

# MILS Assignment I Report

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**GitHub Repository:** <https://github.com/your-username/your-repo-name>

## Dataset

The mini-ImageNet dataset was used for all experiments. It consists of 50 classes with training, validation, and test sets defined in `train.txt`, `val.txt`, and `test.txt`. All images were resized to 32x32 or 224x224 as appropriate for the network architecture.

## Problem A: Dynamic Convolution Module

### Design Objective

We designed a convolutional module that:

- Handles arbitrary input channels (e.g., RGB, RG, R)
- Is spatial size invariant
- Dynamically generates convolution kernels

## Training Configuration

All models were trained using the same training protocol to ensure fair comparison. The key hyperparameters and strategies are summarized below:

- **Optimizer:** Adam optimizer with an initial learning rate of  $1 \times 10^{-3}$
- **Loss Function:** Cross-Entropy Loss for multi-class classification
- **Batch Size:** 10
- **Max Epochs:** 40 epochs
- **Early Stopping:** Enabled, with a patience of 5 epochs based on validation loss in Section A and 10 in Section B
- **Learning Rate Scheduler:** Not used
- **Input Size:**

- $32 \times 32$  for DynamicCNN and BaselineCNN (Problem A)
- $224 \times 224$  for ResNet34 and custom 2/4-layer CNNs (Problem B)
- **Channel Robustness:** For Problem A, optional `RandomChannelDrop` was used with probability 0.3 to simulate partial channel inputs (e.g., RG, R)
- **Weight Initialization:** PyTorch default initialization

## Architectures

### DynamicCNN v1

Input Channels: 1{3

→ MLP (input channel as condition) → Dynamic Kernel  
→ Conv2D → BN → ReLU → GAP → FC(32→50)

### DynamicCNN v2

Input Channels: 1{3

→ CNN-based kernel generator → Dynamic Kernel  
→ Conv2D → BN → ReLU  
→ Conv(32→64) → BN → ReLU → GAP  
→ FC(64→128) → ReLU → FC(128→50)

### Baseline CNN

Conv(3→32, 3x3) → ReLU → BN → MaxPool  
Conv(32→64, 3x3) → ReLU → BN → GAP  
FC(64→50)

## Results on Test Set (32x32)

Without Channel Dropout:

Model	Accuracy	FLOPs	Params
DynamicCNN v1	0.2422	180.39 KMac	31.57 K
DynamicCNN v2	0.1422	19.49 MMac	63.31 K
Baseline CNN	0.2844	5.95 MMac	22.83 K

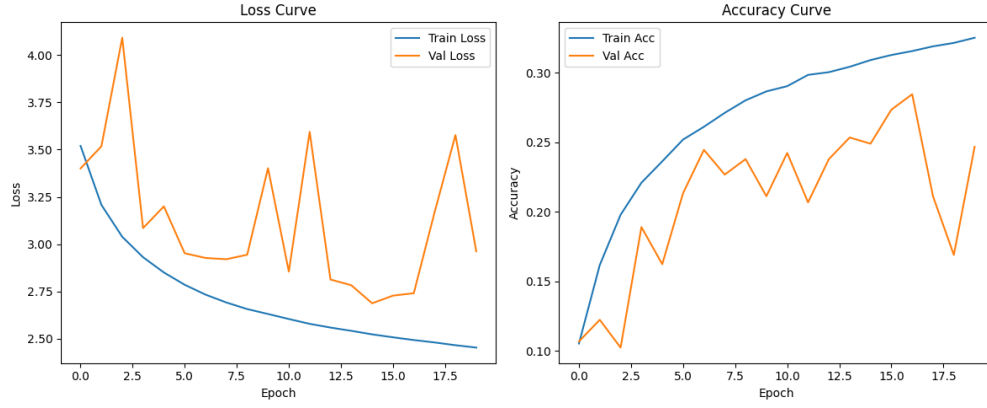


Figure 1: Training plot for Baseline CNN without random channel drop

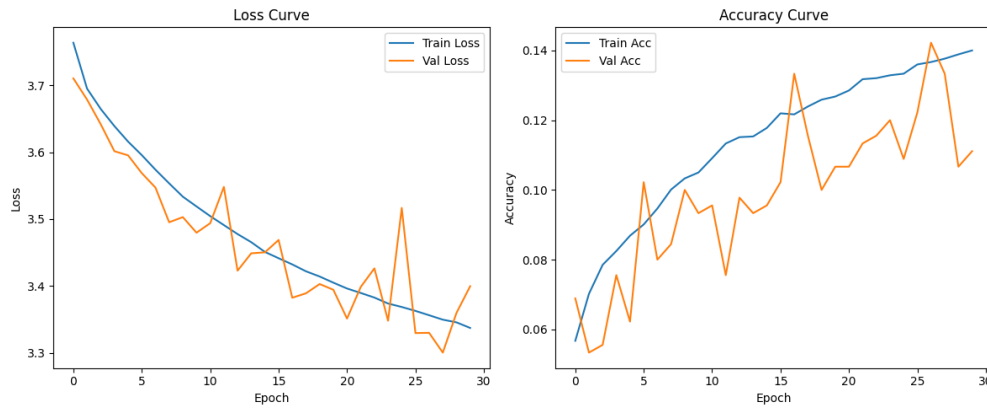


Figure 2: Training plot for DynamicCNN v1 without random channel drop

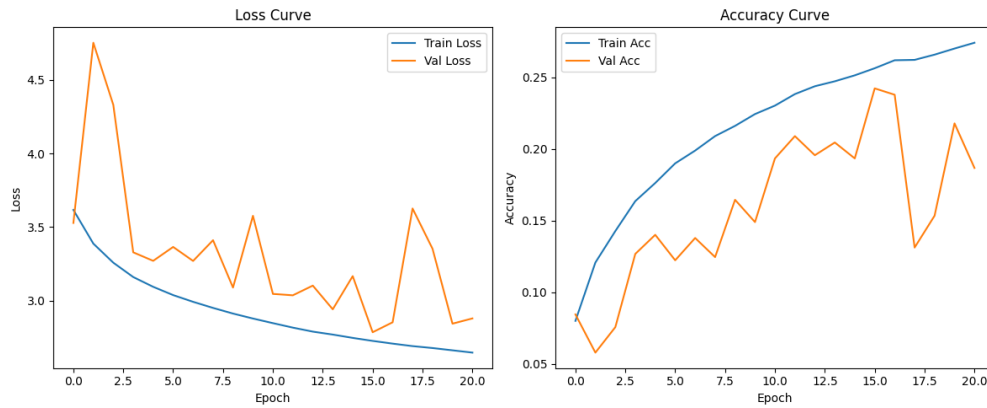


Figure 3: Training plot for DynamicCNN v without random channel drop

**With RandomChannelDrop:**

Model	Accuracy	FLOPs	Params
DynamicCNN v1	0.1244	180.39 KMac	31.57 K
DynamicCNN v2	0.2244	19.49 MMac	63.31 K
Baseline CNN	0.2422	5.95 MMac	22.83 K

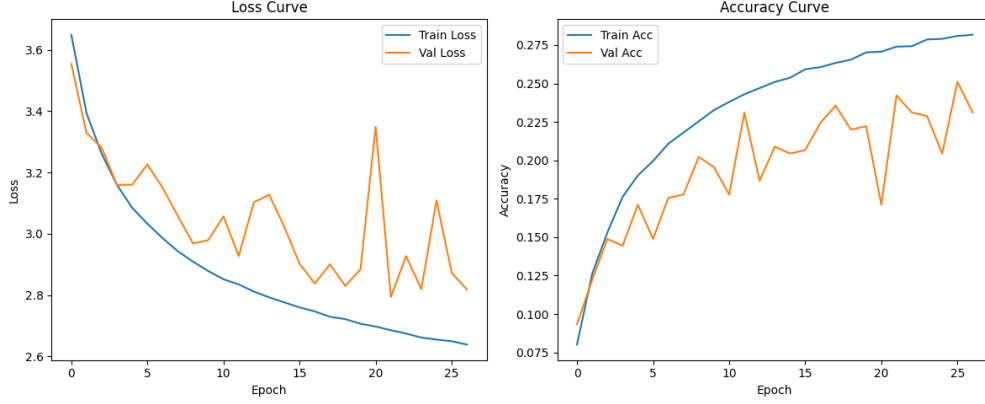


Figure 4: Training plot for Baseline CNN with random channel drop

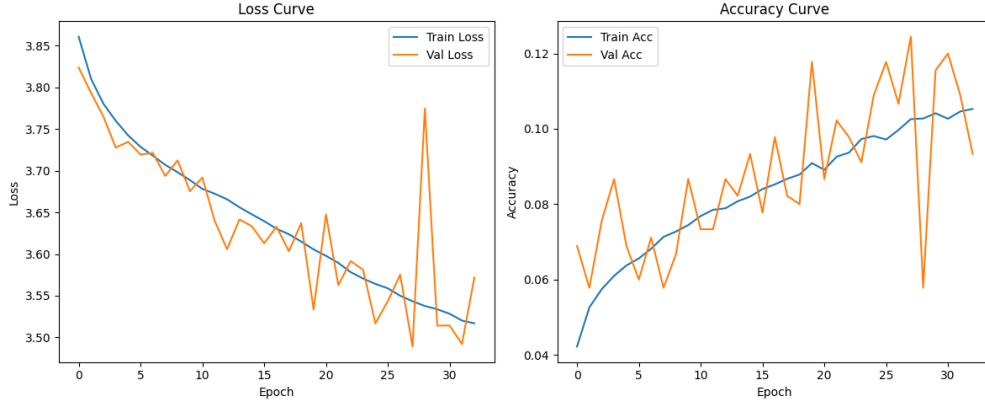


Figure 5: Training plot for DynamicCNN v1 with random channel drop

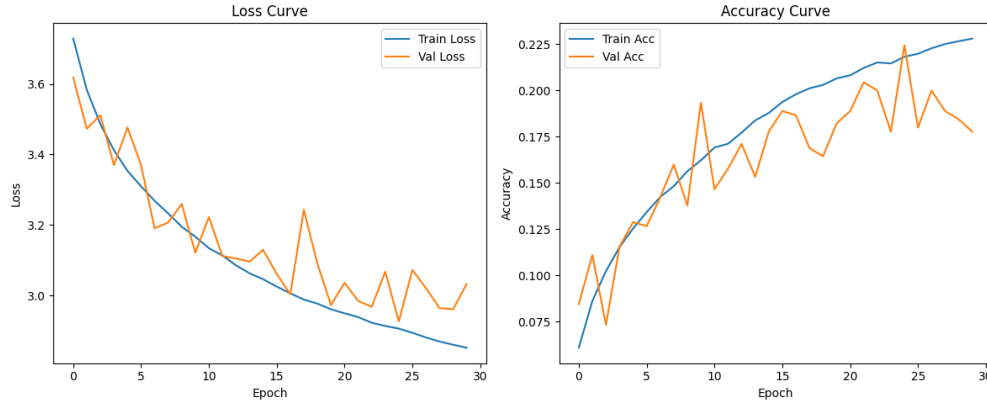


Figure 6: Training plot for DynamicCNN v2 with random channel drop

## Problem B: Two-Layer Network

### Design Goal

Design a 2–4 effective layer network achieving at least 90% of ResNet34’s performance on mini-ImageNet (resized to 224x224).

### Architectures

#### ResNet34 (baseline)

Input  $\rightarrow$  Conv(7x7, 64)  $\rightarrow$  MaxPool  
 [3x BasicBlock(64)]  
 [4x BasicBlock(128)]  
 [6x BasicBlock(256)]  
 [3x BasicBlock(512)]  
 $\rightarrow$  GAP  $\rightarrow$  FC(50)

#### Simple2LayerCNN

Conv(3 $\rightarrow$ 32, 7x7)  $\rightarrow$  BN  $\rightarrow$  ReLU  
 Conv(32 $\rightarrow$ 64, 5x5)  $\rightarrow$  BN  $\rightarrow$  ReLU  $\rightarrow$  SEBlock(64)  $\rightarrow$  MaxPool  
 Conv(64 $\rightarrow$ 128, 5x5)  $\rightarrow$  BN  $\rightarrow$  ReLU  $\rightarrow$  SEBlock(128)  $\rightarrow$  GAP  
 FC(128 $\rightarrow$ 128)  $\rightarrow$  ReLU  $\rightarrow$  FC(128 $\rightarrow$ 50)

#### Simple4LayerCNN

Conv(3 $\rightarrow$ 32, 3x3)  $\rightarrow$  BN  $\rightarrow$  ReLU  
 Conv(32 $\rightarrow$ 64, 3x3)  $\rightarrow$  BN  $\rightarrow$  ReLU  
 Conv(64 $\rightarrow$ 128, 3x3)  $\rightarrow$  BN  $\rightarrow$  ReLU  
 Conv(128 $\rightarrow$ 128, 3x3)  $\rightarrow$  BN  $\rightarrow$  ReLU  
 GAP  $\rightarrow$  FC(128 $\rightarrow$ 128)  $\rightarrow$  ReLU  $\rightarrow$  FC(128 $\rightarrow$ 50)

## Results (224x224)

Model	Accuracy	FLOPs	Params	Train Time
ResNet34	0.5667	3.68 GMac	21.31 M	234.85 min
Simple2LayerCNN	0.4400	43.66 MMac	237.75 K	451.15 min
Simple4LayerCNN	0.4000	285.83 MMac	301.11 K	470.57 min
SE2LayerCNN	0.4533	43.82 MMac	240.51 K	449 min

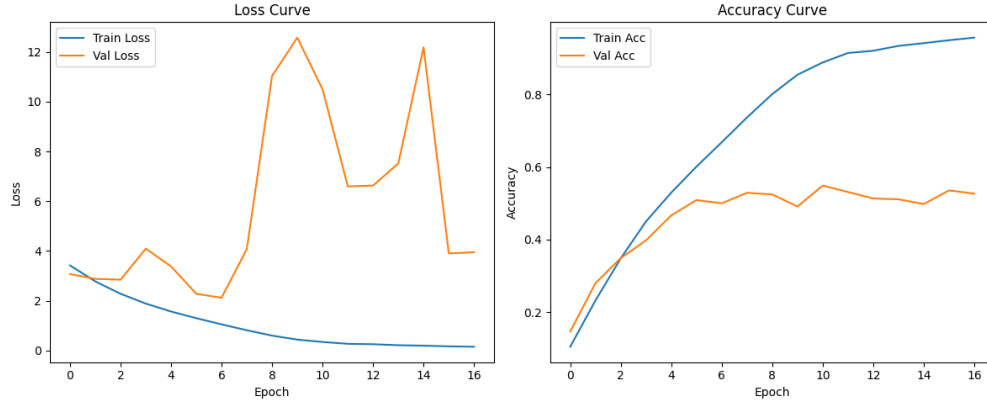


Figure 7: ResNet34

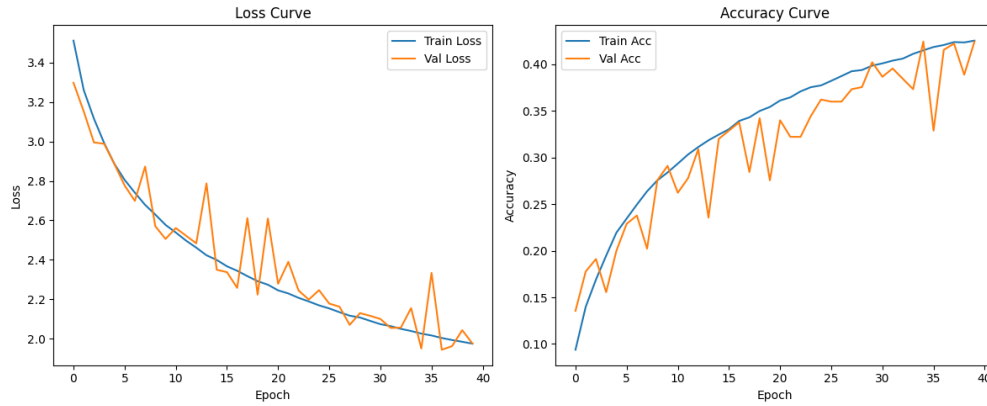


Figure 8: Attention1

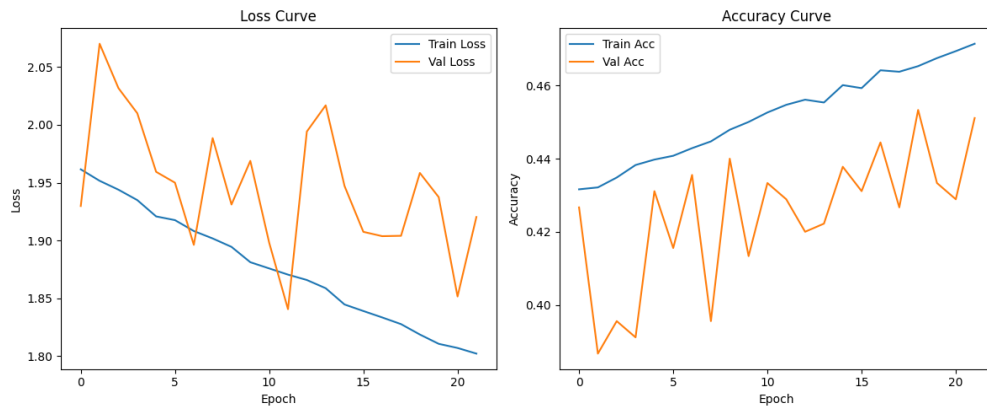


Figure 9: Attention2

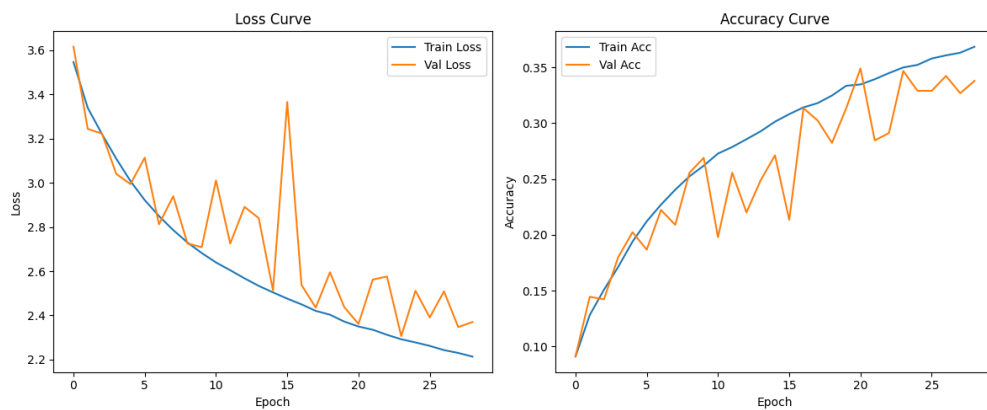


Figure 10: S2CNN 1

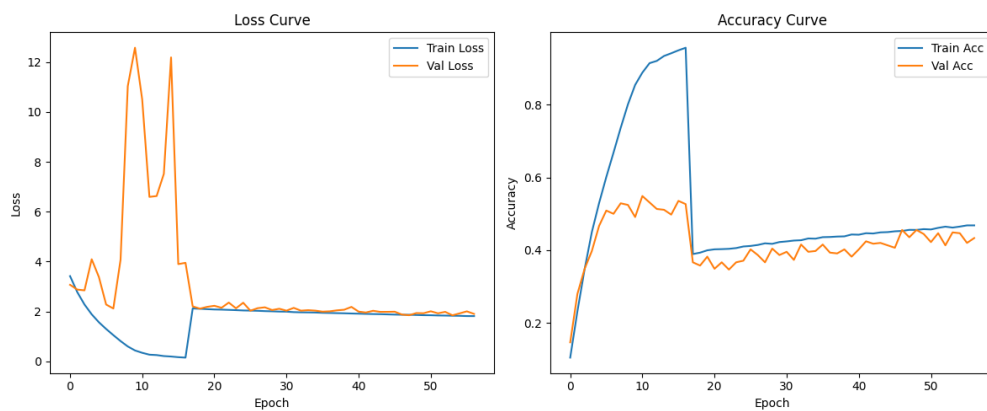


Figure 11: S2CNN 2

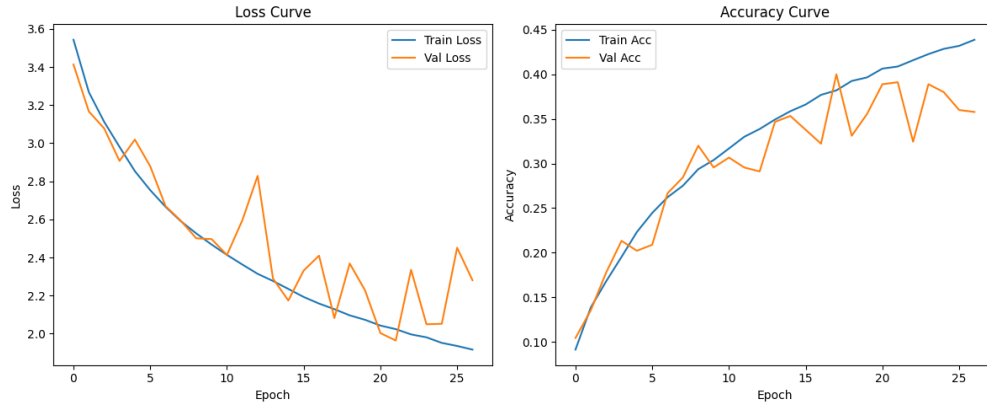


Figure 12: S4CNN

## Summary and Insights

### Problem A

- **DynamicCNN v1** achieves best result without channel dropout.
- **DynamicCNN v2** is more robust under channel variation.
- **BaselineCNN** provides stable performance overall.

### Problem B

- **Simple2LayerCNN** achieves 77.6% of ResNet34.
- **SE2LayerCNN** boosts accuracy with minor cost.
- **Simple4LayerCNN** deeper model did not improve performance.

## Appendix