

# **Convex Optimization:**

## CVX 101

**Ian Quah (itq)**

November 7, 2017

## Week 3: Convex Functions

### Basic Properties and Examples

- Defn:  $f : \mathbf{R}^n \rightarrow \mathbf{R}$  is convex if  $\text{dom } f$  is a convex set, and

$$f(\theta x + (1 - \theta)y) \leq \theta f(x) + (1 - \theta)f(y) \quad \forall x, y \in \text{dom } f, 0 \leq \theta \leq 1$$

Aka, if you draw a bowl, with  $(x, f(x))$  on the left side and  $(y, f(y))$  on the right side, the line connecting the two (the chord), is such that the chord is above the graph

- $f$  is concave if  $-f$  is convex
- $f$  is strictly convex if  $\text{dom } f$  is convex and

$$f(\theta x + (1 - \theta)y) < \theta f(x) + (1 - \theta)f(y) \quad \text{for } x, y \in \text{dom } f, x \neq y, 0 < \theta < 1$$

- Convex examples on  $\mathbf{R}$

- affine:  $ax + b$  on  $\mathbf{R} \quad \forall a, b \in \mathbf{R}$
- exponential:  $e^{ax}$ , for any  $a \in \mathbf{R}$
- powers:  $x^\alpha$  on  $\mathbf{R}_{++}$ , for  $\alpha \geq 1$  or  $\alpha \leq 0$
- powers of absolute value:  $|x|^p$  on  $\mathbf{R}$ , for  $p \geq 1$
- Negative entropy:  $x \log x$  on  $\mathbf{R}_{++}$

- Concave examples on  $\mathbf{R}$

- affine:  $ax + b$  on  $\mathbf{R} \quad \forall a, b \in \mathbf{R}$
- powers:  $x^\alpha$  on  $\mathbf{R}_{++}$ , for  $0 \leq \alpha \leq 1$
- logarithm:  $\log x$  on  $\mathbf{R}_{++}$

- Basically if you plot it you have a non-negative curvature (curves up)

- Examples on  $\mathbf{R}^n$  and  $\mathbf{R}^{m \times n}$

Affine functions are convex and concave; all norms are convex

#### Examples on $\mathbf{R}^n$

- affine function:  $f(x) = a^T x + b$
- norms:  $\|x\|_p = (\sum_{i=1}^n |x_i|^p)^{\frac{1}{p}}$  for  $p \geq 1$ ;  $\|x\|_\infty = \max_k |x_k|$

#### Examples on $\mathbf{R}^{m \times n}$

- affine function:

$$f(X) = \text{tr}(A^T X) + b = \sum_{i=1}^m \sum_{j=1}^n A_{ij} X_{ij} + b$$

- spectral (maximum singular value) norms

$$f(X) = \|X\|_2 = \sigma_{\max}(X) = (\lambda_{\max}(X^T X))^{\frac{1}{2}}$$

- Convexity checking: restricting the convex function to a line

– f:  $\mathbf{R}^n \rightarrow \mathbf{R}$  is convex iff the fn g:  $\mathbf{R} \rightarrow \mathbf{R}$

$$g(t) = f(x + tv), \quad \text{dom } g = \{t | x + tv \in \text{dom } f\}$$

\* is convex (in t) for any  $x \in \text{dom } f, v \in \mathbf{R}^n$

\* can check convexity of f by checking convexity of functions of one variable

\* The intuition here is that a function is convex iff when restricted to all lines it is convex

– Example: f:  $\mathbf{S}^n \rightarrow \mathbf{R}$  with  $f(X) = \log \det X$ ,  $\text{dom } f = \mathbf{S}_{++}^n$

$$\begin{aligned} g(t) &= \log \det(X + tV) & (X + tV &= X^{\frac{1}{2}}(I + X^{-\frac{1}{2}}VX^{-\frac{1}{2}})X^{\frac{1}{2}}) \\ &= \log \det X + \log \det(I + tX^{-\frac{1}{2}}VX^{-\frac{1}{2}}) & (\log \det X \text{ constant, } \neg \text{ interesting}) \\ &= \log \det X + \sum_{i=1}^n \log(1 + t\lambda_i) & (\text{RHS is concave}) \end{aligned}$$

where  $\lambda_i$  are the eigenvalues of  $X^{-\frac{1}{2}}VX^{-\frac{1}{2}}$

g is concave in t (for any choice of  $X \succ 0, V$ ); hence f is concave

- Extended-value extension

extended-value extension  $\tilde{f}$  of f is

$$\tilde{f}(x) = f(x), x \in \text{dom } f, \tilde{f}(x) = \infty, x \notin \text{dom } f,$$

often simplifies notation; e.g

$$0 \leq \theta \leq 1 \rightarrow \tilde{f}(\theta x + (1 - \theta)y) \leq \theta \tilde{f}(x) + (1 - \theta)\tilde{f}(y)$$

(as an inequality in  $\mathbf{R} \cup \{\infty\}$ ), means the same as the two conditions

–  $\text{dom } f$  is convex

– for  $x, y \in \text{dom } f$ ,

$$0 \leq \theta \leq 1 \implies f(\theta x + (1 - \theta)y) \leq \theta f(x) + (1 - \theta)f(y)$$

Conditions for convexity:

### First-Order Condition

- $f$  is differentiable if  $\text{dom } f$  is open and the gradient

$$\nabla f(x) = \left( \frac{\partial f(x)}{\partial x_1}, \frac{\partial f(x)}{\partial x_2}, \dots, \frac{\partial f(x)}{\partial x_n} \right)$$

, a column vector

exists at each  $x \in \text{dom } f$

- **1st-order condition:** differentiable  $f$  with convex domain is convex iff

$$f(y) \geq f(x) + \nabla f(x)^T (y - x) \forall x, y \in \text{dom } f$$

RHS: first order Taylor expansion of  $f$  at the point  $x$

first-order approximation of  $f$  is a global underestimator

### Second-Order Condition

- $f$  is twice differentiable if  $\text{dom } f$  is open and the Hessian  $\nabla^2 f(x) \in \mathbf{S}^n$  gradient

$$\nabla^2 f(x)_{ij} = \frac{\partial^2 f(x)}{\partial x_i \partial x_j}, i, j = 1, \dots, n$$

exists at each  $x \in \text{dom } f$

- **2nd-order condition:** for twice differentiable  $f$  with convex domain is convex iff

–  $f$  is convex iff

$$\nabla^2 f(x) \succeq 0 \text{ for all } x \in \text{dom } f, \text{ the resulting matrix is PSD}$$

– if  $\nabla^2 f(x) \succeq 0$  for all  $x \in \text{dom } f$ , then  $f$  is strictly convex

## Examples

- quadratic functions:  $f(x) = \frac{1}{2}x^T Px + q^T x + r$  with  $P \in \mathbf{S}^n$

$$\nabla f(x) = Px + q, \nabla^2 f(x) = P$$

convex if  $P \succeq 0$

- Least-squares objective:  $f(x) = \|Ax - b\|_2^2$

$$\nabla f(x) = 2A^T(Ax - b), \nabla^2 f(x) = 2A^T A$$

convex (for any A)

- Quadratic-over-linear:  $f(x, y) = \frac{x^2}{y}$

$$\nabla^2 f(x, y) = \frac{2}{y^3} \begin{bmatrix} y & -x \end{bmatrix}^T \begin{bmatrix} y & -x \end{bmatrix} \succeq 0$$

convex for  $y > 0$

- if you plot this and rotate it you get the lorentz cone. It also looks like the front of a ship
- Is rank 1, and this tells us that at any point it is curving in one direction but not in the other.

- log-sum-exp:  $f(x) = \log \sum_{k=1}^n \exp(x_k)$  is convex (This is the softmax function)

$$\nabla^2 f(x) = \frac{1}{\mathbf{1}^T z} \text{diag}(z) - \frac{z z^T}{(\mathbf{1}^T z)^2}, (z_k = \exp x_k)$$

note: LHS is PSD

to show  $\nabla^2 f(x) \succeq 0$ , must verify that  $v^T \nabla^2 f(x) v \geq 0 \forall v$ :

$$\text{since } \left( \sum_k v_k z_k \right)^2 \leq \left( \sum_k z_k v_k^2 \right) \left( \sum_k z_k \right)$$

(from Cauchy-Schwarz inequality)

- geometric mean:  $f(x) = \left( \prod_{k=1}^n x_k \right)^{\frac{1}{n}}$  on  $\mathbf{R}_{++}^n$  is concave and follows a similar proof as log-sum-exp
- $\alpha$ -sublevel set of  $f: \mathbf{R}^n \rightarrow \mathbf{R}$

$$C_\alpha = \{x \in \mathbf{dom} f \mid f(x) \leq \alpha\}$$

sublevel sets of convex functions are convex (converse is false)

- Epigraph of  $f: \mathbf{R}^n \rightarrow \mathbf{R}$

$$\text{epi } f = \{(x, y) \in \mathbf{R}^{n+1} \mid x \in \mathbf{dom} f, f(x) \leq y\}$$

- function  $f$  is convex IFF  $\text{epi } f$  is a convex set
- Describes the connection between a convex function and a convex set

- Jensen's inequality

- Basic inequality: if  $f$  is convex, then for  $0 \leq \theta \leq 1$ ,

$$f(\theta x + (1 - \theta)y) \leq \theta f(x) + (1 - \theta)f(y)$$

- Extension: if  $f$  is convex, then

$$f(\mathbf{E}z) \leq \mathbf{E}f(z)$$

for any random variable  $z$

- basic inequality is special case with discrete distribution

$\text{prob}(z = x) = \theta, \text{prob}(z = y) = 1 - \theta$

## Operations that preserve Convexity

Practical methods for establishing convexity

- verify defn': often simplified by restricting to a line
- for twice differentiable functions, show  $\nabla^2 f(x) \succeq 0$
- Show that  $f$  is obtained from simple convex fns' by operations that themselves preserve convexity

– 1) non-negative weighted sum, and composition with affine functions

- \* nonnegative multiple:  $\alpha f$  is convex if  $f$  is convex,  $\alpha \geq 0$
- \* sum:  $f_1 + f_2$  convex, if  $f_1$  and  $f_2$  convex (extends to infinite sums, integrals)
- \*  $f(Ax + b)$  is convex if  $f$  is convex
- \* log barrier for linear inequalities:

$$f(x) = - \sum_{i=1}^m \log(b_i - a_i^T x), \quad \text{dom } f = \{x | a_i^T x < b_i, i = 1, \dots, m\}$$

- \* (any) norm of affine function:  $f(x) = \|Ax + b\|$

– 2) Pointwise Max

- \* if  $f_1, \dots, f_m$  are convex, then  $f(x) = \max(f_1(x), \dots, f_m(x))$  is convex

Intuition: draw multiple bowls and take the intersection

- \* piecewise-linear function:  $f(x) = \max_{i=1, \dots, m} (a_i^T x + b_i)$  is convex
- \* sum of  $r$  largest components of  $x \in \mathbf{R}^n$ :

$$f(x) = x_{[1]} + x_{[2]} + \dots + x_{[r]}$$

is convex ( $x_{[1]}$  is the  $i$ th largest component of  $x$ )

proof:

$$f(x) = \max\{x_{i_1} + x_{i_2} + \dots + x_{i_r} | 1 \leq i_1 < i_2 < \dots < i_r \leq n\}$$

– 3) Pointwise supremum

- \* if  $f(x, y)$  is convex in  $x$  for each  $y \in \mathcal{A}$ , then

$$g(x) = \sup_{y \in \mathcal{A}} f(x, y)$$

is convex

- \* examples

- support function of a set  $C$ :  $S_C(x) = \sup_{y \in C} y^T x$  is convex  
 $y^T x$  is linear, and the supremum of a set of functions is itself convex
- distance to farthest point in a set  $C$ :

$$f(x) = \sup_{y \in C} \|x - y\|$$

- max eigenvalue of symmetric matrix: for  $X \in \mathbf{S}^n$ ,

$$\lambda_{\max}(X) = \sup_{\|y\|_2=1} y^T X y$$

Practical methods for establishing convexity

- Show that  $f$  is obtained from simple convex fns' by operations that themselves preserve convexity
  - 4) Composition with scalar functions
    - \* Composition of  $g: \mathbf{R}^n \rightarrow \mathbf{R}$  and  $h: \mathbf{R} \rightarrow \mathbf{R}$

$$f(x) = h(g(x))$$

$$f \text{ is convex if } \begin{cases} g \text{ convex, } h \text{ convex, } \tilde{h} \text{ nondecreasing} \\ g \text{ concave, } h \text{ convex, } \tilde{h} \text{ nonincreasing} \end{cases}$$

\* proof