**Aryan Mishra**

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**EDUCATION**

**University of Maryland** College Park, Maryland

*Master of Engineering – Robotics Expected: May 2025*

**Vellore Institute of Technology** Vellore, India

*Bachelor of Technology – Electronics and Communication Engineering*  *June 2023*

**RESEARCH AND WORK EXPERIENCE**

**National Institute of Technology and Standards** - *Gaithersburg, MD* November 2024 - Present

**Generative AI Software Developer**

Professional Research and Experience Program student from UMD, part of Retrieval Group, Information Technology Laboratory

* Developing pipeline for testing of multi-modal inputs as authentic or fabricated.
* Generated images using diffusion and style GAN models, fine-tuned Flux models using LoRa.
* Deployed anti-spoof, vision transformer classifier, spatial based image for facial detection, recognition and verification on image and video inputs.

**Department of Statistics, Uni of MD**- *College Park, MD* August 2024 - Present

**Machine Learning Researcher**

Worked as a volunteer on Geometric Deep learning, currently took it as an independent study for Spring 2025 semester.

* Independent research on geometric deep learning for graphs, grids and data manifolds.
* Working on understanding and devising novel methods to harness the power of expressiveness in graph neural networks.

**Department of Mechanical Engineering** – *College Park, MD* January 2024 – December 2024

**Machine Learning Research Volunteer**

Part of two projects: Development of a soft robotic gripper, Medical Image analysis

* Developed soft robotic grippers by 3D-printed bases, based on the gripping action force, deployed machine learning models to predict object size, shape, and material from

Pressure-Volume curves.

* Deployed VNET with Attention Mechanism on the Stanford Type B Aorta Dissection dataset, achieving a Dice Coefficient of 0.80, Jaccard Mean of 76.3, AsD Mean of 0.98.
* Developed a transformer-based encoder for the VNET architecture.

**PROJECTS**

**Autonomous Scene Segmentation** September 2024 – December 2024

*PyTorch, Swin Transformer, Trans-UNET, Python*

* Devised and trained from scratch Trans-UNET, Swin-Trans-UNET and UNET. Performed pixel-wise segmentation of KITTI Images
* Achieved Dice coefficients of 0.88, 0.80, and 0.87 for three segmentation models, with the Swin Transformer-UNET architecture demonstrating superior performance and attained the lowest cross-entropy loss of 0.27 among the compared approaches.

**Vision Language Model** August 2024 – December 2024

*PyTorch, SigLip, Python, Google-Gemma, OpenCV*

* Combined 400M SigLIP and 2B Gemma Models into a sub-3B VLM works for VQA, QA tasks and referring segmentation.

**Multimodel Trajectory Prediction** July 2024 – August 2024

*PyTorch, Python, OpenCV*

* Addressing the uncertainties faced by self-driving vehicles with a Multiple Trajectory Prediction (MTP) model by predicting multiple possible paths and the likelihood of each using probability adhering to geometric and angular meaning using the NuScenes Dataset.

**Retrieval Augmented Generation**  June 2024 – July 2024

*PyTorch, RAG, Python*

* Implemented a Retrieval Augmented Generation (RAG) pipeline using the Gemma-2-9b-it LLM model. Achieved high efficiency for real-time query answering, optimizing for scalable performance and reduced latency.

**Generative Adversarial Networks**  June 2024

*PyTorch, OpenCV, PIL, Python*

* Successfully deployed multiple GAN models, including Deep Convolution GAN, Cycle GAN, and Progressive GAN, on diverse datasets such as MNIST, Celeb A, and the Summer to Winter Yosemite dataset.

**TECHNICAL SKILLS**

* **Languages:** Python, C++, MATLAB, RUST
* **Frameworks:** TensorFlow, PyTorch, Keras, CUDA, OpenAI Gym, OpenCV, Jax, LORA, Hugging Face, Flux
* **Software/Tools:** AWS, ROS1/2, C-Make, Gazebo, Linux, Git/GitHub, Docker, Robot Perception, Localization, Deep Learning, Computer Vision, Artificial Intelligence, Microsoft Suite, Content Writing