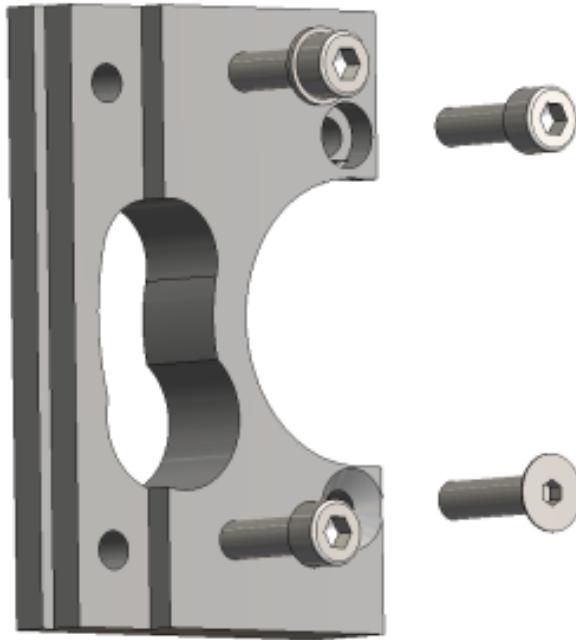


AS-35036 (Casa del cojinete del sensor)



Retire AS-35036 (carcasa del cojinete del sensor)

Herramientas necesarias:

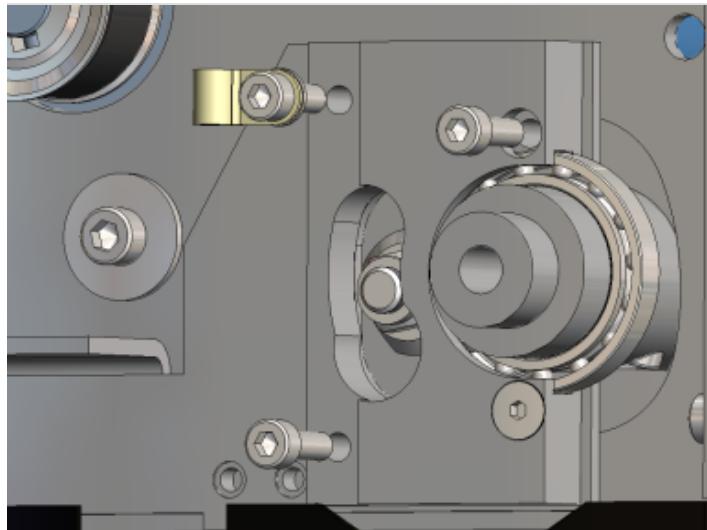
- Llave hexagonal - 3 mm
- Llave hexagonal - 4 mm
- Llave hexagonal - 5mm
- Tirador
- Llave inglesa - 13 mm
- Llave inglesa - 24 mm

Preparación:

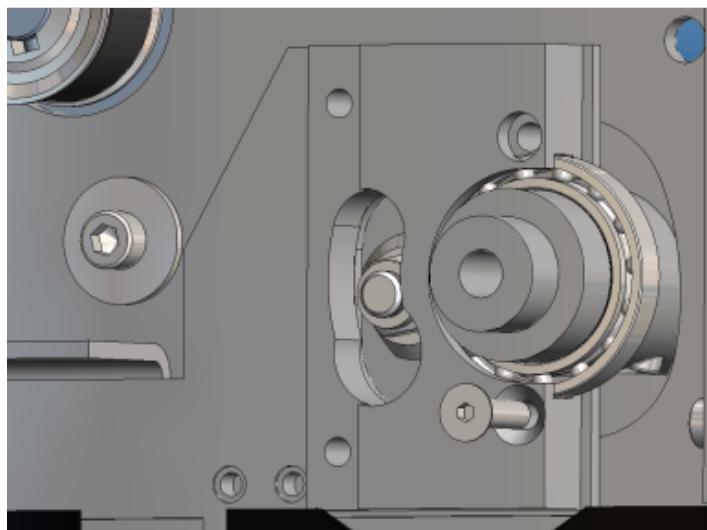
- Retire AS-35021 (Anverso de la hoja)[as-35021-r5--as-35945-r5---sheet-front-.html#UUID-31b10256-172a-aa77-27f3-70611fd2f729_UUID-e830e1e1-7335-76b1-3edd-915246c7f0c6]
- Retire AS-35019 (Rueda y llanta)[as-35019-wheel-and-rim-assembly-.html#UUID-a57833bb-bb28-b866-5f4a-0632c426f81b_UUID-d9642700-dc5e-64e3-0090-478497c3e47d]
- Retire AS-35219 (correa 1420)[as-35219-belt-1420-.html#UUID-31ceec0b-5465-c73b-7e39-8964b2c47ae7_UUID-339ccecc-65fe-63d6-2142-0ddf42794ce5]
- Retire AS-35035 (Perno de rueda)[as-35035-wheel-stud-.html#UUID-b260c4a1-8d3f-1628-b40d-a38a1289085b_UUID-1049aa8c-92cc-e7d2-6296-99b7ff149fbc]
- Retire AS-35041 (Rueda de polea Y)[as-35041-pulley-wheel-y-.html#UUID-74ea0711-cff4-2cc9-0fea-39155555f7dd_UUID-19d39f1e-bf7f-5fcc-414a-77c5d633c34e]

Procedimiento:

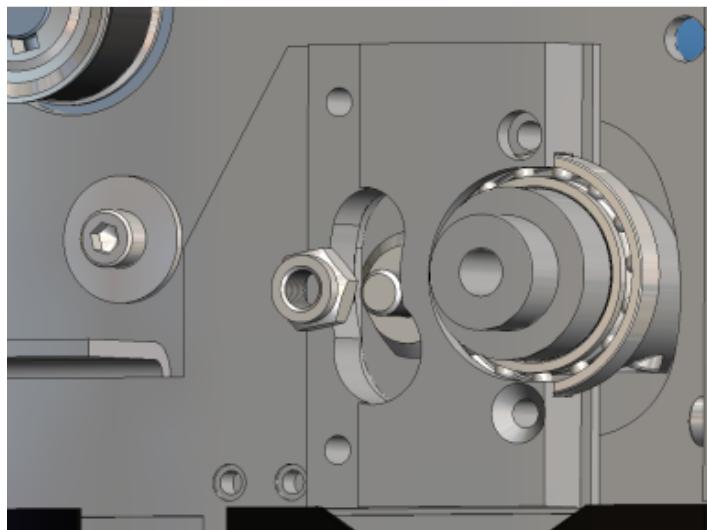
-
1. Desatornille los tres tornillos hexagonales m5x16mm (llave hexagonal de 4 mm)



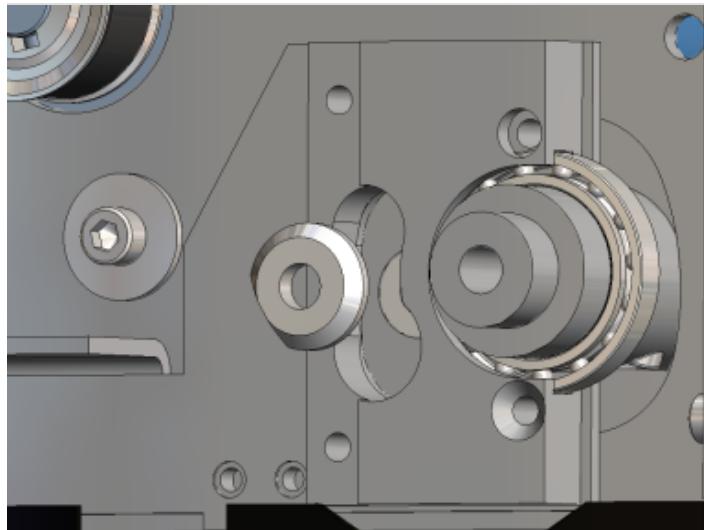
2. Desatornille el tornillo hexagonal m5x20mm (llave hexagonal de 3mm)



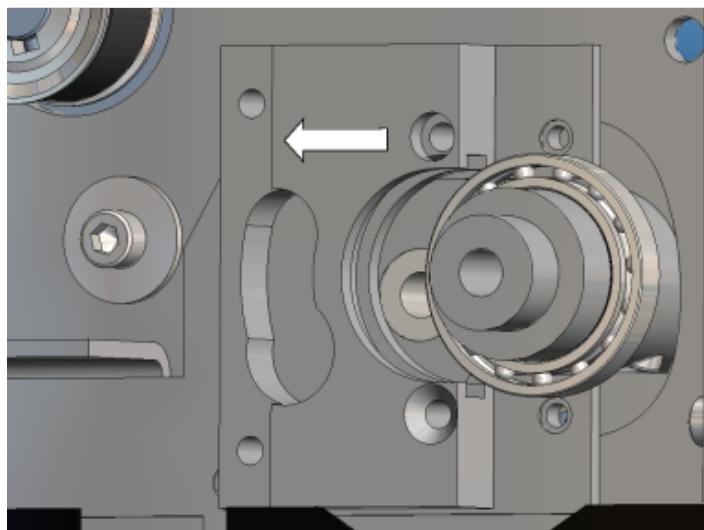
3. En el lado izquierdo del robot, desatornille el tornillo hexagonal m8x30mm (llave hexagonal de 5mm) con arandela y tuerca m8 (llave de 13mm) dentro del Robot.



-
4. Retire el tornillo, la tuerca y la arandela.



-
5. Empuje la carcasa del cojinete del sensor de rodamientos hacia el centro del robot para extraerlo.



Instalar AS-35036 (Casa del cojinete del sensor)

Herramientas necesarias:

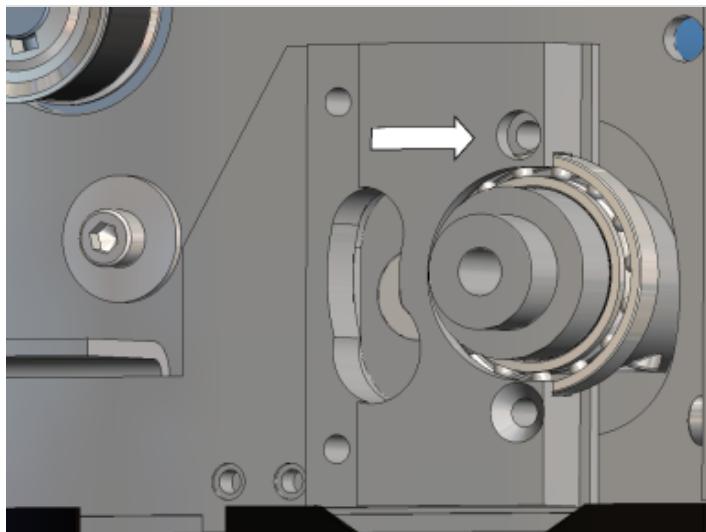
- Llave hexagonal - 3 mm
- Llave hexagonal - 4 mm
- Llave hexagonal - 5mm
- Llave inglesa - 13 mm
- Llave inglesa - 24 mm

Procedimiento:

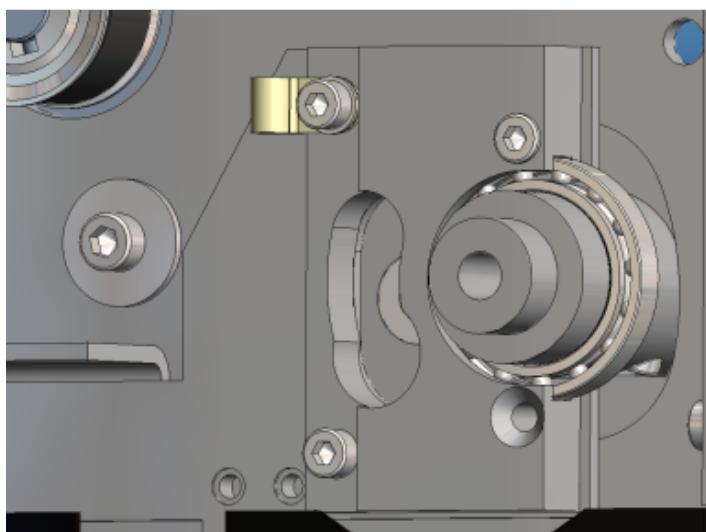
A Advertencia

El tornillo hexagonal de 3 mm SIEMPRE debe estar en el orificio marcado en la carcasa del cojinete del sensor. Esto es para garantizar que la carcasa del cojinete del sensor tenga suficiente presión contra el rodamiento.

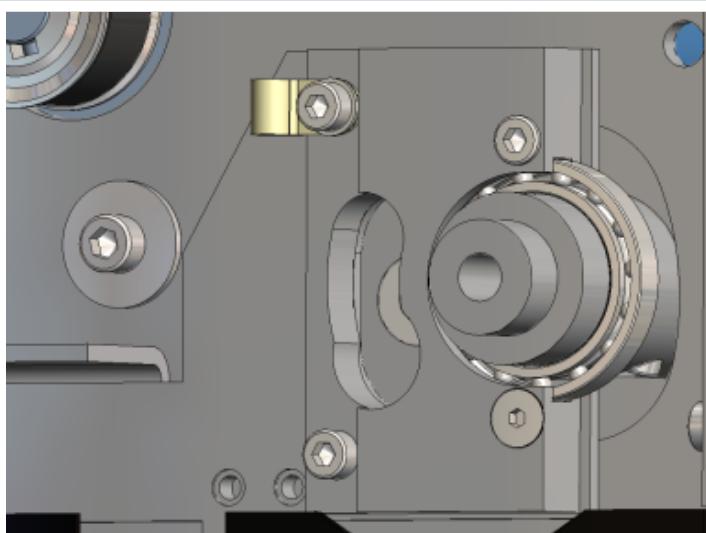
-
1. Empuje la carcasa del cojinete del sensor contra el cojinete desde el centro del robot y hacia afuera.



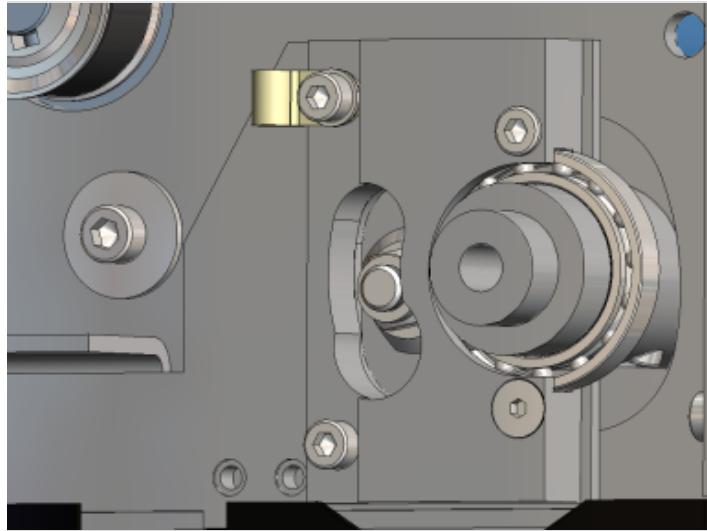
2. Tighten the three m5x16mm hex socket screw (4mm hex key)



3. Tighten the m5x20mm hex socket screw (3mm hex key)



-
4. On the left side of the Robot. Mount the m8x30mm hex socket screw (5mm hex key) with washer and m8 nut (13mm wrench)



Completion:

- Install AS-35041 (Pulley wheel Y)[as-35041-pulley-wheel-y-.html#UUID-74ea0711-cff4-2cc9-0fea-39155555f7dd_UUID-c9e390f1-e7b8-a421-c12a-394a6f17834c]
- Install AS-35035 (Wheel stud)[as-35035-wheel-stud-.html#UUID-b260c4a1-8d3f-1628-b40d-a38a1289085b_UUID-b8c27156-0d8e-e661-b288-d6e5fc263ea5]
- Install AS-35219 (Belt 1420)[as-35219-belt-1420-.html#UUID-31ceec0b-5465-c73b-7e39-8964b2c47ae7_UUID-9f5f97cb-af94-3f75-0459-70a54949495e]
- Tighten AS-35219 (Belt 1420)[as-35219-belt-1420-.html#UUID-31ceec0b-5465-c73b-7e39-8964b2c47ae7_UUID-756c22c4-4f07-7c62-ed8d-6ebe1a1d8a51]
- Install AS-35019 (Wheel and rim)[as-35019-wheel-and-rim-assembly-.html#UUID-a57833bb-bb28-b866-5f4a-0632c426f81b_UUID-4b8e5716-7388-69a7-63a2-ed49da768e56]
- Install AS-35021 (Sheet front)[as-35021-r5---as-35945-r5---sheet-front-.html#UUID-31b10256-172a-aa77-27f3-70611fd2f729_UUID-9b92d4e7-aba2-2c22-3c5d-0a94f0ac7d0a]