

UEFI & EDK II TRAINING EDK II BUILD SPECIFICATION FILES LAB

See also Lab Guide.md for Copy & Paste examples in labs

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LESSON OBJECTIVE



Examine the Build components and build text files DSC, DEC, & FDF

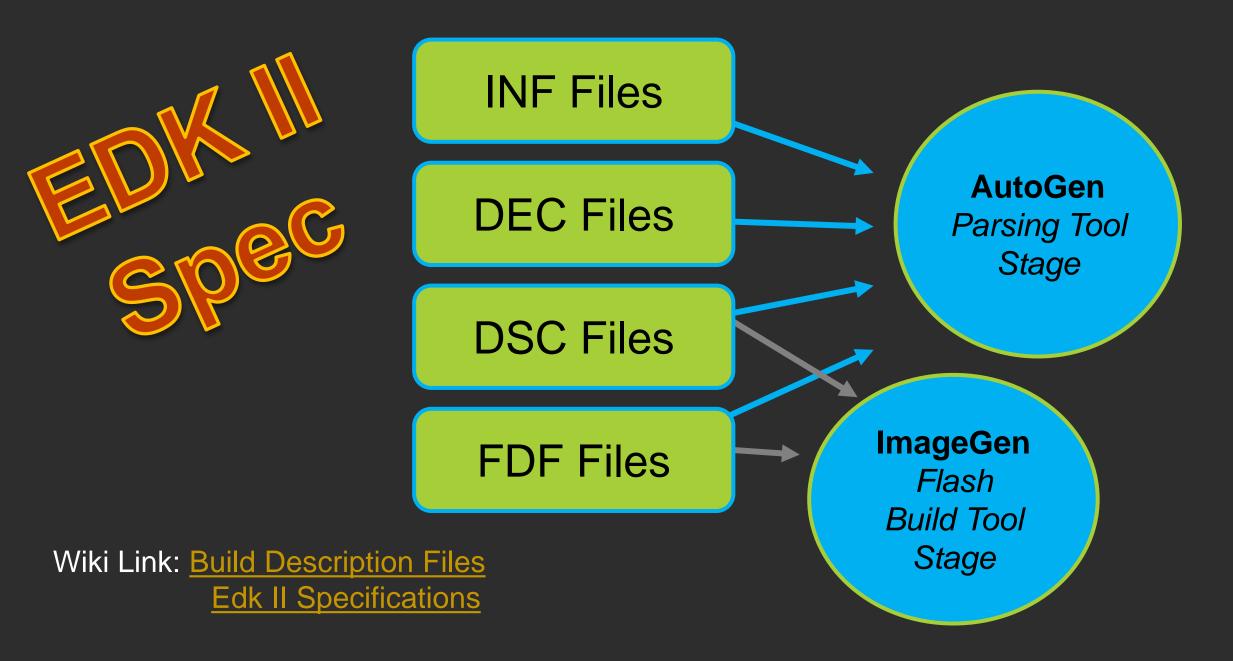


EDK II BUILD TEXT FILES

EDK II tools use INI-style text-based files to describe components, platforms and firmware volumes.



Build Description File Types





General Format for All Build Text Files

INI

 The EDK II Build Text Files use meta-data files using the INI format style

Section "[]"

 All Build text files consists of sections delineated by section tags enclosed within Square "[" "]" brackets

Case

Section tag entries are case-insensitive

Mult-Sections

 Text of a given section can be used for multiple section names by separating the section names with a comma

Section End

 Sections are terminated by the start of another section or the end of the file.

Comments

• The hash-tag "#" indicates text following to EOL is a comment (exception is within a quoted string)

Include

The "!include" statements are permitted in .DSC and .FDF but NOT .DEC

Conditional

Condition Statements Supported in .DSC and .FDF but NOT .DEC

• !ifdef, !ifndef, !if, !elseif, !else and !endif



Lab 1: Examine the DEC, DSC and FDF files

In this lab, you'll learn about the layout of the DEC, DSC and FDF files.





Package Declaration File (DEC)

```
Oeclare
Syntax:
  <DECfile> ::= <Defines>
             Include
              [<LibraryClass>]
              [<Guids>]
              [<Protocols>]
              [<Ppis>]
              [<Pcd>]
              [<UserExtensions>]
```

Review the Wiki Explanation: https://github.com/tianocore/tianocore.github.io/wiki/Build-Description-Files#the-dec-file



Example DEC File

```
[Defines]
 DEC SPECIFICATION
                                 = 0 \times 00010005
 PACKAGE NAME
                                 = OvmfPkg
 PACKAGE GUID
                                 = 2daf5f34-50e5-4b9d-b8e3-5562334d87e5
 PACKAGE VERSION
                                 = 0.1
[Includes]
 Include
[LibraryClasses]
     @libraryclass Loads and boots a Linux kernel image
 LoadLinuxLib Include/Library/LoadLinuxLib.h
[Guids]
 gUefiOvmfPkgTokenSpaceGuid
                                      = \{0x93bb96af, 0xb9f2, 0x4eb8, \{0x94, 0x62, 0xe0, 0xba, 0x74, 0x56, 0x42, 0x36\}\}
                                      = \{0xd3b46f3b, 0xd441, 0x1244, \{0x9a, 0x12, 0x0, 0x12, 0x27, 0x3f, 0xc1, 0x4d\}\}
 gEfiXenInfoGuid
[Protocols]
 gVirtioDeviceProtocolGuid
                                      = \{0xfa920010, 0x6785, 0x4941, \{0xb6, 0xec, 0x49, 0x8c, 0x57, 0x9f, 0x16, 0x0a\}\}
                                      = {0x3d3ca290, 0xb9a5, 0x11e3, {0xb7, 0x5d, 0xb8, 0xac, 0x6f, 0x7d, 0x65, 0xe6}}
 gXenBusProtocolGuid
[PcdsFixedAtBuild]
                                                                               Tokens need to be unique
 gUefiOvmfPkgTokenSpaceGuid.PcdOvmfPeiMemFvBase | 0x0 | UINT32 | 0x00001014
 gUefiOvmfPkgTokenSpaceGuid.PcdOvmfPeiMemFvSize | 0x0 | UINT32 | 0x00001015
                                                                               to the DEC file (1 per PCD)
```



Examine the Dec File Details

Follow the following Links and examine the examples of the EmulatorPkg.dec file

Next open the same EmulatorPkg.dec in the %WORKSPACE% and become familiar with the different sections

EmulatorPkg.dec.md#dec-file-for-emulatorpkg

Link: List of List of Defines, Package Name, GUILD, Version ...

Link: The Include section

Link: Library classes section

Link: Protocols Section

Link: GUIDs section

Link: PCDs Section

Link: Patchable PCDs Section



Platform Description File (DSC)

```
Description
Syntax:
DSCfile ::= [<Header>]
          <Defines>
          [<SkuIds>]
          [<Libraries>]
          [<LibraryClasses>]
          [<Pcds>]
          [<Components>]
          [<UserExtensions>]
```

Review the Wiki Explanation: https://github.com/tianocore/tianocore.github.io/wiki/Build-Description-Files#the-dsc-file

www.tianocore.org



Platform Description File (DSC)

DSC file is the recipe for creating a package

Definitions for the package build

EDK II Library Class Instance Mappings (for EDK II Modules)

EDK II PCD Entry Settings

Components / Modules to build (list of .inf files)

DSC file must define all libraries, components and/or modules that will be used by one package



Example: DSC File

```
[Defines]
 PLATFORM NAME
                                 = Ovmf
 PLATFORM GUID
                                 = 5a9e7754-d81b-49ea-85ad-69eaa7b1539b
 PLATFORM VERSION
                                 = 0.1
 DSC_SPECIFICATION
                                 = 0 \times 00010005
 OUTPUT DIRECTORY
                                 = Build/OvmfX64
 SUPPORTED_ARCHITECTURES
                                 = X64
                                 = NOOPT | DEBUG | RELEASE
 BUILD TARGETS
 SKUID_IDENTIFIER
                                 = DEFAULT
 FLASH_DEFINITION
                                 = OvmfPkg/OvmfPkgX64.fdf
 # Defines for default states. These can be changed on the command line.
 # -D FLAG=VALUE
[BuildOptions.common.EDKII.DXE_RUNTIME_DRIVER]
 GCC:*_*_*_*_DLINK_FLAGS = -z common-page-size=0x1000
 XCODE:*_*_*_DLINK_FLAGS =
[LibraryClasses]
 PcdLib|MdePkg/Library/BasePcdLibNull/BasePcdLibNull.inf
 TimerLib OvmfPkg/Library/AcpiTimerLib/BaseAcpiTimerLib.inf
```

DSC must contain a [Components] Section



Examine: DSC File Details

Follow the following Links and examine the examples of the EmulatorPkg.dsc file

Next open the same EmulatorPkg.dsc in the %WORKSPACE% and become familiar with the different sections

EmulatorPkg.dsc.md#dsc-file-for-emulatorpkg

Link: List of Defines

Link: Define Switches to determine some configurations

Link: Library Classes - Global

Link: Library Classes for UEFI Boot phases

Link: PCDs Section, changing the default

Link: Dynamic PCDs Section

Link: Components Section

Link: Build Options Section

Link: Adding More



Flash Description File(FDF)

```
Elashlayout
Syntax:
   FDFfile ::= [<Header>]
      [<Defines>]
      <FD>
      <FV>
      [<Capsule>]
      [<VTF>]
      [<Rules>]
      [<OptionRom>]
      [<UserExtensions>]
```

Must have a FD (Flash Device) and FV (Firmware Volume) Section



Flash Description File(FDF)

Describes information about flash parts

Used to create firmware images, Option ROM images or bootable images

Rules for combining binaries (Firmware Image) built from a DSC file



FLASH DEVICE CONFIGURATION COMMON LAYOUT FILE (.FDF)

FV Recovery **Used to store SEC/PEI phase code** FTW spare space **Fault Tolerant Write (FTW) regions** FTW working space **Event Log NVRAM** storage for event logs Microcode **CPU Microcode** Variable Region Variables & platform settings **FV Main Contains DXE/BDF/ Etc. phase drivers**



Example: FDF File

```
[Defines]
!include OvmfPkg.fdf.inc
# Build the variable store and the firmware code
# as one unified flash device image.
                                   Ovmf.fd file
[FD.OVMF] ←
                                    created by
             = $(FW BASE ADDRESS)
BaseAddress
                                       Build
              = $(FW SIZE)
Size
ErasePolarity = 1
BlockSize
             = $(BLOCK SIZE)
             = $(FW BLOCKS)
NumBlocks
     Offset | Size
                                   Firmware
$(VARS_SIZE)|$(FVMAIN_SIZE)
                                    Volumes
FV = FVMAIN COMPACT
                                   created by
                                      Build
        Offset | Size
$(SECFV_OFFSET)|$(SECFV_SIZE)
FV = SECFV
```

Included Mapping file

```
DEFINE BLOCK SIZE
                         = 0x1000
DEFINE VARS OFFSET
                         = 0
!if ($(FD_SIZE_IN_KB) == 1024) || ($(FD_SIZE_IN_KB) == 2048)
DEFINE VARS SIZE
                         = 0x20000
DEFINE VARS BLOCKS
                         = 0x20
DEFINE VARS LIVE SIZE
                         = 0 \times E000
DEFINE VARS SPARE SIZE
                         = 0 \times 10000
!endif
# . . .
SET gUefiOvmfPkgTokenSpaceGuid.PcdOvmfFdBaseAddress
    $(FW BASE ADDRESS)
SET gUefiOvmfPkgTokenSpaceGuid.PcdOvmfFirmwareFdSize
    $(FW SIZE)
SET gUefiOvmfPkgTokenSpaceGuid.PcdOvmfFirmwareBlockSize =
    $(BLOCK SIZE)
SET gUefiOvmfPkgTokenSpaceGuid.PcdOvmfFlashNvStorageVariableBase =
   $(FW BASE ADDRESS)
SET gEfiMdeModulePkgTokenSpaceGuid.PcdFlashNvStorageVariableSize =
   $(VARS LIVE SIZE)
```

Link to Gitpitch 17



Examine: FDF File Details

Follow the following Links and examine the examples of the EmulatorPkg.fdf file

Next open the same EmulatorPkg.fdf in the %WORKSPACE% and become familiar with the different sections

EmulatorPkg.fdf.md#fdf-file-for-the-emulatorpkg

Link: FD Section

<u>Link</u>: Firmware Volume – FvRecovery

Link: Begin Firmware Layout Regions

Link: Declaring each Firmware Volumes

Link: Apriori Section

Link: Example: #include of fdf file

Link: Rules Section

Following are for the Whiskey Lake UPX (these examples will be used in later

projects

Link: FDF For Whiskey Lake Up Xtreme

Link: Flash Map of Up Xtreme



Lab 2: Add a Simple Driver to the Build

In this lab, you'll learn how to add a UEFI Driver to the Build and final image .FD file.





Add a UEFI Driver to a Platform

Requirements:

Add a simple UEFI driver to a platform based on a Macro switch passed to the build using "-D ADD_BLANKDRV"

This simple UEFI driver should also be added to the FV for the DXE code.

Requires Building the Platform Lab first

- Windows Build Emulator Platform Lab <u>Link</u>
- Linux Build Ovmf Platform Lab <u>Link</u>
- The simple UEFI driver to add is found on the <u>Lab Material FW</u>
 FW/LabSampleCode/LabSolutions/BlankDrv



Add a UEFI Driver to a Platform

Windows

- Copy the LabSampleCode/LabSolutions/BlankDrv directory to C:/FW/edk2-ws/edk2
- 2. Edit EmulatorPkg.dsc and add the BlankDrv component at the end and use a "if" statement based on macro ADD_BLANKDRV
- 3. Edit EmlatorPkg.fdf and add the BlankDrv Driver to the DXE section of Firmware Volumes and use a "if" statement based on macro ADD_BLANKDRV

C:/FW/edk2-ws/edk2> Build -D ADD_BLANKDRV

C:/FW/edk2-ws/edk2> RunEmulator.bat

Linux

- Copy the LabSampleCode/LabSolutions/BlankDrv directory to ~/src/edk2-ws/edk2
- 2. Edit OvmfPkgX64.dsc and add the BlankDrv component at the end and use a "if" statement based on macro ADD_BLANKDRV
- 3. Edit OvmfPkgX64.fdf and add the BlankDrv Driver to the DXE section of Firmware Volumes and use a "if" statement based on macro ADD_BLANKDRV

```
bash$> cd ~/src/edk-ws/edk2
bash$> build -D ADD_BLANKDRV -a X64
bash$ cd $HOME/run-ovmf
bash$ cp ~/src/edk2-
ws/Build/OvmfX64/DEBUG_GCC5/FV/OVMF.fd bios.bin
bash$ . RunQemu.sh
```



Verify the BlankDrv Driver was Added

At the Shell Prompt:

Shell> Exit

This will open the BIOS Setup

Go to the "Device Manager" menu and Verify the "Blank Driver Configuration page" is available

Enter into the BlankDrv Setup Page

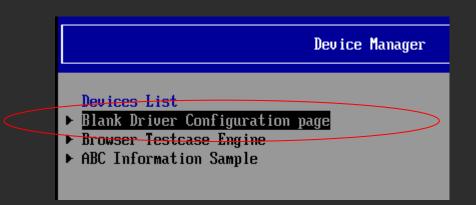
Exit Emulation

Windows: ESC key twice then use the "Reset"

Linux: Exit QEMU Linux

Solution: Lab_Material_FW

FW/LabSampleCode/LabSolutions/BlankDrv_Solution







Summary

Examine the Build components and build text files DSC, DEC, & FDF







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ACKNOWLEDGEMENTS

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