Bayesian Theory
Quick Notes

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Spring 2020

Contents

1 Statistics Basics

General Structure: Probability Space/Triple

Probability Space/Triple $(\Omega, \mathcal{F}, \mathbb{P})$

- Ω: **Sample Space**, set of all posible outcomes.
- $\mathcal{F}$: **Set of events** σ, each event is a subset of Ω
- $\mathbb{P}$ Probability of event $\sigma \in \mathcal{F}$

Conditional Probability

Conditional probability of A given B: $\mathbb{P}(A|B) = \frac{\mathbb{P}(A \cap B)}{\mathbb{P}(B)} \Leftrightarrow \mathbb{P}(A|B)\mathbb{P}(B) = \mathbb{P}(A \cap B)$

General properties

- $\mathbb{P}(A \cup B) = \mathbb{P}(A) + \mathbb{P}(B) - \mathbb{P}(A \cap B)$

  Events are mutually exclusive $\Rightarrow \mathbb{P}(A \cap B) = 0$
- $\mathbb{P}(A \cap B) = \mathbb{P}(A|B)\mathbb{P}(B)$

  Events are independent $\Rightarrow \mathbb{P}(A|B) = \mathbb{P}(A)$
- Law of Total Probability

  If events A_1, A_2, A_N are mutually exclusive and exhaustive ($\bigcup_{i=1}^{N} A_i = \Omega$) then:

$$\mathbb{P}(B) = \sum_{i=1}^{N} \mathbb{P}(A_i \cap B) = \sum_{i=1}^{N} \mathbb{P}(B|A_i)\mathbb{P}(A_i)$$

Random Variables

$X \sim$ Distribution	$\mathbb{E}[X]$	$\text{Var}[X]$
Normal(μ, σ^2)	μ	σ^2
Bernoulli(θ)	θ	$\theta(1-\theta)$
Binomial(θ)	$n\theta$	$n\theta(1-\theta)$
Poisson(μ)	μ	μ
Uniform(α, β)	$\frac{\alpha+\beta}{2}$	$\frac{(\alpha+\beta)^2}{12}$
Beta(α, β)	$\frac{\alpha}{\alpha+\beta}$	$\frac{\alpha\beta}{(\alpha+\beta)^2(\alpha+\beta+1)}$
Gamma(α, β)	$\frac{\alpha}{\beta}$	$\frac{\alpha}{\beta^2}$
Inv. Gamma(α, β)	$\frac{\beta}{\alpha-1}$	$\frac{\beta^2}{(\alpha-1)^2(\alpha-2)}$
Exponential(λ)	$\frac{1}{\lambda}$	$\frac{1}{\lambda^2}$

Random Vectors

$\mathbf{X} = X_1, ..., X_k \sim$ Distribution	$\mathbb{E}[X_i]$	$\text{Var}[X_i]$	$\text{Cov}[X_i, X_j]$
Multivariative Normal$(\boldsymbol{\mu}, \Sigma)$	μ_i	$\Sigma_{i,i}$	$\Sigma_{i,j}$
Multinomial$(n, \theta_1, ..., \theta_k)$	$n\theta_i$	$n(1-\theta_i)$	$-n\theta_i\theta_j$

2 Bayes Throrem

Discrete Case

$$\begin{aligned}
\mathbb{P}(X = x_i | Y = y_j) &= \frac{\mathbb{P}(X = x_i, Y = y_j)}{\mathbb{P}(Y = y_j)} \\
&= \frac{\mathbb{P}(Y = y_j | X = x_i)\mathbb{P}(X = x_i)}{\mathbb{P}(Y = y_j)} \\
&= \frac{\text{Likelihood} \times \text{Prior}}{\text{Marginal}} \\
&= \frac{\mathbb{P}(Y = y_j | X = x_i)\mathbb{P}(X = x_i)}{\sum_{k=1}^{n} \mathbb{P}(X = x_k, Y = y_j)} \\
&= \frac{\mathbb{P}(Y = y_j | X = x_i)\mathbb{P}(X = x_i)}{\sum_{k=1}^{n} \mathbb{P}(Y = y_j | X = x_k) P(X = x_k)} \\
\Rightarrow \mathbb{P}((X|Y)) &= \frac{\mathbb{P}(Y|X)\mathbb{P}(X)}{\sum_x \mathbb{P}(X = x, Y)} = \frac{\text{Likelihood} \times \text{Prior}}{\text{Marginal}}
\end{aligned}$$

Continous Case

$$f(X|Y) = \frac{f(X,Y)}{g(Y)} = \frac{g(Y|X)f(X)}{\int g(Y|X)f(X)dX}$$

Bayesian Statistical Inference

- $L(\theta|y) = f(y|\theta)$: Likelihood
- $\pi(\theta)$: Prior
- $m(y) = p(y)$: Marginal distribution/Normalizing constant

$$\text{Posterior Distribution: } p(\theta|y) = \frac{f(y|\theta)\pi(\theta)}{\int p(\theta, y)d\theta} = \frac{f(y|\theta)\pi(\theta)}{\int f(y|\theta)\pi(\theta)d\theta} \propto f(y|\theta)\pi(\theta)$$

Predictive Distrubutions

$$\begin{aligned}
\text{Prior Predictive Distribution:} \quad & p(y^{new}) = \int_\theta f(y^{new}|\theta)\pi(\theta)d\theta \\
\text{Posterior Predictive Distribution:} \quad & p(y^{new}|y^{old}) = \int_\theta f(y^{new}|\theta, y^{old})p(\theta|y^{old})d\theta
\end{aligned}$$

Bayes Theorem for Multiple Parameters $\Theta = \{\theta_1, ..., \theta_q\}$

$$\mathbb{P}(\Theta|\boldsymbol{y}) = \frac{\mathbb{P}(\boldsymbol{y}|\Theta)\mathbb{P}(\Theta)}{\mathbb{P}(\boldsymbol{y})} \propto \mathbb{P}(\boldsymbol{y}|\Theta)\mathbb{P}(\Theta)$$

3 Conjugate Priors

Sample Distribution	Parameter	Prior
Bernoulli(θ)	θ	Beta(α, β)
Binomial(n, θ)	θ	Beta(α, β)
Poisson(θ)	θ	Gamma(α, β)
Exponential(θ)	θ	Gamma(α, β)
Normal(μ, σ_0^2)	μ	Normal(μ_h, σ_h^2)
Normal(μ_0, σ^2)	σ^2	Inverse Gamma(α, β)
Normal($\mu_0, 1/\tau$)	$\tau = 1/\sigma^2$	Gamma(α, β)
Multinomial($n, \theta_1, ..., \theta_k$)	$\theta_1, ..., \theta_k$	Dirichlet($\alpha_1, ..., \alpha_k$)
Uniform($0, \theta$)	θ	Pareto(θ_m, α)

4 Normal Distribution Priors

Unknown μ, known σ^2

- Sample $\boldsymbol{y} \in \mathbb{R}^n$
- Prior $\mu \sim \text{Normal}(\mu_0, \sigma_0^2) = \text{Normal}\left(\mu_0, \frac{\sigma^2}{m}\right) \Rightarrow m = \sigma^2/\sigma_0^2$
- Posterior:

$$\mu|\boldsymbol{y}, \sigma^2 \sim \text{Normal}\left(\frac{m\mu_0 + n\bar{y}}{m+n}, \frac{\sigma^2}{m+n}\right) = \text{Normal}\left((1-w)\mu_0 + w\bar{y}, \frac{\sigma^2}{m+n}\right)$$

$w = \frac{m}{m+n}$

Unknown μ, known τ

- Sample $\boldsymbol{y} \in \mathbb{R}^n$
- Prior $\mu \sim \text{Normal}\left(\mu_0, \frac{\sigma^2}{m}\right) = \text{Normal}\left(\mu_0, \frac{1}{\tau m}\right)$
- Posterior:

$$\mu|\boldsymbol{y}, \sigma^2 \sim \text{Normal}\left(\frac{m\mu_0 + n\bar{y}}{m+n}, \frac{1}{\tau(m+n)}\right) = \text{Normal}\left((1-w)\mu_0 + w\bar{y}, \frac{1}{\tau(m+n)}\right)$$

$w = \frac{m}{m+n}$

Unknown τ, known μ

- Sample $\boldsymbol{y} \in \mathbb{R}^n$
- Prior $\tau \sim \text{Gamma}(\alpha, \beta)$
- Posterior:

$$\tau|\boldsymbol{y}, \mu \sim \text{Gamma}\left(\alpha + \frac{n}{2}, \beta + \frac{z^2}{2}\right)$$

$z^2 = \sum_i (y_i - \mu)^2$

Unknown σ^2, known μ

- Sample $\boldsymbol{y} \in \mathbb{R}^n$
- Prior $\mu, \sigma^2 \sim \text{Normal}\left(\mu_0, \frac{\sigma^2}{\kappa}\right) \times \text{Inverse Gamma}(\alpha, \beta)$
- Posterior:

$$\mu, \sigma^2 | \boldsymbol{y} \sim \text{Normal}\left(\frac{\kappa\mu_0 + n\bar{y}}{\kappa + n}, \frac{\sigma^2}{\kappa + n}\right) \times \text{Inverse Gamma}\left(\alpha + \frac{n}{2}, \beta + \frac{(n-1)s^2}{2} + \frac{\kappa n(\bar{y} - \mu_0)^2}{2(\kappa + n)}\right)$$

$s^2 = \sum_i (y_i - \bar{y})^2/(n-1)$
$\kappa = \sigma^2(\alpha - 1)/\beta$ or given (seriously it's not written anywhere Ken, I'm just guessing here man)

5 Jeffrey's Prior

Definition

Jeffery Prior: $\pi_{JP}(\theta) \propto \sqrt{I(\theta|y)}$
Fisher Information:

$$I(\theta|y) = \mathbb{E}\left[\left(\frac{d \log f(y|\theta)}{d\theta}\right)^2\right] = -\mathbb{E}\left[\frac{d^2 \log f(y|\theta)}{d\theta^2}\right]$$

1:1 transformation of Jeffrey's Prior

$$\pi(\phi) = \pi_{JP}(\theta)\left|\frac{d\theta}{d\phi}\right|$$

Jeffrey's Prior for Multivariate Parameter Vector

Gradient of log likelihood:

$$S(\boldsymbol{\theta}) = \begin{bmatrix} \partial_{\theta_1} \log f(x) \\ \vdots \\ \partial_{\theta_n} \log f(x) \end{bmatrix}$$

Hessian Matrix of log likelihood:

$$H(\boldsymbol{\theta}) = \text{Jacobian}\left[S(\boldsymbol{\theta})\right] = \begin{bmatrix} \partial_{\theta_1}\partial_{\theta_1} \ln f(x) & \cdots & \partial_{\theta_1}\partial_{\theta_n} \ln f(x) \\ \vdots & \ddots & \vdots \\ \partial_{\theta_n}\partial_{\theta_1} \ln f(x) & \cdots & \partial_{\theta_n}\partial_{\theta_n} \ln f(x) \end{bmatrix}$$

Fisher Information: $I(\theta|x) = -\mathbb{E}\left[H(\theta)\right]$
Jeffrey's Prior: $\pi_{JP} \propto \sqrt{\det(I(\theta|x))}$

6 Reference Prior

Kullback-Leibler (KL) divergence

A measure of the difference between two pmfs/pdfs. When $KL(f,g)=0$, the two distributions are idetical.

Properties

- $KL(f,g) \neq KL(g,f)$
- $KL(fmg) \geq 0$

Continous parameter x

$$KL(f,g) = \int \ln\left[\frac{f(x)}{g(x)}\right] dx = \mathbb{E}_f[\log f(X)] - \mathbb{E}_g[\log f(X)]$$

Discrete parameter x

$$KL(f,g) = \sum_{x\in X} \ln\left[\frac{f(x)}{g(x)}\right] = \mathbb{E}_f[\log f(X)] - \mathbb{E}_g[\log f(X)]$$

Reference Prior

Read week 4 notes (2.2)

7 Point Estimates

Components of Decision Theory with emphasis on parameter estimation

- State Spcae Θ, unknown true value $\theta \in \Theta$
- Action Space $\mathcal{A} \ni a$, sometimes $\mathcal{A} = \Theta$
- Sampling Distribution $f(\boldsymbol{y}|\theta)$
- Loss Function $\mathcal{L}(a|\theta)$
- Risk $R_\theta(a|\boldsymbol{y}) = \mathbb{E}_\theta[L(a|\theta,y)] = \int_{\theta\in\Theta} \mathcal{L}(a|\theta)p(\theta|\boldsymbol{y})d\theta$
- Bayes Estimator of a parameter $\hat{\theta}_{BE} = \arg\min_{\hat{\theta}\in\Theta} R_\theta(\hat{\theta}|\boldsymbol{y})$

Common Loss Functions and Corresponding Estimators

- **Squared Error Loss**: $\mathcal{L}(\theta|\hat{\theta}) = (\theta-\hat{\theta})^2$, Bayes Estimator $\hat{\theta} = \mathbb{E}[\theta|\boldsymbol{y}]$
- **Absolute Error Loss**: $\mathcal{L}(\theta|\hat{\theta}) = |\theta-\hat{\theta}|$, Bayes Estimator $\hat{\theta} = \theta_{0.5}$, $(\mathbb{P}(\theta \leq \theta_{0.5}) = 0.5)$
- **0-1 Loss**: $\mathcal{L}(\theta|\hat{\theta}) = I(\theta \neq \hat{\theta})$, Bayes Estimator $\hat{\theta}$ is the posterior mode

8 Interval Estimates

$$P \times 100\% \text{ Bayesian Credible interval} = [LB, UB] \text{ where } \int_{LB}^{UB} p(\theta, \boldsymbol{y}) d\theta = P$$

If loooking for one side-confidence bounds then $LB = -\infty$ or $UB = \infty$

Symmetric Credicble Interval

$$[LB, UB] \text{ where } \mathbb{P}(\theta \leq LB) = \mathbb{P}(\theta \geq UB) = \alpha/2 = (1 - P)/2$$

Highest Posterior Density Interval (HPDI)

Credible Interval where all values outside the interval has a density smaller than any of the values in the interval.

Credible Regions

$$\iint p(\theta_1, \theta_2 | \boldsymbol{y}) d\theta_1 d\theta_2 = 1 - \alpha = P$$

9 Classic Hypothesis Testing

1. Assume hypothesis H_0 is true
2. Calculate test statistic $T(\boldsymbol{y}_{obs})$ based on observed sample data regarding to H_0 and H_1
3. Conditional on H_0 being true, p-value $= \mathbb{P}(T(\boldsymbol{y})$ more extreme than $T(\boldsymbol{y}_{obs}) | \theta, H_0)$
4. Reject H_0 and accept H_1 for sufficiently small p-values, do not reject H_0 otherwise

10 Bayesian Hypothesis Testing

Suppose there are tow hypotheses about parameter θ:

$$H_0 : \theta \in \Theta_1 \quad H_1 : \theta \in \Theta_1$$

where $\Theta_0 \cup \Theta_1 = \Theta$ and $\Theta_0 \cap \Theta_1 = \emptyset$.

The Bayesian approach specifies prior probabilities on each hypotheses:

$$p_0 = \mathbb{P}(H_0 \text{ is true}) = \mathbb{P}(\theta \in \Theta_0)$$
$$p_1 = \mathbb{P}(H_1 \text{ is true}) = \mathbb{P}(\theta \in \Theta_1)$$

Where the posteriors are as follows:

$$\mathbb{P}(H_0 | \boldsymbol{y}) = \mathbb{P}(\theta \in \Theta_0 | \boldsymbol{y})$$
$$\mathbb{P}(H_1 | \boldsymbol{y}) = \mathbb{P}(\theta \in \Theta_1 | \boldsymbol{y})$$

Where $\mathbb{P}(H_0 | \boldsymbol{y}) + \mathbb{P}(H_1 | \boldsymbol{y}) = 1$

Simple

- Single parameter values $H_0 : \theta = \theta_0 \quad H_1 : \theta = \theta_1$
- Posteriors:

$$\mathbb{P}(H_0|\boldsymbol{y}) = \mathbb{P}(\theta = \theta_0|\boldsymbol{y}) = \frac{f(\boldsymbol{y}|\theta_0)p_0}{m(\boldsymbol{y})} = \frac{f(\boldsymbol{y}|\theta_0)p_0}{f(\boldsymbol{y}|\theta_0)p_0 + f(\boldsymbol{y}|\theta_1)p_1}$$
$$\mathbb{P}(H_1|\boldsymbol{y}) = \mathbb{P}(\theta = \theta_1|\boldsymbol{y}) = \frac{f(\boldsymbol{y}|\theta_1)p_1}{m(\boldsymbol{y})} = \frac{f(\boldsymbol{y}|\theta_1)p_1}{f(\boldsymbol{y}|\theta_0)p_0 + f(\boldsymbol{y}|\theta_1)p_1}$$
$$\mathbb{P}(H_0|\boldsymbol{y}) = 1 - \mathbb{P}(H_1|\boldsymbol{y})$$

- posterior odds of H_0 against H_1:

$$\frac{\mathbb{P}(H_0|\boldsymbol{y})}{\mathbb{P}(H_1|\boldsymbol{y})} = \frac{f(\boldsymbol{y}|\theta_0)p_0}{f(\boldsymbol{y}|\theta_1)p_1}$$

Composite

- Single parameter values $H_0 : \theta \in \Theta_0 \quad H_1 : \theta \in \Theta_1$
- Prior: $p_i = \int_{\theta \in \Theta_i} \pi(\theta) d\theta$
- Posteriors:

$$\mathbb{P}(H_i|\boldsymbol{y}) = \frac{p(\boldsymbol{y}, H_i)}{m(\boldsymbol{y})} = \frac{p_i \; p(\boldsymbol{y}|H_i)}{m(\boldsymbol{y})} = \frac{p_i \int p(\boldsymbol{y}, \theta|H_i) d\theta}{m(\boldsymbol{y})} = \frac{p_i \int f(\boldsymbol{y}|\theta)\pi(\theta|H_i) d\theta}{m(\boldsymbol{y})}$$
$$= \frac{p_i \int_{\theta \in \Theta_i} f(\boldsymbol{y}|\theta) \frac{\pi(\theta)}{p_i} d\theta}{m(\boldsymbol{y})} = \frac{\int_{\theta \in \Theta_i} f(\boldsymbol{y}|\theta)\pi(\theta) d\theta}{m(\boldsymbol{y})} = \int_{\theta \in \Theta_i} p(\theta|\boldsymbol{y}) d\theta = \mathbb{P}(\theta \in \Theta_i|\boldsymbol{y})$$

- posterior odds of H_0 against H_1:

$$\frac{\mathbb{P}(H_0|\boldsymbol{y})}{\mathbb{P}(H_1|\boldsymbol{y})} = \frac{\int_{\theta \in \Theta_0} f(\boldsymbol{y}|\theta)\pi(\theta) d\theta}{\int_{\theta \in \Theta_1} f(\boldsymbol{y}|\theta)\pi(\theta) d\theta} = \frac{\mathbb{P}(\theta \in \Theta_0|\boldsymbol{y})}{\mathbb{P}(\theta \in \Theta_1|\boldsymbol{y})} = \frac{\mathbb{P}(\theta \in \Theta_0|\boldsymbol{y})}{1 - \mathbb{P}(\theta \in \Theta_0|\boldsymbol{y})}$$

Multiple models

- Set of models $M_1, ..., M_K$
- H_i: The correct model is M_i

$$\mathbb{P}(H_i|\boldsymbol{y}) = \frac{\mathbb{P}(H_i, \boldsymbol{y})}{\mathbb{P}(\boldsymbol{y})} = \frac{\mathbb{P}(H_i, \boldsymbol{y})}{\sum_{j=1}^{K} \mathbb{P}(H_j, \boldsymbol{y})}$$

Bayes Factor

- Prior odds for H_0 against $H_1 = p_0/p_1$
- Posterior odds for H_0 against $H_1 = \mathbb{P}(H_0|\boldsymbol{y})/\mathbb{P}(H_1|\boldsymbol{y})$
- Bayes Factor for H_0 against H_1:

$$BF_{01} = \frac{\text{Posterior odds for } H_0 \text{ against } H_1}{\text{Prior odds for } H_0 \text{ against } H_1} = \frac{\mathbb{P}(H_0|\boldsymbol{y})/\mathbb{P}(H_1|\boldsymbol{y})}{p_0/p_1}$$
$$BF_{10} = \frac{1}{BF_{01}}$$

BF_{ij}	Interpretation
< 3	No edvidence for H_i over H_j
> 3	Positive edvidence for H_i
> 20	Strong edvidence for H_i
> 150	Very strong edvidence for H_i

Simple H_0 vs Simple H_1

$$BF_{01} = \frac{\mathbb{P}(H_0|\boldsymbol{y})/\mathbb{P}(H_1|\boldsymbol{y})}{p_0/p_1} = \frac{(f(\boldsymbol{y}|\theta_0)p_0)/(f(\boldsymbol{y}|\theta_1)p_1)}{p_0/p_1} = \frac{f(\boldsymbol{y}|\theta_0)}{f(\boldsymbol{y}|\theta_1)}$$

Composite H_0 vs Composite H_1

$$BF_{01} = \frac{\mathbb{P}(H_0|\boldsymbol{y})/\mathbb{P}(H_1|\boldsymbol{y})}{p_0/p_1} = \frac{\left[\int_{\theta\in\Theta_0} f(\boldsymbol{y}|\theta)\pi(\theta)d\theta\right] / \left[\int_{\theta\in\Theta_1} f(\boldsymbol{y}|\theta)\pi(\theta)d\theta\right]}{p_0/p_1} = \frac{\mathbb{P}(\theta\in\Theta_0|\boldsymbol{y})/\mathbb{P}(\theta\in\Theta_1|\boldsymbol{y})}{p_0/p_1}$$

Simple H_0 vs Composite H_1

$$BF_{01} = \frac{\mathbb{P}(H_0|\boldsymbol{y})/\mathbb{P}(H_1|\boldsymbol{y})}{p_0/p_1} = \frac{[f(\boldsymbol{y}|\theta_0)p_0] / \left[p_1 \int_{-\infty}^{\infty} f(\boldsymbol{y}|\theta)\pi(\theta)d\theta\right]}{p_0/p_1} = \frac{f(\boldsymbol{y}|\theta_0)}{\int_{-\infty}^{\infty} f(\boldsymbol{y}|\theta)\pi(\theta)d\theta} = \frac{f(\boldsymbol{y}|\theta_0)}{m(\boldsymbol{y})}$$

Multipes Hypotheses

Read 5B.7 cba to type

11 Deterministic Numerical Integration

$$\int_{x_i}^{x_{i+m}} f(x)dx \approx \sum_{j=1}^{m} w_{ij} f(x_{i+j})$$

12 Monte Carlo Integration

$$\text{Expectaqtion } \mathbb{E}[\theta] = \int \theta p(\theta) d\theta$$

$$\text{Samples of } \theta : \theta_1, ..., \theta_N$$

$$\Rightarrow \text{Monte Carlo Estimae } \hat{\mathbb{E}}[\theta] = \frac{1}{N} \sum_{i=1}^{N} \theta_i \approx \mathbb{E}[\theta]$$

By the Law of Large Numbers, $\mathbb{P}(\lim_{N\to\infty} \hat{\mathbb{E}}[\theta] = \mathbb{E}[\theta]) = 1$.

Many Bayesian integrals can be viewed as expectations, such as probabilities and normalising constants.

Direct Sampling

- Target Distribution, often the posterior $p(\theta|\boldsymbol{y})$
- Integrals of interest: $\mathbb{E}[h(\theta|\boldsymbol{y})] = \int h(\theta) p(\theta|\boldsymbol{y}) dy$
  - Common choises for $h(\theta)$:
    $h(\theta) = \theta$, the posterior mean
    $h(\theta) = (\theta - \mathbb{E}[\theta])^2$, the posterior variance
    $h(\theta) = I(a \leq \theta \leq b)$, $\mathbb{P}(\theta \in [a, b])$
- Samples $\theta_1, ..., \theta_N$
- Monto Carlo estimation of Integrals of interest $\mathbb{E}[h(\theta|\boldsymbol{y})] \approx \hat{\mathbb{E}}[h(\theta|\boldsymbol{y})] = \frac{1}{N} \sum h(\theta_i)$
- Monte Carlo Error $= \hat{\mathbb{E}}[h(\theta|\boldsymbol{y})] - \mathbb{E}[h(\theta|\boldsymbol{y})]$

Inverse Probability Integral Transform Method (Inverse PIT)

Continous Random Variable

- Let Y be continous random variables with cdf $F_Y(y) \in [0, 1]$
- Define new random variable $U = F_Y(Y) \sim \text{Uniform}(0, 1)$

The Inverse PIT method

- Transform a uniform variable U using the inverse CDF of Y $(g(U) = F_Y^{-1}(U))$. $g \sim Y$
- Therefore if one can evaluate F^{-1} for Y, then sample y can be generated by $y = F^{-1}(u)$, where $u \sim \text{Uniform}(0, 1)$

Discrete Random Variable

The Inverse PIT method

- Same for Continous method where:

$$F^{-1}(u) = \min_y \{y : F_Y(y) \geq u\}$$

Rejection Sampling

Target distribution $p(\theta|\boldsymbol{y})$

- Generates independent samples form envelope distribution $g(\theta)$
- Only some generated values are kept/used, while the rest are discarded
- Often used for generating univariate random variables than a multivariate random vector

General Rejection Algorithm

For target distribution $p()\theta$ and envelope $g(\theta)$, the (upper) bound M pf p/g is defined:

$$M \geq \frac{p(\theta)}{g(\theta)} \quad \forall\theta \Leftrightarrow M(g)\theta \geq p(\theta)$$

The Algorithm to generate a single value form $p(\theta)$ is as follows:

1. Generate θ^* from $g(\theta^*)$
2. Generate u form Uniform$(0, Mg(\theta^*))$
3. If $u \leq p(\theta^*)$ keep θ^* else reject and return step 1

The acceptance rate is $\frac{1}{M}$ which M is defined as above. For optimal acceptance rate, we choose $M_{opt} = \sup\left\{\frac{p(\theta)}{g(\theta)}\right\}$

Importance Sampling

Simlar to Rejection sampling. However, we adjust the values to correspond to the rightr distribution instead of rejecting them. Therefore all generated θ are kept, there's no rejection.

Suppose there is another distribution has the same support as $p(\theta|\boldsymbol{y})$, the integral then can be written as $\mathbb{E}_p[h(\theta|\boldsymbol{y})] = \mathbb{E}_g[h(\theta)w(\theta)]$ where $w(\theta) = p(\theta|\boldsymbol{y})/g(\theta)$ is the **importance ratio**.

The Monte Carlo estimats can be calculated $\hat{\mathbb{E}}_p[h(\theta|\boldsymbol{y})] \equiv \hat{\mathbb{E}}_g[h(\theta)w(\theta)] = \frac{1}{N}\sum h(\theta^i)w(\theta^i)$

Sampling Importance Re-Sampling

Algorithm for generating a samplem sixe of n

1. Choosing $N > n$. generate N samples of $\theta^i, i = 1, ..., N$ form the envolope distribution (importance sampler) $g(\theta)$
2. Calculate the importance ratio $w_i = p(\theta^i|\boldsymbol{y})/g(\theta)$, then scale by the some of weights:

$$w^{*i} = \frac{w^i}{\sum_j^N w^j}$$

3. randomly sample n θ^i's with replacement, with probabilities $w^{*1}, ..., w^{*N}$

13 Markov Chain Monte Carlo (MCMC)

Overwiew

- **Dependent Samples**: $\theta|\boldsymbol{y}$
- **Iterative Conditional Generation**: $g(\theta^i|\theta^{i-1})$
- **Burn-in**: The initial vales $\theta^1, ..., \theta^B$ are not distributed according to th target distribution $p(\theta)$, therefore would be discarded
- **Sample for Inference**: The additional $N - B$ samples $\theta^{B+1}, ..., \theta^N$ are used for inference

Markov Chain

- **State Space** S: is a set of all possible states j
- **Process** $\theta^t = j$: process at time t is in state j

Definition

$$\begin{aligned}\mathbb{P}(\theta^0 = x_0, ..., \theta^T = x_T) = \mathbb{P}(\theta^T = x_T|\theta^0 = x_0, ..., \theta^{T-1} = x_{T-1}) \\ \times \mathbb{P}(\theta^{T-1} = x_{T-1}|\theta^0 = x_0, ..., \theta^{T-2} = x_{T-2}) \\ \times \mathbb{P}(\theta^0 = \theta_0)\end{aligned}$$

Markov Peoperty: if $\theta^t|\theta^{t-1}$ is independent to other values, then
$\mathbb{P}(\theta^T = x_T|\theta^0 = x_0, ..., \theta^{T-1} = x_{T-1}) = \mathbb{P}(\theta^T = x_T|\theta^{T-1} = x_{T-1})$. Therefore:

$$\mathbb{P}(\theta^0 = x_0, ..., \theta^T = x_T) = \prod_{t=1}^{T} \mathbb{P}(\theta^t = x_t|\theta^{t-1} = x_{t-1}) \times \mathbb{P}(\theta^0 = x_0)$$

The sequence of random variables $\theta^1, ..., \theta^K$ with Markov Property is a Markov Chain

Terminology and Notation

- **One-Step Transistion Probability** $p_{ij}^t = \mathbb{P}(\theta^t = j|\theta^{t-1} = i)$
- if $p_{ij}^t = p_{ij}\ \forall t$ then the chain is **time homogeneous** otherwise **time imhomogeneous**
- **Transistion probability matrix** $(P_t)_{ij} = p_{ij}$, where each row sums to one
  for a time homogeneous chain $P_t = P\ \forall t$

Limiting Behaviour of Markov Chain

- **Recurrent State**: state where a Markov Chain returns with probability 1
- **Nonnull State**: state where it will eventually recurrence in a finite ecpected time
- **Irreducible Markov Chain**: $\exists m \in \mathbb{N}$ *s.t.* $\mathbb{P}(\theta^{m+n} = j | \theta^n = i) > 0 \ \forall i$
- **Periodic Markov Chain**: $\exists m \in \mathbb{N}$ *s.t.* $\exists d \in$ *s.t.* $\mathbb{P}(\theta^{m+n} = j | \theta^n = i) > 0 \cap m/d \in \mathbb{Z}^+ \ \forall i$
  otherwise **Aperiodic Markov Chain**
- **Ergodic Markov Chain**: **Irreducible**, **aperiodic**, all states are **nonnull** and **recurrent**