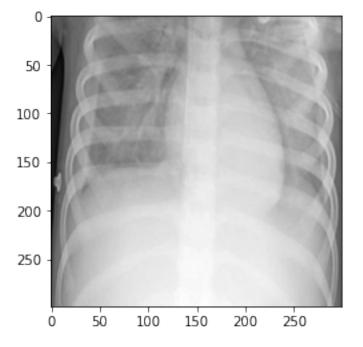
Experimento 2

```
[1]: import torch
     import torch.nn as nn
     import torchvision
     import torchvision.transforms as transform
     import torch.nn.functional as F
     import matplotlib.pyplot as plt
     import numpy as np
     import math
     device = torch.device('cuda:0' if torch.cuda.is_available() else 'cpu')
     #device='cpu'
     print(device)
     batch_size = 32
     img_transform = transform.Compose([transform.ToTensor(), transform.Normalize((0.))
      \rightarrow 5,),(0.5,))])
     data = torchvision.datasets.ImageFolder("C:/Users/matia/Desktop/AI_UTEC/
      →proyecto5/fotos",transform=img_transform)
     print(len(data))
     train_set,test_set=torch.utils.data.random_split(data,[14815,6350],_
      →generator=torch.Generator().manual_seed(0))
     val_set,test_set=torch.utils.data.random_split(test_set,[4233,2117],_
      →generator=torch.Generator().manual_seed(0))
     img, _ = train_set[0]
     print(img.shape)
     train_loader = torch.utils.data.DataLoader(dataset=train_set,_
      →batch_size=batch_size, shuffle=True)
     test_loader = torch.utils.data.DataLoader(dataset=test_set,__
      →batch_size=batch_size, shuffle=False)
```

```
val_loader = torch.utils.data.DataLoader(dataset=val_set, batch_size=batch_size,_
      ⇒shuffle=False)
    cuda:0
    21165
    torch.Size([3, 299, 299])
[2]: def show_img(img):
         plt.imshow(img.numpy()[0], cmap='gray')
[3]: print(len(train_set))
     print(len(test_set))
     print(len(val_set))
    14815
    2117
    4233
[4]: img, label = train_set[999]
     print(label)
     show_img(img)
```

3



```
[5]: #hyperparametros
num_classes = 4
learning_rate = 0.01
```

```
num_epochs = 20
     class CNN(nn.Module):
         def __init__(self, num_classes=4):
             super(CNN, self).__init__()
             self.layer1 = nn.Sequential(
                 nn.Conv2d(in_channels=3, out_channels=16, kernel_size=10,__

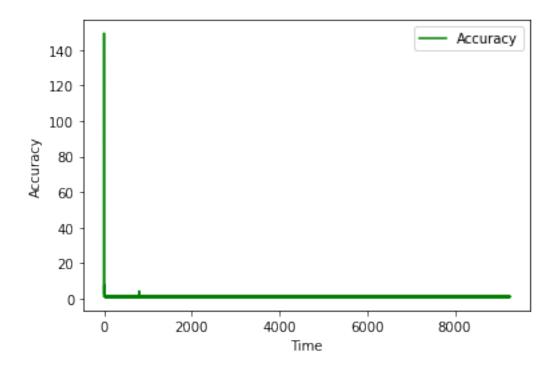
stride=1,padding=0),
                 nn.ReLU())
             self.layer2 = nn.Sequential(
                 nn.Conv2d(in_channels=16,out_channels=32, kernel_size=6, stride=1,_u
      →padding=2),
                 nn.ReLU(),
                 nn.MaxPool2d(kernel_size=2, stride=2))
             self.layer3 = nn.Sequential(
                 nn.Conv2d(in_channels=32, out_channels=64, kernel_size=3, stride=1,_
      →padding=2),
                 nn.ReLU(),
                 nn.MaxPool2d(kernel_size=2, stride=2))
             self.layer4 = nn.Sequential(
                 nn.Conv2d(in_channels=64, out_channels=128, kernel_size=3, stride=1,_
      →padding=2),
                 nn.ReLU(),
                 nn.MaxPool2d(kernel_size=2, stride=2))
             self.fc = nn.Linear(37*37*128, num_classes)
         def forward(self, x):
             out = self.layer1(x)
             out = self.layer2(out)
             out = self.layer3(out)
             out = self.layer4(out)
             out = out.reshape(out.size(0), -1)
             out = self.fc(out)
             return out
[6]: model
                 = CNN(num_classes).to(device)
     loss_fn
                  = nn.CrossEntropyLoss()
     optimizer
                 = torch.optim.Adam(model.parameters(), lr = learning_rate)
     #loss_train = train(model, optimizer, loss_fn, num_epochs)
     #test(model)
     print([ e.shape for e in model.fc.parameters()])
     model.fc.weight
```

[torch.Size([4, 175232]), torch.Size([4])]

```
[6]: Parameter containing:
     tensor([[ 1.9060e-03, 3.4415e-04, 5.2328e-05, ..., 1.2915e-03,
               6.0591e-04, -6.3812e-04],
             [1.5982e-03, -1.6400e-03, -6.5031e-04, ..., 1.3073e-03,
              -2.1961e-05, -2.3485e-03],
             [-1.5196e-04, 1.0452e-03, -5.0353e-04, ..., 1.4927e-03,
               6.5300e-04, 2.0211e-03],
             [-1.9493e-03, -1.5882e-04, -2.2413e-03, ..., -6.4911e-04,
              -1.4299e-03, -1.0236e-03]], device='cuda:0', requires_grad=True)
[7]: def train(model, optimizer, loos_fn, num_epochs):
         loss_vals = []
         running_loss =0.0
         # train the model
         total_step = len(train_loader)
         list_loss= []
         list_time = []
         j=0
         for epoch in range(num_epochs):
             for i, (images, labels) in enumerate(train_loader):
                 images = images.to(device)
                 labels = labels.to(device)
                 # forward
                 output = model(images)
                 loss = loss_fn(output, labels)
                 # change the params
                 optimizer.zero_grad()
                 loss.backward()
                 optimizer.step()
                 list_loss.append(loss.item())
                 list_time.append(j)
                 j+=1
                 #print(i, end=", ")
                 if (i+1) \% 100 == 0:
                     #print()
                     print ('Epoch [{}/{}], Step [{}/{}], Loss: {:.4f}' .
      →format(epoch+1, num_epochs, i+1, total_step, loss.item()))
         print('Finished Training Trainset')
         return list_loss,list_time
[8]: list_loss, list_time=train(model, optimizer, loss_fn, num_epochs)
     plt.plot(list_time,list_loss,color="green", label="Accuracy")
```

```
plt.legend()
plt.xlabel("Time")
plt.ylabel("Accuracy")
plt.show()
Epoch [1/20], Step [100/463], Loss: 1.2170
Epoch [1/20], Step [200/463], Loss: 1.1619
Epoch [1/20], Step [300/463], Loss: 1.2960
Epoch [1/20], Step [400/463], Loss: 1.1681
Epoch [2/20], Step [100/463], Loss: 1.0581
Epoch [2/20], Step [200/463], Loss: 1.0721
Epoch [2/20], Step [300/463], Loss: 1.3485
Epoch [2/20], Step [400/463], Loss: 1.0444
Epoch [3/20], Step [100/463], Loss: 1.1047
Epoch [3/20], Step [200/463], Loss: 1.0933
Epoch [3/20], Step [300/463], Loss: 1.0818
Epoch [3/20], Step [400/463], Loss: 1.3065
Epoch [4/20], Step [100/463], Loss: 1.1350
Epoch [4/20], Step [200/463], Loss: 1.1389
Epoch [4/20], Step [300/463], Loss: 1.0255
Epoch [4/20], Step [400/463], Loss: 1.2788
Epoch [5/20], Step [100/463], Loss: 1.1458
Epoch [5/20], Step [200/463], Loss: 1.1862
Epoch [5/20], Step [300/463], Loss: 1.1572
Epoch [5/20], Step [400/463], Loss: 1.1031
Epoch [6/20], Step [100/463], Loss: 1.1641
Epoch [6/20], Step [200/463], Loss: 1.2140
Epoch [6/20], Step [300/463], Loss: 1.1591
Epoch [6/20], Step [400/463], Loss: 1.2148
Epoch [7/20], Step [100/463], Loss: 1.0920
Epoch [7/20], Step [200/463], Loss: 1.2884
Epoch [7/20], Step [300/463], Loss: 1.1501
Epoch [7/20], Step [400/463], Loss: 1.2383
Epoch [8/20], Step [100/463], Loss: 1.1200
Epoch [8/20], Step [200/463], Loss: 1.1371
Epoch [8/20], Step [300/463], Loss: 1.1676
Epoch [8/20], Step [400/463], Loss: 1.1040
Epoch [9/20], Step [100/463], Loss: 1.3566
Epoch [9/20], Step [200/463], Loss: 1.1848
Epoch [9/20], Step [300/463], Loss: 1.1364
Epoch [9/20], Step [400/463], Loss: 1.2150
Epoch [10/20], Step [100/463], Loss: 0.9769
Epoch [10/20], Step [200/463], Loss: 1.2156
Epoch [10/20], Step [300/463], Loss: 1.2124
Epoch [10/20], Step [400/463], Loss: 1.1565
Epoch [11/20], Step [100/463], Loss: 1.1831
Epoch [11/20], Step [200/463], Loss: 1.2134
Epoch [11/20], Step [300/463], Loss: 1.1297
```

```
Epoch [11/20], Step [400/463], Loss: 1.1836
Epoch [12/20], Step [100/463], Loss: 1.0867
Epoch [12/20], Step [200/463], Loss: 1.2105
Epoch [12/20], Step [300/463], Loss: 1.2926
Epoch [12/20], Step [400/463], Loss: 1.2141
Epoch [13/20], Step [100/463], Loss: 1.1525
Epoch [13/20], Step [200/463], Loss: 1.0914
Epoch [13/20], Step [300/463], Loss: 1.2012
Epoch [13/20], Step [400/463], Loss: 1.1652
Epoch [14/20], Step [100/463], Loss: 1.3184
Epoch [14/20], Step [200/463], Loss: 1.1367
Epoch [14/20], Step [300/463], Loss: 1.4085
Epoch [14/20], Step [400/463], Loss: 1.1453
Epoch [15/20], Step [100/463], Loss: 1.1277
Epoch [15/20], Step [200/463], Loss: 1.2675
Epoch [15/20], Step [300/463], Loss: 1.1358
Epoch [15/20], Step [400/463], Loss: 1.2266
Epoch [16/20], Step [100/463], Loss: 1.1988
Epoch [16/20], Step [200/463], Loss: 1.3594
Epoch [16/20], Step [300/463], Loss: 1.1721
Epoch [16/20], Step [400/463], Loss: 1.3141
Epoch [17/20], Step [100/463], Loss: 1.1503
Epoch [17/20], Step [200/463], Loss: 1.0854
Epoch [17/20], Step [300/463], Loss: 1.1865
Epoch [17/20], Step [400/463], Loss: 1.2475
Epoch [18/20], Step [100/463], Loss: 1.2370
Epoch [18/20], Step [200/463], Loss: 1.1041
Epoch [18/20], Step [300/463], Loss: 1.1687
Epoch [18/20], Step [400/463], Loss: 1.2607
Epoch [19/20], Step [100/463], Loss: 1.2816
Epoch [19/20], Step [200/463], Loss: 1.1843
Epoch [19/20], Step [300/463], Loss: 1.2922
Epoch [19/20], Step [400/463], Loss: 1.0686
Epoch [20/20], Step [100/463], Loss: 1.0100
Epoch [20/20], Step [200/463], Loss: 1.4263
Epoch [20/20], Step [300/463], Loss: 1.2155
Epoch [20/20], Step [400/463], Loss: 1.0680
Finished Training Trainset
```



```
[9]: with torch.no_grad():
         correct = 0
         total = 0
         for images, labels in test_loader:
             images = images.to(device)
             labels = labels.to(device)
             outputs = model(images)
             _, predicted = torch.max(outputs.data, 1)
             total += labels.size(0)
             correct += (predicted == labels).sum().item()
         print("Test Accuracy",correct / total)
         correct = 0
         total = 0
         for images, labels in val_loader:
             images = images.to(device)
             labels = labels.to(device)
             outputs = model(images)
             _, predicted = torch.max(outputs.data, 1)
             total += labels.size(0)
             correct += (predicted == labels).sum().item()
```

```
print("Validation Accuracy",correct / total)

correct = 0
total = 0

for images, labels in train_loader:
    images = images.to(device)
    labels = labels.to(device)
    outputs = model(images)
    _, predicted = torch.max(outputs.data, 1)
    total += labels.size(0)
    correct += (predicted == labels).sum().item()

print("Train Accuracy",correct / total)
```

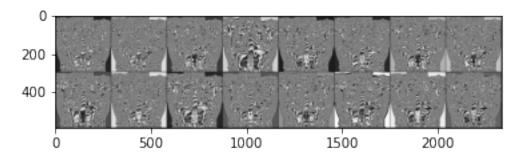
Test Accuracy 0.485592820028342 Validation Accuracy 0.4899598393574297 Train Accuracy 0.4785690178872764

```
[10]: def Show(out, title = ''):
          print(title)
          out = out.permute(1,0,2,3)
          grilla = torchvision.utils.make_grid(out)
          plt.imshow(transform.ToPILImage()(grilla), 'jet')
          plt.show()
      def Show_Weight(out):
          grilla = torchvision.utils.make_grid(out)
          plt.imshow(transform.ToPILImage()(grilla), 'jet')
          plt.show()
      with torch.no_grad():
          model.to('cpu')
          img, label = test_set[456]
          img = img.unsqueeze(0)
          out = model(img)
          print(out)
          print ((out == out.max()).nonzero())
          out = model.layer1[0](img)
          Show(out, 'layer 1: Convolution output')
          out = model.layer1[1](out)
          Show(out, 'layer 1: Activation function output')
```

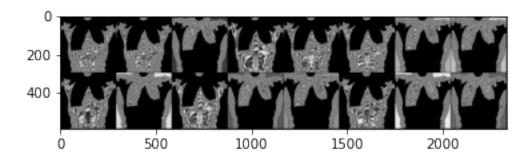
```
out = model.layer2[0](out)
Show(out, 'layer 2: Convolution output')
out = model.layer2[1](out)
Show(out, 'layer 2: Activation function output')
out = model.layer2[2](out)
Show(out, 'layer 2: Max-Pooling')
out = model.layer3[0](out)
Show(out, 'layer 3: Convolution output')
out = model.layer3[1](out)
Show(out, 'layer 3: Activation function output')
out = model.layer3[2](out)
Show(out, 'layer 3: Max-Pooling')
out = model.layer4[0](out)
Show(out, 'layer 4: Convolution output')
out = model.layer4[1](out)
Show(out, 'layer 4: Activation function output')
out = model.layer4[2](out)
Show(out, 'layer 4: Max-Pooling')
```

```
tensor([[-0.2828, 0.1994, 0.6836, -1.3067]])
tensor([[0, 2]])
```

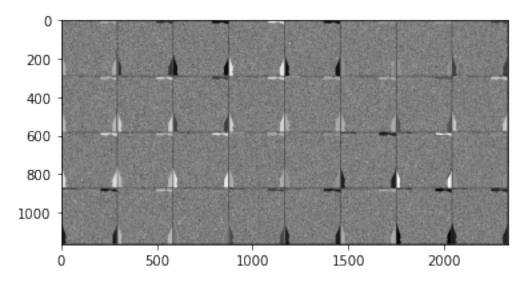
layer 1: Convolution output



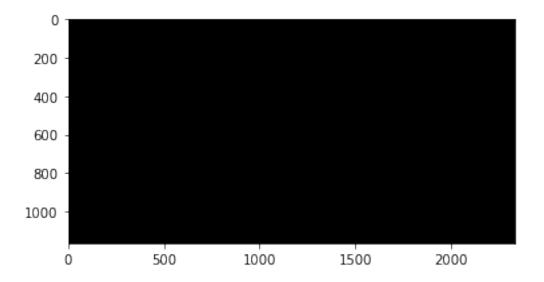
layer 1: Activation function output



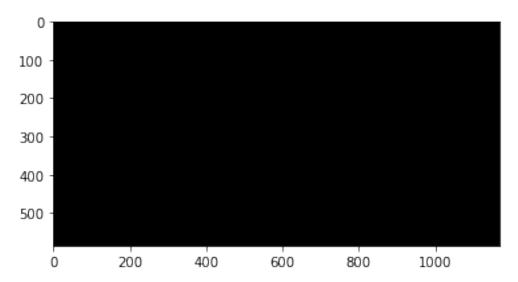
layer 2: Convolution output



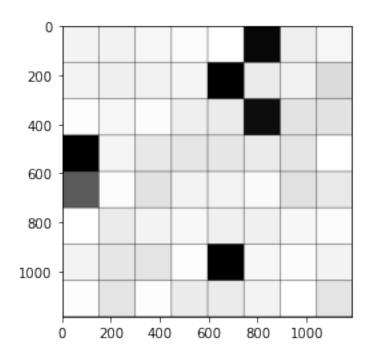
layer 2: Activation function output



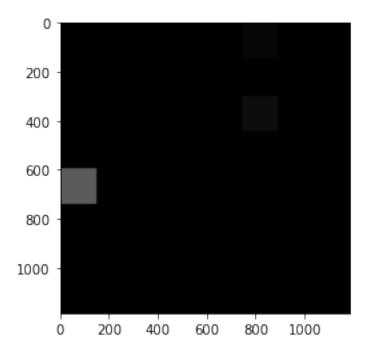
layer 2: Max-Pooling



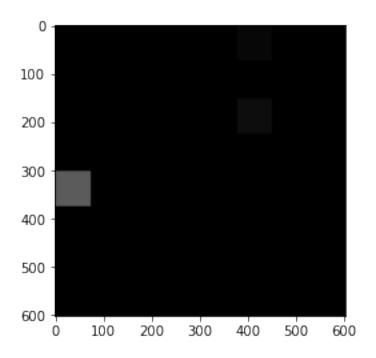
layer 3: Convolution output



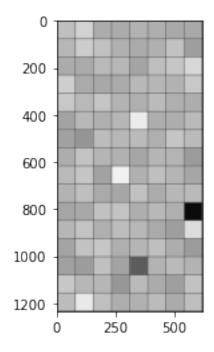
layer 3: Activation function output



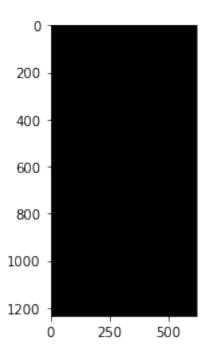
layer 3: Max-Pooling



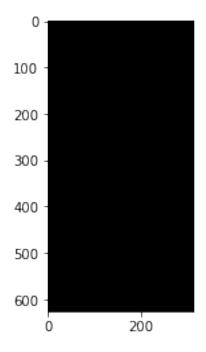
layer 4: Convolution output



layer 4: Activation function output



layer 4: Max-Pooling



[]: