

The Kac-Rice Formula for Landscape Complexity

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Based on *Landscape Complexity for the Empirical Risk of Generalized Linear Models* by Antoine Maillard, Gerard Ben Arous, and Giulio Biroli, 2019

Presented February 2024 for Stat 37797

Setup

We consider random GLMs

$$y_\mu = \phi(\xi_\mu \cdot x^*)$$

- ξ_μ is a gaussian random vector
- x^* the the true vector we are trying to recover, $\|x^*\|_2^2 = 1$
- ϕ is a nonlinearity
- There are m samples, indexed by μ
- x^* is n -dimensional
- Ex: Phase Retrieval

We estimate x^* with x . The loss is

$$L_2(x) = \frac{1}{2m} \sum_{\mu=1}^m [\phi(\xi_\mu \cdot x) - y_\mu]^2$$

How many critical points does L_2 have?

Understanding Kac-Rice

Kac-Rice counts the number of critical points, N , of a function by counting the zeros of its derivative over some interval. Let γ be the curve characterized by L , and let $\delta(\cdot)$ be the dirac delta.

$$\begin{aligned} N &= \int_{\gamma} 1 \cdot \delta(\omega) d\omega \\ &= \int_a^b \delta(L'(x)) |L''(x)| dx \\ \mathbb{E}(N) &= \int_{x=a}^b \int_{y=-\infty}^{\infty} \mathbb{E} \left[\delta(L'(x)) |L''(x)| \middle| L'(x) = y \right] p_{L'(x)}(y) dy dx \\ &\quad \text{(conditioning on } L'(x)) \\ &= \int_{x=a}^b \int_{y=-\infty}^{\infty} \delta(L'(y)) \mathbb{E} \left[|L''(x)| \middle| L'(x) = y \right] p_{L'(x)}(y) dy dx \\ &= \int_a^b \mathbb{E} \left[|L''(x)| \middle| L'(x) = 0 \right] p_{L'(x)}(0) dx \end{aligned}$$

Understanding Kac-Rice

$$\mathbb{E}(N) = \int_a^b \mathbb{E} \left[|L''(x)| \mid L'(x) = 0 \right] p_{L'(x)}(0) dx$$

In multiple dimensions, infinitesimal distances are scaled by
 $|\det \nabla(\nabla L)| = |\det \nabla^2 L|$

The Multidimensional Kac-Rice Formula

$$\mathbb{E}(N) = \int_A \mathbb{E} \left[|\det(\nabla^2 L(x))| \mid \nabla L(x) = \mathbf{0} \right] p_{\nabla L(x)}(\mathbf{0}) dx$$

Applying Kac-Rice

The landscape complexity expresses the number of critical points

- Annealed complexity: $\log \mathbb{E}(N)$
- Quenched complexity: $\mathbb{E}(\log N)$
- Thermodynamic limit: $n, m \rightarrow \infty; m/n \rightarrow \alpha > 1$

Let y_μ and z_μ be independent Gaussian random vectors. Using $L = \frac{1}{m} \sum_{\mu=1}^m \phi(\xi_\mu \cdot x)$,

$$L(x) \stackrel{d}{=} \frac{1}{m} \sum_{\mu=1}^m \phi(y_\mu)$$

$$\nabla L(x) \stackrel{d}{=} \frac{1}{m} \sum_{\mu=1}^m \phi'(y_\mu) z_\mu$$

$$\nabla^2 L(x) \stackrel{d}{=} \left[\frac{1}{m} \sum_{\mu=1}^m \phi''(y_\mu) z_\mu z_\mu^T \right] - \left[\left(\frac{1}{m} \sum_{\mu=1}^m y_\mu \phi'(y_\mu) \right) I_{n-1} \right]$$

∇L and $\nabla^2 L$ do not depend on x !

Applying Kac-Rice

Since $\nabla L, \nabla^2 L \perp x$, the integral is a “rectangle” and we can evaluate at any point, say $x = [1, 0, 0, \dots, 0]^T = e_n$. Using Gaussian calculations,

$$\begin{aligned}\mathbb{E}(N) &= \int_A \mathbb{E} \left[\left| \det(\nabla^2 L(x)) \right| \middle| \nabla L(x) = \mathbf{0} \right] p_{\nabla L(x)}(\mathbf{0}) dx \\ &= \omega_n \cdot p_{\nabla L(e_n)}(\mathbf{0}) \cdot \mathbb{E}_{y,z} \left[\left| \det(\nabla^2 L(e_n)) \right| \middle| \nabla L(e_n) = \mathbf{0} \right] \\ &= \omega_n \cdot \mathbb{E}_y \left[p_{\nabla L(e_n)}(\mathbf{0}) \cdot \mathbb{E}_z \left[\left| \det(\nabla^2 L(e_n)) \right| \middle| \nabla L(e_n) = \mathbf{0}, y \right] \right] \\ &= C e^{n \frac{1+\log \alpha}{2}} \mathbb{E}_y \left[e^{-\frac{n-1}{2} \log(\frac{1}{m} \sum_{\mu} \phi'(y_{\mu})^2)} \mathbb{E}_z \left[\left| \det H_n^{\Lambda}(y, z) \right| \right] \right]\end{aligned}$$

C , which mostly comes from ω_n (the volume of A), is trivial at the limit we will take, and H_n^{Λ} is a messy $n \times n$ matrix.

Results at the Limit

For the L we have been working with, large deviation theory (see Varadhan's Lemma) yields annealed complexity

$$\lim_{n \rightarrow \infty} \frac{1}{n} \log \mathbb{E}(N) = \sup_{\nu \in \mathcal{M}_\phi(A)} \left[\frac{1 + \log \alpha}{2} - \frac{\mathcal{E}_\phi(\nu)}{2} + \kappa_{\alpha, \phi}(\nu, t_\phi(\nu)) - \alpha H(\nu | \mu_G) \right]$$

A similar procedure leads us to

Annealed Complexity of L_2

$$\lim_{n \rightarrow \infty} \frac{1}{n} \log \mathbb{E}(N) = \frac{1 + \log \alpha}{2} + \sup_{q \in Q} \sup_{\nu \in M_\phi(B, q)} \left[\frac{1}{2} \log(1 - q^2) - \frac{1}{2} \mathcal{E}_\phi(q, \nu) + \kappa_{\alpha, \phi}(q, \nu) - \alpha H(\nu | \mu_G) \right]$$

where Q is the set of allowed signal sizes $x^* \cdot x$ ($Q \subseteq [-1, 1]$ since $\|x\|_2^2 = 1$)

Using the Result

M,A,&B develop a fixed point iteration algorithm to compute the annealed complexity from the supremum formulas. For my report, I'm working to use this to get an exact number for N with L_2 loss on phase retrieval.

Augeri, Guionnet, and Husson (2021) used a method called “tilting of the measure” to count local minima (instead of all critical points).