

# UEFI & EDK II TRAINING EDK II BUILD SPECIFICATION FILES LAB

See also Lab Guide.md for Copy & Paste examples in labs

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## LESSON OBJECTIVE



Examine the Build components and build text files DSC, DEC, & FDF

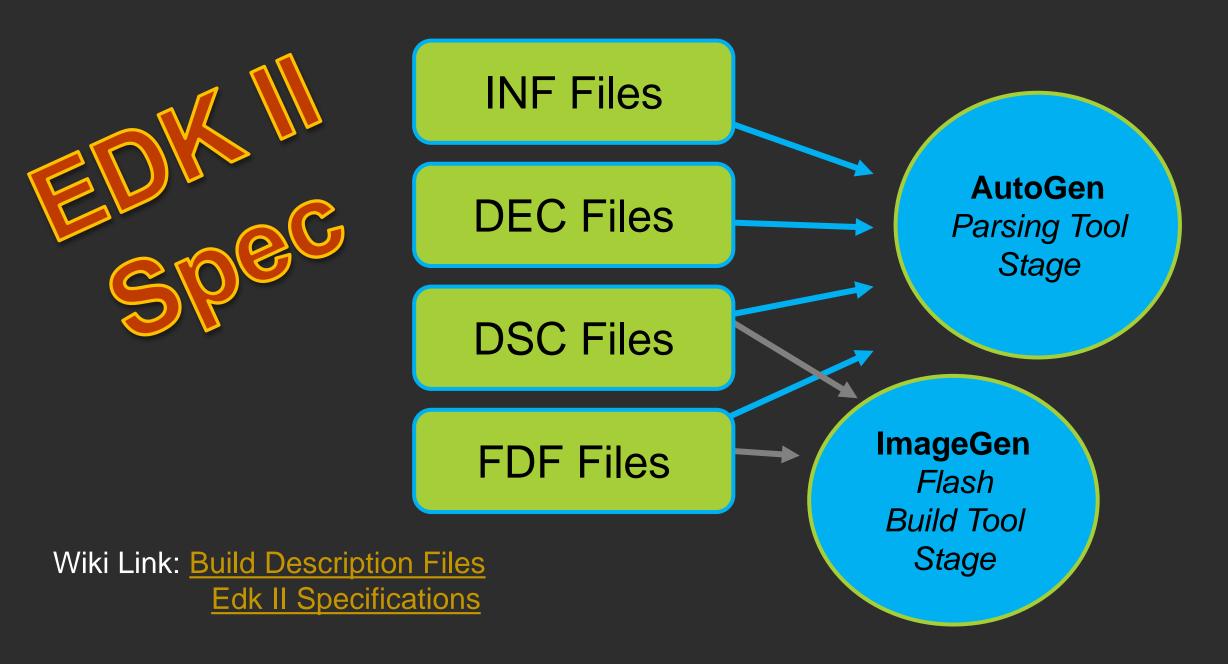


# EDK II BUILD TEXT FILES

EDK II tools use INI-style text-based files to describe components, platforms and firmware volumes.



## **Build Description File Types**





### **General Format for All Build Text Files**

#### INI

 The EDK II Build Text Files use meta-data files using the INI format style

## Section "[]"

 All Build text files consists of sections delineated by section tags enclosed within Square "[" "]" brackets

#### Case

Section tag entries are case-insensitive

## Mult-Sections

 Text of a given section can be used for multiple section names by separating the section names with a comma

#### Section End

 Sections are terminated by the start of another section or the end of the file.

#### Comments

• The hash-tag "#" indicates text following to EOL is a comment (exception is within a quoted string)

#### Include

The "!include" statements are permitted in .DSC and .FDF but NOT .DEC

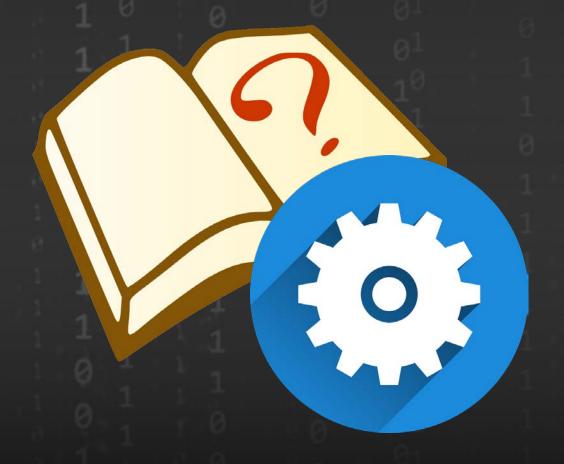
#### Conditional

- Condition Statements Supported in .DSC and .FDF but NOT .DEC
- !ifdef, !ifndef, !if, !elseif, !else and !endif



# Lab 1: Examine the DEC, DSC and FDF files

In this lab, you'll learn about the layout of the DEC, DSC and FDF files.





## Package Declaration File (DEC)

```
oeclare
Syntax:
  <DECfile> ::= <Defines>
             Include
              [<LibraryClass>]
              [<Guids>]
              [<Protocols>]
              [<Ppis>]
              [<Pcd>]
              [<UserExtensions>]
```

Review the Wiki Explanation: <a href="https://github.com/tianocore/tianocore.github.io/wiki/Build-Description-Files#the-dec-file">https://github.com/tianocore/tianocore.github.io/wiki/Build-Description-Files#the-dec-file</a>



## **Example DEC File**

```
[Defines]
 DEC SPECIFICATION
                                 = 0 \times 00010005
 PACKAGE NAME
                                 = OvmfPkg
 PACKAGE GUID
                                 = 2daf5f34-50e5-4b9d-b8e3-5562334d87e5
 PACKAGE VERSION
                                 = 0.1
[Includes]
 Include
[LibraryClasses]
     @libraryclass Loads and boots a Linux kernel image
 LoadLinuxLib Include/Library/LoadLinuxLib.h
[Guids]
 gUefiOvmfPkgTokenSpaceGuid
                                      = \{0x93bb96af, 0xb9f2, 0x4eb8, \{0x94, 0x62, 0xe0, 0xba, 0x74, 0x56, 0x42, 0x36\}\}
                                      = \{0xd3b46f3b, 0xd441, 0x1244, \{0x9a, 0x12, 0x0, 0x12, 0x27, 0x3f, 0xc1, 0x4d\}\}
 gEfiXenInfoGuid
[Protocols]
 gVirtioDeviceProtocolGuid
                                      = \{0xfa920010, 0x6785, 0x4941, \{0xb6, 0xec, 0x49, 0x8c, 0x57, 0x9f, 0x16, 0x0a\}\}
                                      = {0x3d3ca290, 0xb9a5, 0x11e3, {0xb7, 0x5d, 0xb8, 0xac, 0x6f, 0x7d, 0x65, 0xe6}}
 gXenBusProtocolGuid
[PcdsFixedAtBuild]
                                                                               Tokens need to be unique
 gUefiOvmfPkgTokenSpaceGuid.PcdOvmfPeiMemFvBase | 0x0 | UINT32 | 0x00001014
 gUefiOvmfPkgTokenSpaceGuid.PcdOvmfPeiMemFvSize | 0x0 | UINT32 | 0x00001015
                                                                               to the DEC file (1 per PCD)
```



## **Examine the Dec File Details**

Follow the following Links and examine the examples of the EmulatorPkg.dec file

Next open the same EmulatorPkg.dec in the %WORKSPACE% and become familiar with the different sections

#### EmulatorPkg.dec.md#dec-file-for-emulatorpkg

Link: List of List of Defines, Package Name, GUILD, Version ...

Link: The Include section

Link: Library classes section

Link: Protocols Section

Link: GUIDs section

Link: PCDs Section

Link: Patchable PCDs Section



## Platform Description File (DSC)

```
Description
Syntax:
DSCfile ::= [<Header>]
          <Defines>
          [<SkuIds>]
          [<Libraries>]
          [<LibraryClasses>]
          [<Pcds>]
          [<Components>]
          [<UserExtensions>]
```

Review the Wiki Explanation: <a href="https://github.com/tianocore/tianocore.github.io/wiki/Build-Description-Files#the-dsc-file">https://github.com/tianocore/tianocore.github.io/wiki/Build-Description-Files#the-dsc-file</a>

www.tianocore.org



## Platform Description File (DSC)

## DSC file is the recipe for creating a package

Definitions for the package build

**EDK II Library Class Instance Mappings (for EDK II Modules)** 

**EDK II PCD Entry Settings** 

Components / Modules to build (list of .inf files)

DSC file must define all libraries, components and/or modules that will be used by one package



## **Example: DSC File**

```
[Defines]
 PLATFORM NAME
                                 = Ovmf
 PLATFORM GUID
                                  = 5a9e7754-d81b-49ea-85ad-69eaa7b1539b
 PLATFORM VERSION
                                  = 0.1
 DSC_SPECIFICATION
                                  = 0 \times 00010005
 OUTPUT DIRECTORY
                                  = Build/OvmfX64
 SUPPORTED_ARCHITECTURES
                                  = X64
                                 = NOOPT | DEBUG | RELEASE
 BUILD TARGETS
 SKUID_IDENTIFIER
                                  = DEFAULT
 FLASH_DEFINITION
                                  = OvmfPkg/OvmfPkgX64.fdf
 # Defines for default states. These can be changed on the command line.
 # -D FLAG=VALUE
[BuildOptions.common.EDKII.DXE_RUNTIME_DRIVER]
 GCC:*_*_*_*_DLINK_FLAGS = -z common-page-size=0x1000
 XCODE:*_*_*_DLINK_FLAGS =
[LibraryClasses]
 PcdLib | MdePkg / Library / BasePcdLib Null / BasePcdLib Null . inf
 TimerLib OvmfPkg/Library/AcpiTimerLib/BaseAcpiTimerLib.inf
```

DSC must contain a [Components] Section



### **Examine: DSC File Details**

Follow the following Links and examine the examples of the EmulatorPkg.dsc file

Next open the same EmulatorPkg.dsc in the %WORKSPACE% and become familiar with the different sections

#### EmulatorPkg.dsc.md#dsc-file-for-emulatorpkg

Link: List of Defines

Link: Define Switches to determine some configurations

Link: Library Classes – Global

**Link:** Library Classes for UEFI Boot phases

Link: PCDs Section, changing the default

Link: Dynamic PCDs Section

**Link**: Components Section

Link: Build Options Section

Link: Adding More



## Flash Description File(FDF)

```
Elashlayout
Syntax:
   FDFfile ::= [<Header>]
      [<Defines>]
      <FD>
      <FV>
      [<Capsule>]
      [<VTF>]
      [<Rules>]
      [<OptionRom>]
      [<UserExtensions>]
```

Must have a FD (Flash Device) and FV (Firmware Volume) Section



## Flash Description File(FDF)

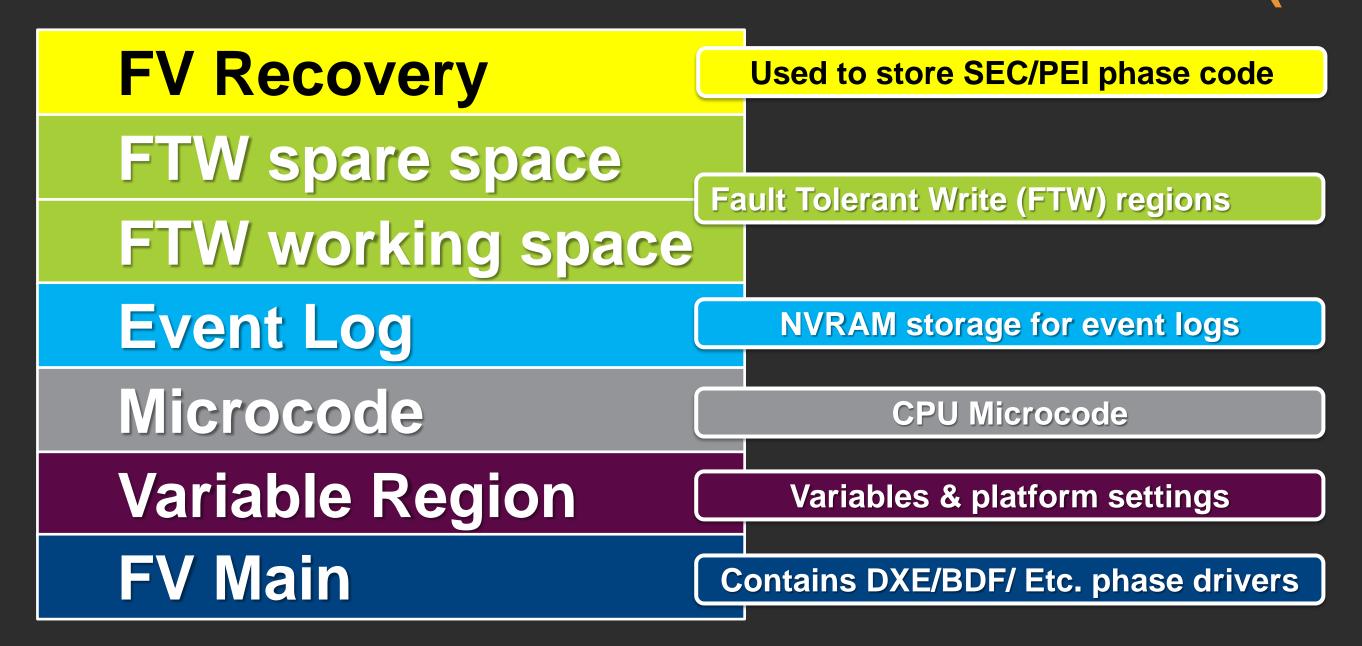
# Describes information about flash parts

Used to create firmware images, Option ROM images or bootable images

Rules for combining binaries (Firmware Image) built from a DSC file



# FLASH DEVICE CONFIGURATION COMMON LAYOUT FILE (.FDF)





## **Example: FDF File**

```
[Defines]
!include OvmfPkg.fdf.inc
# Build the variable store and the firmware code
# as one unified flash device image.
                                   Ovmf.fd file
[FD.OVMF] ←
                                    created by
             = $(FW BASE ADDRESS)
BaseAddress
                                       Build
              = $(FW SIZE)
Size
ErasePolarity = 1
BlockSize
             = $(BLOCK SIZE)
             = $(FW BLOCKS)
NumBlocks
     Offset | Size
                                   Firmware
$(VARS_SIZE)|$(FVMAIN_SIZE)
                                    Volumes
FV = FVMAIN COMPACT
                                   created by
                                      Build
        Offset | Size
$(SECFV_OFFSET)|$(SECFV_SIZE)
FV = SECFV
```

#### Included Mapping file

```
DEFINE BLOCK SIZE
                         = 0x1000
DEFINE VARS OFFSET
                         = 0
!if ($(FD_SIZE_IN_KB) == 1024) || ($(FD_SIZE_IN_KB) == 2048)
DEFINE VARS SIZE
                         = 0x20000
DEFINE VARS BLOCKS
                         = 0x20
DEFINE VARS LIVE SIZE
                         = 0 \times E000
DEFINE VARS SPARE SIZE
                         = 0 \times 10000
!endif
# . . .
SET gUefiOvmfPkgTokenSpaceGuid.PcdOvmfFdBaseAddress
    $(FW BASE ADDRESS)
SET gUefiOvmfPkgTokenSpaceGuid.PcdOvmfFirmwareFdSize
    $(FW SIZE)
SET gUefiOvmfPkgTokenSpaceGuid.PcdOvmfFirmwareBlockSize =
    $(BLOCK SIZE)
SET gUefiOvmfPkgTokenSpaceGuid.PcdOvmfFlashNvStorageVariableBase =
   $(FW BASE ADDRESS)
SET gEfiMdeModulePkgTokenSpaceGuid.PcdFlashNvStorageVariableSize =
   $(VARS LIVE SIZE)
```

Link to Gitpitch 17



### **Examine: FDF File Details**

Follow the following Links and examine the examples of the EmulatorPkg.fdf file

Next open the same EmulatorPkg.fdf in the %WORKSPACE% and become familiar with the different sections

EmulatorPkg.fdf.md#fdf-file-for-the-emulatorpkg

Link: FD Section

<u>Link</u>: Firmware Volume – FvRecovery

**Link**: Begin Firmware Layout Regions

Link: Declaring each Firmware Volumes

Link: Apriori Section

Link: Example: #include of fdf file

Link: Rules Section

Following are for the Whiskey Lake UPX (these examples will be used in later

projects

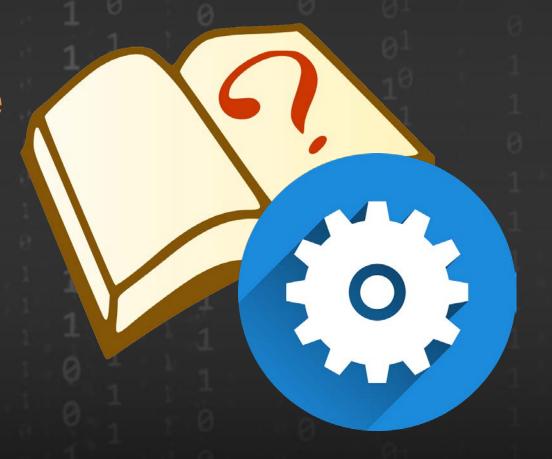
**Link:** FDF For Whiskey Lake Up Xtreme

**Link**: Flash Map of Up Xtreme



# Lab 2: Add a Simple Driver to the Build

In this lab, you'll learn how to add a UEFI Driver to the Build and final image .FD file.





### Add a UEFI Driver to a Platform

#### Requirements:

Add a simple UEFI driver to a platform based on a Macro switch passed to the build using "-D ADD\_BLANKDRV"

Requires Building the Platform Lab first

- Windows Build Emulator Platform Lab <u>Link</u>
- Linux Build Ovmf Platform Lab Link



## Add a UEFI Driver to a Platform

#### Windows

- Copy the LabSampleCode/LabSolutions/BlankDrv directory to C:/FW/edk2-ws/edk2
- 2. Edit EmulatorPkg.dsc and add the BlankDrv component at the end and use a "if" statement based on macro ADD\_BLANKDRV
- 3. Edit EmlatorPkg.fdf and add the BlankDrv Driver to the DXE section of Firmware Volumes and use a "if" statement based on macro ADD\_BLANKDRV

C:/FW/edk2-ws/edk2> Build -D ADD\_BLANKDRV

C:/FW/edk2-ws/edk2> RunEmulator.bat

#### Linux

- Copy the LabSampleCode/LabSolutions/BlankDrv directory to ~/src/edk2-ws/edk2
- 2. Edit OvmfPkgX64.dsc and add the BlankDrv component at the end and use a "if" statement based on macro ADD\_BLANKDRV
- 3. Edit OvmfPkgX64.fdf and add the BlankDrv Driver to the DXE section of Firmware Volumes and use a "if" statement based on macro ADD\_BLANKDRV

```
bash$> cd ~/src/edk-ws/edk2
bash$> build -D ADD_BLANKDRV -a X64
bash$ cd $HOME/run-ovmf
bash$ cp ~/src/edk2-
ws/Build/OvmfX64/DEBUG_GCC5/FV/OVMF.fd bios.bin
bash$ . RunQemu.sh
```



## Verify the BlankDrv Driver was Added

At the Shell Prompt:

Shell> Exit

This will open the BIOS Setup

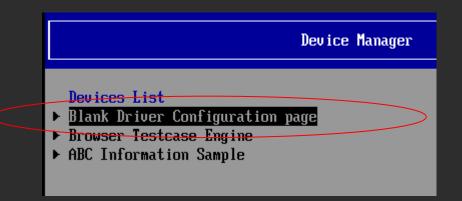
Go to the "Device Manager" menu and Verify the "Blank Driver Configuration page" is available

Enter into the BlankDrv Setup Page

**Exit Emulation** 

Windows: ESC key twice then use the "Reset"

Linux: Exit QEMU Linux







# Summary

Examine the Build components and build text files DSC, DEC, & FDF







## Return to Main Training Page



Return to Training Table of contents for next presentation link





### **ACKNOWLEDGEMENTS**

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