

Ensemble Time Series Forecasting with Applications in Renewable Energy



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Outline

Introduction

- Motivation

- Background

Ensemble Time Series Forecasting

- Competitive Ensemble Methods

- Cooperative Ensemble Methods

Empirical Mode Decomposition

- EMD-ANN/SVR with Input Vector Reconstruction

- Ensemble EMD

- Ensemble EMD-ANN/SVR for Wind/Solar Forecasting

Random Vector Functional Link Network

- Variations on Structure

- RVFL for Wind/Solar Forecasting

- RVFL for Wind Power Ramp Forecasting

Conclusion & Future Work

- Conclusion

- Future Work

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Renewable Energy

Why Renewable Energy? \Rightarrow Advantages

- ▶ Abundant
- ▶ Sustainable
- ▶ Environmental Friendly

Why NOT Renewable Energy? \Rightarrow Challenges

- ▶ Unstable
- ▶ Time/Weather Dependent
- ▶ High Initial Cost

Forecasting

Benefit of Forecasting

- ▶ Reduce Reserve
- ▶ Reduce Risk of Overloading
- ▶ Precaution on Extreme Weather Conditions

Application of Forecasting

- ▶ *Very Short Term*: active generator control
- ▶ *Short Term*: power grid scheduling
- ▶ *Mid & Long Term*: maintenance scheduling

Development of Forecasting

Intuition

observation; empirical experiences

Statistics

exponential smoothing; autoregressive moving average

Physics, Meteorology & Geography

numeric weather prediction

Computational Intelligence

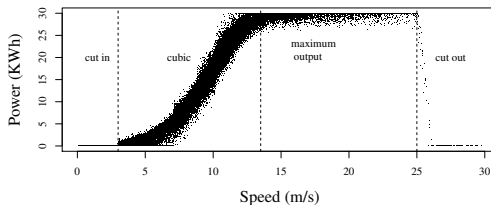
neural networks; fuzzy systems, etc.

Wind and Solar Energy Basics

Wind Energy¹

$$P = \frac{1}{2} \rho_a A_t C_p(\lambda, \beta) v^3$$

where ρ_a : air density, A_t : area of the turbine, $C_p(\lambda, \beta)$: efficiency, λ : tip speed ratio, β : blade pitch, v : up-wind speed.



Wind Power vs Wind Speed Curve

¹ Soman et al. 2010.

Wind and Solar Energy Basics

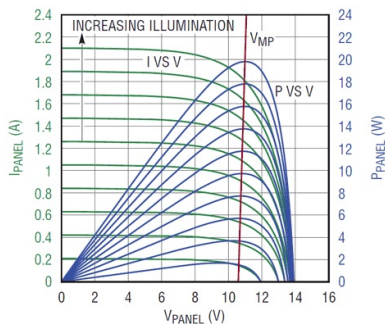
Solar Energy¹

$$G = \alpha G_0 \left(1 + 0.033 \cos \frac{360d}{365}\right) \sin \theta_s$$

$$\sin \theta_s = \cos h \cos \delta \cos \phi + \sin \delta \sin \phi$$

where θ_s : solar elevation angle, h : solar hour angle, δ : sun declination, ϕ : local latitude, d : date sequence of a year, α : cloud/haze cover index,

$G_0 = 1367 \text{ W/m}^2$: solar irradiance constant.



Solar PV Current-Voltage and Power Curve

¹ Wang et al. 2012.

Time Series Basics

Probability Density Function (PDF)

distribution, likelihood of value

Stationary

statistical characteristics are independent of the time when it is observed.

Weakly stationary

1. the mean of the TS is constant and does not depend on time
2. the autocorrelation function (ACF) depends on s and t only through their difference $|s - t|$.

Time Series Basics

Autocorrelation Function

$$\gamma(s, t) = E[(X_s - \mu_s)(X_t - \mu_t)]$$

$$\rho(s, t) = \frac{\gamma(s, t)}{\sqrt{\gamma(s, s)\gamma(t, t)}} = \frac{\gamma(s, t)}{|\sigma_s \sigma_t|}$$

where μ : sample mean, σ : sample standard deviation, γ : auto covariance, ρ : auto correlation.

Trend

additive term, slowly varying

Seasonality

repeated pattern, additive and/or multiplicative

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Ensemble Methods⁴

- ▶ Uses multiple predictors to obtain an aggregated decision which is better than any of the base predictors²
- ▶ Three fundamental reasons for the success of ensemble methods: statistical, computational and representational³
- ▶ Bias-variance-covariance decomposition
- ▶ Divide and conquer

² Opitz and Maclin 1999.

³ **Dietterich2000ensemble** .

⁴ Ren, Suganthan, and Srikanth 2015b; Ren, Zhang, and Suganthan 2016.

Bias-variance-covariance decomposition

$$E[\bar{f} - t]^2 = bias^2 + \frac{1}{M}var + (1 - \frac{1}{M})covar$$

$$bias = \frac{1}{M} \sum_{i=1}^M (E[f_i] - t)$$

$$var = \frac{1}{M} \sum_{i=1}^M E[f_i - E[f_i]]^2$$

$$covar = \frac{1}{M(M-1)} \sum_i \sum_{j \neq i} E[f_i - E[f_i]](f_j - E[f_j])$$

where t : target, M : ensemble size, $E(\cdot)$: expectation function, f_i : output from each single model.

Diversity

Data Diversity

Bagging, boosting, random subspace, spatial correlation

Parameter Diversity

Negative correlation learning, multiple kernel learning,
multi-objective optimization

Structural Diversity

Heterogeneous ensemble

Preprocessing

Wavelet decomposition

Wavelet-ANN

Empirical mode decomposition

EMD-ANN/SVR

Complex Value

Complex value ANN

Postprocessing

Linear-residual analysis

ARIMA-GARCH

Linear-nonlinear

ARIMA-ANN/SVR, RVFL

Converted from ensemble classification

SVR-SVC, extreme randomized discretization

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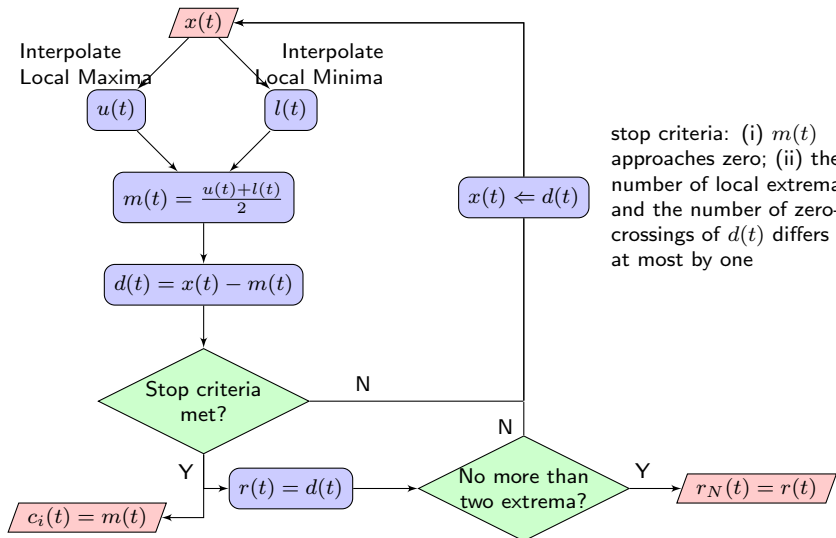
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Conclusion & Future Work

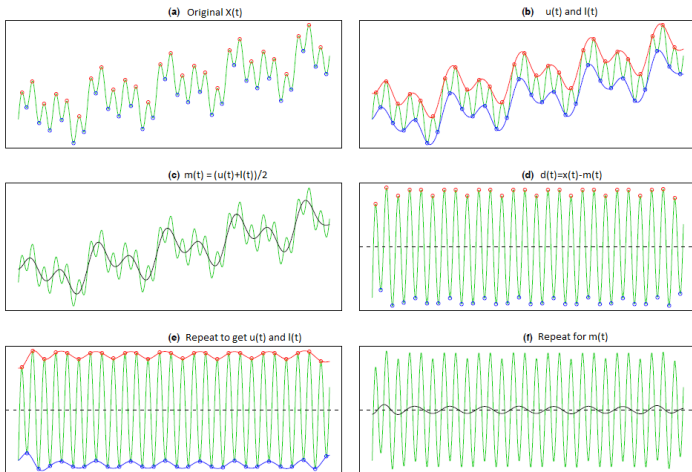
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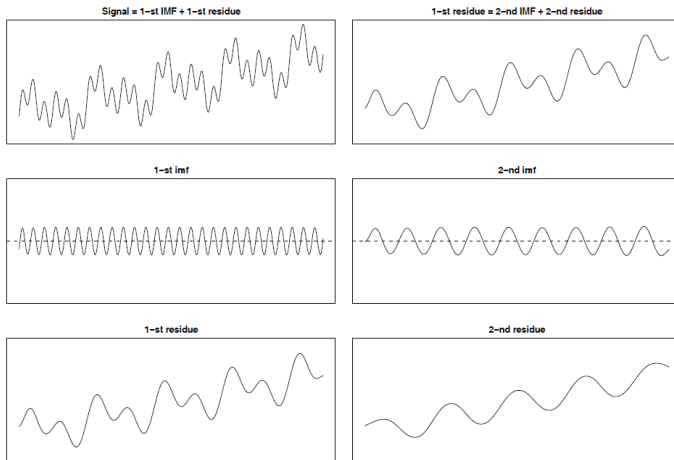
Flowchart



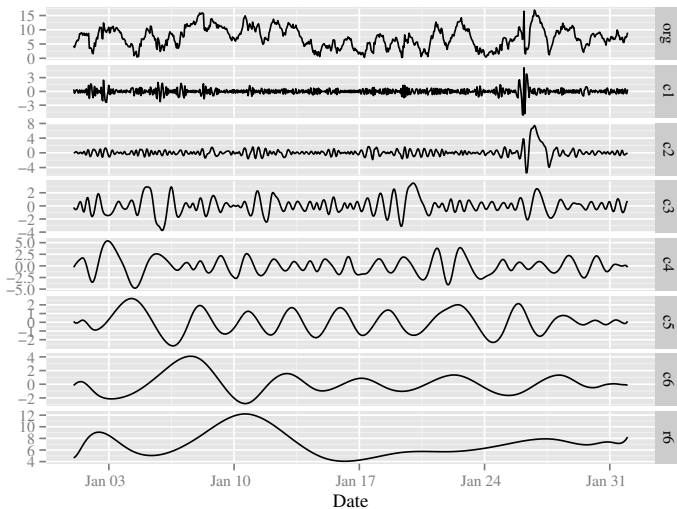
Example⁵



Example⁵



Example⁵



Characteristics⁶

$$x(t) = \sum_{i=1}^N c_i(t) + r_N(t)$$

- ▶ Decompose complex time series into simpler time series
- ▶ Narrow band, symmetric
- ▶ Reveal hidden features/correlations of the original time series

Advantages

- ▶ Adaptive
- ▶ Local
- ▶ Orthogonal
- ▶ Completeness

Disadvantages

- ▶ Mode mixing
- ▶ Uncertain iteration

EMD-ANN/SVR

Multiple predictors approach

$$\hat{x}(t+h) = \sum_{i=1}^N f_i(c_i(t), \dots, c_i(t-p_i+1), \theta_{c_i}) + f(R_N(t), \dots, R_N(t-l_i+1), \theta_R)$$

$\hat{x}(t+h)$: h -step ahead predicted value, $c_i(t)$: i th decomposed IMF, $R_N(t)$: residue,
 p_i : i th lag

- ▶ $N+1$ predictor needed
- ▶ Additive error

EMD-ANN/SVR

Single predictor approach⁷

$$\hat{x}(t+h) = f(c_i(t), R_N(t), \theta), i \in \{1, \dots, N\}$$

$\hat{x}(t+h)$: h -step ahead predicted value, $c_i(t)$: i th decomposed IMF, $R_N(t)$: residue,
 p_i : i th lag

- ▶ Reduce computation time
- ▶ Sacrifice accuracy
- ▶ Issue on feature selection

Input Vector Reconstruction

Main Algorithm⁸

1. Decomposes $\mathbf{x}(t)$ by EMD into a collection of IMFs: $c_i(t)$ $i \in \{1, \dots, N\}$, and a Residue r_N ,
2. Combines the IMFs up-to an optimal lag l based on a feature selection module \Rightarrow input vector
3. Forecast the output from the input vector by ANN/SVR

Advantages

1. Does not require more than one predictor to model the decomposed time series \Rightarrow low computational power
2. Retains the importance of autocorrelation of time series

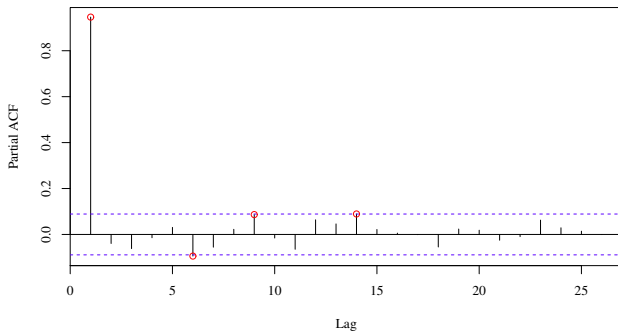
Input Vector Reconstruction

Feature selection

- ▶ PACF selection
- ▶ mRMR selection
- ▶ 2-days' historical data (FULL)

Input Vector Reconstruction

PACF selection



Input Vector Reconstruction

mRMR selection

- ▶ minimum Redundancy Maximum Relevance
- ▶ select the top 50% salient features
- ▶

$$I(x, y) = -0.5 \ln(1 - \rho(x, y)^2)$$

where x : input feature, y : output data, I : mutual information, ρ : correlation coefficient (usually Pearson's or Spearman's correlation coefficient)

First select:

$$x_i = \operatorname{argmax}_{x_i \in X} I(x_i, y)$$

Repeatedly select:

$$x_j = \operatorname{argmax}_{x_j \in X} I(x_j, y) - \frac{1}{|S|} \sum_{x_i \in S} I(x_j, x_i)$$

Experiment Setup

- ▶ NDBC sites 41004, 44009, 46077, year 2011.
- ▶ Monthly, 70% for training, 30% for testing.
- ▶ 1 – 12 hour ahead forecasting
- ▶ Error metric: nRMSE, nMAE, MASE

$$\text{nRMSE} = \frac{1}{x_{\max} - x_{\min}} \sqrt{\text{E}[(\hat{x} - x)^2]}$$

$$\text{nMAE} = \frac{1}{x_{\max} - x_{\min}} \sqrt{\text{E}|\hat{x} - x|}$$

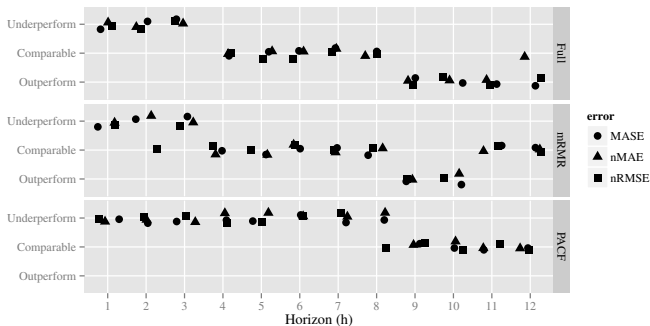
$$\text{MASE} = \frac{\sum_{t=1}^n |\hat{x} - x|}{\frac{n}{n-1} \sum_{i=2}^n |x_i - x_{i-1}|}$$

$$\text{sMAPE} = \frac{1}{n} \sum_{t=1}^n \frac{|x - \hat{x}|}{(|x| + |\hat{x}|)/2} \times 100\%$$

where \hat{x} : predicted data, x : desired data, n : number of data points in the time series.

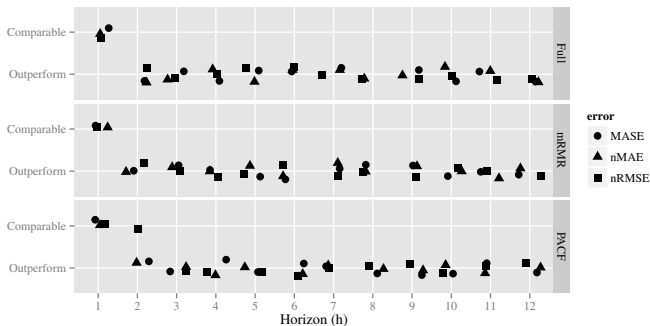
Results and Discussion

Improvement Contributed by EMD to ANN, Wilcoxon Signed Rank Test



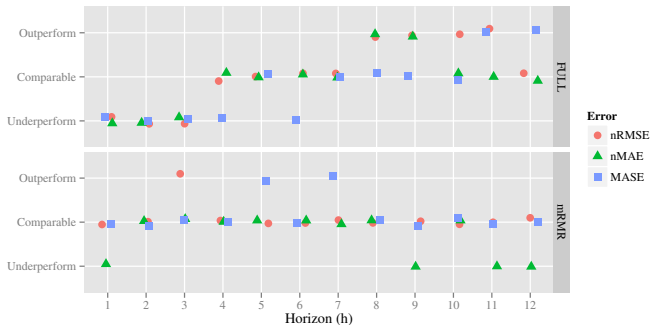
Results and Discussion

Improvement Contributed by EMD to SVR, Wilcoxon Signed Rank Test



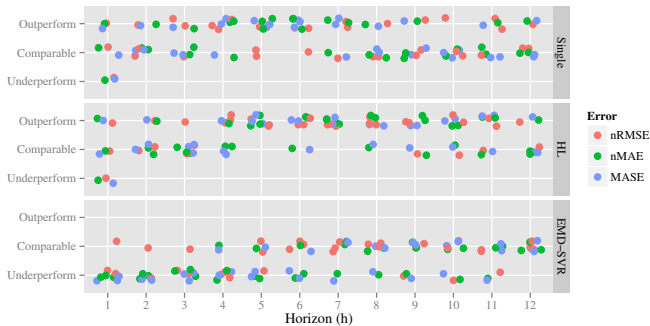
Results and Discussion

Feature Selection Comparison (PACF vs FULL and mRMR), Nemenyi Test



Results and Discussion

Comparison with Benchmark Methods (vs Single⁸ and HL⁹), Nemenyi Test



⁸ Han and Zhu 2011.

⁹ Ye and Liu 2011.

Concluding Remarks

- ▶ Improvement of EMD on SVR is significant
- ▶ PACF reduces the input space complexity without degrading the performance
- ▶ Outperformed two benchmark methods and comparable with multiple predictor based EMD-SVR

Noise assisted ensemble EMD (EEMD)¹⁰

Noise assisting

- ▶ Uncorrelated Gaussian noise
- ▶ Multiple Trials
- ▶ Noise may cancel each other after aggregation

Side effect

- ▶ Completeness violated
- ▶ Large number of trials

¹⁰ Wu and Norden E. Huang 2009.

Noise assisted ensemble EMD (EEMD)¹⁰

1. Create a collection of noise added original time series:
 $x^i(t) = x(t) + \varepsilon^i(t)$, $i \in \{1, \dots, I\}$, where $\varepsilon(t)$ are independent Gaussian white noise.
2. For each $x^i(t)$, apply EMD to obtain the decomposed IMFs and residue: $x^i(t) = \sum_{j=1}^N c_j^i + r_N^i$.
3. In order to reconstruct back the original time series, one just needs to average on all trials:

$$x(t) = \frac{1}{I} \left(\sum_{i=1}^I \sum_{j=1}^N c_j^i + r_N^i \right) + \varepsilon_I$$

where $\varepsilon_I = \frac{\varepsilon}{\sqrt{I}}$ is the aggregated error.

¹⁰ Wu and Norden E. Huang 2009.

Complementary ensemble EMD (CEEMD)¹¹

Improvement

- ▶ Correlated Gaussian noise
- ▶ Noise can 100% cancel each other after aggregation

$$\varepsilon^i(t) \in \{\varepsilon_+^{i/2}(t), \varepsilon_-^{i/2}(t)\}$$

where $\varepsilon_+^{i/2}(t) + \varepsilon_-^{i/2}(t) = 0$, $i \in \{1, \dots, I\}$.

Side effect

- ▶ Double the trials

¹¹ Yeh, Shieh, and N. E. Huang 2010.

Complete ensemble EMD with adaptive noise (CEEMDAN)¹²

Improvement

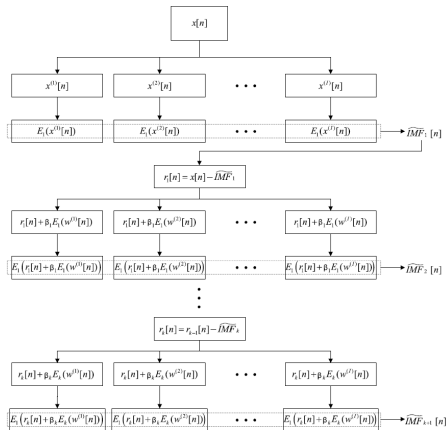
- ▶ Controlled noise generation
- ▶ Reduce number of iteration
- ▶ Completeness

Side effect

- ▶ Sequential, cannot use parallel computing
- ▶ Question on noise s.d. selection

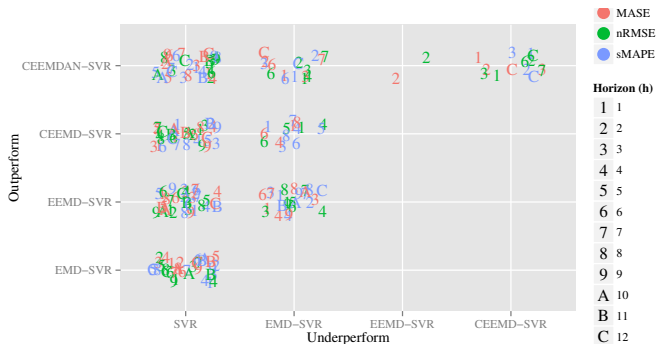
¹² Torres et al. 2011.

Complete ensemble EMD with adaptive noise (CEEMDAN)¹²



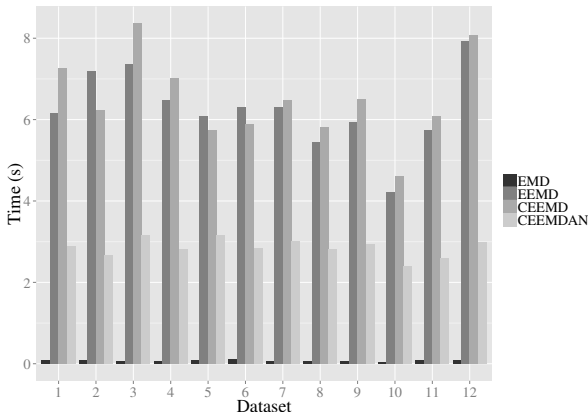
EEMD vs EMD on Wind Speed Forecasting

Wilcoxon Signed Rank Test among the SVR based Methods



EEMD vs EMD on Wind Speed Forecasting

CPU Time



EEMD vs EMD on Solar Irradiance Forecasting¹³

Wilcoxon Signed Rank Test between the Persistent model and the SVR based Methods

Horizon(h)	SVR	EMD-SVR	EEMD-SVR	CEEMD-SVR	CEEMDAN-SVR
24	0.006	0.999	0.000	0.001	0.001
48	0.017	0.992	0.000	0.006	0.001

¹³ Ren, Suganthan, and Srikanth 2015a.

EEMD vs EMD on Solar Irradiance Forecasting¹³

Wilcoxon Signed Rank Test among the SVR based Methods

		Underperformance				
		SVR	EMD-SVR	EEMD-SVR	CEEMD-SVR	CEEMDAN-SVR
Output performance	24 h ahead	SVR	–	0.000	0.993	0.935
		EMD-SVR	1	–	1	0.999
		EEMD-SVR	0.008	0.000	–	0.0319
		CEEMD-SVR	0.075	0.000	0.973	–
		CEEMDAN-SVR	0.026	0.001	0.986	0.338
	48 h ahead	SVR	–	0.001	0.997	0.830
		EMD-SVR	0.999	–	0.999	0.999
		EEMD-SVR	0.003	0.001	–	0.008
		CEEMD-SVR	0.190	0.001	0.993	–
		CEEMDAN-SVR	0.017	0.001	0.999	0.425

Concluding Remarks

Wind Speed Forecasting

- ▶ Noise assisted Ensemble EMD-SVR outperform EMD-SVR
- ▶ CEEMDAN-SVR has the best performance (accuracy and time)

Solar Irradiance Forecasting

- ▶ EMD-SVR underperform SVR and persistent method (mode mixing)
- ▶ Noise-assisted ensemble EMD versions have attenuated the mode mixing problem and the performance has been elevated significantly
- ▶ EEMD-SVR has the best performance

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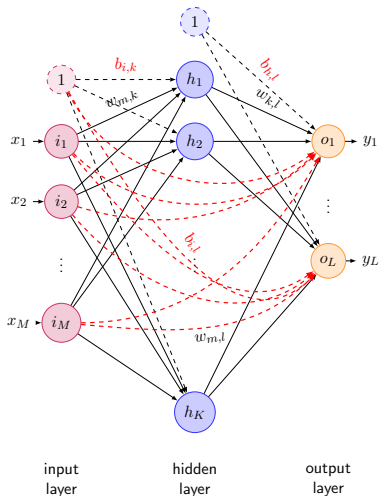
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Schematic Diagram



Dashed red arrows: direct connections between the input neurons and the output neurons, Dashed black arrows: connections from a bias neuron, $f(\cdot)$: *logsig* activation function. N : number of samples, M : number of input neurons, K : number of hidden neurons. $w_{m,k}$: weights between the input and hidden layer neurons, $w_{k,l}$: weights between the hidden and output layer neurons and $b_{i,k}$ and $b_{h,j}$: input layer and hidden layer biases.

Feature

Compare with ANN¹⁴

- ▶ No Need backpropagation to train the network
- ▶ Random weights for $w_{m,k}$
- ▶ Least square estimation to obtain $w_{k,l}$ and $w_{m,l}$

¹⁴ Pao, Park, and Sobajic 1994; Chen 1996.

Variations¹⁷

Method	Input Layer Bias	Hidden Layer Bias	Input-Output Connection	Formula
M1	✓	✓	✓	$h_k = f(\sum_{m=1}^M w_{m,k} i_m + b_{i,k})$ $o_l = \sum_{k=1}^K w_{k,l} h_k + b_{h,l} + \sum_{m=1}^M w_{m,l} i_m + b_{i,l}$
M2 15	✓	✓	×	$h_k = f(\sum_{m=1}^M w_{m,k} i_m + b_{i,k})$ $o_l = \sum_{k=1}^K w_{k,l} h_k + b_{h,l}$
M3 16	✓	×	✓	$h_k = f(\sum_{m=1}^M w_{m,k} i_m + b_{i,k})$ $o_l = \sum_{k=1}^K w_{k,l} h_k + \sum_{m=1}^M w_{m,l} i_m + b_{i,l}$
M4	✓	×	×	$h_k = f(\sum_{m=1}^M w_{m,k} i_m + b_{i,k})$ $o_l = \sum_{k=1}^K w_{k,l} h_k$
M5	×	✓	✓	$h_k = f(\sum_{m=1}^M w_{m,k} i_m)$ $o_l = \sum_{k=1}^K w_{k,l} h_k + b_{h,l} + \sum_{m=1}^M w_{m,l} i_m$
M6	×	✓	×	$h_k = f(\sum_{m=1}^M w_{m,k} i_m)$ $o_l = \sum_{k=1}^K w_{k,l} h_k + b_{h,l}$
M7	×	×	✓	$h_k = f(\sum_{m=1}^M w_{m,k} i_m)$ $o_l = \sum_{k=1}^K w_{k,l} h_k + \sum_{m=1}^M w_{m,l} i_m$
M8	×	×	×	$h_k = f(\sum_{m=1}^M w_{m,k} i_m)$ $o_l = \sum_{k=1}^K w_{k,l} h_k, \forall k \in \{1, \dots, K\}, \forall l \in \{1, \dots, L\}$

15 Schmidt, Kraaijveld, and Duin 1992.

16 Pao, Park, and Sobajic 1994.

17 Ren, Suganthan, Srikanth, and Amaratunga 2016.

Influence of Input Layer Bias

Wind Speed Forecasting, Wilcoxon Signed Rank Test

Comparison	Horizon (h)			
	1	4	8	12
M1 v.s. M5	0.081	0.013	0.011	0.115
M2 v.s. M6	0.101	0.229	0.008	0.001
M3 v.s. M7	0.408	0.007	0.002	0.057
M4 v.s. M8	0.377	0.121	0.012	0.001

Solar Irradiance Forecasting, Wilcoxon Signed Rank Test

Comparison	Horizon (h)	
	24	48
M1 v.s. M5	0.694	0.952
M2 v.s. M6	0.910	0.608
M3 v.s. M7	0.435	0.333
M4 v.s. M8	0.805	0.201

Influence of Hidden Layer Bias

Wind Speed Forecasting, Wilcoxon Signed Rank Test

Comparison	Horizon (h)			
	1	4	8	12
M1 v.s. M3	0.121	0.281	0.313	0.637
M2 v.s. M4	0.144	0.964	0.242	0.187
M5 v.s. M7	0.387	0.387	0.006	0.096
M6 v.s. M8	0.906	0.281	0.523	0.160

Solar Irradiance Forecasting, Wilcoxon Signed Rank Test

Comparison	Horizon (h)	
	24	48
M1 v.s. M3	0.026	0.777
M2 v.s. M4	0.847	0.744
M5 v.s. M7	0.675	0.157
M6 v.s. M8	0.142	0.221

Influence of Direct Input–Output Connections

Wind Speed Forecasting, Wilcoxon Signed Rank Test

Comparison	Horizon (h)			
	1	4	8	12
M1 v.s. M2	<i>0.290</i>	0.002	7.0e-07	3.5e-05
M3 v.s. M4	<i>0.550</i>	1.8e-04	5.2e-07	1.6e-05
M5 v.s. M6	<i>0.560</i>	0.002	8.4e-07	1.3e-05
M7 v.s. M8	<i>0.632</i>	0.002	3.7e-06	2.5e-05

Solar Irradiance Forecasting, Wilcoxon Signed Rank Test

Comparison	Horizon (h)	
	24	48
M1 v.s. M2	0.029	0.004
M3 v.s. M4	0.010	0.005
M5 v.s. M6	0.029	0.017
M7 v.s. M8	0.004	0.006

Compare with Benchmark Methods

Wilcoxon Signed Rank Test

RVFL vs hierarchical ensemble methods				
	Horizon (h)	ARIMA-ANN	ARIMA-SVR	
RVFL	1	9.09e-13	1.00	
	4	9.09e-13	0.99	
	8	9.09e-13	0.89	
	12	1.18e-13	0.64	
RVFL vs other machine learning methods				
	Horizon (h)	ANN	SVR	RF
RVFL	1	0.006	0.125	0.500
	4	0.006	0.187	0.437
	8	0.006	0.437	0.312
	12	0.006	0.312	0.312

Concluding Remarks

- ▶ Hidden layer bias: no significant improvement
- ▶ Input layer bias: improve for wind forecasting only
- ▶ Direct input–output connections: significant improvement
- ▶ RVFL better than two stage hierarchical ensemble methods (ARIMA-ANN)

Wind Power Ramp¹⁸

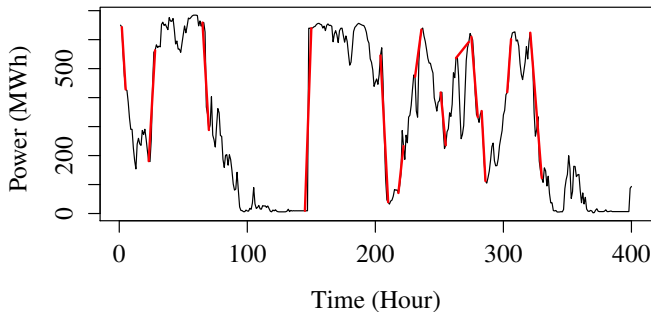
$$\Gamma_{ext} = \max(P(t, \dots, t + \Delta t)) - \min(P(t, \dots, t + \Delta t)) > \Gamma_{val}$$

$$\Gamma_{end} = |P(t + \Delta t) - P(t)| > \Gamma_{val}$$

where $P(t)$: wind power generated at time t , Δt : time interval, Γ_{val} : threshold

¹⁸ Bossavy, Girard, and Kariniotakis 2013.

Wind Power Ramp¹⁸



¹⁸ Bossavy, Girard, and Kariniotakis 2013.

Dataset Processing¹⁹

	$\hat{x} = +1$	$\hat{x} = -1$
$x = +1$	TP	FN
$x = -1$	FP	TN

Imbalance

- ▶ Upsample minority class training data
- ▶ Keep test data untouched
- ▶ Use F Score instead of accuracy

$$\text{Recall} = \frac{TP}{TP + FN}$$

$$\text{Precision} = \frac{TP}{TP + FP}$$

$$F \text{ Score} = 2 \frac{\text{Precision} \cdot \text{Recall}}{\text{Precision} + \text{Recall}}$$

where TP stands for true positive, FN stands for false negative, FP stands for false positive and TN stands for true negative.

Classification Performance

Friedman Test

Measure	Γ_{ext}				Γ_{end}			
	6 Hour		12 Hour		6 Hour		12 Hour	
	χ^2	p	χ^2	p	χ^2	p	χ^2	p
<i>F</i> Score	4.92	0.177	10.92	0.0121	3.7826	0.286	7.8	0.050
Precision	1.08	0.781	12.12	0.0069	1.1739	0.759	7.8	0.050
Recall	8.1875	0.0423	9.72	0.021	7.6957	0.053	4.4667	0.215

Nemenyi Test

		Γ_{ext}			Γ_{end}		
		ANN	RF	SVM	ANN	RF	SVM
RVFL	<i>F</i> Score	0.203	0.961	0.017	0.20	0.99	0.12
	Precision	0.068	0.995	0.122	0.32	0.99	0.20
	Recall	0.122	0.611	0.017	0.53	0.69	0.20

CPU Time (s)

Dataset	6 Hour								12 Hour							
	RF		SVM		ANN		RVFL		RF		SVM		ANN		RVFL	
	Train	Test	Train	Test	Train	Test	Train	Test	Train	Test	Train	Test	Train	Test	Train	Test
Γ_{ext}																
D1	1.2	1.13	85.85	0.24	205.42	7.55	1.72	0.09	0.81	0.78	64.36	0.22	151.3	3.95	1.37	0.08
D2	0.88	0.9	75.56	0.2	176.92	4.52	1.7	0.09	0.7	0.67	50.3	0.17	118.95	3.62	1.27	0.06
D3	1.17	1.22	88.48	0.22	181.02	6.27	1.67	0.88	0.67	0.7	57.47	0.16	113.88	4.57	1.22	0.06
D4	0.78	0.81	72.88	0.21	157.63	4.48	1.89	0.08	0.62	0.63	51.01	0.15	122.21	3.71	1.26	0.06
D5	0.98	1.01	92.18	0.33	187.18	5.04	1.73	0.1	0.89	0.85	64.46	0.2	141.37	3.32	1.39	0.08
Ave	1	1	82.99	0.24	181.63	5.57	1.74	0.25	0.74	0.73	57.52	0.18	129.54	3.83	1.30	0.07
Sd	0.182	0.166	8.37	0.05	17.29	1.32	0.09	0.35	0.11	0.09	6.88	0.03	16.00	0.47	0.07	0.01
Γ_{end}																
D1	1.06	1.07	86.03	0.25	214.61	5.55	1.72	0.09	0.98	0.8	70.18	0.21	154.19	4.42	1.55	0.08
D2	0.92	1.12	78.76	0.12	173.92	5.48	1.75	0.08	0.66	0.63	46.34	0.13	115.34	4.64	1.22	0.09
D3	1.14	1.17	89.94	0.25	183.11	5.3	1.76	0.09	0.78	0.98	64.57	0.2	139.76	4.15	1.61	0.05
D4	1	0.78	71.74	0.21	157.38	4.07	1.81	0.08	0.64	0.61	51.28	0.16	124.77	3.2	1.26	0.05
D5	1	1.14	93.96	0.3	176.78	4.92	1.73	0.09	0.85	1.09	71	0.21	146.03	3.52	1.48	0.08
Ave	1.03	1.06	84.09	0.23	181.16	5.06	1.75	0.09	0.78	0.82	60.67	0.18	136.02	3.99	1.42	0.07
Sd	0.08	0.16	8.89	0.07	20.97	0.61	0.04	0.01	0.14	0.31	11.25	0.04	15.80	0.61	0.17	0.02

Concluding Remarks

- ▶ RVFL has better performance than SVM for 12 h ahead forecasting; comparable as ANN and RF
- ▶ RVFL has fast training time as RF but has the fastest testing time

Outline

Introduction

- Motivation

- Background

Ensemble Time Series Forecasting

- Competitive Ensemble Methods

- Cooperative Ensemble Methods

Empirical Mode Decomposition

- EMD-ANN/SVR with Input Vector Reconstruction

- Ensemble EMD

- Ensemble EMD-ANN/SVR for Wind/Solar Forecasting

Random Vector Functional Link Network

- Variations on Structure

- RVFL for Wind/Solar Forecasting

- RVFL for Wind Power Ramp Forecasting

Conclusion & Future Work

- Conclusion

- Future Work

Conclusion I

- ▶ Introduction of time series characteristics
- ▶ Review of ensemble forecasting methods

EMD based method

- ▶ EMD-ANN/SVR with input vector reconstruction
- ▶ Significant improvement over SVR
- ▶ Outperformed two benchmark methods
- ▶ Noise assisted ensemble EMD improved the performance of SVR for wind speed forecasting, best method is CEEMDAN-SVR
- ▶ EEMD-SVR is the best for solar irradiance forecasting

Conclusion II

RVFL network

- ▶ Direct input output connections have significantly improved the performance
- ▶ No evidence of hidden layer bias
- ▶ Advantageous over hierarchical forecasting method
- ▶ Outperformed ANN, comparable performance as SVR and RF
- ▶ Short computational time

- ▶ For higher accuracy: ensemble EMD, e.g. CEEMDAN-SVR
- ▶ Rapid updating, fast training: RVFL network
- ▶ IoT applications: RVFL network

Future Work

- ▶ Multivariate datasets, multiple renewable energy sources
- ▶ 2-dimensional EMD
- ▶ Ensemble of RVFL network
- ▶ Resource constrained RVFL network

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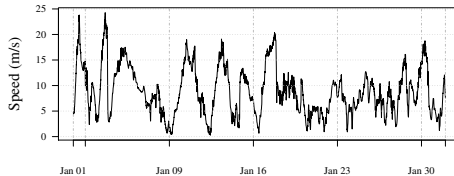
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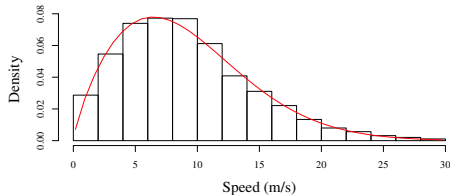
Thank you!

Wind speed time series plot

Plot of wind speed time series

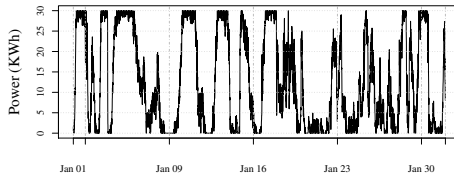


Histogram of wind speed time series

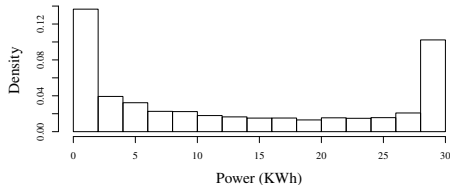


Wind speed time series plot

Plot of wind power time series

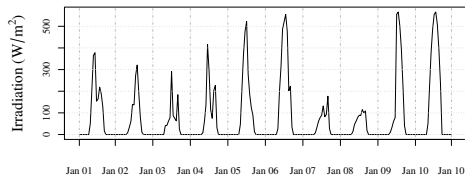


Histogram of wind power time series

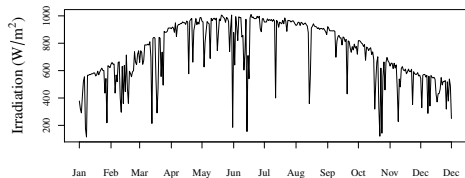


Wind speed time series plot

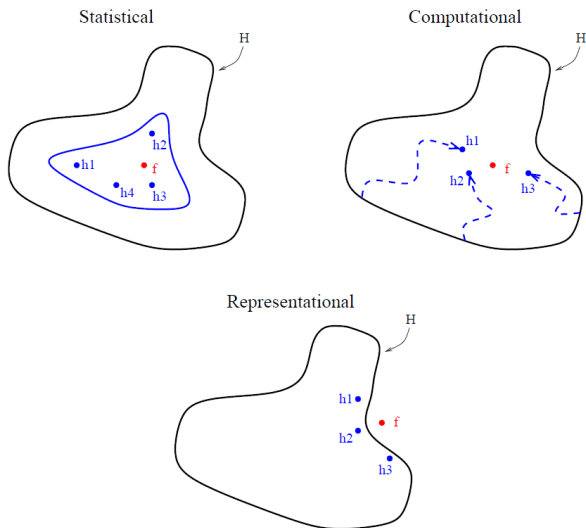
Plot of solar irradiance time series



Daily maximum of solar irradiance time series



Reason for good ensembles



Statistical Forecasting Methods

Exponential Smoothing

$$\hat{x}(t+1) = \alpha x(t) + \alpha(1-\alpha)x(t-1)$$

α : exponentially decreasing weight over time

Statistical Forecasting Methods

ARIMA

$$\nabla^d x(t) = \underbrace{\sum_{i=1}^p \phi_i \nabla^d x(t-i)}_{\text{AR Term}} + w_t + \underbrace{\sum_{j=1}^q \theta_j w(t-j)}_{\text{MA Term}}$$

$$\nabla^d x = [x(t) - x(t-1)] - [x(t-1) - x(t-2)] - \dots - [x(t-d+1) - x(t-d)]$$

Statistical Forecasting Methods

ARIMA Order

		PACF	
		Decay	Cut-off at Lag p
ACF	Decay	—	ARMA(p,d,0)
	Cut-off at Lag q	ARIMA(0,d,q)	ARIMA (p,d,q)

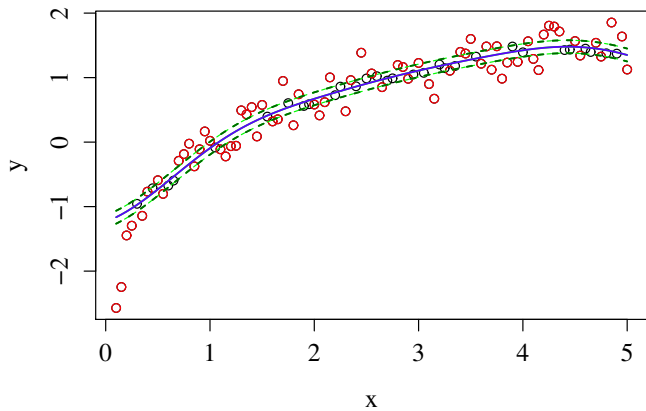
Statistical Forecasting Methods

AIC and BIC

$$\text{AIC} = \log \frac{\sum_{t=k}^n (x(t) - \bar{x})^2}{n} + \frac{n + 2k}{n}$$

$$\text{BIC} = \log \frac{\sum_{t=k}^n (x(t) - \bar{x})^2}{n} + \frac{k \log n}{n}$$

SVR



SVR

$$\min \frac{1}{2} ||w||^2 + C \sum_i (\xi_i + \xi_i^*)$$

subject to:

$$y_i - w^T x_i - b \leq \epsilon + \xi_i$$

$$w^T x_i + b - y_i \leq \epsilon + \xi_i^*$$

$$\xi_i^{(*)} \geq 0$$

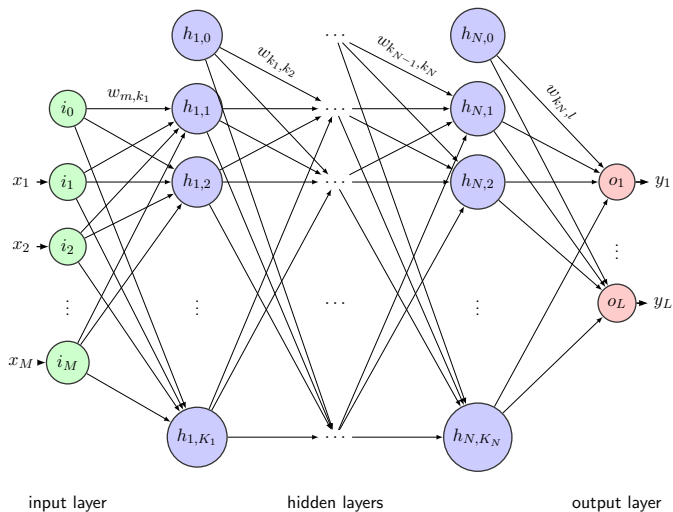
where C is the cost factor for trade-off between flatness and tolerance. $\xi_i^{(*)}$ is the slack variable.

Polynomial Kernel: $K(x_i, x_j) = (\gamma x_i^T x_j)^d$

RBF Kernel: $K(x_i, x_j) = e^{\gamma |x_i - x_j|^2}$

Sigmoid Kernel: $K(x_i, x_j) = \tanh(\gamma x_i^T x_j)$

Neural Network



Neural Network

$$\begin{aligned}h_{1,k_1} &= f\left(\sum_{m=0}^M w_{m,k_1} i_m\right), \forall k_1 \in \{1, \dots, K_1\} \\h_{n,k_n} &= f\left(\sum_{k_{n-1}=0}^{K_{n-1}} w_{k_{n-1},k_n} h_{n-1,k_{n-1}}\right), \forall k_n \in \{2, \dots, K_n\} \\o_l &= \sum_{k_N=0}^{K_N} w_{k_N,l} h_{N,k_N}, \forall l \in \{1, \dots, L\}\end{aligned}\tag{1}$$

Neural Network

$$\begin{aligned} \text{logsig}(x) &= \frac{1}{1 + e^{-x}} \\ \text{tanh}(x) &= \frac{e^x - e^{-x}}{e^x + e^{-x}} \end{aligned}$$

AdaBoost²⁰ EMD

$\{\mathbf{x}\} := m \times n$: training data

y : corresponding future value

I_m : maximum number of iterations

$f(\cdot)$: base learning algorithm

$\mathbf{w} := m \times 1$: weight vector

$\mathbf{w}^1 = \{w_i^1 | 1/m, 1 \leq i \leq m\}$

$\bar{L} = 0$

FOR $t = 1$ to I_m & $\bar{L} < 0.5$

Sample with replacement from \mathbf{x} with distribution $\mathbf{w} \Rightarrow \mathbf{x}^t$

Obtain a trained model $h_t = f(\mathbf{x}^t)$

Calculate maximum loss $L_m = \max |y_i - h_t(x_i)|$

Calculate individual loss $L_i = \frac{|y_i - h_t(x_i)|}{L_m}$

Calculate weighted loss $\bar{L} = \sum_{i=1}^m L_i w_i^t$

Update weight vector $w_i^{t+1} = \frac{w_i^t \beta_t^{(1-L_i)}}{Z_t}$,

where $\beta_t = \frac{\bar{L}}{1-\bar{L}}$ and Z_t is a normalization factor.

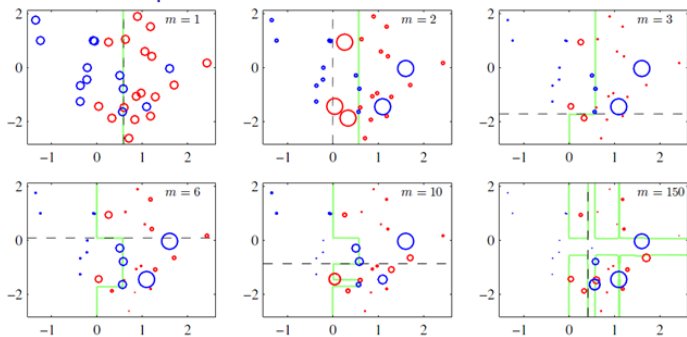
END

RETURN $\hat{y}^* = \text{median}(h_t(x^*) * \ln \frac{1}{\beta_t}), t = 1 \cdots I_m$.

where x^* is a testing data and \hat{y}^* is the predicted output.

AdaBoost²⁰ EMD

AdaBoost Example



AdaBoost Characteristics

- ▶ Weak learners
- ▶ Diversity
- ▶ Sequential
- ▶ Apply AdaBoost to each decomposed series

AdaBoost-EMD-ANN Performance²¹

Nemenyi Test

Nemenyi Test of AdaBoost-EMD-ANN vs Benchmarks

Horizon (h)	Persistent	AdaBoost-RT	ANN	AdaBoost-ANN	EMD-ANN	ABEMD-RT
1	5.5e-08	0.36529	0.17533	7.5e-05	0.11252	0.79266
3	3.0e-07	0.48706	0.03479	0.00856	0.00052	1.00000
5	4.7e-05	0.61549	0.00028	0.14133	7.0e-06	1.00000

Concluding Remarks

AdaBoost framework improved EMD-ANN's performance

²¹ Ren, Qiu, et al. 2015.

ELIA power ramp data

	6 Hour				12 Hour			
	Training		Testing		Training		Testing	
	+1	-1	+1	-1	+1	-1	+1	-1
Γ_{ext}								
D1	64	387	32	184	153	292	71	145
D2	332	136	55	168	252	210	111	112
D3	103	365	54	169	220	242	120	103
D4	77	340	58	144	152	259	75	127
D5	78	389	58	165	164	297	107	116
Γ_{end}								
D1	62	389	26	190	124	321	54	162
D2	130	228	45	178	237	225	85	138
D3	93	375	60	163	167	295	115	108
D4	82	335	78	124	150	261	62	140
D5	84	383	59	164	144	317	117	106