# Homework 3: Multi-Agent Search

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## Part I. Implementation (5%):

Please screenshot your code snippets of Part 1 ~ Part 4, and explain your implementation.

### Part 1: Minimax Search (20%)

```
def minimax(depth,agentID,state): # define a function to do recursive
                  if state.isWin() | state.isLose(): # current state is already win lose
                     return self.evaluationFunction(state) # return current evaluation value
140 V
                  if depth == self.depth: # reach the required depth
                     return self.evaluationFunction(state) # return current evaluation value
                  action = state.getLegalActions(agentID) # get the current state action with agent ID
                  if agentID == 0: # agent is 0 => then is pacman
                      tmp score = float("-INF") # set a max value with the min num
                      for acts in action: # go through all action
                         next_state = state.getNextState(agentID,acts) # get the action's next state
                          tmp_score = max(minimax(depth,agentID + 1,next_state),tmp_score)
                      return tmp score # return the max value in this action
                  else: # agent is not 0 => then is ghost
                      min score = float("INF") # set a min value with the max num
                          next_state = state.getNextState(agentID,acts) # get the action's next state
154 V
                          if agentID + 1 >= state.getNumAgents(): # all agents choose action
                             min_score = min(minimax(depth + 1,0,next_state),min_score)
158 ~
                              min_score = min(minimax(depth,agentID + 1,next_state),min_score)
                              # if the minimax return value is smaller than min score, change min score
                      return min score # return the min value in this action
              best = float("-INF") # set a max value with the min num
              move = None # define a variable to store action
              if gameState.isWin() | gameState.isLose() | self.depth == 0:
              for act in gameState.getLegalActions(0): # go through all actions
                  next = gameState.getNextState(0,act) # get the action's next state
                  score = minimax(0,1,next) # find out it's minimax value
                  if score > best: # choose the max one
                      best = score # store its value
                      move = act # store its action
              return move # return the action found
```

I define a function, so that I can do recursive. At first, I do the depth = 0, agentID = 0 outside, so that I can get the specific action, and then the recursive function can just return the value. At every time the agentID + 1 reaches the total number of the agents, depth needs to add 1.

#### Part 2: Alpha-Beta Pruning (25%)

```
def alphabeta(depth,agentID,state,alpha,beta): # define a function to do recursive
   if state.isWin() | state.isLose(): # current state is already win lose
       return self.evaluationFunction(state) # return current evaluation value
   if depth == self.depth: # reach the required depth
       return self.evaluationFunction(state) # return current evaluation value
   action = state.getLegalActions(agentID) # get the current state action with agent ID
   if agentID == 0: # agent is 0 => then is pacman
       tmp score = float("-INF") # set a max value with the min num
           next_state = state.getNextState(agentID,acts) # get the action's next state
           tmp_score = max(alphabeta(depth,agentID + 1,next_state,alpha,beta),tmp_score)
           if tmp score > beta:
               return tmp_score # return if current value is larger than beta
           alpha = max(tmp_score,alpha) # update alpha with the max value in this action
       return tmp_score # return the max value in this action
       min_score = float("INF") # set a min value with the max num
           next_state = state.getNextState(agentID,acts) # get the action's next state
           if agentID + 1 >= state.getNumAgents(): # all agents choose action
               min_score = min(alphabeta(depth + 1,0,next_state,alpha,beta),min_score)
               min_score = min(alphabeta(depth,agentID + 1,next_state,alpha,beta),min_score)
           if min score < alpha:
               return min_score # return if current value is smaller than alpha
           beta = min(min_score,beta) # update beta with the min value in this action
       return min_score # return the min value in this action
```

```
best = float("-INF") # set a max value with the min num

alpha = float("-INF") # set alpha to the minimal, then later update its value

beta = float("INF") # set beta to the maximal, then later update its value

move = None # define a variable to store action

if gameState.isWin() | gameState.isLose() | self.depth == 0:

return None # if already win/lose or reach required depth, do nothing

for act in gameState.getLegalActions(0): # go through all actions

next = gameState.getNextState(0,act) # get the action's next state

score = alphabeta(0,1,next,alpha,beta) # find out it's minimax value

if score > best: # choose the max one

best = score # store its value

move = act # store its action

alpha = max(score,alpha) # in here, need to update alpha

return move # return the action found

# End your code (Part 2)
```

I define a function, so that I can do recursive. At first, I do the depth = 0, agentID = 0 outside, so that I can get the specific action, and then the recursive function can just return the value. Because of this reason, I need to update alpha at that part, which is line 231. Also, the parameters in the recursive function need to contain alpha and beta, when doing the algorithm, update alpha and beta, then pass down. At every time the agentID + 1 reaches the total number of the agents, depth needs to add 1.

## Part 3: Expectimax Search (25%)

```
def expectimax(depth,agentID,state): # define a function to do recursive
    if state.isWin() | state.isLose(): # current state is already win lose
       return self.evaluationFunction(state) # return current evaluation value
    if depth == self.depth: # reach the required depth
       return self.evaluationFunction(state) # return current evaluation value
   action = state.getLegalActions(agentID) # get the current state action with agent ID
    if agentID == 0: # agent is 0 => then is pacman
       tmp_score = float("-INF") # set a max value with the min num
        for acts in action: # go through all action
           next_state = state.getNextState(agentID,acts) # get the action's next state
           tmp_score = max(expectimax(depth,agentID + 1,next_state),tmp_score)
       return tmp score # return the max value in this action
       val = 0. # variable to sum up all action value
       count = 0 # counting the numbers of the value
           count = count + 1 # the number of the value add 1
            next_state = state.getNextState(agentID,acts) # get the action's next state
           if agentID + 1 >= state.getNumAgents(): # all agents choose action
               val += expectimax(depth + 1,0,next_state)
               val += expectimax(depth,agentID + 1,next_state) # sum up the action value
        return val/count # return the expection
best = float("-INF") # set a max value with the min num
move = None # define a variable to store action
```

```
best = float("-INF") # set a max value with the min num

move = None # define a variable to store action

if gameState.isWin() | gameState.isLose() | self.depth == 0:

return None # if already win/lose or reach required depth, do nothing

for act in gameState.getLegalActions(0): # go through all actions

next = gameState.getNextState(0,act) # get the action's next state

score = expectimax(0,1,next) # find out it's minimax value

if score > best: # choose the max one

best = score # store its value

move = act # store its action

return move # return the action found

# End your code (Part 3)
```

I define a function, so that I can do recursive. At first, I do the depth = 0, agentID = 0 outside, so that I can get the specific action, and then the recursive function can just return the value. At every time the agentID + 1 reaches the total number of the agents, depth needs to add 1. The special part of this is that I don't choose the min value for ghost, but the expectation, so I use a variable to store the sum, and then take average when I return value.

#### Part 4: Evaluation Function (20%)

```
# Begin your code (Part 4)
pac_pos = currentGameState.getPacmanPosition() # get pacman's position
food list = currentGameState.getFood().asList() # get the food list
score = currentGameState.getScore() # get current score
ghost_state = currentGameState.getGhostStates() # get the ghosts' state
remain_cap = len(currentGameState.getCapsules()) # calculate remain capsules
remian_food = len(food_list) # calculate remain food
score -= 15 * remian_food # remain more, score is less
score -= 30 * remain_cap # remain more, score is less
for food in food_list: # go through all food
   dis = manhattanDistance(pac_pos,food) # calculate the distance
       score -= 1 * dis
       score -= 0.5 * dis
for ghost in ghost_state: # go through all ghost
   dis = manhattanDistance(pac_pos,ghost.getPosition())
   if dis < 3: # according the the distance to decide the weight
       score -= 20 * dis
       score -= 10 * dis
return score
```

I maintain the score by the distance between the pacman and the food/ghosts. Then, I give it a reasonable value to reach the goal.

# Part II. Results & Analysis (5%):

Please screenshot the results.

```
Pacman emerges victorious! Score: 1090
Pacman emerges victorious! Score: 1371
Pacman emerges victorious! Score: 1171
Pacman emerges victorious! Score: 1166
Pacman emerges victorious! Score: 1129
Pacman emerges victorious! Score: 1149
Pacman emerges victorious! Score: 1155
Pacman emerges victorious! Score: 1126
Pacman emerges victorious! Score: 1216
Pacman emerges victorious! Score: 1216
Pacman emerges victorious! Score: 943
Average Score: 1151.6
Scores: 1090.0, 1371.0, 1171.0, 1166.0, 1129.0, 1149.0, 1155.0, 1126.0, 1216.0, 943.0
Win Rate: 10/10 (1.00)
```