MAML is a Noisy Contrastive Learner

NewInML Workshop@NeuroIPS'21

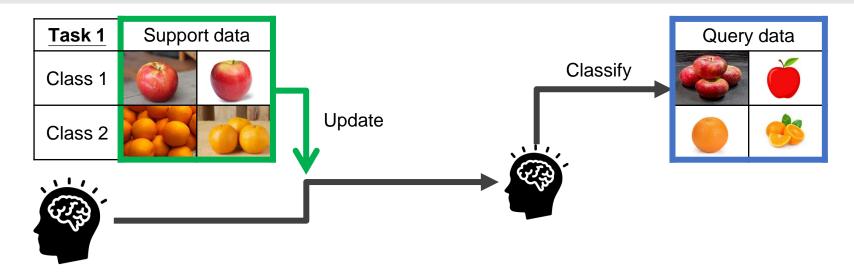
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¹National Yang Ming Chiao Tung University

²MIT-IBM Watson AI Lab

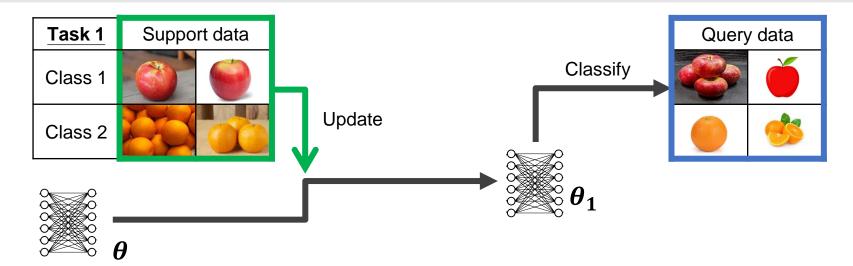


Humans learn to classify even with limited experience.

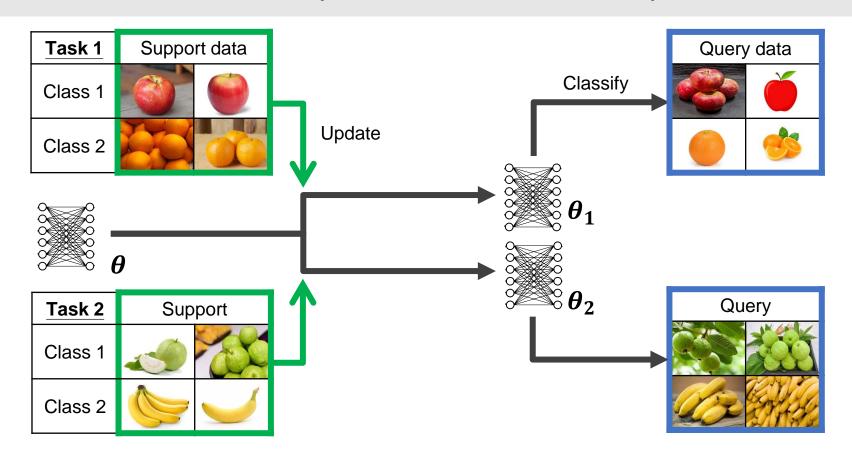




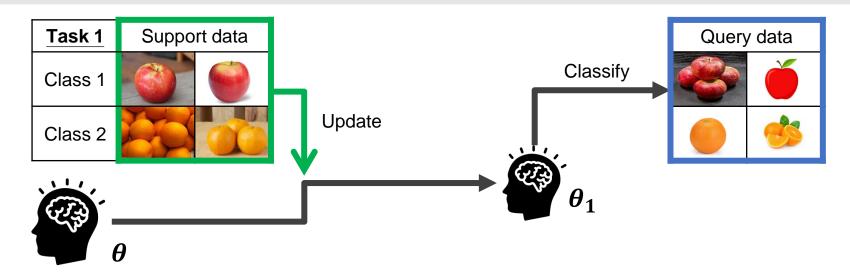
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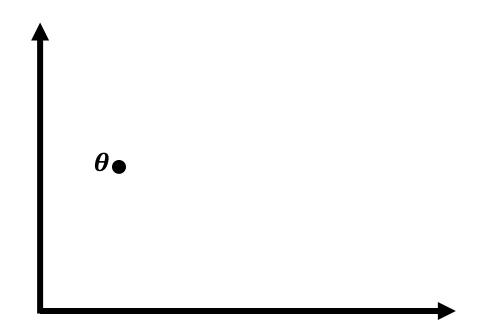


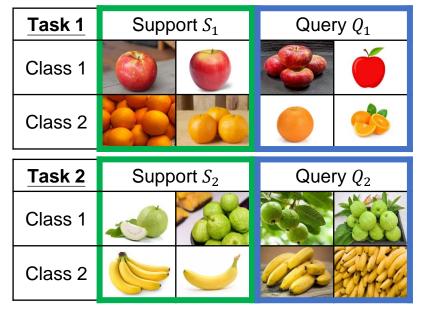
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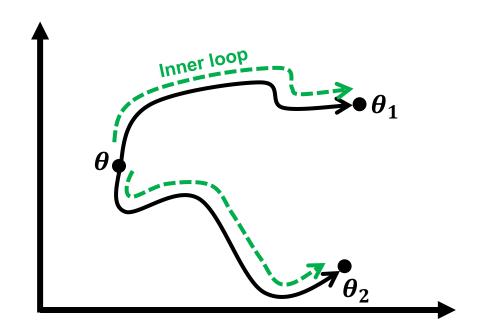
MAML is a gradient-based meta-learning algorithm that finds a good θ .

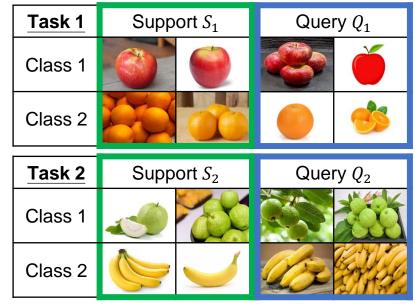
MAML makes model learn to classify after seeing little data.



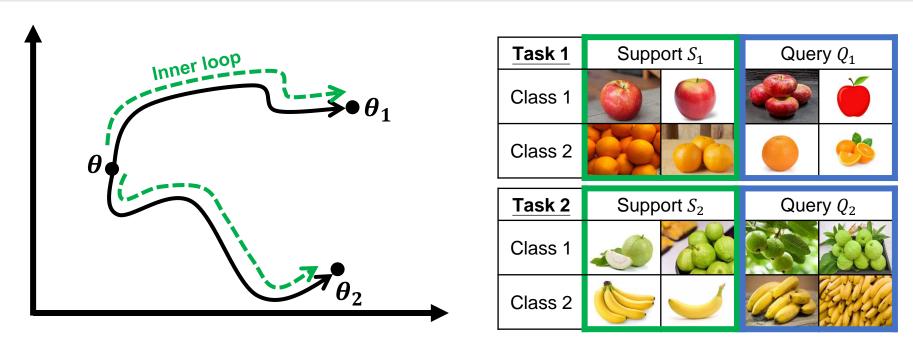


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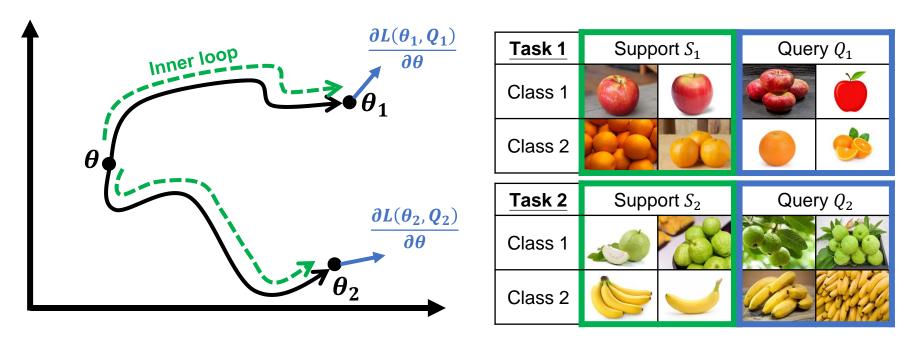


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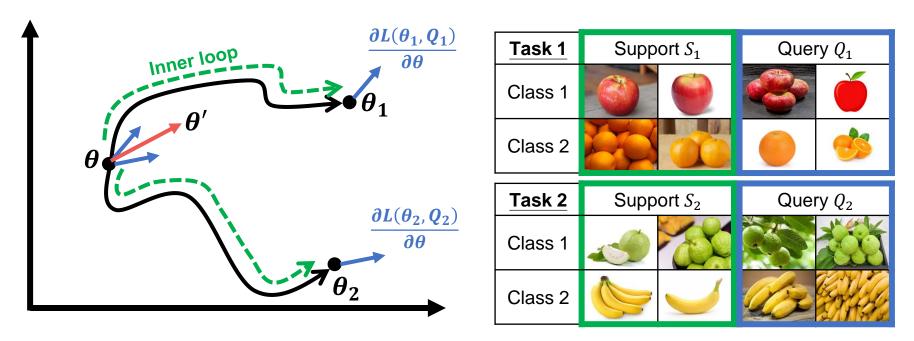
• Goal: Minimize $L(\theta_1, Q_1)$ and $L(\theta_2, Q_2)$ by finding best θ .

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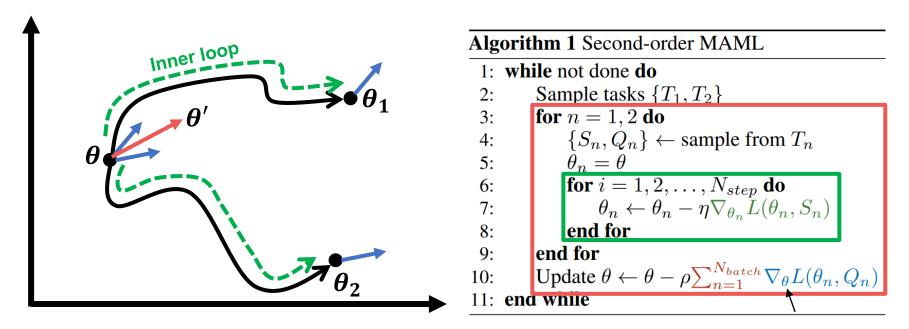
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- Goal: Minimize $L(\theta_1, Q_1)$ and $L(\theta_2, Q_2)$ by finding best θ .
- Method: update θ by $\theta' = \theta \sum \frac{\partial L(\theta_n, Q_n)}{\partial \theta}$

MAML makes model learn to classify after seeing little data.

Why is MAML successful?

 It is widely believed that MAML <u>encourages</u> models to learn a general-purpose representations which are applicable to novel tasks.

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In this paper, we step further and ask:

- <u>How</u> does MAML <u>encourage</u> any model to learn general-purpose representations?
- What is the role of the support and query data and how do they interact with each other?

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In this paper, we step further and ask:

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- What is the role of the support and query data and how do they interact with each other?

Our contribution:

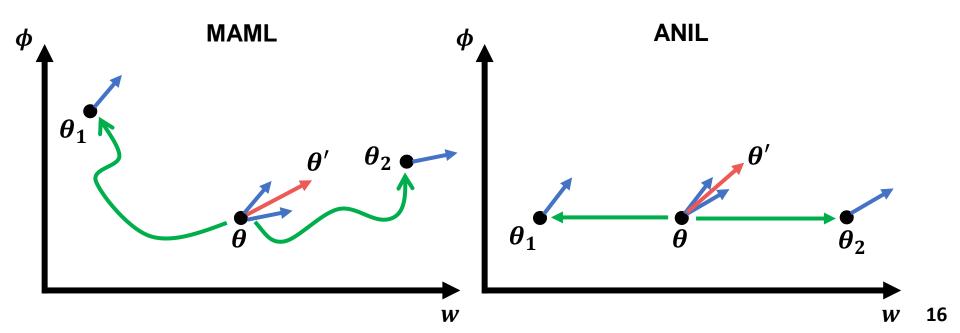
We show that MAML is a noisy supervised contrastive learning algorithm.

Assumption

ANIL (Almost no inner loop)

Consider a model $\boldsymbol{\theta} = \{\boldsymbol{\phi}, \boldsymbol{w}\}$, where $\boldsymbol{\phi}$ is an encoder and \boldsymbol{w} is a linear classifier.

ANIL states that the encoder ϕ is not updated during the inner loop.



Assumption

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The ANIL Assumption empirically sounds.

	Mini-ImageNet 5way-1shot	Mini-ImageNet 5way-5shot	Omniglot 20way-1shot	Omniglot 20way-5shot
MAML	46.9±0.2	63.1±0.4	93.7±0.7	96.4±0.1
ANIL	46.7±0.4	61.5±0.5	96.2±0.5	98.0±0.3

Main Derivation Motivating example

Assumptions:

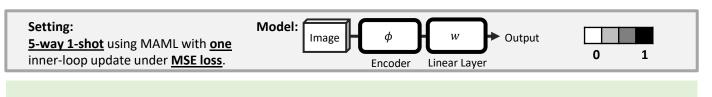
- ANIL.
- Linear classifier w is zeroed at the beginning.

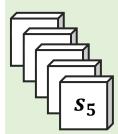
Loss: Mean square error.

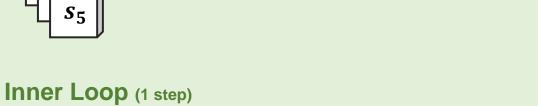
Condition: One inner loop update.

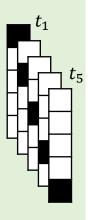
Setting

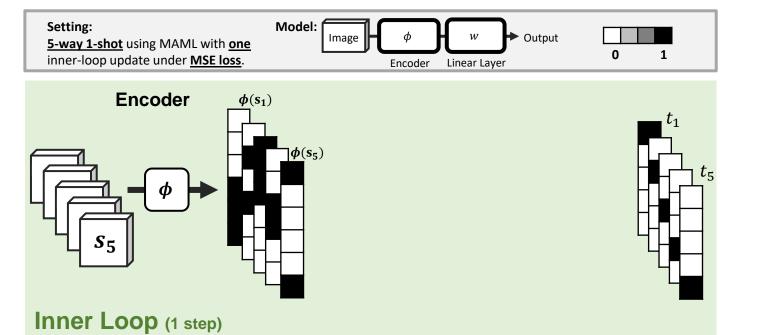
- 5-way: Each task contains 5 classes of images.
- 1-shot: Only one image per class in the support data.

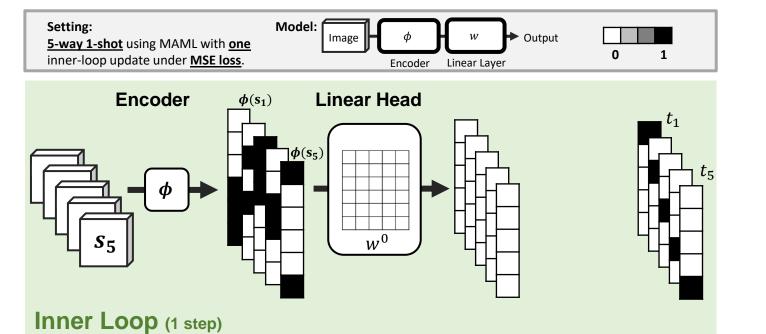


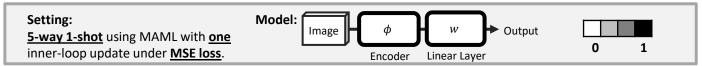


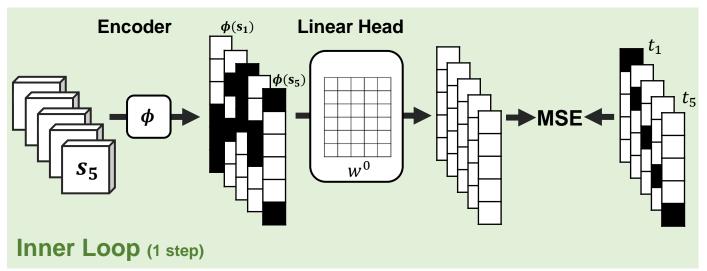


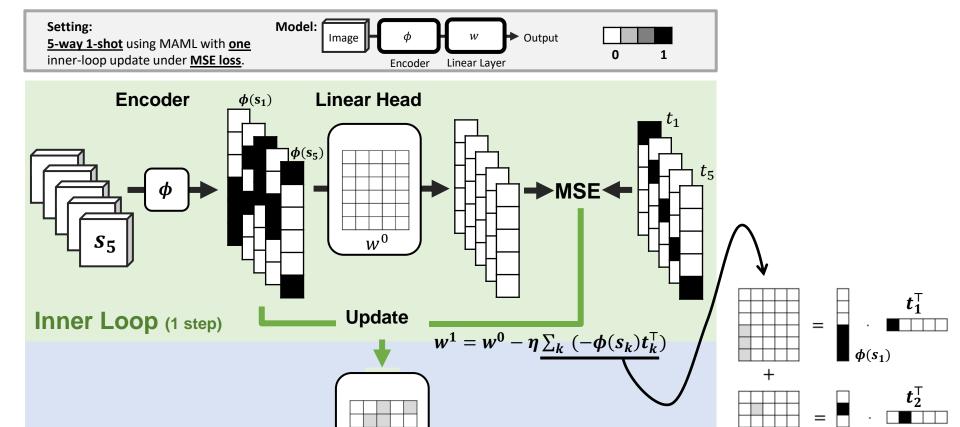






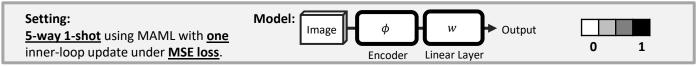


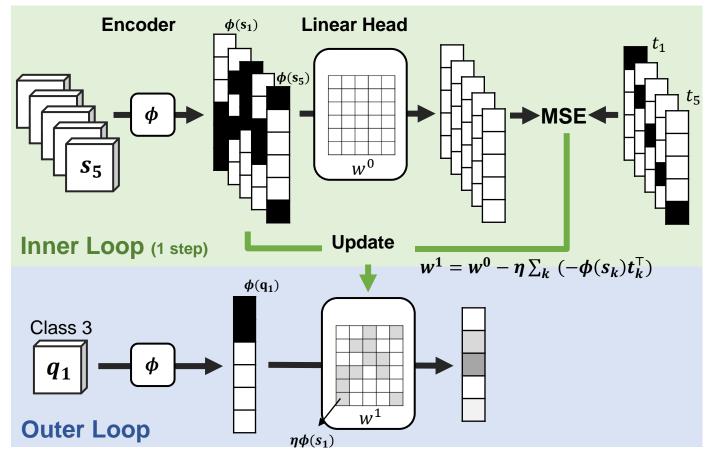


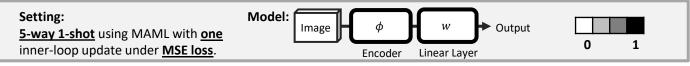


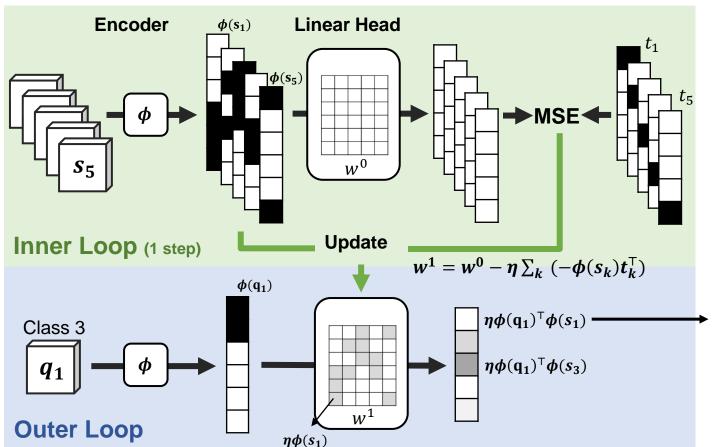
 $\eta \phi(s_1)$

 $\phi(s_2)$

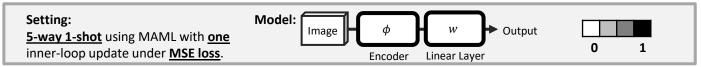


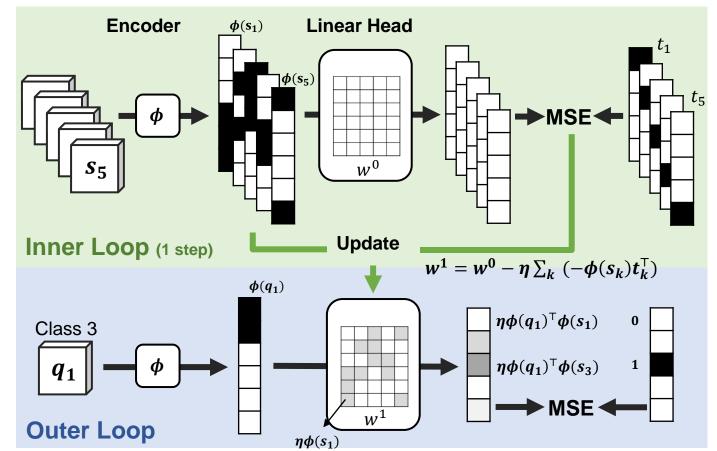


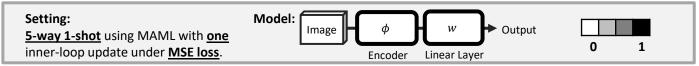


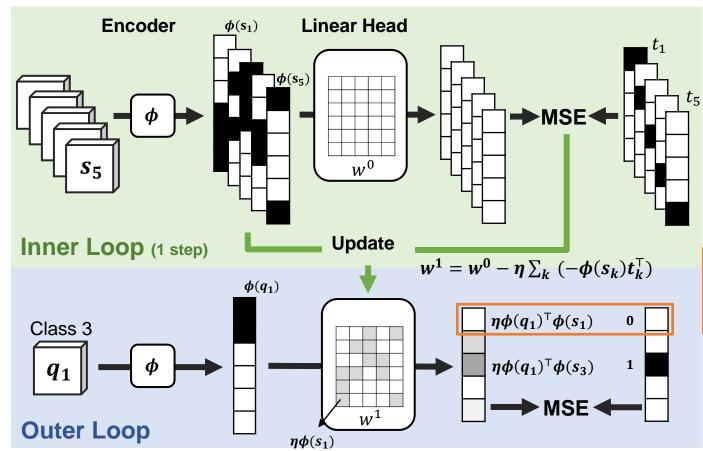


The inner product between support feature s_1 and query feature q_1 .



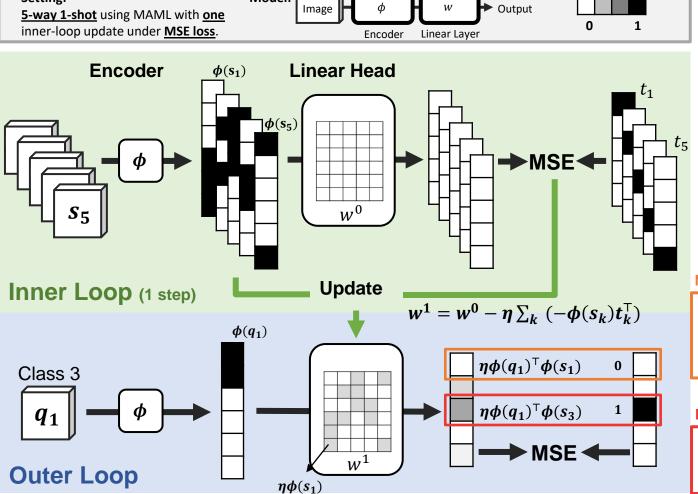






Negative sample

- q₁ and s₁ have different labels
- Their <u>inner product</u> of their features should <u>be zero</u>.



Model:

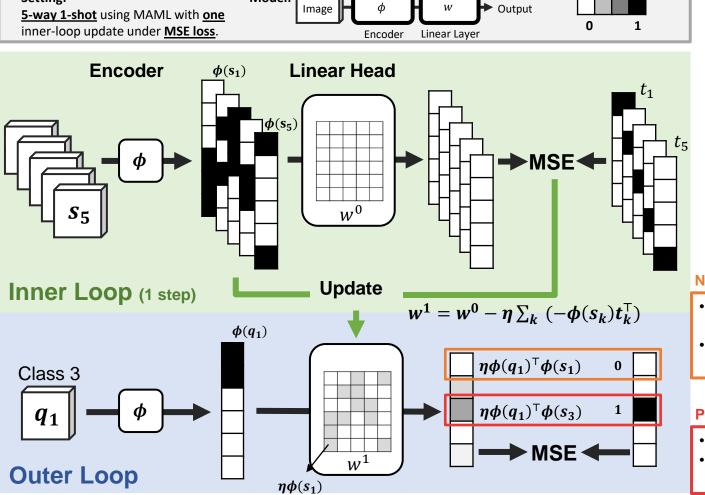
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Positive sample

- q_1 and s_3 have same labels,
 - Their <u>inner product</u> of their features should <u>be one</u>.



Model:

Setting:

Supervised contrastive learning



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Main Derivation Main result

Consider support data $S = \{(s, t)\}$ and one query data (q, u).

Under **ANIL assumption**, the **loss for the encoder** is :

First-order MAML:

$$L = \sum_{i=1}^{N_{class}} \underline{(\mathbf{q}_i - \mathbf{1}_{i=u}) \mathbf{w_i}^{\top}} \phi(q) + \eta \underbrace{\mathbf{E}}_{(s,t) \sim S} \left[-\sum_{i=1}^{N_{class}} \mathbf{q}_i \mathbf{s}_i + \mathbf{s}_u + \mathbf{q}_t - \mathbf{1}_{t=u} \right] \phi(s)^{\top} \phi(q)$$
stop gradient

- Meaning:
 - If q and s have sample label, then update ϕ s.t. $\phi(q)$ is closer to $\phi(s)$.
 - Otherwise, update ϕ s.t. $\phi(q)$ is closer to $\phi(s)$.

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stop gradient

Contractive coefficient

Contrastive coefficient

Inner product

- Expected effect of the second term:
 - If q and s have sample label, then update ϕ s.t. $\phi(q)$ is closer to $\phi(s)$.
 - Otherwise, update ϕ s.t. $\phi(q)$ is closer to $\phi(s)$.

Main result. Feature space illustration.

First-order MAML $\phi(s_1)$ $\phi(q)$ $\phi(s_3)$ $\phi(s_2)$

Gradient from positive sample Gradient from negative sample

update ϕ such that $\phi(q)$ is closer/further to $\phi(s)$

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Main Derivation Main result

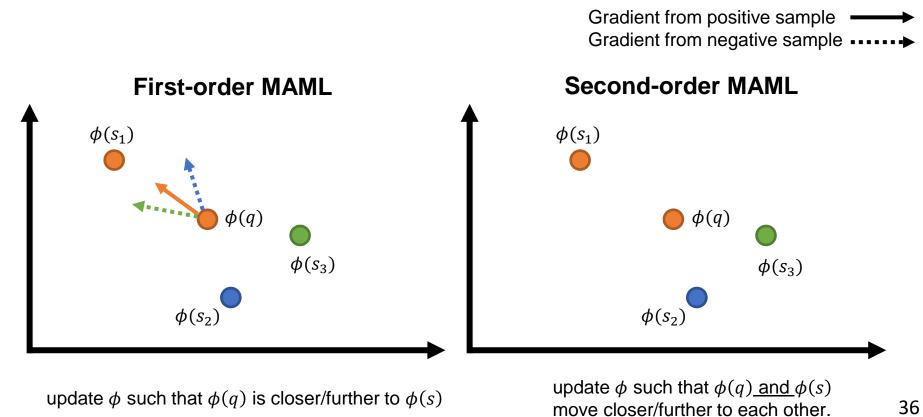
Consider support data $S = \{(s, t)\}$ and one query data (q, u).

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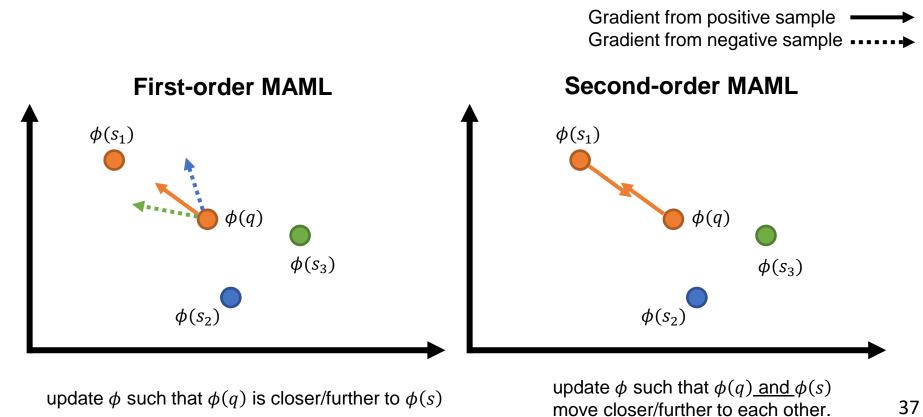
Second-order MAML:

- Expected effect of the second term:
 - If q and s have sample label, then update ϕ such that $\phi(q)$ and $\phi(s)$ move closer to each other.
 - Otherwise, update ϕ such that $\phi(q)$ and $\phi(s)$ move further to each other.

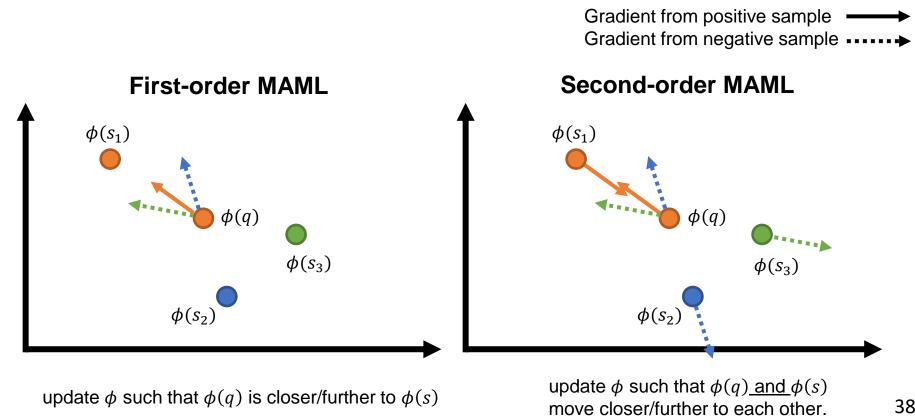
Main result. Feature space illustration.



Main result. Feature space illustration.



Main result. Feature space illustration.



Main Derivation Main result

Consider support data $S = \{(s, t)\}$ and one query data (q, u).

Under **ANIL assumption**, the **loss for the encoder** is :

First-order MAML:

$$L = \sum_{i=1}^{N_{class}} \underbrace{(\mathbf{q}_i - \mathbf{1}_{i=u}) \mathbf{w_i}^{\top}}_{\text{stop gradient}} \phi(q) + \eta \underbrace{\mathbf{E}}_{(s,t) \sim S} \left[-\sum_{i=1}^{N_{class}} \mathbf{q}_i \mathbf{s}_i + \mathbf{s}_u + \mathbf{q}_t - \mathbf{1}_{t=u} \right] \phi(s)^{\top} \phi(q)$$

- Random initialization
- Cross task interference

 The coefficient is not always positive when s and q come from different classes

Theorem 1 With the assumption of (a) no inner loop update of the encoder, FOMAML is a noisy SCL algorithm. With assumptions of (a) no inner loop update of the encoder and (b) a single inner-loop update, SOMAML is a noisy SCL algorithm.

Main result. Introducing the zeroing trick.

Consider support data $S = \{(s, t)\}$ and one query data (q, u).

Under **ANIL assumption** and **the zeroing trick**, the **loss for the encoder** is :

First-order MAML:

$$L = \eta \mathop{\mathbf{E}}_{(s,t)\sim S} \left(\mathbf{q}_t - \mathbf{t} = \mathbf{u} \right) \phi(s)^{\top} \phi(q)$$

Second-order MAML:

$$L = \eta \mathop{\mathbf{E}}_{(s,t)\sim S} \left(\mathbf{q}_t - \mathbf{1}_{t=u} \right) \phi(s)^{\top} \phi(q)$$

Corollary 1 With mild assumptions of (a) no inner loop update of the encoder, (b) a single inner-loop update and (c) training with the zeroing trick (i.e., the linear layer is zeroed at the end of each outer loop), both FOMAML and SOMAML are SCL algorithms.

Main result. Introducing the zeroing trick.

Algorithm 1 Second-order MAML	Algorithm 2 Second-order MAML with zeroing trick		
1: while not done do	1: while not done do		
2: Sample tasks $\{T_1, T_2\}$	2: Sample tasks $\{T_1, T_2\}$		
3:	3: $w = 0$		
4: for $n = 1, 2$ do	4: for $n = 1, 2$ do		
5: $\{S_n, Q_n\} \leftarrow \text{sample from } T_n$	5: $\{S_n, Q_n\} \leftarrow \text{sample from } T_n$		
6: $\theta_n = \theta$	6: $\theta_n = \theta$		
7: for $i = 1, 2,, N_{step}$ do	7: for $i = 1, 2,, N_{step}$ do		
8: $\theta_n \leftarrow \theta_n - \eta \nabla_{\theta_n} L(\theta_n, S_n)$	8: $\theta_n \leftarrow \theta_n - \eta \nabla_{\theta_n} L(\theta_n, S_n)$		
9: end for	9: end for		
10: end for	10: end for		
11: Update $\theta \leftarrow \theta - \rho \sum_{n=1}^{N_{batch}} \nabla_{\theta} L(\theta_n, Q_n)$	11: Update $\theta \leftarrow \theta - \rho \sum_{n=1}^{N_{batch}} \nabla_{\theta} L(\theta_n, Q_n)$		
12:	12: $w = 0$		
13: end while	13: end while		

Results

Using the zeroing trick improves performance.

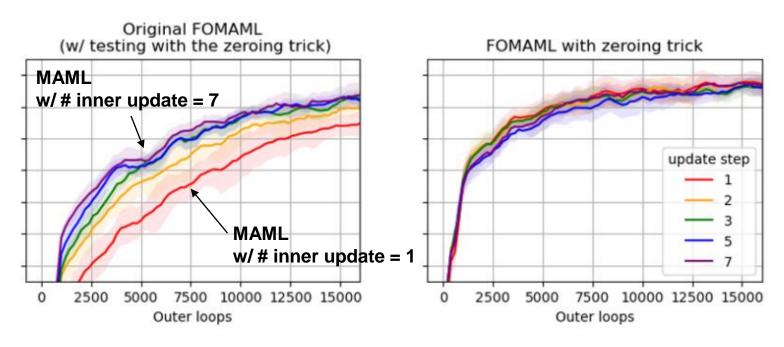
Setting: MiniImageNet.



Results

With zeroing trick, # of inner loop steps no longer matters

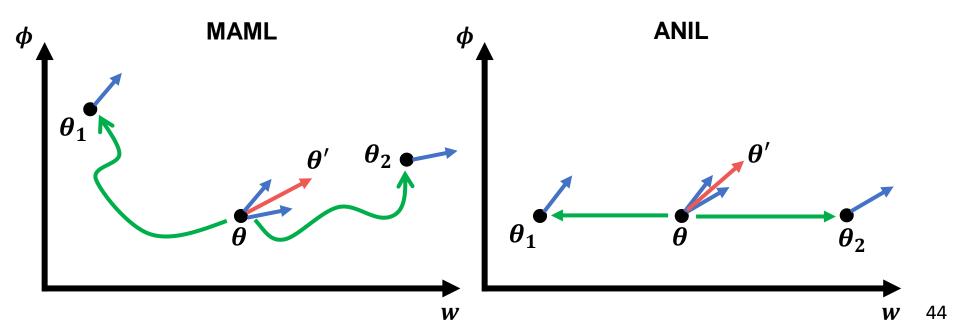
Setting: MiniImageNet 5-way 1-shot.



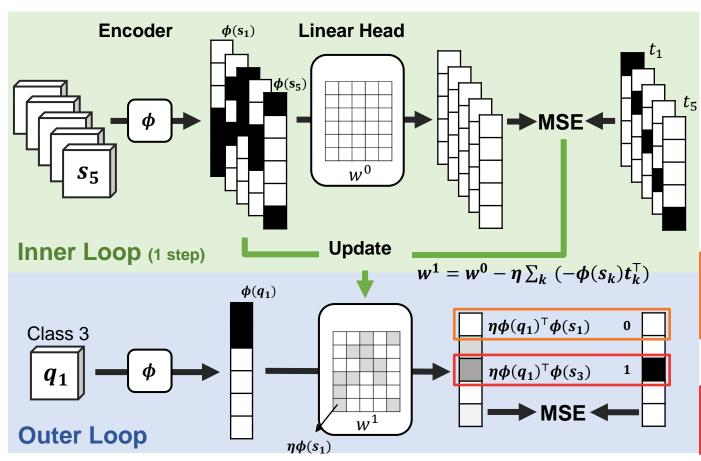
Wrap up

We use the ANIL assumption for derivation.

Consider a model $\theta = \{\phi, w\}$, where ϕ is an encoder and w is a linear classifier. ANIL states that the encoder ϕ is not updated during the inner loop.



Wrap up



Supervised contrastive learning



Negative sample

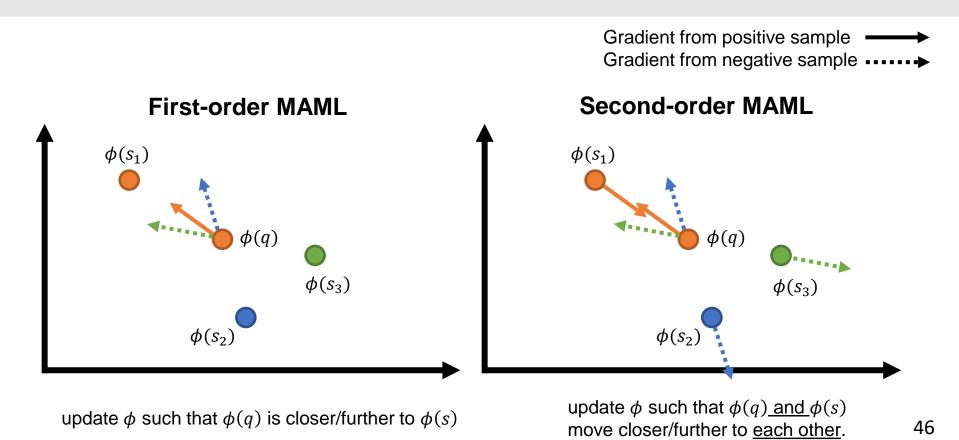
- q₁ and s₁ have different labels
- Their <u>inner product</u> of their features should <u>be zero</u>.

Positive sample

- q_1 and s_3 have same labels,
 - Their <u>inner product</u> of their features should <u>be one</u>.

Wrap up

We show how FOMAML different from SOMAML.



Wrap up We show that the zeroing trick improves MAML.

Setting: MiniImageNet.

