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# Physics 441: Assignment #1 - Math Review

Due on Friday, May 10, 2013

Berrondo

May 10, 2013

## Problem 1.2

Is the cross product associative?

$$(\mathbf{A} \times \mathbf{B}) \times \mathbf{C} \stackrel{?}{=} \mathbf{A} \times (\mathbf{B} \times \mathbf{C})$$

If so prove it, if not provide a counter example

Let A = i = <1,0,0>, B = i = <1,0,0>, C = k = <0,0,1>.

In this case

$$(\mathbf{A} \times \mathbf{B}) \times \mathbf{C} = (<0,0,0>) \times <0,0,1> = <0,0,0>$$

and

$$A \times (B \times C) = <1,0,0> \times (<0,-1,0>) = <0,0,-1>$$

This two aren't equal to the cross product is non associative.

## Problem 1.4

Use the cross product to find the components of the unit vector  $\hat{n}$  that is normal to the plane passing through the following points: <1,00>,<0,2,0>,<0,0,3>.

We need to find two vectors parallel to the plane. We can use < 1, -2, 0 > and < 0, 2, -3 >. Now that we have those vectors we can take the cross product between them and normalize the resultant vector.

$$<1,-2,0>\times<0,2,-3>=<6,3,2>$$

Now we normalize this vector to make it a unit vector:

$$\frac{<6,3,2>}{\text{norm}(<6,3,2>)} = \frac{<6,3,2>}{7} = <0.86,0.43,0.29>$$

## Problem 1.9

Find the transformation matrix R that describes rotation by  $120^{\circ}$  about an axis from the origin through the point (1,1,1). The rotation is clockwise as you look down the axis toward the origin.

The general form for the rotation matrix of a vector about an axis of direction k is given below<sup>4</sup>:

$$R = \begin{pmatrix} a^2 + b^2 - c^2 - d^2 & 2(bc - ad) & 2(bd + ac) \\ 2(bc + ad) & a^2 + c^2 - b^2 - d^2 & 2(cd - ab) \\ 2(bd - ac) & 2(cd + ab) & a^2 + d^2 - b^2 - c^2 \end{pmatrix}$$

where  $\mathbf{k} = (k_x, k_y, k_z)$  is the axis of rotation and

$$a = \cos(\phi/2);$$

$$b = k_x \sin(\phi/2);$$

$$c = k_y \sin(\phi/2);$$

$$d = k_z \sin(\phi/2).$$

In our case  $\phi = 120^{\circ}$  and k = <1,1,1>. Plugging those things in that a = 0.5 and b = c = d = 0.866. Plugging these values in to the matrix above we get:

$$R = \begin{bmatrix} 0 & 0 & 1 \\ 1 & 0 & 0 \\ 0 & 1 & 0 \end{bmatrix}$$

#### Problem 1.12

The height of a certain hill (in feet) is given by

$$h(x, y) = 10(2xy - 3x^2 - 4y^2018x + 28y + 12)$$

where *y* is the distance (in miles) north, *x* is the distance east of South Hadley.

- 1. Where is the top of the hill located?
- 2. How high is the hill?
- 3. How steep is the slope (in feet per mile) at a point 1 mile north and one mile east of South Hadley? In what direction is the slope steepest, at that point?

 $<sup>^</sup>a$ This algorithm was found at http://en.wikipedia.org/wiki/Euler%E2%80%93Rodrigues\_parameters

To answer these questions we need the gradient

$$\nabla h(x, y) = 10 \left( (2y - 6x - 18) \hat{x} + (2x - 8y + 28) \hat{y} \right)$$

1. The top of the hill is where  $\nabla h(x, y) = 0$ . To find this we set each component equal to 0 and solve the linear system.

$$0 = 10 ((2y - 6x - 18) \hat{x})$$
$$= 2y - 6x - 18$$
$$18 = 2y - 6x$$

$$0 = 10 ((2x - 8y + 28) \hat{y})$$
$$= 2x - 8y + 28$$
$$-28 = 2x - 8y$$

We can now solve the equation Ax = b, where  $A = \begin{pmatrix} -6 & 2 \\ 2 & -8 \end{pmatrix}$ ,  $x = \begin{pmatrix} x \\ y \end{pmatrix}$ , and  $b = \begin{pmatrix} 18 \\ -28 \end{pmatrix}$ 

This yields the solution that x = -2, y = 3, which means that the peak is 3 miles north and two miles west of South Hadley.

- 2. For this part we just plug (-2,3) in to h(x,y) and get  $h^*(x,y) = h(-2,3) = 720$  ft.
- 3. One mile north and one mile east of South Hadley means that x = y = 1. Plugging those into the gradient we get

$$\nabla h(1,1) = 10 \left( (2(1) - 6(1) - 18) \hat{x} + (2(1) - 8(1) + 28) \hat{y} \right) = 10 \left( -22 \hat{x} + 22 \hat{y} \right)$$

The magnitude of this vector represents the steepness of the slope and is equal to  $\sqrt{(-220)^2 + (220)^2} \approx 311.13$ . Because the *x* portion is negative and the *y* portion is positive, the direction of steepest slope is northwest.

## Problem 1.13

Let  $\eta$  be the separation vector from a fixed point (x', y', z') to hte point (x, y, z) and let  $\eta$  be its length. Show that:

- 1.  $\nabla(\eta^2) = 2\eta$
- 2.  $\nabla(1/\eta) = -\eta/\eta^2$
- 3. What is the general formula for  $\nabla(\eta^n)$ ?

We begin by defining  $\eta$ 

$$\eta = (x - x')\hat{x} + (y - y')\hat{y} + (z - z')\hat{z}$$

1. We recognize that  $\eta^2$  is simply the sum of each squared component:

$$n^2 = (x - x')^2 + (y - y')^2 + (z - z')^2$$

We can now compute  $\nabla(\eta^2)$ 

$$\nabla(\eta^2) = \frac{\partial \eta^2}{\partial x}\hat{x} + \frac{\partial \eta^2}{\partial y}\hat{y} + \frac{\partial \eta^2}{\partial z}\hat{z}$$
$$= 2(x - x')\hat{x} + 2(y - y')\hat{y} + 2(z - z')\hat{z}$$
$$= 2\boldsymbol{\eta}$$

2. We know that  $\eta = \sqrt{\eta^2} = \left( (x - x')^2 + (y - y')^2 + (z - z')^2 \right)^{1/2}$ . Using this we can say that  $(1/\eta) = \left( (x - x')^2 + (y - y')^2 + (z - z')^2 \right)^{-1/2}$ . We will use this definition to solve the problem. Note that I define  $\xi \equiv \left( (x - x')^2 + (y - y')^2 + (z - z')^2 \right)^{-3/2} \equiv \eta^{1/3}$ . Also note that  $\eta = \eta \hat{\eta}$ 

$$\begin{split} \nabla(1/\eta) &= \frac{\partial(1/\eta)}{\partial x} \hat{x} + \frac{\partial(1/\eta)}{\partial y} \hat{y} + \frac{\partial(1/\eta)}{\partial z} \hat{z} \\ &= \frac{-1}{2} \xi 2(x - x') \hat{x} - \frac{1}{2} \xi 2(y - y') \hat{y} - \frac{1}{2} \xi 2(z - z') \hat{z} \\ &= -\xi \left[ (x - x') \hat{x} + (y - y') \hat{y} + (z - z') \hat{z} \right] \\ &= -\eta^{1/3} \boldsymbol{\eta} = -\hat{\boldsymbol{\eta}}/\eta^2 \end{split}$$

3. The general formula is pretty easy:

$$\nabla(\eta^{n}) = n\eta^{n-1} \frac{\partial \eta}{\partial x} + n\eta^{n-1} \frac{\partial \eta}{\partial y} + n\eta^{n-1} \frac{\partial \eta}{\partial z}$$

$$= n\eta^{n-1} \left[ \frac{1}{2} \eta^{-1} 2\eta_{x} + \frac{1}{2} \eta^{-1} 2\eta_{y} + \frac{1}{2} \eta^{-1} 2\eta_{z} \right]$$

$$= n\eta^{n-1} \left[ \hat{\boldsymbol{\eta}}_{x} + \hat{\boldsymbol{\eta}}_{y} + \hat{\boldsymbol{\eta}}_{z} \right]$$

$$= n\eta^{n-1} \hat{\boldsymbol{\eta}}$$

#### Problem 1.16

Sketch the vector function

$$v = \frac{\hat{r}}{r^2}$$

and compute its divergence. The ansewr may surprise you ... can you explain it?

The plot of the vector field can be found in Figure 1.

For this problem  $\mathbf{r} = x\hat{x} + y\hat{y} + z\hat{z}$  and  $r = \sqrt{x^2 + y^2 + z^2}$ , so  $\mathbf{v}$  becomes

$$\mathbf{v} = \frac{\hat{\mathbf{r}}}{x^2 + y^2 + z^2} = \frac{\mathbf{r}}{(x^2 + y^2 + z^2)^{3/2}} = \frac{x\hat{x} + y\hat{y} + z\hat{z}}{(x^2 + y^2 + z^2)^{3/2}}$$

The divergence can now be computed. Note that we make the substitution  $\hat{r} = r/r$ 

```
x,y,z=var('x y z')

btm = (x^2 + y^2 + z^2)^(3/2)

plot_vector_field3d((x/btm, y/btm, z/btm), (x,-2,2), (y,-2,2), (z,-2,2))
```

Sleeping... Make Interactive

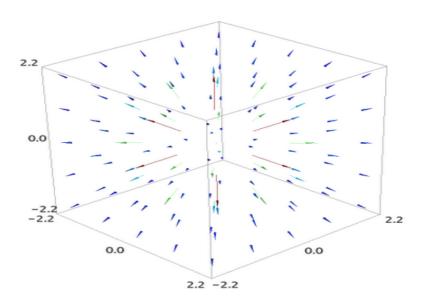


Figure 1: The vector field  $\mathbf{v} = \frac{\hat{\mathbf{r}}}{r^2}$ 

$$\nabla \cdot \boldsymbol{v} = \frac{\partial \boldsymbol{v}}{\partial x} + \frac{\partial \boldsymbol{v}}{\partial y} + \frac{\partial \boldsymbol{v}}{\partial z}$$

$$= \frac{\partial (\boldsymbol{r}/r^3)}{\partial x} + \frac{\partial (\boldsymbol{r}/r^3)}{\partial y} + \frac{\partial (\boldsymbol{r}/r^3)}{\partial z}$$

$$= \frac{\partial}{\partial x} \left[ x(x^2 + y^2 + z^2)^{-3/2} \right] + \frac{\partial}{\partial y} \left[ y(x^2 + y^2 + z^2)^{-3/2} \right] + \frac{\partial}{\partial z} \left[ z(x^2 + y^2 + z^2)^{-3/2} \right]$$

$$= 3(x^2 + y^2 + z^2)^{-3/2} + (-3/2)(x^2 + y^2 + z^2)^{-5/2} \left( 2x^2 + 2y^2 + 2z^2 \right)$$

$$= 3r^{-3} - 3r^{-5} \left( r^2 \right)$$

$$= 3r^{-3} - 3r^{-3} = 0$$

This is in the same form as Coulomb's law for a point charge. In this case the divergence represents the flux at a distance r. Because Coulomb's law describes point charges, the flux is zero for all radii not equal to 0. In other words, the only place flux exists is where the point charge is located.

## Problem 1.18

Calculate the curl of the vector functions:

1. 
$$\mathbf{v} = (x^2)\hat{\mathbf{x}} + (3xz^2)\hat{\mathbf{v}} + (-2xz)\hat{\mathbf{z}}$$

2. 
$$\mathbf{v} = (xy)\hat{\mathbf{x}} + (2yz)\hat{\mathbf{y}} + (3xz)\hat{\mathbf{z}}$$

3. 
$$\mathbf{v} = (y^2)\hat{\mathbf{x}} + (2xy + z^2)\hat{\mathbf{y}} + (2yz)\hat{\mathbf{z}}$$

The curl of a vector  $\boldsymbol{v}$  is defined as

$$\nabla \times \boldsymbol{v} = \begin{vmatrix} \hat{\boldsymbol{x}} & \hat{\boldsymbol{y}} & \hat{\boldsymbol{z}} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ v_x & v_y & v_z \end{vmatrix}$$

We will apply this definition each vector function.

1.

$$\nabla \times \boldsymbol{v} = \begin{vmatrix} \hat{\boldsymbol{x}} & \hat{\boldsymbol{y}} & \hat{\boldsymbol{z}} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \end{vmatrix}$$

$$= \hat{\boldsymbol{x}} \left( \frac{\partial(-2xz)}{\partial y} - \frac{\partial(3xz^2)}{\partial z} \right) - \hat{\boldsymbol{y}} \left( \frac{\partial(-2xz)}{\partial x} - \frac{\partial(x^2)}{\partial z} \right) + \hat{\boldsymbol{z}} \left( \frac{\partial(3xz^2)}{\partial x} - \frac{\partial(x^2)}{\partial y} \right)$$

$$= (-6xz)\hat{\boldsymbol{x}} + (2z)\hat{\boldsymbol{y}} + (3z^2)\hat{\boldsymbol{z}}$$

2.

$$\nabla \times \boldsymbol{v} = \begin{vmatrix} \hat{\boldsymbol{x}} & \hat{\boldsymbol{y}} & \hat{\boldsymbol{z}} \\ \frac{\partial/\partial x}{\partial y} & \frac{\partial/\partial y}{\partial z} & \frac{\partial/\partial z}{\partial z} \end{vmatrix}$$

$$= \hat{\boldsymbol{x}} \left( \frac{\partial(3xz)}{\partial y} - \frac{\partial(2yz)}{\partial z} \right) - \hat{\boldsymbol{y}} \left( \frac{\partial(3xz)}{\partial x} - \frac{\partial(xy)}{\partial z} \right) + \hat{\boldsymbol{z}} \left( \frac{\partial(2yz)}{\partial x} - \frac{\partial(xy)}{\partial y} \right)$$

$$= (-2y)\hat{\boldsymbol{x}} + (-3z)\hat{\boldsymbol{y}} + (-x)\hat{\boldsymbol{z}}$$

3.

$$\nabla \times \boldsymbol{v} = \begin{vmatrix} \hat{\boldsymbol{x}} & \hat{\boldsymbol{y}} & \hat{\boldsymbol{z}} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ \frac{\partial}{\partial z} & \frac{\partial}{\partial z} & \frac{\partial}{\partial z} \end{vmatrix}$$

$$= \hat{\boldsymbol{x}} \left( \frac{\partial (2yz)}{\partial y} - \frac{\partial (2xy + z^2)}{\partial z} \right) - \hat{\boldsymbol{y}} \left( \frac{\partial (2yz)}{\partial x} - \frac{\partial (y^2)}{\partial z} \right) + \hat{\boldsymbol{z}} \left( \frac{\partial (2xy + z^2)}{\partial x} - \frac{\partial (y^2)}{\partial y} \right)$$

$$= (2z - 2z)\hat{\boldsymbol{x}} + (0)\hat{\boldsymbol{y}} + (2y - 2y)\hat{\boldsymbol{z}}$$

$$= 0$$

## Problem 1.19

Draw a circle in the xy plane. At a few representative points draw the vector  $\boldsymbol{v}$  tangent to the circle, pointing in the clockwise direction. By comparing adjacent vectors, determine the sign of  $\frac{\partial v_x}{\partial y}$  and  $\frac{\partial v_y}{\partial x}$ . According to the definition of the curl, what is the direction of  $\nabla \times \boldsymbol{v}$ ? Explain how this example illustrates the geometrical interpretation of the curl.

Moving from point 1 to point 2 in Figure 2 we are increasing in y and decreasing in x. We can also see that both  $v_x$  and  $v_y$  are increasing. Moving from point 3 to point 4 we see that we are increasing in x and decreasing in y, but that  $v_x$  and  $v_y$  are decreasing. From this analysis we can determine the following signs:

$$\frac{\partial v_x}{\partial y} > 0$$

$$\frac{\partial v_y}{\partial x} < 0$$

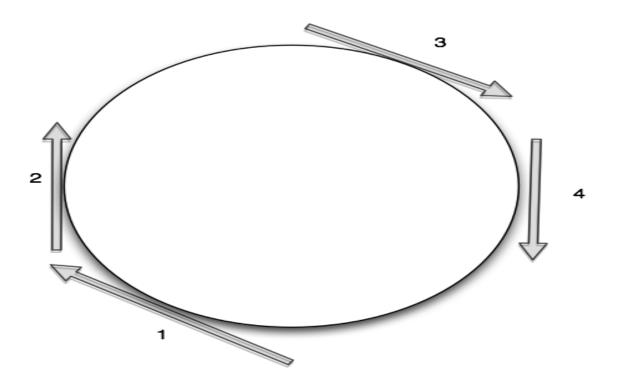


Figure 2: Tangent vectors in the clockwise direction on a circle in the *xy* plane.

Coupling this with the definition of the curl we see that  $\nabla \times \boldsymbol{v}$  is in the negative  $\hat{\boldsymbol{z}}$  direction (terms in the  $\hat{\boldsymbol{x}}$  and  $\hat{\boldsymbol{y}}$  directions are all zero). It follows the direction of the right hand rule. If we take our right hand and twist in the direction of the tangent vectors, we will have our thumb pointing directly into the circle, which is the  $-\hat{\boldsymbol{z}}$  direction.