100 == 0:
                     #print()
                     print ('Epoch [{}/{}], Step [{}/{}], Loss: {:.4f}' .
      →format(epoch+1, num_epochs, i+1, total_step, loss.item()))
         print('Finished Training Trainset')
         return list_loss,list_time
[8]: list_loss, list_time=train(model, optimizer, loss_fn, num_epochs)
     plt.plot(list_time,list_loss,color="green", label="Accuracy")
     plt.legend()
     plt.xlabel("Time")
     plt.ylabel("Accuracy")
```

plt.show()

```
Epoch [1/20], Step [100/463], Loss: 26.5680
Epoch [1/20], Step [200/463], Loss: 17.9783
Epoch [1/20], Step [300/463], Loss: 4.2819
Epoch [1/20], Step [400/463], Loss: 0.7125
Epoch [2/20], Step [100/463], Loss: 0.4105
Epoch [2/20], Step [200/463], Loss: 0.6548
Epoch [2/20], Step [300/463], Loss: 0.3909
Epoch [2/20], Step [400/463], Loss: 0.8094
Epoch [3/20], Step [100/463], Loss: 0.3243
Epoch [3/20], Step [200/463], Loss: 0.3466
Epoch [3/20], Step [300/463], Loss: 0.6585
Epoch [3/20], Step [400/463], Loss: 1.0781
Epoch [4/20], Step [100/463], Loss: 0.3112
Epoch [4/20], Step [200/463], Loss: 0.4940
Epoch [4/20], Step [300/463], Loss: 0.5900
Epoch [4/20], Step [400/463], Loss: 0.1904
Epoch [5/20], Step [100/463], Loss: 0.5739
Epoch [5/20], Step [200/463], Loss: 0.6155
Epoch [5/20], Step [300/463], Loss: 0.3001
Epoch [5/20], Step [400/463], Loss: 0.3333
Epoch [6/20], Step [100/463], Loss: 0.5945
Epoch [6/20], Step [200/463], Loss: 0.2525
Epoch [6/20], Step [300/463], Loss: 0.8553
Epoch [6/20], Step [400/463], Loss: 0.6627
Epoch [7/20], Step [100/463], Loss: 0.4400
Epoch [7/20], Step [200/463], Loss: 0.6392
Epoch [7/20], Step [300/463], Loss: 1.1934
Epoch [7/20], Step [400/463], Loss: 0.1875
Epoch [8/20], Step [100/463], Loss: 0.7594
Epoch [8/20], Step [200/463], Loss: 0.5291
Epoch [8/20], Step [300/463], Loss: 0.7889
Epoch [8/20], Step [400/463], Loss: 0.6325
Epoch [9/20], Step [100/463], Loss: 0.1640
Epoch [9/20], Step [200/463], Loss: 1.0866
Epoch [9/20], Step [300/463], Loss: 0.9030
Epoch [9/20], Step [400/463], Loss: 1.5918
Epoch [10/20], Step [100/463], Loss: 0.7051
Epoch [10/20], Step [200/463], Loss: 2.0270
Epoch [10/20], Step [300/463], Loss: 0.2571
Epoch [10/20], Step [400/463], Loss: 1.0388
Epoch [11/20], Step [100/463], Loss: 0.2761
Epoch [11/20], Step [200/463], Loss: 0.6677
Epoch [11/20], Step [300/463], Loss: 0.7748
Epoch [11/20], Step [400/463], Loss: 0.7447
Epoch [12/20], Step [100/463], Loss: 1.9397
Epoch [12/20], Step [200/463], Loss: 1.0744
```

```
Epoch [12/20], Step [300/463], Loss: 0.2082
Epoch [12/20], Step [400/463], Loss: 2.4821
Epoch [13/20], Step [100/463], Loss: 1.6145
Epoch [13/20], Step [200/463], Loss: 1.7571
Epoch [13/20], Step [300/463], Loss: 1.2336
Epoch [13/20], Step [400/463], Loss: 1.3819
Epoch [14/20], Step [100/463], Loss: 0.5558
Epoch [14/20], Step [200/463], Loss: 1.9162
Epoch [14/20], Step [300/463], Loss: 0.7344
Epoch [14/20], Step [400/463], Loss: 0.0889
Epoch [15/20], Step [100/463], Loss: 0.6145
Epoch [15/20], Step [200/463], Loss: 0.2542
Epoch [15/20], Step [300/463], Loss: 0.3374
Epoch [15/20], Step [400/463], Loss: 1.1852
Epoch [16/20], Step [100/463], Loss: 0.4219
Epoch [16/20], Step [200/463], Loss: 0.5924
Epoch [16/20], Step [300/463], Loss: 0.4941
Epoch [16/20], Step [400/463], Loss: 0.7897
Epoch [17/20], Step [100/463], Loss: 1.4301
Epoch [17/20], Step [200/463], Loss: 1.1623
Epoch [17/20], Step [300/463], Loss: 4.7026
Epoch [17/20], Step [400/463], Loss: 0.3348
Epoch [18/20], Step [100/463], Loss: 0.2741
Epoch [18/20], Step [200/463], Loss: 0.6788
Epoch [18/20], Step [300/463], Loss: 0.8928
Epoch [18/20], Step [400/463], Loss: 0.2067
Epoch [19/20], Step [100/463], Loss: 0.1447
Epoch [19/20], Step [200/463], Loss: 0.0273
Epoch [19/20], Step [300/463], Loss: 0.6088
Epoch [19/20], Step [400/463], Loss: 1.0564
Epoch [20/20], Step [100/463], Loss: 1.4888
Epoch [20/20], Step [200/463], Loss: 1.6213
Epoch [20/20], Step [300/463], Loss: 0.9583
Epoch [20/20], Step [400/463], Loss: 0.8872
Finished Training Trainset
```



```
[9]: with torch.no_grad():
         correct = 0
         total = 0
         for images, labels in test_loader:
             images = images.to(device)
             labels = labels.to(device)
             outputs = model(images)
             _, predicted = torch.max(outputs.data, 1)
             total += labels.size(0)
             correct += (predicted == labels).sum().item()
         print("Test Accuracy",correct / total)
         correct = 0
         total = 0
         for images, labels in val_loader:
             images = images.to(device)
             labels = labels.to(device)
             outputs = model(images)
             _, predicted = torch.max(outputs.data, 1)
             total += labels.size(0)
             correct += (predicted == labels).sum().item()
```

```
print("Validation Accuracy",correct / total)

correct = 0
total = 0

for images, labels in train_loader:
    images = images.to(device)
    labels = labels.to(device)
    outputs = model(images)
    _, predicted = torch.max(outputs.data, 1)
    total += labels.size(0)
    correct += (predicted == labels).sum().item()

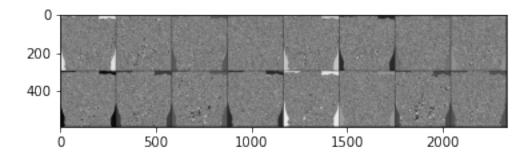
print("Train Accuracy",correct / total)
```

Test Accuracy 0.8375059045819556 Validation Accuracy 0.8230569336168202 Train Accuracy 0.9561930475869052

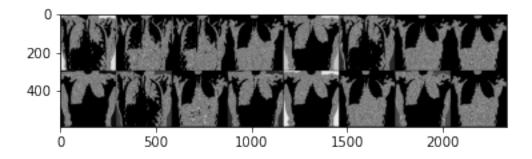
```
[16]: def Show(out, title = ''):
          print(title)
          out = out.permute(1,0,2,3)
          grilla = torchvision.utils.make_grid(out)
          plt.imshow(transform.ToPILImage()(grilla), 'jet')
          plt.show()
      def Show_Weight(out):
          grilla = torchvision.utils.make_grid(out)
          plt.imshow(transform.ToPILImage()(grilla), 'jet')
          plt.show()
      with torch.no_grad():
          model.to('cpu')
          img, label = test_set[456]
          img = img.unsqueeze(0)
          out = model(img)
          print(out)
          print ((out == out.max()).nonzero())
          out = model.layer1[0](img)
          Show(out, 'layer 1: Convolution output')
          out = model.layer1[1](out)
          Show(out, 'layer 1: Activation function output')
```

```
out = model.layer2[0](out)
Show(out, 'layer 2: Convolution output')
out = model.layer2[1](out)
Show(out, 'layer 2: Activation function output')
out = model.layer2[2](out)
Show(out, 'layer 2: Max-Pooling')
out = model.layer3[0](out)
Show(out, 'layer 3: Convolution output')
out = model.layer3[1](out)
Show(out, 'layer 3: Activation function output')
out = model.layer3[2](out)
Show(out, 'layer 3: Max-Pooling')
out = model.layer4[0](out)
Show(out, 'layer 4: Convolution output')
out = model.layer4[1](out)
Show(out, 'layer 4: Activation function output')
out = model.layer4[2](out)
Show(out, 'layer 4: Max-Pooling')
```

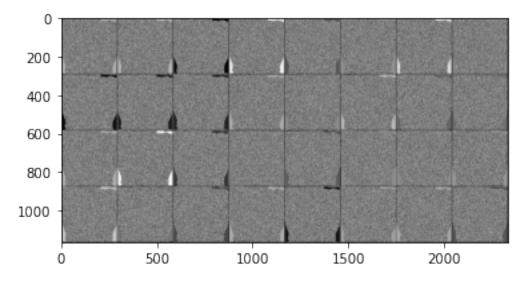
```
tensor([[-59.4509, 22.0876, 24.1623, -76.1220]])
tensor([[0, 2]])
layer 1: Convolution output
```



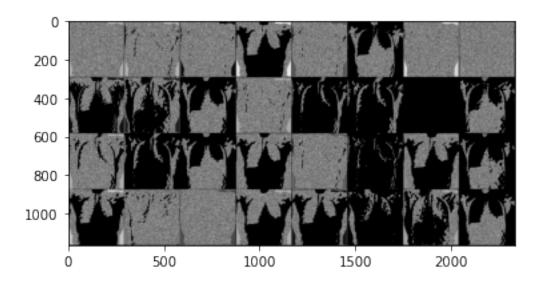
layer 1: Activation function output



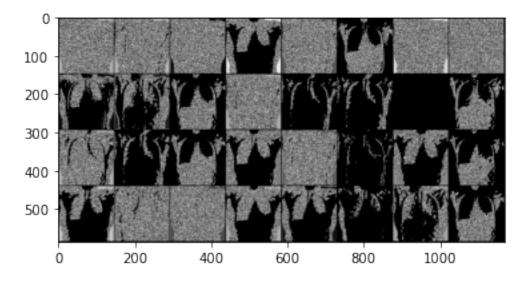
layer 2: Convolution output



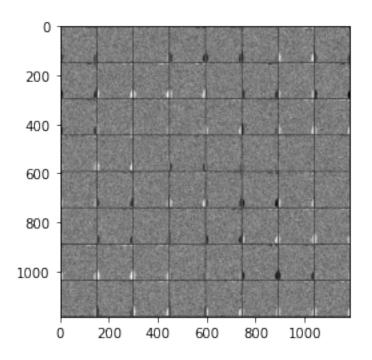
layer 2: Activation function output



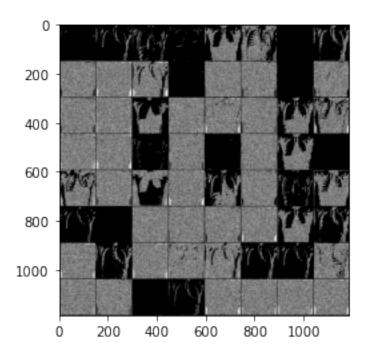
layer 2: Max-Pooling



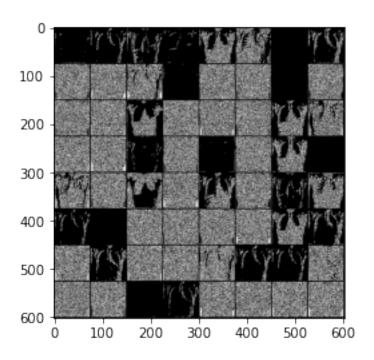
layer 3: Convolution output



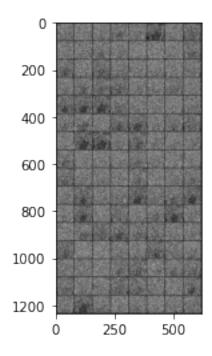
layer 3: Activation function output



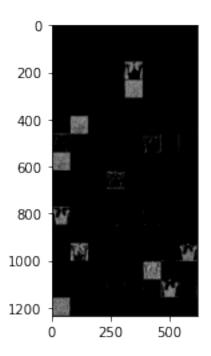
layer 3: Max-Pooling



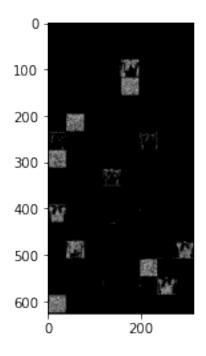
layer 4: Convolution output



layer 4: Activation function output



layer 4: Max-Pooling



[]: