

Deep learning Based Image Recognition Course Logistics

Instructor: 鍾昕燁

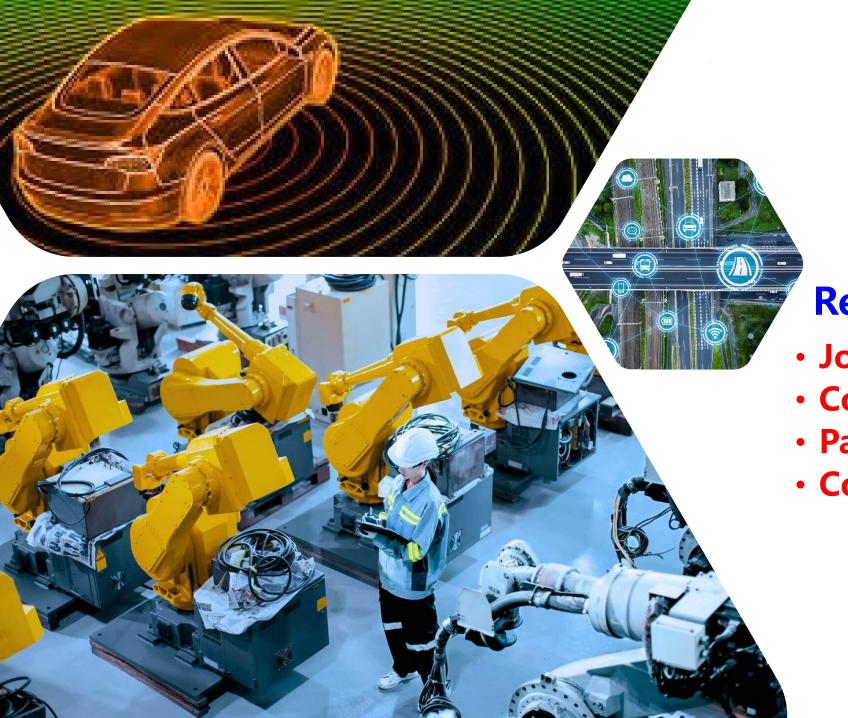
About Me

鍾昕燁 Sin-Ye Jhong

- Current Positions:
 - Assistant Professor, Dept. GIMT, NTUST
- Work Experiences:
 - Assistant Professor, Dept. AI, Tamkang University (TKU).
 - Research Fellow, Smart Electric Vehicle (SEV) Research Center, NTUST. (Recognized for Outstanding R&D Substitute Service)
 - Visiting Scholar, Dept. EE, University of South Florida (USF), Florida, USA (Supported by NSTC Postdoctoral Research Abroad Program)
 - ☐ Full-time Computer Vision Intern, Real Touch Corp. Ltd.

Research Areas:

- Computer Vision and Image Processing
- Machine/Deep Learning
- Reinforcement Learning
- Multimodal Fusion
- Generative Al
- Agentic Al
- Smart IoT
- Intelligent Unmanned Vehicles
- Smart Manufacturing
- Intelligent Transportation



Research Achievements

Journal Publications: 20

Conference Papers: 21

• Patents: 10

Competition Awards: 47

Course Logistics

- Instructor: 鍾昕燁 Sin-Ye Jhong
- Time & Location:
 - □ Tuesday, 13:20-16:10, TR-615
- Email: <u>sinyejhong@mail.ntust.edu.tw</u>
 - To ensure timely response, please include "[DLIR2025]" in the email subject
 - Leaving a message on Moodle is also an option, but responses may not be immediate

Always check the up-to-date information from Moodle

Course Goal

Problem-Based Learning (PBL):

- This is an advanced, hands-on course focused on independent research and implementation.
- □ Goal: To research, implement, and analyze cutting-edge papers in image recognition.

Core Task:

- Research & Implementation: You are required to independently research and implement four academic papers (2 top-tier conference, 2 Q1 journal)
- □ Presentations: You will deliver **four** presentations in total:
 - ✓ Two 10-minute presentations on your paper research (during the semester).
 - ✓ One 20-minute midterm project presentation.
 - ✓ One 20-minute final project presentation.

Key Requirements for Success

Skills:

Proficiency in Python, PyTorch, Git, Docker, ROS, deep learning and image processing fundamentals is required

Hardware (Mandatory):

☐ A high-performance PC is essential. A GPU with at least 16GB of VRAM (e.g., RTX 3090, 4070Ti Super,4080, 4090, 5070Ti, 5080, 5090) is required for model training

Time Commitment:

☐ This course is demanding. Expect to invest at least 20 hours per week

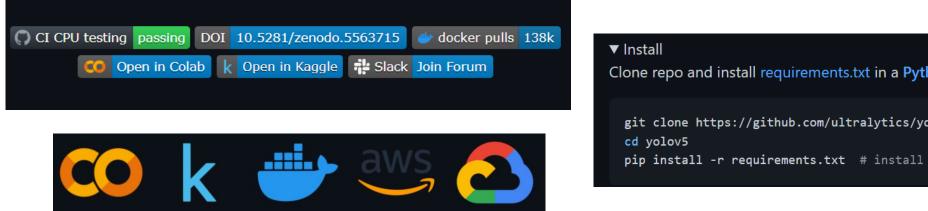
Research Paper Requirements & Deadlines

- Core Task: Read and implement 2 top-tier conference papers & 2 Q1 journal papers (from 2022-2025)
- Deliverables (For Each Paper):
 - Written Report: A detailed analysis of the paper's contributions, methods, and experiments, with clear explanations of your code
 - □ Implementation Code (with Docker): Your code must successfully reproduce the key results described in the paper
- Schedule & Deadlines:
 - ☐ Paper Topic Confirmation: Paper 1 (9/9), Paper 2 (9/30), Paper 3 (10/28), Paper 4 (11/18)
 - ☐ Final Submission: Paper 1 (9/23), Paper 2 (10/14), Paper 3 (11/11), Paper 4 (12/2)

Grading: Your performance on these tasks will directly impact your participation, midterm, and final grades. **Time Commitment:** Be prepared to invest at **least 20 hours per week** on this work. **Please evaluate your schedule and capabilities carefully**.

Example: YOLOv5 as a Standard for Good Projects

Yolov5(ultralytics): https://github.com/ultralytics/yolov5:



Clone repo and install requirements.txt in a Python>=3.7.0 environment, including PyTorch>=1.7. git clone https://github.com/ultralytics/yolov5 # clone

- **Your Project Requirements:**
 - ☐ GitHub: All of your project code must be hosted on GitHub
 - README.md: You must write a detailed README.md file
 - Docker: A Dockerfile is mandatory to ensure your project is reproducible and can be easily tested by the TA.

Grading Policy

- Participation & Paper Reports: 35%
 - ☐ Includes class engagement and four paper implementation reports.
 - HW0 is 15% of this grade
- Midterm Project: 30%
 - Evaluated on Live Demo (20%), Performance Metrics (20%), your 20-min Oral Presentation (30%), and a Written Report (30%)
- Final Project Project: 30%
 - Evaluated on Live Demo (20%), Performance Metrics (20%), your 20-min Oral Presentation (30%), and a Written Report (30%)

All project code must be successfully demonstrated on the TA's computer.

Midterm & Final Project Challenges

Project Format:

- ☐ Unlike the individual paper implementations, these are challenge-based projects
- ☐ We will provide a specific challenge topic and the necessary dataset
- ☐ Your task is to use existing research papers as a foundation to solve the challenge

Midterm Goal:

☐ Implement and optimize a relevant research paper to complete the given image challenge task.

Final Goal:

- Extend your midterm project
- ☐ Improve your results by integrating ideas from one or more additional papers, or by proposing your own novel approach

Midterm & Final Challenge Topics

- Hair Density & Width Estimation (2D Semantic & Instance Segmentation)
- Scalp Analysis (Image Classification, 2D Object Detection)
- Surround-View RGB Object Detection (2D Object Detection)
- Lane Line Detection (2D Semantic & Instance Segmentation)
- Dual-Sensor (RGB + Thermal) Object Detection (2D Object Detection)
- High Dynamic Range (HDR) Imaging (Image-to-Image, HDR Reconstruction)
- Radar & RGB Fusion for Object Detection (2D/3D Object Detection)
- 3D LiDAR Object Detection (3D object detection)
- 3D LiDAR & RGB Fusion for Object Detection (3D object detection)
- 3D LiDAR SLAM (Simultaneous Localization and Mapping)

Important Dates & Deadlines

- TA's Email: <u>D11102001@gapps.ntust.edu.tw</u>
- Regular Paper Reports:
 - ☐ Oral Presentations (10 min): Paper 1 (9/23), Paper 3 (11/11)
 - □ Written Report & Code Submission: Paper 1 (9/23), Paper 2 (10/14), Paper 3 (11/11), Paper 4 (12/2)
- Midterm Project:
 - □ Topic Decision Deadline: 9/23 (Before Week 4)
 - □ Code Confirmation Period: 10/13 ~ 10/31 (Email TA to schedule)
 - ☐ Oral Presentation (20 min): 10/21, 10/28
 - ☐ Final Report & Code Submission: 10/31
- Final Project:
 - □ Code Confirmation Period: 12/1 ~ 12/19 (Email TA to schedule)
 - ☐ Oral Presentation (20 min): 12/9, 12/16
 - ☐ Final Report & Code Submission: 12/19

You must confirm your project topic with the TA. The TA has the final say and may ask you to choose a different topic if it is unsuitable or selected by too many students.

Homework 0: Skills & Hardware Verification

Objective:

☐ To verify your practical skills in **Python**, **ROS**, **Git**, **Docker**, **OpenCV**, and a **major deep learning framework** (PyTorch or TensorFlow).

Tasks:

- □ Task 1 (2D Segmentation): Perform tongue image segmentation using a 2D semantic segmentation model.
- ☐ Task 2 (3D Detection): Train the DeepFusion network (a 3D object detection model using LiDAR & RGB data) and visualize the results on the KITTI dataset.

Grading & Deadline:

- ☐ Grading: This assignment is mandatory and accounts for 15% of your total participation grade.
- □ Due: Next Week (9/8~9/12) (Please schedule a demo time with the TA).

HW0 Task 1: Tongue Segmentation (2D Semantic Segmentation)

Task Description:

- □ Download the provided **Tongue Dataset** and train a **segmentation model** of your choice
- ☐ Your implementation must use a **Docker** environment.
- ☐ Upload your complete project to GitHub
- □ Schedule a demo with the TA to test your model on a designated computer

Evaluation:

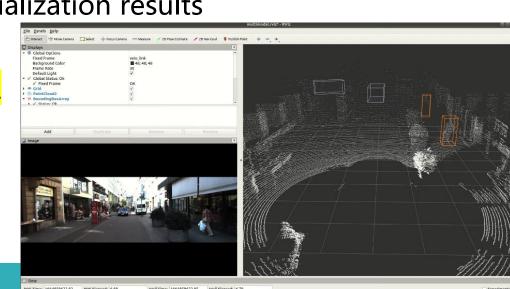
- ☐ Your model will be tested on a private dataset of 250 images.
- ☐ Important Note: The TA will not provide any help or hints during the demo and testing process. You are on your own.
- Links: Tongue Dataset, MMSegmentation, Segmentation models.pytorch



HW0 Task 2: LiDAR + RGB Object Detection (3D Object Detection)

Task Description:

- □ Download the KITTI Dataset and use it to train, validate, and visualize the DeepFusion model.
- ☐ Your implementation must use a Docker environment.
- □ Upload your complete project to GitHub
- Deliverables:
 - ☐ Your full project code on GitHub
 - ☐ A 20-second demo video showing your model's visualization results
- Task Description:
 - Email your GitHub link and the demo video to the TA
- Links: <u>DeepFusion</u>、 <u>KITTI Dataset</u>



Thanks!

Any questions?

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