

UEFI & EDK II TRAINING

EDK II Open Board Platform Design for Intel
Architecture (IA)

tianocore.org

Lesson Objective

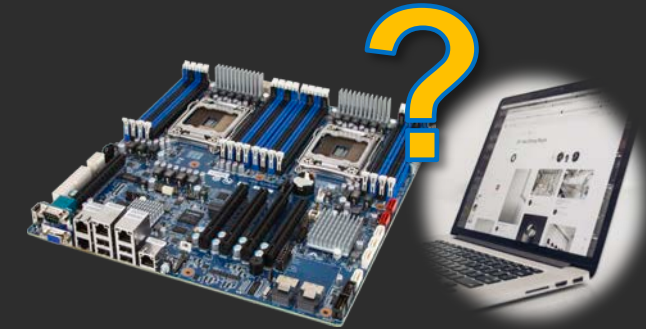
- ★ Introduce Minimum Platform Architecture (MPA)
- ★ Explain the EDK II Open board platforms infrastructure & focus areas
- ★ Describe Intel® FSP with the EDK II open board platforms

Reference: [Minimum Platform Architecture Specification](#)

INTRODUCING

Minimum Platform Architecture (MPA)

How to Build Intel UEFI FW for a System



Core

- Typically, open source.
- Industry standard drivers
- Generic firmware infrastructure code.


Silicon

- Typically, closed source
- Has some tie to a specific class of physical hardware.
- Sometimes governed by industry standards, sometimes proprietary.

Platform

- Typically, closed source.
- Advanced or platform feature code.
- Board specific code for one or more motherboards.


Firmware is Built on Standards



Core

UEFI Forum

- UEFI Specification
- ACPI Specification
- Platform Initialization Specification



Silicon

Intel Firmware

- Intel® FSP Specification

Hardware

The Platform code brings it all together

- Defines the firmware flash map
- Specifies the core and hardware drivers needed
- Calls into the silicon initialization API
- Provides board specific setting like GPIO values, SPD settings, etc.

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Lack of Platform Code Consistency

Platform code is largely missing from EDKII

- EDKII leaves a lot of functionality to platform code
- A QEMU example is given: OvmfPkg
- Implementation is an exercise for the user

Result: Many platform implementations across the industry

It is difficult to understand and debug.

- Boot flows vary arbitrarily between systems

It is difficult to secure.

- Same thing done different ways



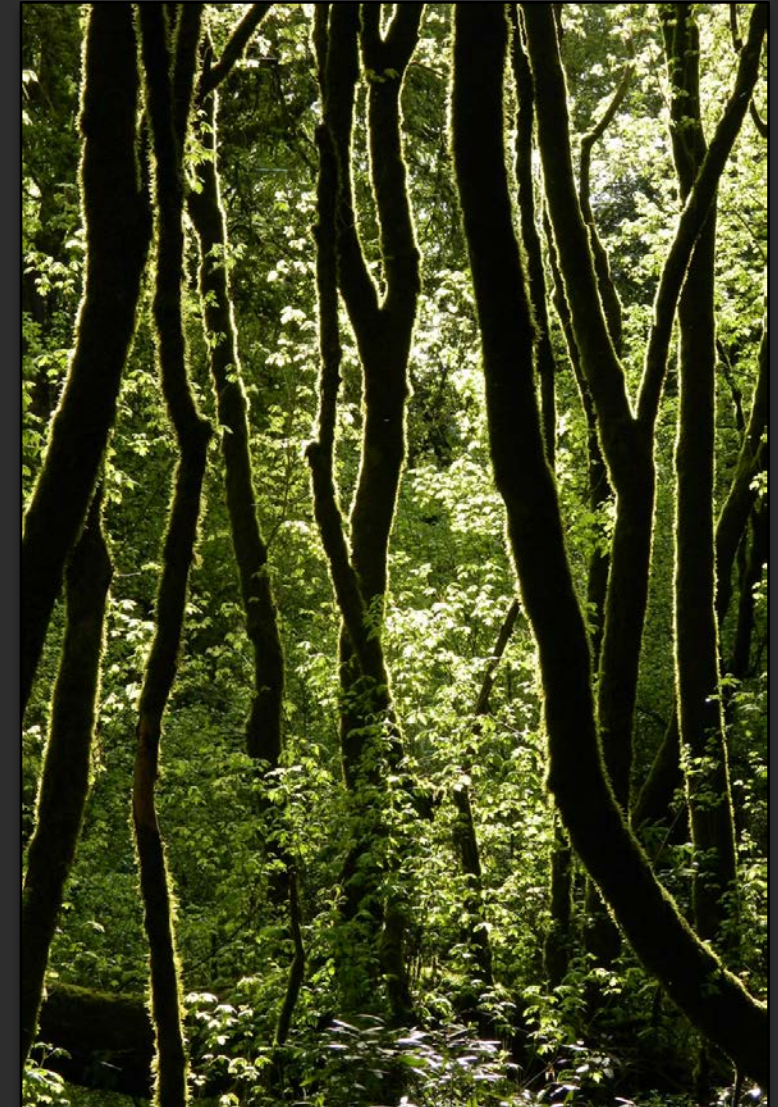
Server



Client

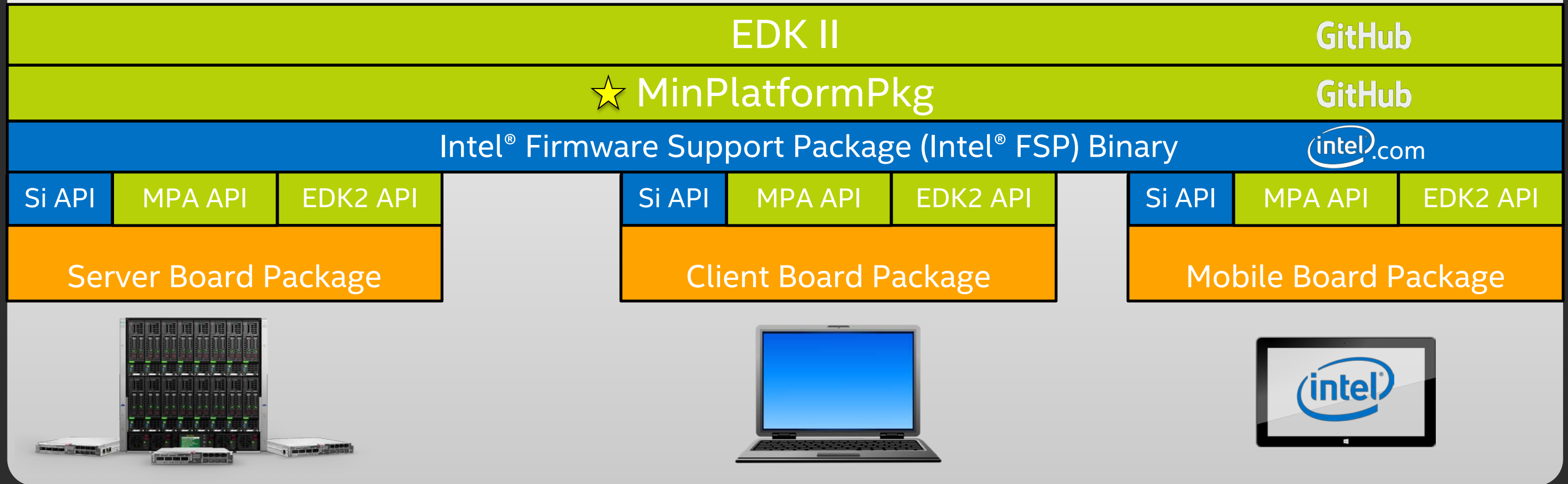


Ultra Mobile



MinPlatform + Intel® Firmware Support Package (Intel® FSP)

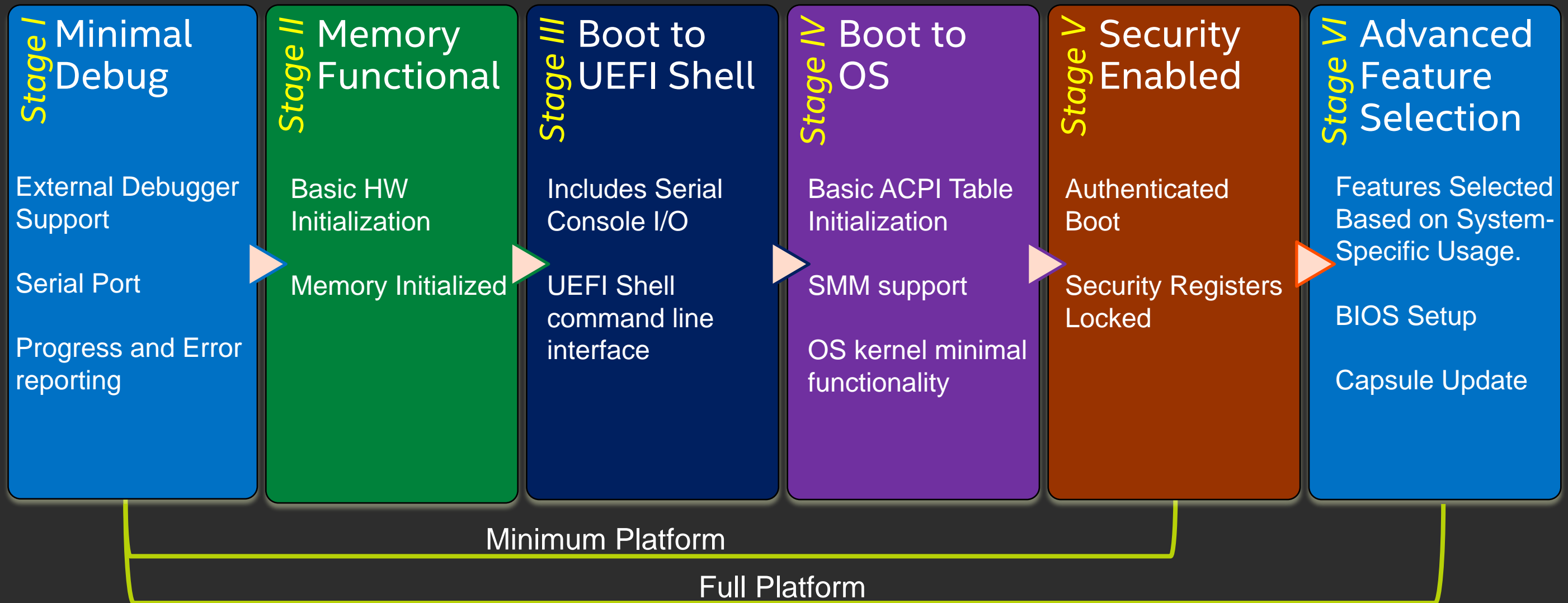
Open source
 Closed source
 Implementation Choice



Intel Open Platform Firmware Stack - Minimum Platform

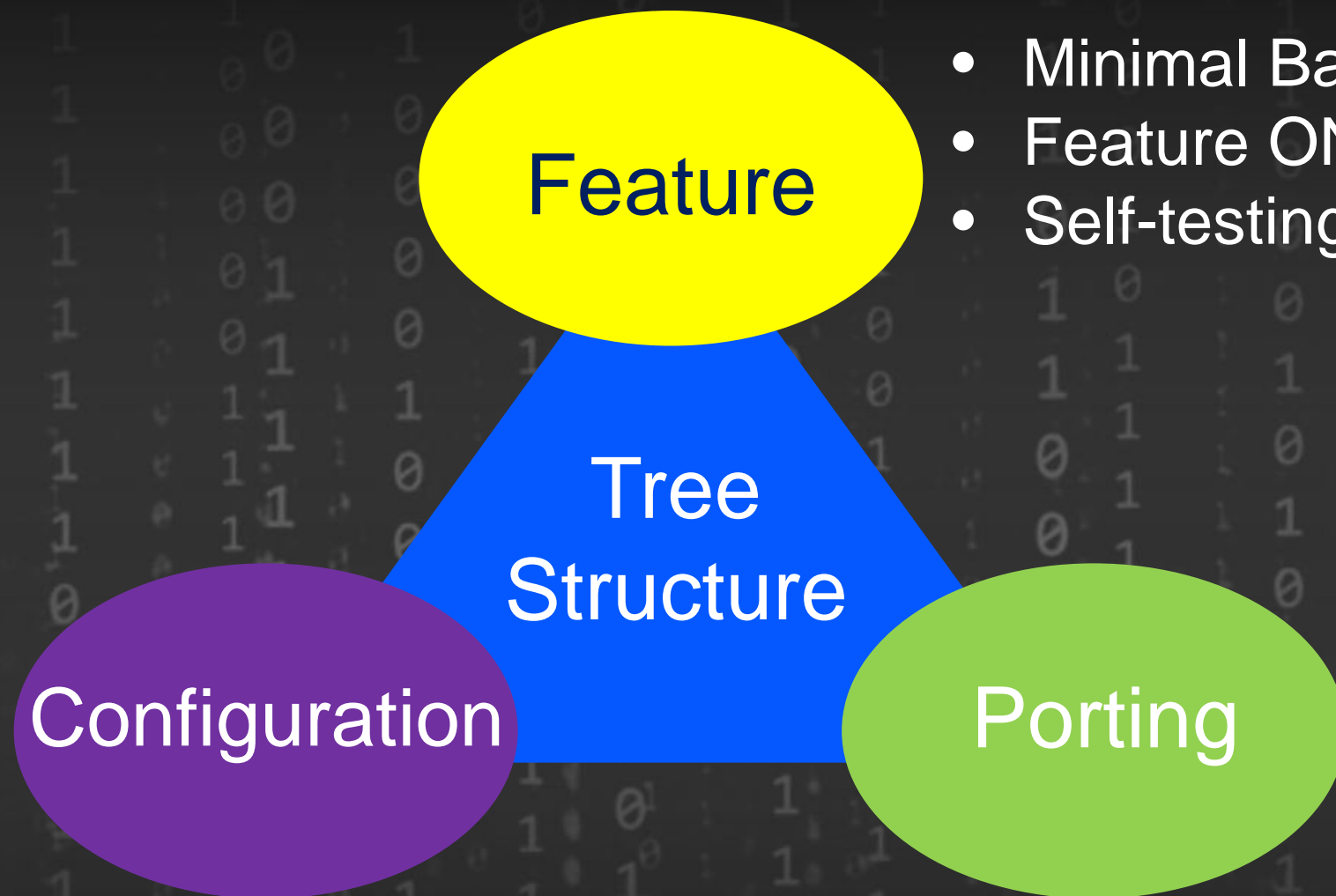
Consistent boot flows and interfaces
Approachable across the ecosystem
Scalable from pre-silicon to derivatives

What are Minimum Platform Stages?



Stages reflect firmware development lifecycle and how a system bootstraps itself

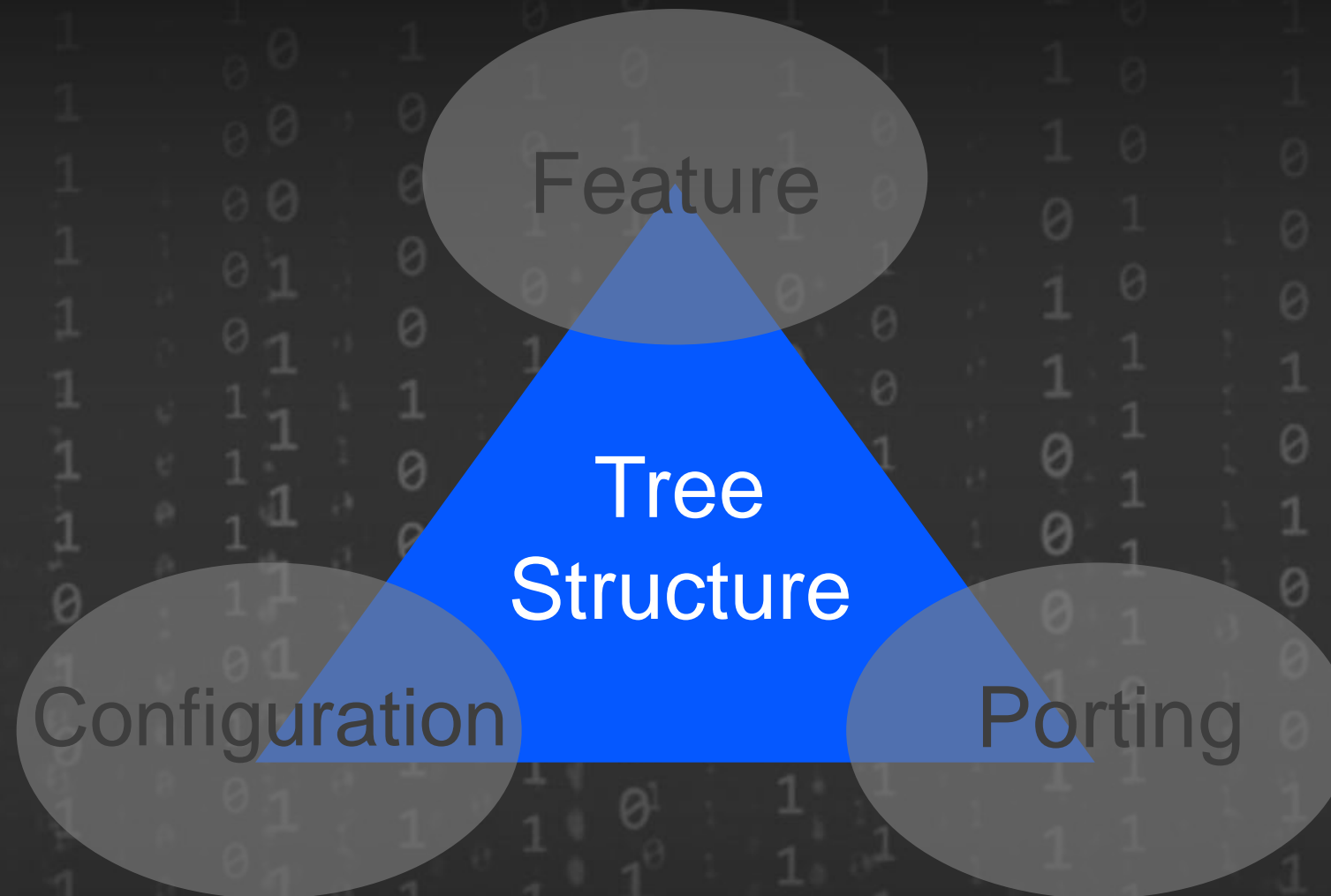
FOUR FOCUS AREAS



- Minimal Baseline
- Feature ON/OFF
- Self-testing

- Incremental
- Simple PCD usage model
- No setup

- Incremental
- Simple C libraries
- The same each time



Organization

Common

- No direct HW requirements

Platform

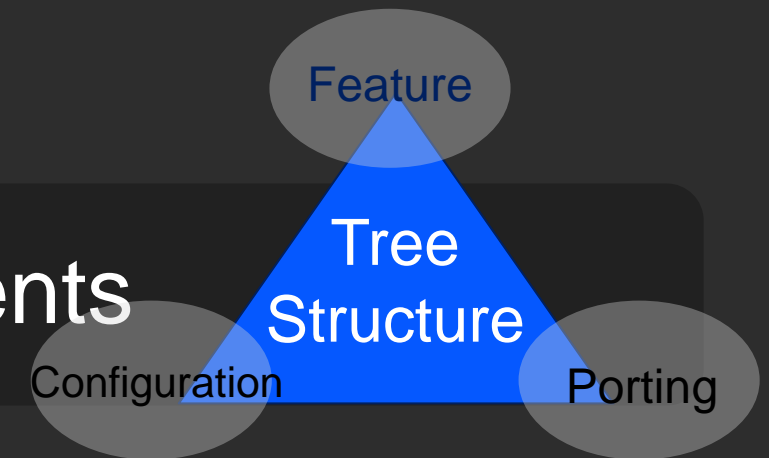
- Enable a specific platform's capabilities.

Board

- Board specific code

Silicon

- Hardware specific code



Open Source EDK II Workspace

MyWorkSpace/

edk2/

- “*edk2 Common*”

edk2-platforms/

Platform/ “*Platform*”

Intel/

MinPlatformPkg/ “*Platform
Common*”

XxxOpenBoardPkg/ “*Platform*”

BoardX/ “*Board Instance*”

Silicon/ “*Silicon*”

Intel/

XxxSiliconPkg/

Features/ “*any*”

edk2-non-os/

Silicon/

Intel/

FSP/ “*Silicon*”

. . . /

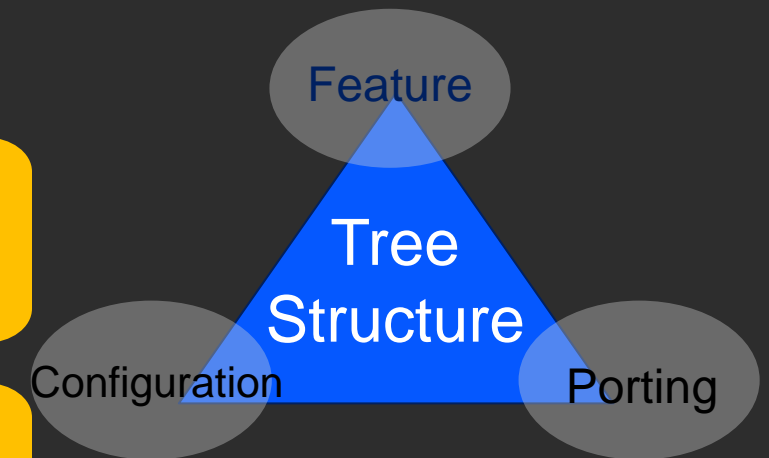
Common

Platform

Board

Silicon

Features



Open Board Tree Structure

edk2/ <https://github.com/tianocore/edk2> ← **Common**

...

edk2-platforms/ <https://github.com/tianocore/edk2-platforms>

Platform/

Intel/

BoardModulePkg

KabylakeOpenBoardPkg

KabylakeRvp3

MinPlatformPkg

← **Platform(family)**

← **Board (instance)**

← **Platform (common)**

Silicon/

Intel/

KabylakeSiliconPkg

← **Silicon**

...

Features/Intel

AdvancedFeaturePkg

← **Features**

edk2-non-os/ <https://github.com/tianocore/edk2-non-os>

Silicon/

Intel/

KabylakeSiliconBinPkg

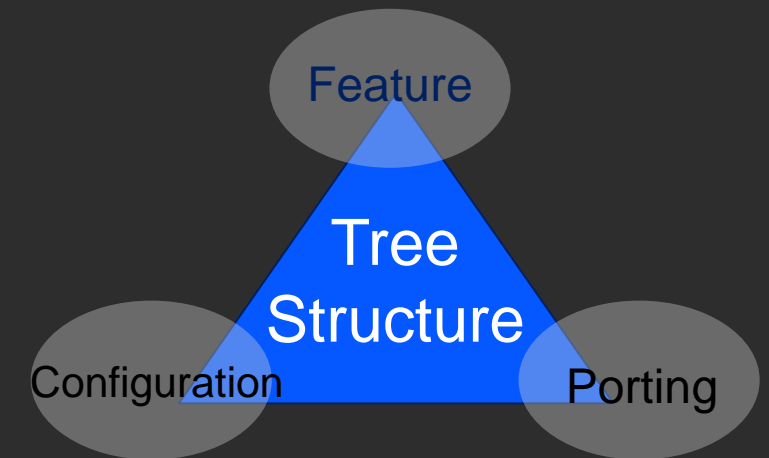
PurleySiliconBinPkg

← **Silicon**

FSP/ <https://github.com/IntelFsp/FSP>

KabylakeFspBinPkg

← **Silicon**



Platform Package Structure

MinPlatformPkg

```
MinPlatformPkg /  
  <Basic Common Driver>/  
  Include /  
  Library /  
  PlatformInit /
```

Platform Common Driver

Where:

- **<Basic Common Driver>**: The basic features to support OS boot, such as ACPI, flash, and FspWrapper. It also includes the basic security features such as Hardware Security Test Interface (HSTI).
- **Include**: The include file as the package interface. All interfaces defined in MinPlatformPkg.dec are put to here.
- **Library**: It only contains feature independent library, such as PeiLib. If a library is related to a feature, this library is put to <Feature>/Library folder, instead of root Library folder.
- **PlatformInit**: The common platform initialization module. There is PreMemPEI, PostMemPEI, DXE and SMM version. These modules control boot flow and provide some hook point to let board code do initialization.

Open Board Package Structure

```
<Generation>OpenBoardPkg /  
  <BasicCommonBoardDrivers>/  
  Include /  
  Library /  
  Features /  
    <AdvancedCommonBoardDrivers> /  
  <BoardX> /  
    Include/  
    Library/  
    <BoardSpecificDriver> /  
    OpenBoardPkg.dsc  
    OpenBoardPkg.fdf
```

<Generation>OpenBoardPkg

Where:

- **<BasicCommonBoardDrivers>** and **<AdvancedCommonBoardDrivers>** designate a board generation specific feature. They need to be updated when we enable a board generation.
- **<Board>** contains all the board specific settings. If we need to port a new board in this generation, copy the <Board> folder and update the copy's settings

One Feature, One directory Guideline

Use a hierarchical layout , KabylakeOpenBoardPkg example

```
KabylakeOpenBoardPkg /  
  Acpi /  
    BoardAcpiDxe /  
  FspWrapper /  
    Library /  
    PeiFspPolicyUpdateLib /  
  Include /  
  KabylakeRvp3  
  Library /  
    BaseEcLib /  
    BaseGpioExpanderLib /  
    PeiI2cAccessLib /  
  Policy /  
    Library /
```

```
KabylakeRvp3 / (cont.)  
  Include /  
  Library /  
  OpenBoardPkg.dsc  
  OpenBoardPkg.fdf
```

Only put the basic features into the root directory

Minimum Platform Stage Selection

Platform Firmware Boot Stage PCD :

OpenBoardPkgPcd.dsc

```
[PcdsFixedAtBuild]
```

```
#
```

```
# Please select BootStage here.
```

```
# Stage 1 - enable debug (system deadlock after debug init)
```

```
# Stage 2 - mem init (system deadlock after mem init)
```

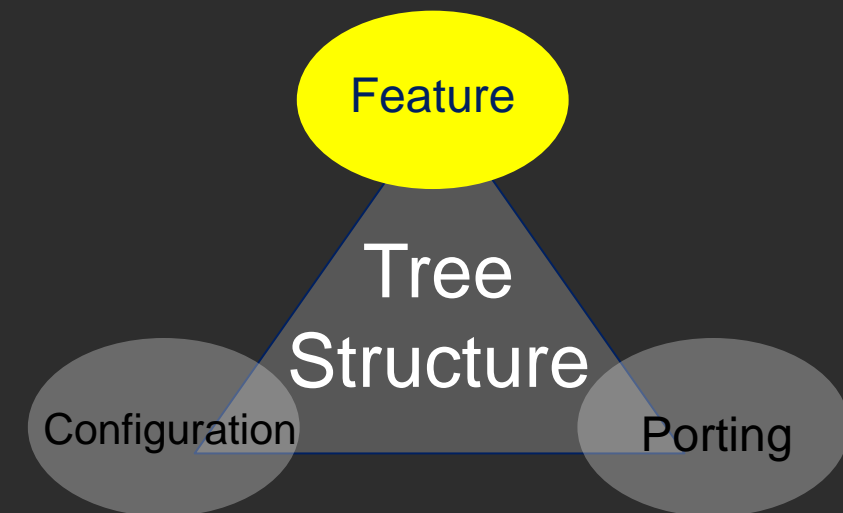
```
# Stage 3 - boot to UEFI shell only
```

```
# Stage 4 - boot to OS
```

```
# Stage 5 - boot to OS with security boot enabled
```

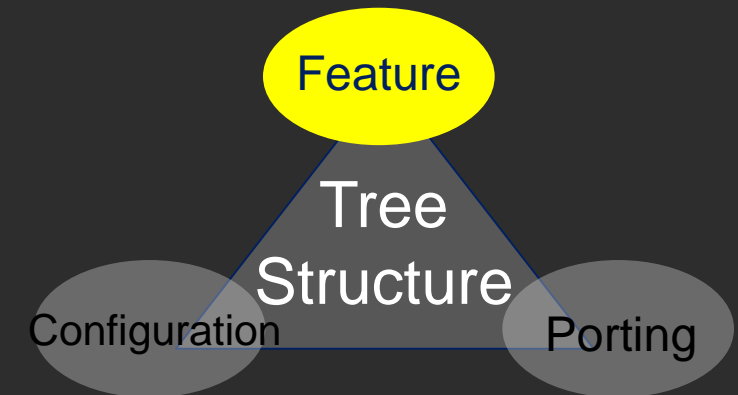
```
# Stage 6 - Add Advanced features
```

```
gMinPlatformPkgTokenSpaceGuid.PcdBootStage|4
```



Required set of PCDs in MPA Spec

Link to Required PCDs according to stages



[Flash Map Config](#)

[Debug Config](#)

[Intel® FSP Config](#)

[Post Memory FV](#)

[UEFI FV](#)

[Driver Related](#)

[Memory Type Information](#)

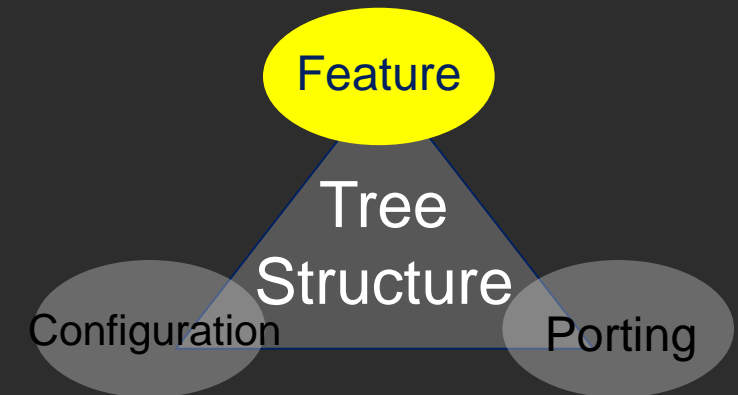
[OS FV](#)

[Security Flash Map](#)

[Stage 5 Features](#)

[Advanced Feature FV](#)

Build Control Files



DSC files

control what gets
compiled and linked

FDF files

control what gets
put in the system
FLASH image

Where are the DSC & FDF files?

Kabylake Open Board

```
Platform/Intel/KabyLakeOpenBoardPkg/  
KabyLakeRvp3/
```

```
OpenBoardPkgPcd.dsc ← Modify PCD Here  
OpenBoardPkgBuildOption.dsc  
OpenBoardPkg.dsc ← Add Features Here  
  
FlashMapInclude.fdf  
OpenBoardPkg.fdf ← Add Features Here
```

```
/edk2-platforms/Platform/  
Intel/MinPlatformPkg/  
Include/  
Fdf/  
Dsc/  
  
/edk2-platforms/Features/  
Intel/YyyAdvancedPkg/  
Include/  
Fdf/  
Dsc/
```

OpenBoardPkgPcd.dsc File Controls if feature ON or OFF

Example Kabylake Configuration .DSC file

```
[PcdsFixedAtBuild]
#
# Please select BootStage here.
# Stage 1 - enable debug (system deadlock after debug init)
# Stage 2 - mem init (system deadlock after mem init)
# Stage 3 - boot to shell only
# Stage 4 - boot to OS
# Stage 5 - boot to OS with security boot enabled
#
gMinPlatformPkgTokenSpaceGuid.PcdBootStage|4

[PcdsFeatureFlag]
gMinPlatformPkgTokenSpaceGuid.PcdStopAfterDebugInit|FALSE
gMinPlatformPkgTokenSpaceGuid.PcdStopAfterMemInit|FALSE
gMinPlatformPkgTokenSpaceGuid.PcdBootToShellOnly|FALSE
gMinPlatformPkgTokenSpaceGuid.PcdUefiSecureBootEnable|FALSE
gMinPlatformPkgTokenSpaceGuid.PcdTpm2Enable|FALSE

!if gMinPlatformPkgTokenSpaceGuid.PcdBootStage >= 1
  gMinPlatformPkgTokenSpaceGuid.PcdStopAfterDebugInit|TRUE
!endif
```

Link to
OpenBoardPkgPcd.dsc
[Config .dsc file](#)

[Link to EDK II DSC Spec.](#)

Example Kabylake .FDF file

[FV.FvPreMemory]

```
INF UefiCpuPkg/SecCore/SecCore.inf
INF MdeModulePkg/Core/Pei/PeiMain.inf
!include $(PLATFORM_PACKAGE)/Include/Fdf/CorePreMemoryInclude.fdf
INF $(PLATFORM_PACKAGE)/PlatformInit/PlatformInitPei/PlatformInitPreMem.inf
INF IntelFsp2WrapperPkg/FspmWrapperPeim/FspmWrapperPeim.inf
INF $(PLATFORM_PACKAGE)/PlatformInit/SiliconPolicyPei/SiliconPolicyPeiPreMem.inf
```

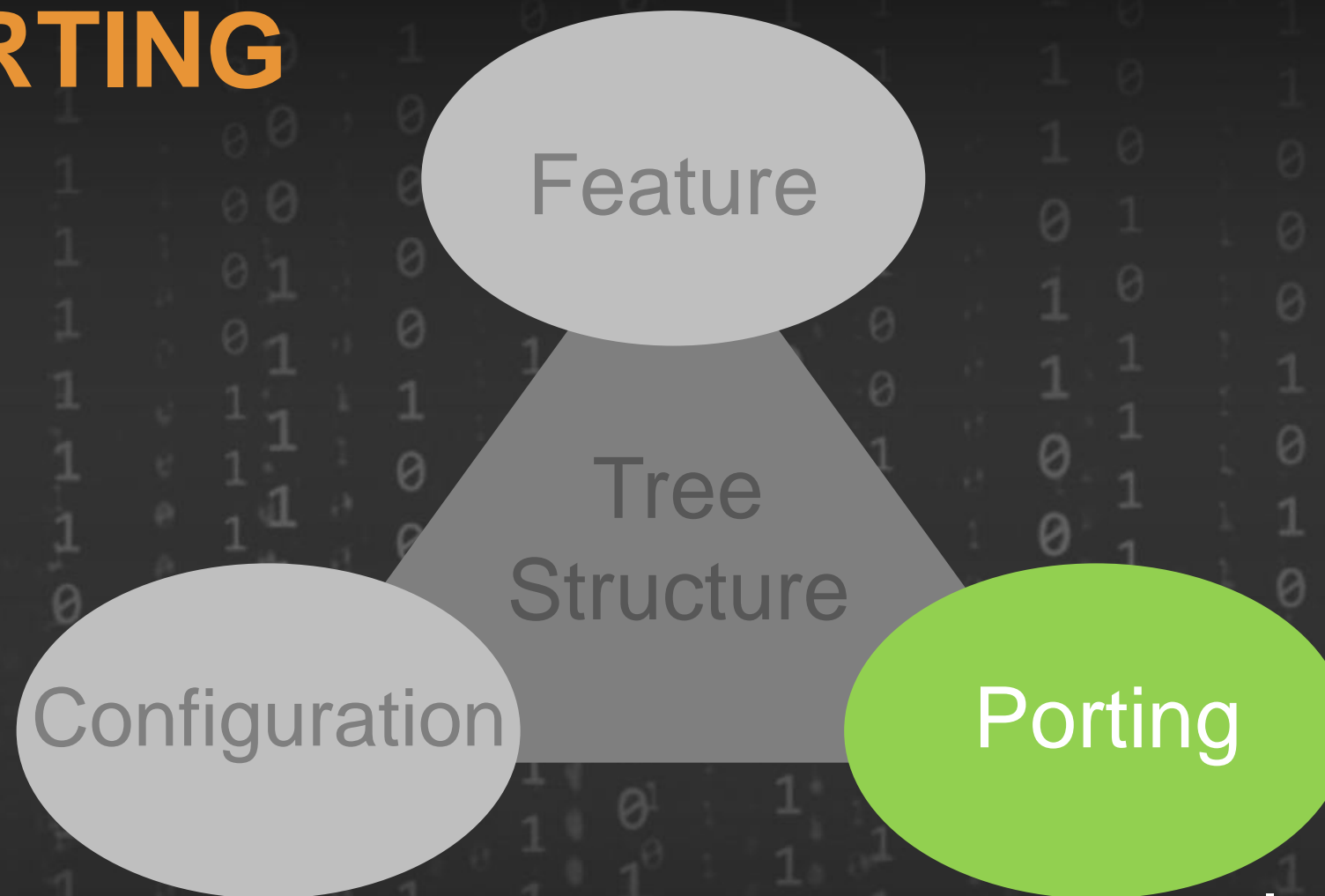
[FV.FvPostMemoryUncompact]

```
!include $(PLATFORM_PACKAGE)/Include/Fdf/CorePostMemoryInclude.fdf
# Init Board Config PCD
INF $(PLATFORM_PACKAGE)/PlatformInit/PlatformInitPei/PlatformInitPostMem.inf
INF IntelFsp2WrapperPkg/FspsWrapperPeim/FspsWrapperPeim.inf
INF $(PLATFORM_PACKAGE)/PlatformInit/SiliconPolicyPei/SiliconPolicyPeiPostMem.inf
!if gSiPkgTokenSpaceGuid.PcdPeiDisplayEnable == TRUE
FILE FREEFORM = 4ad46122-ffeb-4a52-bfb0-518cfca02db0 {
SECTION RAW = $(PLATFORM_FSP_BIN_PACKAGE)/SampleCode/Vbt/Vbt.bin
SECTION UI = "Vbt"
}
FILE FREEFORM = 7BB28B99-61BB-11D5-9A5D-0090273FC14D {
SECTION RAW = MdeModulePkg/Logo/Logo.bmp
}
```

Link to [Kabylake .FDF](#)

[Link to EDK II FDF Spec](#)

BOARD PORTING



- Incremental
- Simple C libraries
- The same each time

Staged Approach by Features

- Platform Firmware Boot Stage PCD

PCD Variable:

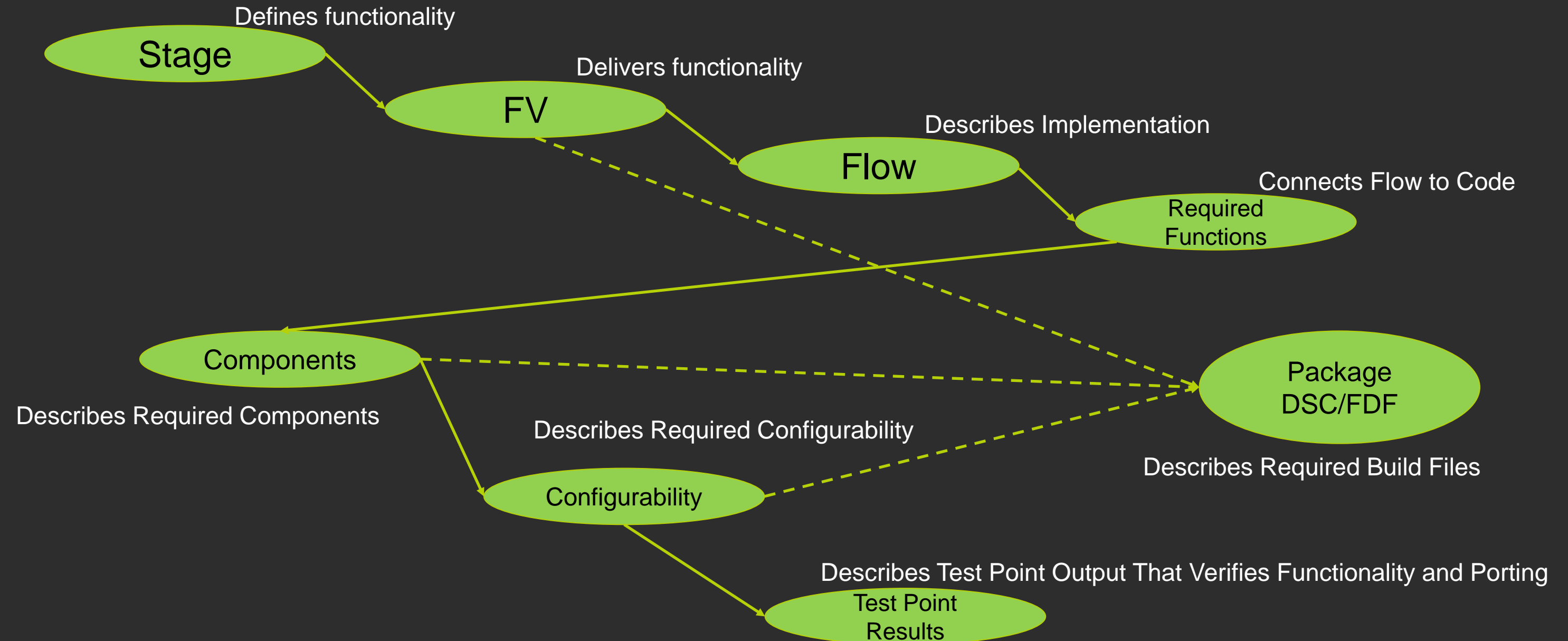
`gPlatformModuleTokenSpaceGuid.PcdBootStage`

Stage 1	enable debug
Stage 2	memory initialization
Stage 3	boot to UEFI shell only
Stage 4	boot to OS
Stage 5	boot to OS w/ security enabled
Stage 6	Advanced Feature Selection
Stage 7	Performance Optimizations



PCD Is tested within .FDF to see which modules to include

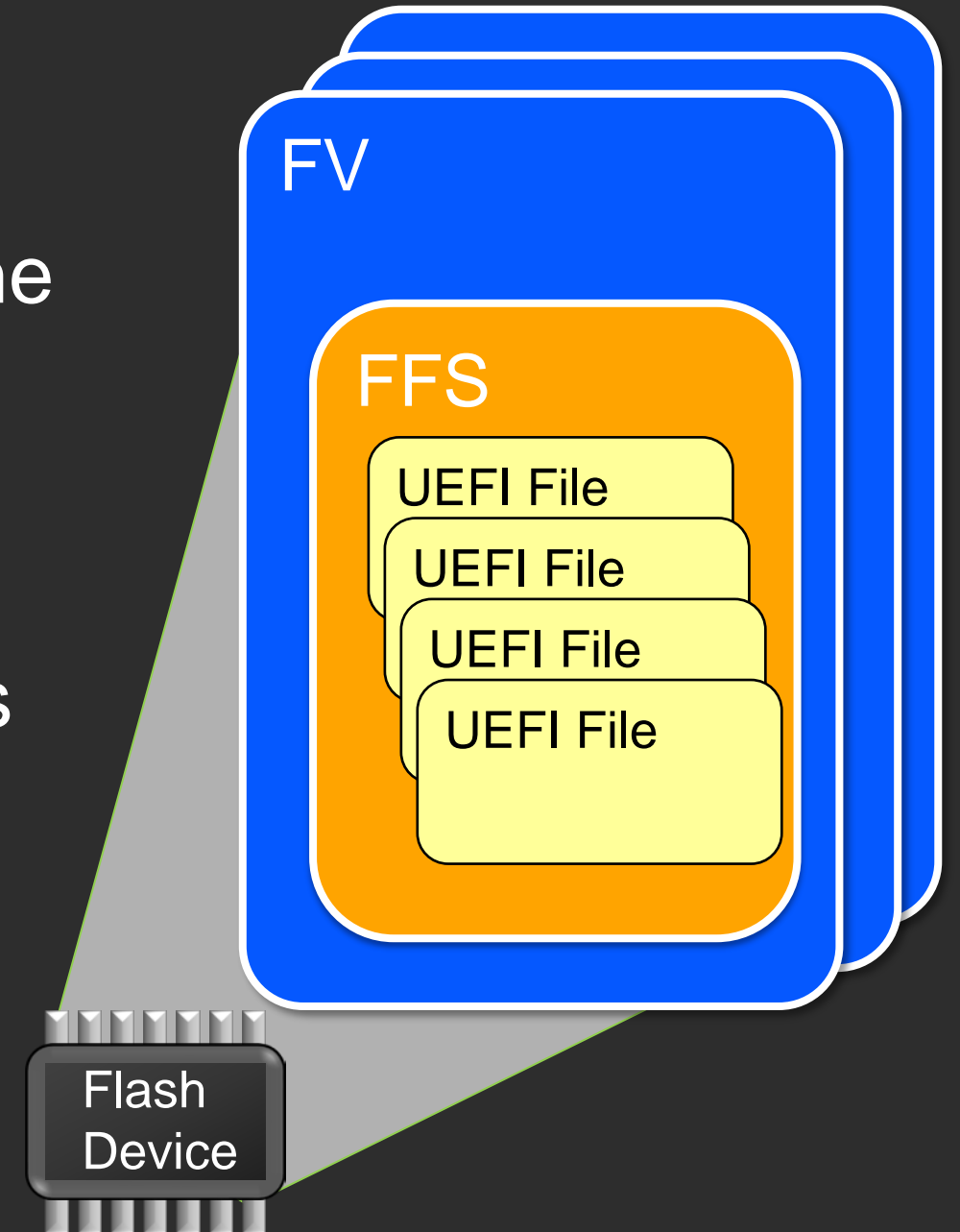
Stages Organize the MPA Specification



UEFI Firmware Volumes (FV) - Review

Platform Initialization - Firmware Volume

- Basic storage repository for data and code is the Firmware Volume (FV)
- Each FV is organized into a file system, each with attributes
- One or more Firmware File Sections (FFS) files are combined into a FV
- Flash Device may contain one or more FVs.
- .FDF file controls the layout → .FD image(s)



Standardize FV By Stages

Pre-Memory

- **FvPreMemory** – The PEIM dispatched before the memory initialization. Also included **FSP - FV**

Post Memory

- **FvPostMemory** – The PEIM dispatched after the memory initialization. Also included **FSP - FV**

UEFI Boot

- **FvUefiBoot** – The DXE driver supporting UEFI boot, such as boot to UEFI shell.

OS Boot

- **FvOsBoot** – The DXE driver supporting UEFI OS boot, such as UEFI Windows.

Security

- **FvSecurity** – The security related modules, such as UEFI Secure boot, TPM etc.

Advanced

- **FvAdvanced** – The advanced feature modules, such as UEFI network, IPMI etc.

Intel FSP Firmware Volumes

– created Pre-Build

```
MyWorkSpace/  
  edk2/  
    - “edk2 Common”  
  edk2-platforms/  
    Platform/Intel “Platform”  
      KabyLakeOpenBoardPkg/  
        include/fdf \  
          FlashMapInclude.fdf  
        BoardXPkg/ “Board”  
      Silicon/ “Silicon”  
        Intel/MinPlatformPkg/  
  edk2-non-osi/  
    Silicon/Intel/  
  FSP/  
    BoardXPkg  
      Fsp.fdf
```

FvFspT

- – Temp Memory

FvFspM

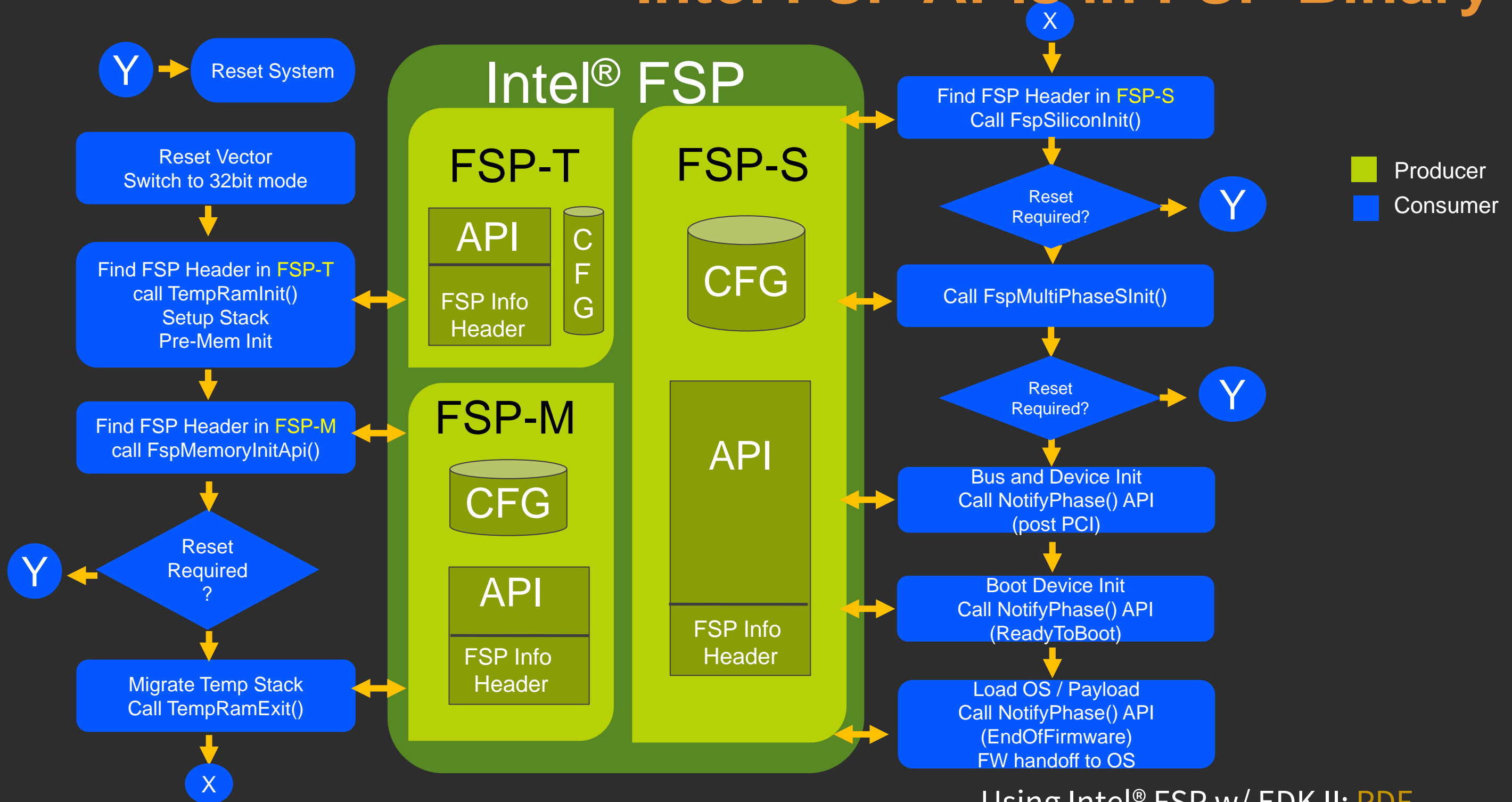
- -> FvPreMemorySilicon

FvFspS

- -> FvPostMemorySilicon

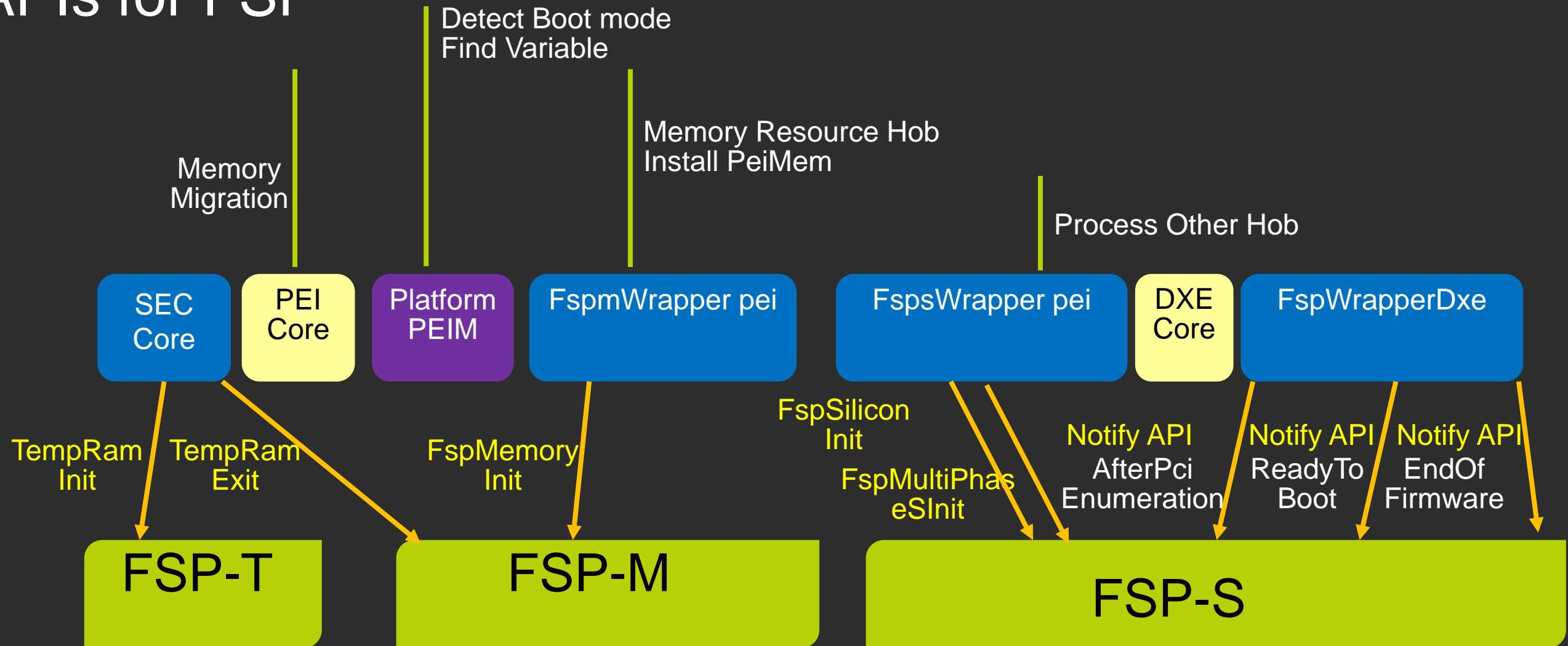
Pre-Build w/
RebaseAndPatchFspBinBaseAddress.py

Intel FSP APIs in FSP Binary



Boot Flow with Intel FSP API Mode

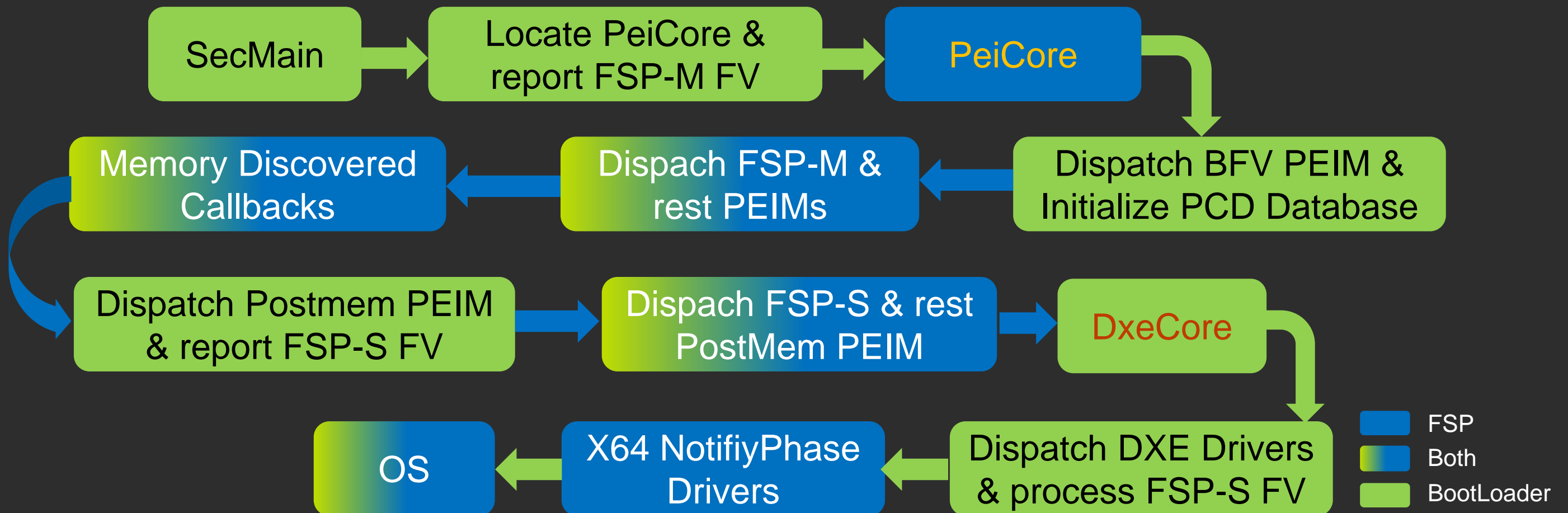
6 APIs for FSP



Original Source: [Using the Intel® FSP with EDK II \(2.0\)](#) Fig 4. – This now shows a 6 API added in FSP 2.2

Intel FSP 2.1 Dispatch Mode Boot Flow

gIntelFsp2WrapperTokenSpaceGuid.PcdFspModeSelection 0 - dispatch, 1 - API



Dispatch Mode Interface

- Optional boot flow intended to enable Intel FSP to integrate well in to UEFI bootloader implementations.
- Conforms to UEFI & PI Specifications
- The FSP-T, FSP-M, and FSP-S are containers that expose firmware volumes (FVs) directly to the bootloader.
- UPD Mechanism to pass Config data is not needed
- PCD Database Required

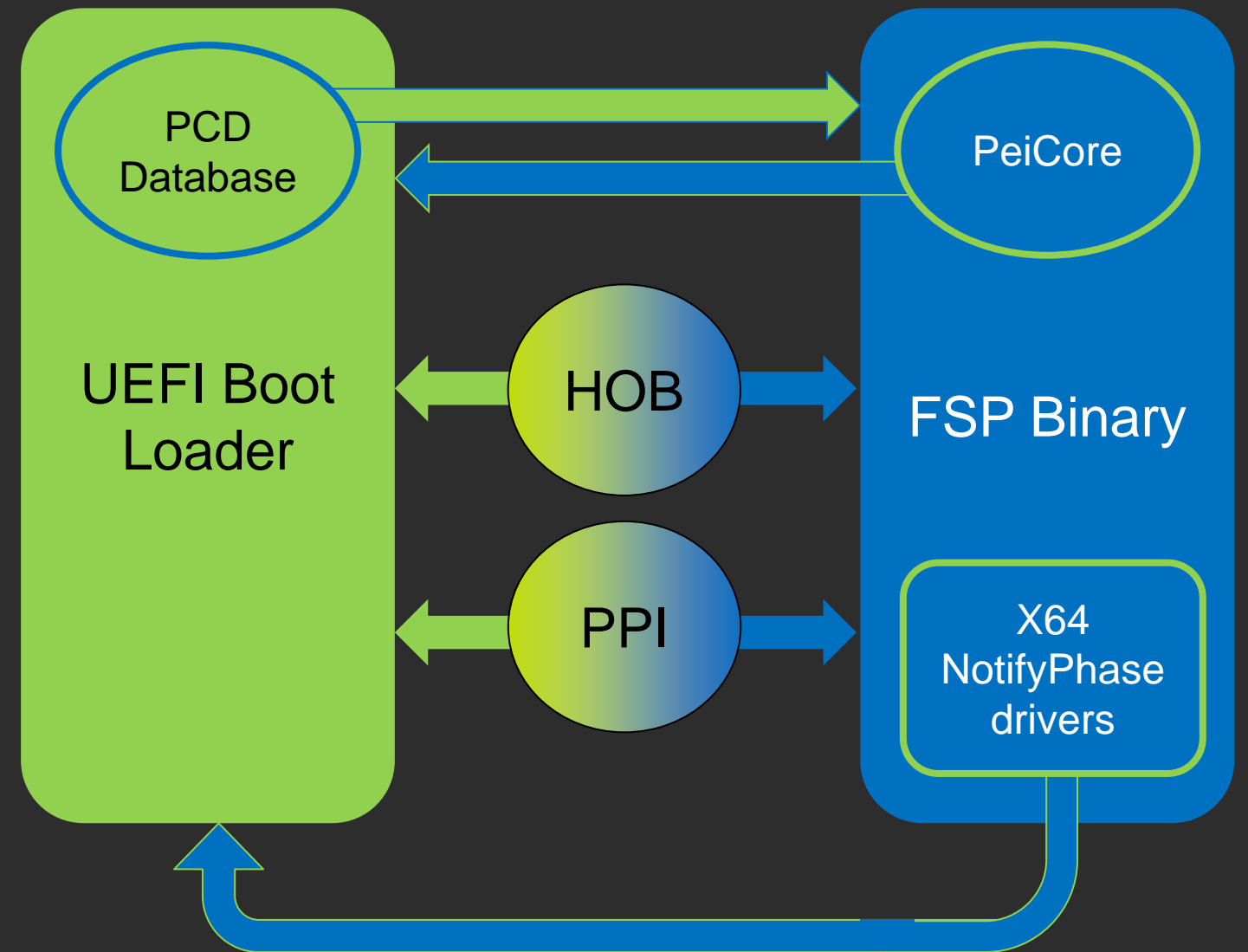


Figure 6 FSP Spec 2.2

PLATFORM HOOKS

Using EDK II Libraries



EDK II Libraries w/ Platform Hooks



DSC maps library class to library-instances

Syntax in DSC file

```
[libraryclasses]
```

```
LibraryClassName|Path/To/LibInstanceNameInstance1.inf
```



Search INF files for string: “**LIBRARY_CLASS** =”

Platform Initialization Board Hook Modules

```
MinPlatformPkg/  
  Include/  
    Library/  
      BoardInitLib.h  
  Library/  
    . . .  
  PlatformInit/  
    PlatformInitPei/  
    PlatformInitPreMem/  
    PlatformInitPostMem/  
    PlatformInitDxe/  
    PlatformInitSmm/
```

```
BoardDetect()  
BoardDebugInit()  
BoardBootModeDetect()  
BoardInitBeforeMemoryInit()  
BoardInitBeforeTempRamExit()  
BoardInitAfterTempRamExit()  
BoardInitAfterMemoryInit()  
BoardInitBeforeSiliconInit()
```

PEI

```
BoardInitAfterPciEnumeration()  
BoardInitReadyToBoot()  
BoardInitEndOfFirmware()
```

DXE



Platform Initialization Board Hook Modules

MinPlatformPkg/

. . .

PlatformInit/

PlatformInitPei/

PlatformInitPreMem/

PlatformInitPostMem/

PlatformInitPreMem/

BoardDetect()

BoardDebugInit()

BoardBootModeDetect()

BoardInitBeforeMemoryInit()

. . .

Notify call back

BoardInitAfterMemoryInit()

PEI

PlatformInitPostMem/

BoardInitBeforeSiliconInit()

. . .

BoardInitAfterSiliconInit()

How to find the Platform Hooks: Process of Porting

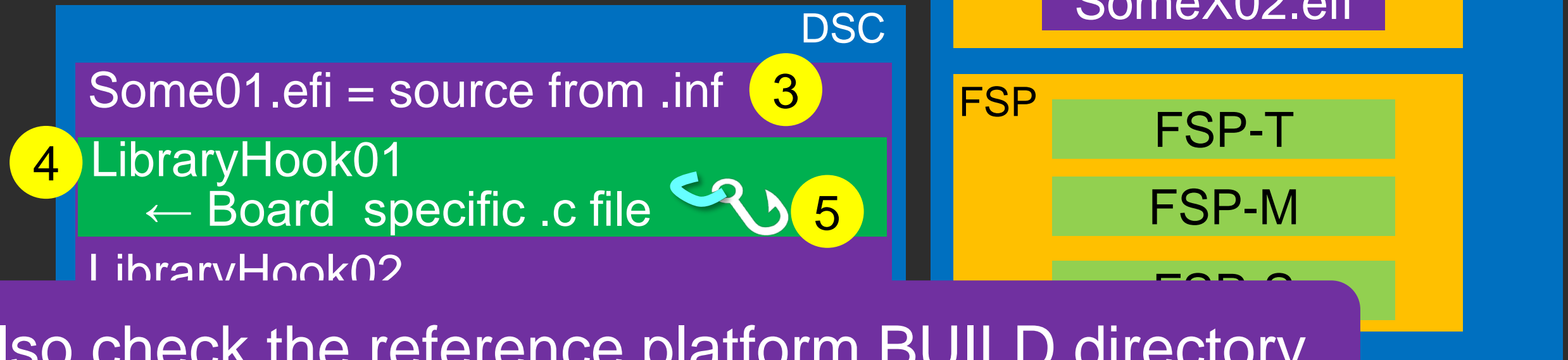


Check the Board/Platform .FDF file layout

Investigate the FDF then DSC files

Porting process per stage find and update platform hooks

- ① Locate FVs for each stage
- ② Modules for each FV contents
- ③ Module Locations
- ④ Platform Porting Libraries per Module
- ⑤ Update the Hook Function for Board



Also check the reference platform BUILD directory

How to search for Libraries in the Workspace

1. Search the workspace .DSC files for the string of the library
2. Open the .DSC files associated with the open board platform project
3. Determine which Library is used and that should have the build path in the workspace
4. DSC file will have similar to:
`SomeLib|Path_to_the_Library_used.inf`
5. Verify the instance used from the Build directory



Platform Initialization Board Hook Modules

- Stage 1

```
MinPlatformPkg/  
  Include/  
    Library/  
      BoardInitLib.h ← // hooks  
  Library/  
    . . .  
PlatformInit/  
  PlatformInitPei/  
    PlatformInitPreMem/
```

```
BoardDetect()  
BoardDebugInit()  
BoardBootModeDetect()  
BoardInitBeforeMemoryInit()
```

Platform folder PlatformInit controls
the platform initialization flow

Example Hook - Board Detection

-Kabylake example



MinPlatformPkg/

. . .

PlatformInit/

PlatformInitPei ->

PlatformInitPreMem.c

BoardDetect()

KabylakeOpenBoardPkg/

. . .

KabylakeRvp3/

Library/

BoardInitLib ->

PeiBoardInitPreMemLib.c

BoardDetect()

PeiKabylakeRvp3Detect.c

KabylakeRvp3BoardDetect()

Uses PCD Library calls to set / get Board SKU for Storing Board ID

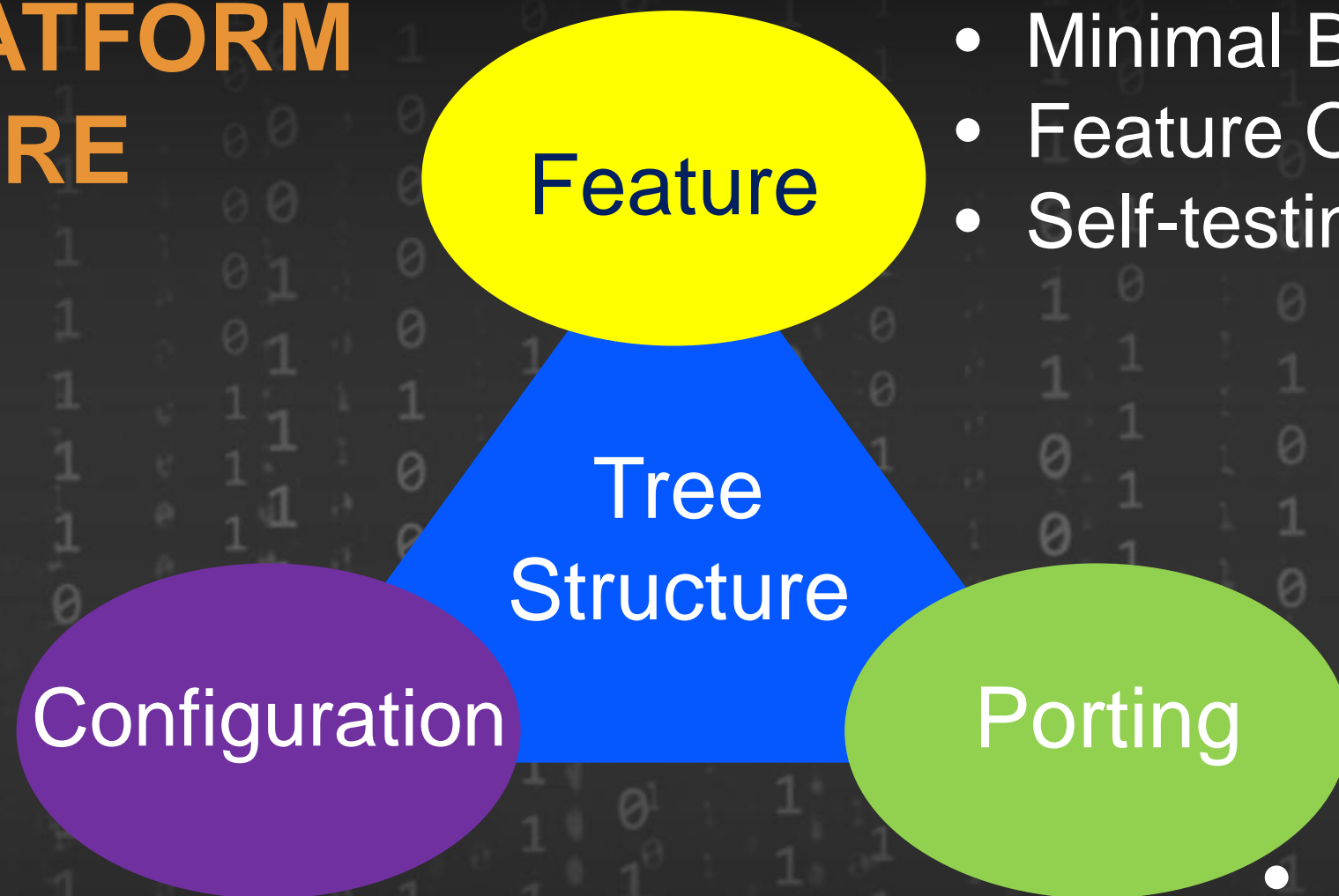
LibPcdGetSku() & LibPcdSetSku()

KabylakeRvp3BoardDetect() function reads Board ID from embedded controller (EC) using the LPC bus

LibPcdSetSku() stores Board ID

LibPcdGetSku() used from that point on

MINIMUM PLATFORM ARCHITECTURE SUMMARY



- Minimal Baseline
- Feature ON/OFF
- Self-testing

- Incremental
- Simple PCD usage model
- No setup

- Incremental
- Simple C libraries
- The same each time

Summary

- ★ Minimum Platform Architecture (MPA) is an Open source Intel platform code base for use with EDK II
- ★ EDK II Minplatform's infrastructure focus areas: Tree, Features, Configuration & Porting
- ★ MinPlatform uses Intel® FSP for processor, silicon and memory init & uses silicon policy guid lines for data flow

Questions?



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