

Ecoflex: $400 \text{ mL} = 1 \text{ lb}$

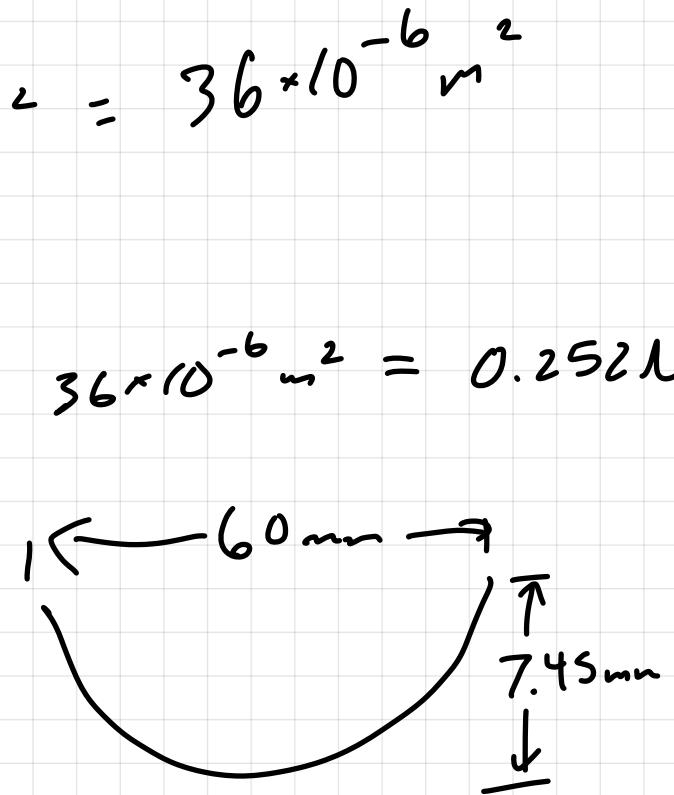
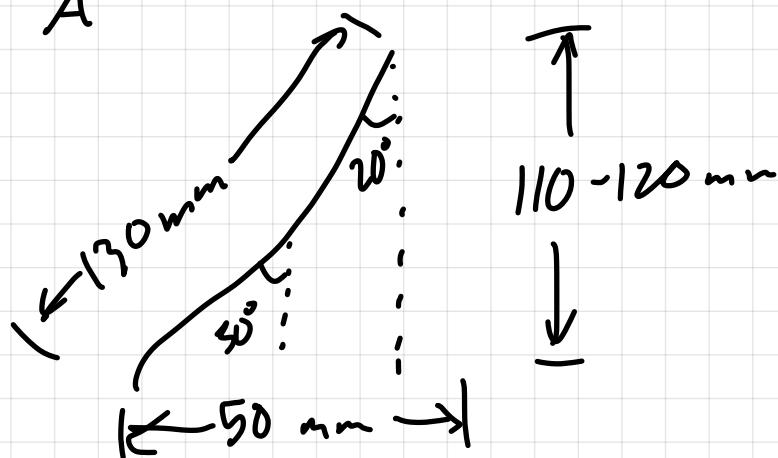
Required size for sensor: $6 \times 6 \times 6 \text{ mm}^3 = 0.216 \text{ mL}$

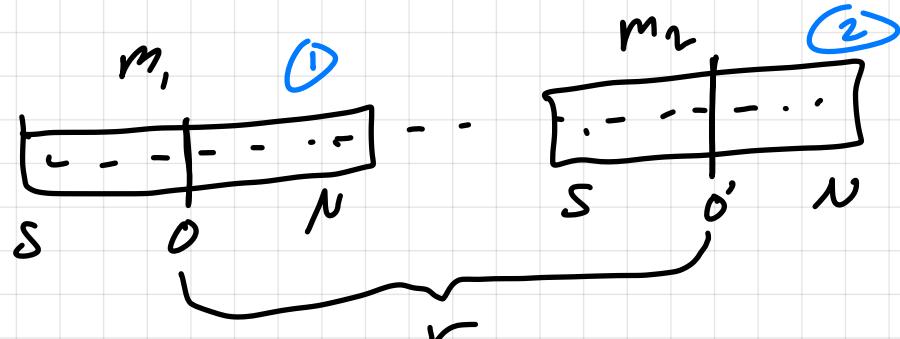
$$\frac{\$42.99}{2 \text{ lbs}} \cdot \frac{1 \text{ lb}}{400 \text{ mL}} \cdot \frac{0.216 \text{ mL}}{1 \text{ sensor}} = \$0.012$$

$$7 \text{ kPa} = 7 \frac{\text{kN}}{\text{m}^2}$$

$$A = 36 \text{ mm}^2 = 36 \times 0.001^2 \text{ m}^2 = 36 \times 10^{-6} \text{ m}^2$$

$$P = \frac{F}{A} \rightarrow F = P \cdot A = 7 \frac{\text{kN}}{\text{m}^2} \cdot 36 \times 10^{-6} \text{ m}^2 = 0.252 \text{ N}$$



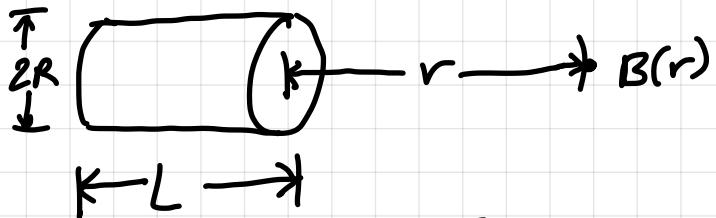


$$\tau = m\beta \sin \theta$$

$$U = -m\beta \cos \theta$$

$$F = -\frac{dU}{dr}$$

$$B_1 = \frac{\mu_0}{4\pi} \cdot \frac{2m_1}{r^3} \quad (\text{From South to North of } ①)$$



$$B(r) = \frac{B_{\text{residual}}}{2} \left[\frac{L+r}{\sqrt{R^2 + (L+r)^2}} - \frac{r}{\sqrt{R^2 + r^2}} \right]$$

$$U_1 = -m_1 B_1 \cos\theta, \quad \theta = \phi^\circ$$

$$U_2 = -m_2 B_2 = -\frac{m_2 B_{res}}{2} \left[\frac{L+r}{\sqrt{R^2 + (L+r)^2}} - \frac{r}{\sqrt{R^2 + r^2}} \right]$$

$$F_2 = -\frac{dU_2}{dr} = -\frac{d}{dr} \left[\frac{m_2 B_{res}}{2} \left(\frac{L+r}{\sqrt{R^2 + (L+r)^2}} - \frac{r}{\sqrt{R^2 + r^2}} \right) \right]$$

$$\frac{-m_2 B_{res}}{2} \frac{d}{dr} \left[\frac{L+r}{\sqrt{R^2 + (L+r)^2}} \right] = \frac{\left(\sqrt{R^2 + (L+r)^2} \right) (1) - (L+r) \frac{d}{dr} \left[\sqrt{R^2 + (L+r)^2} \right]}{R^2 + (L+r)^2}$$

$$= \frac{\sqrt{R^2 + (L+r)^2} - (L+r) \frac{L+r}{\sqrt{R^2 + (L+r)^2}}}{R^2 + (L+r)^2}$$

$$\frac{d}{dr} \left[\frac{r}{\sqrt{R^2+r^2}} \right] = - \left(\frac{\sqrt{R^2+r^2} - r \left(\frac{L+r}{R^2+(L+r)^2} \right)}{R^2+r^2} \right)$$

$$F_2 = -\frac{dU_2}{dr} = -\frac{m_2 \beta_{\text{res}}}{2} \left(\frac{\sqrt{R^2+(L+r)^2} - (L+r) \sqrt{\frac{L+r}{R^2+(L+r)^2}} + \frac{rL+r^2}{R^2+(L+r)^2} - \sqrt{R^2+r^2}}{R^2+(L+r)^2} \right)$$

$$F(r) = \frac{-0.65r^2 m_2}{\sqrt{(256+r^2)^3}} + \frac{0.65 m_2}{\sqrt{256+r^2}} + \frac{2.6 m_2}{\sqrt{(256+(2+r)^2)^3}} + \frac{2.6r m_2}{\sqrt{(256+(2+r)^2)^2}}$$

$$+ \frac{0.65r^2 m_2}{\sqrt{(256+(2+r^2)^2)^3}} - \frac{0.65 m_2}{\sqrt{256+(2+r)^2}}$$

$$F(r) = \frac{-0.65r^2 m_2}{\sqrt{(256+r^2)^3}} + \frac{0.65 m_2}{\sqrt{256+r^2}} + \frac{2.6 m_2}{\sqrt{(256+(2+r)^2)^3}} + \frac{2.6r m_2}{\sqrt{(256+(2+r)^2)^2}} + \frac{0.65r^2 m_2}{\sqrt{(256+(2+r^2)^2)^3}} - \frac{0.65 m_2}{\sqrt{256+(2+r)^2}}$$

$$m_2 = 5.5 \text{ g/cm}^3 \cdot \frac{1 \text{ cm}^3}{10^3 \text{ mm}^3} \cdot \pi \left(\frac{5}{2}\right)^2 \cdot 2 \text{ mm}^3 = 0.21 \text{ g}$$

To log Arduino::Serial.print to .txt:

1) cd into directory of desired .txt path

2) script -a -t0 filename.txt

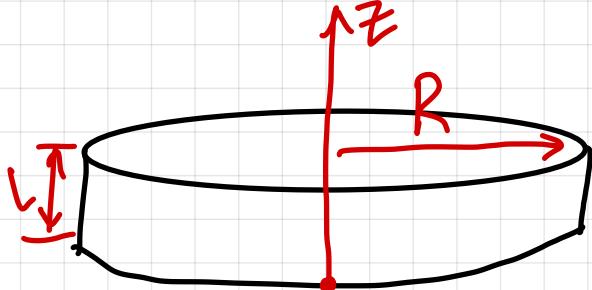
3) screen /dev/cu.usbmodem11301 115200
baud rate
serial port of Arduino

To stop logging:

1) **ctrl+A** then **ctrl+K**

2) **ctrl+D**

$$B(z) = \frac{M_0 N}{2} \left(\frac{z}{\sqrt{z^2 + R^2}} - \frac{z - L}{\sqrt{(z-L)^2 + R^2}} \right)$$



$$T = \frac{N}{A \cdot m}$$

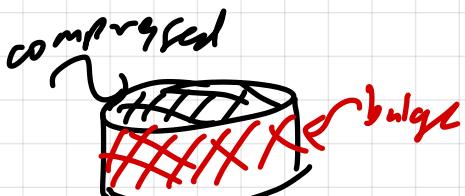
$$M_0 = \frac{N}{A^2}$$

$$\left[\frac{N}{A^2} \right] [m] = \left[\frac{N}{A \cdot m} \right]$$

$$[M] = \frac{A}{m}$$

$$B(z) = d \left(\frac{z}{\sqrt{z^2 + S_{mm}^2}} - \frac{z - 2mm}{\sqrt{(z-2mm)^2 + S_{mm}^2}} \right)$$

$$\Delta = \frac{\rho}{\gamma(1+2f^2)} = \frac{mg}{\gamma(1+2f^2)} = \frac{mg}{\gamma A(1+2f^2)}$$



$$f = \frac{\gamma R^2}{2\pi RL} = \frac{2S\gamma mm^2}{20\pi\gamma mm^2} = \frac{S}{4} = 1.15$$

$$z = z_i - \Delta z_i - t_m$$

% of
original
thickness

$$z = \tilde{v}_e \left(1 - \frac{\beta_m}{\pi R_c^2} \right) - \tilde{v}_m$$

$$B_z = d \left(\frac{z + \tilde{v}_m}{\sqrt{(z + \tilde{v}_m)^2 + R_m^2}} - \frac{z}{\sqrt{z^2 + R_m^2}} \right)$$

$$B_z = d \left(\frac{\tilde{v}_e \left(1 - \frac{\beta_m}{\pi R_c^2} \right) - \tilde{v}_m + \tilde{v}_m}{\sqrt{\left(\tilde{v}_e \left(1 - \frac{\beta_m}{\pi R_c^2} \right) - \tilde{v}_m + \tilde{v}_m \right)^2 + R_m^2}} - \frac{\tilde{v}_e \left(1 - \frac{\beta_m}{\pi R_c^2} \right) - \tilde{v}_m}{\sqrt{\left(\tilde{v}_e \left(1 - \frac{\beta_m}{\pi R_c^2} \right) - \tilde{v}_m \right)^2 + R_m^2}} \right)$$

$$B_z = \frac{d \tilde{v}_e \left(1 - \frac{\beta_m}{\pi R_c^2} \right)}{\sqrt{\left(\tilde{v}_e \left(1 - \frac{\beta_m}{\pi R_c^2} \right) \right)^2 + R_m^2}} - \frac{d \tilde{v}_e \left(1 - \frac{\beta_m}{\pi R_c^2} \right) - d \tilde{v}_m}{\sqrt{\left(\tilde{v}_e \left(1 - \frac{\beta_m}{\pi R_c^2} \right) - \tilde{v}_m \right)^2 + R_m^2}}$$

$$B_Z = \frac{\frac{d\tau_e - d\tau_e \frac{\beta}{\pi R_e^2} M}{-}}{\sqrt{\tau_c^2 - 2\tau_e^2 \frac{\beta M}{\pi R_e^2} + \tau_e^2 \frac{\beta^2 M^2}{\pi^2 R_e^4} + R_m^2} - \frac{d\tau_e + d\frac{\tau_e \beta M}{\pi R_e^2} - d\tau_m}{\sqrt{\tau_c^2 \frac{\beta^2 M^2}{\pi^2 R_e^4} + 2\tau_c \tau_m \frac{\beta M}{\pi R_e^2} + \tau_m^2 - 2\tau_c \tau_m - \tau_e^2 \frac{\beta M}{\pi R_e^2} + R_m^2}}}$$

$$\left(\tau_c - \tau_e \frac{\beta M}{\pi R_e^2}\right) \left(\tau_c - \tau_e \frac{\beta M}{\pi R_e^2}\right) = \tau_c^2 - 2\tau_e^2 \frac{\beta M}{\pi R_e^2} + \tau_e^2 \frac{\beta^2 M^2}{\pi^2 R_e^4}$$

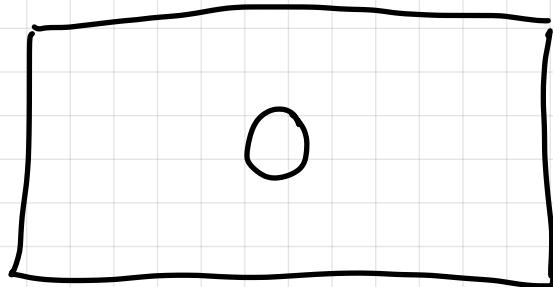
$$\begin{aligned} & \left(\tau_c - \tau_e \frac{\beta M}{\pi R_e^2} - \tau_m\right) \left(\tau_c - \tau_e \frac{\beta M}{\pi R_e^2} - \tau_m\right) \\ &= \cancel{\tau_c^2} - \tau_e^2 \frac{\beta M}{\pi R_e^2} - \underline{\tau_e \tau_m} - \cancel{\tau_e^2} + \tau_e^2 \frac{\beta^2 M^2}{\pi^2 R_e^4} + \underline{\tau_e \tau_m \frac{\beta M}{\pi R_e^2}} - \cancel{\tau_e \tau_m} + \cancel{\tau_e \tau_m \frac{\beta M}{\pi R_e^2}} + \tau_m^2 = \tau_c^2 \frac{\beta^2 M^2}{\pi^2 R_e^4} + 2\tau_c \tau_m \frac{\beta M}{\pi R_e^2} + \tau_m^2 - 2\tau_c \tau_m - \tau_e^2 \frac{\beta M}{\pi R_e^2} \end{aligned}$$

Time (s)	Mass (g)
38	1.07
68	2.46
109	3.93
135	6.73
158	8.46
185	12.75
209	14.17
227	15.95
261	16.96

Experimental Design:

3D data points →

1kg @ 10s/sample = 0.5g/sample for 5 minutes



$$\begin{aligned} 1 \text{ kg/L} \\ = \\ 1 \text{ g/mL} = 1 \text{ g/cc} \end{aligned}$$

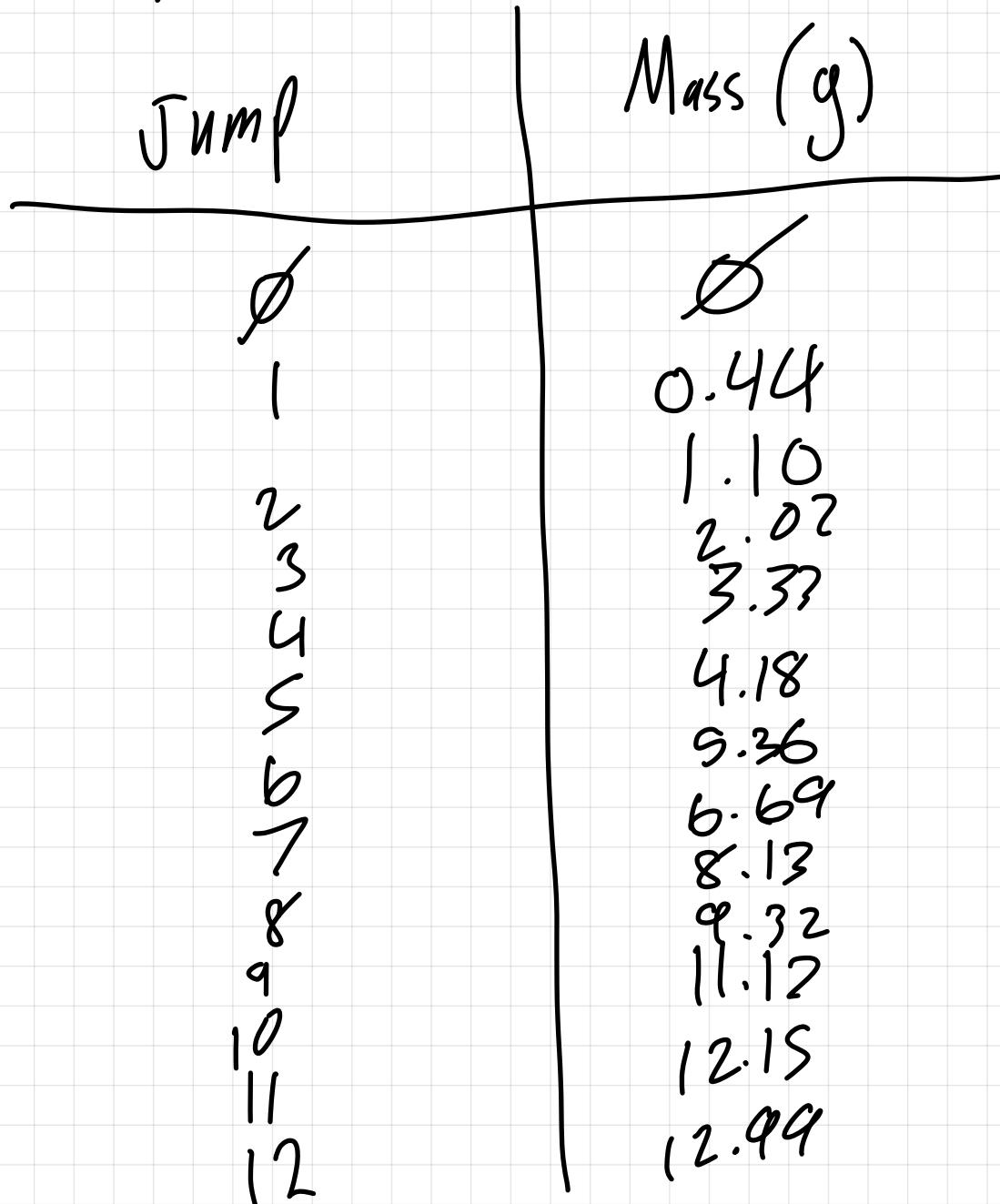
$$50 \text{ cm}^3 = 50 \times 10^3 = 50,000 \text{ mm}^3$$

$$50 \times 50 \times ? = 50,000 \text{ mm}^3$$

2500

$$\sqrt[3]{50,000} = 20$$

Test #2:



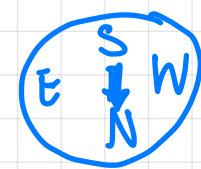
Test 3

Sample	Mass (g)
1	0.8
2	0.90
3	1.96
4	2.92
5	3.79
6	4.75
7	5.80
8	6.73
9	7.61
10	8.58
11	9.56
12	10.58
13	11.54
14	12.49
15	13.55

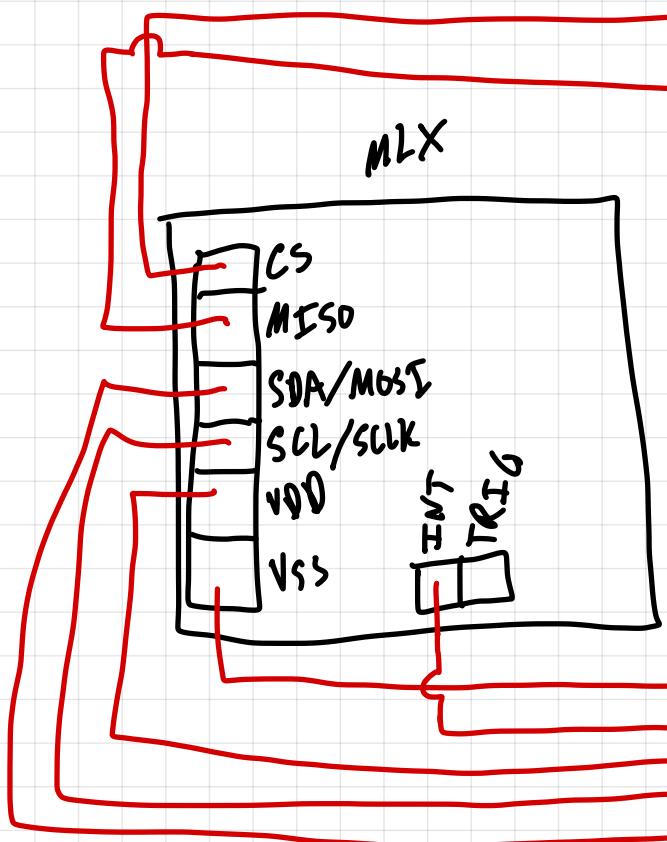
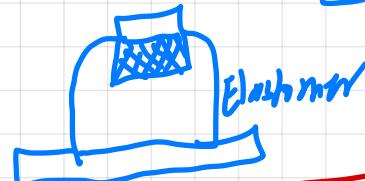
Sample	Mass (g)
16	14.56
17	15.68
18	16.84
19	
20	
21	
22	
23	
24	
25	
26	
27	
28	
29	
30	

Connections

MLX	Arduino Uno
SDA	D6/A4/D11
SCL	D7/A5/D13
(DROY) INT	D9
VDD	3.3V
VSS	GND
CS	D10
MISO	D12

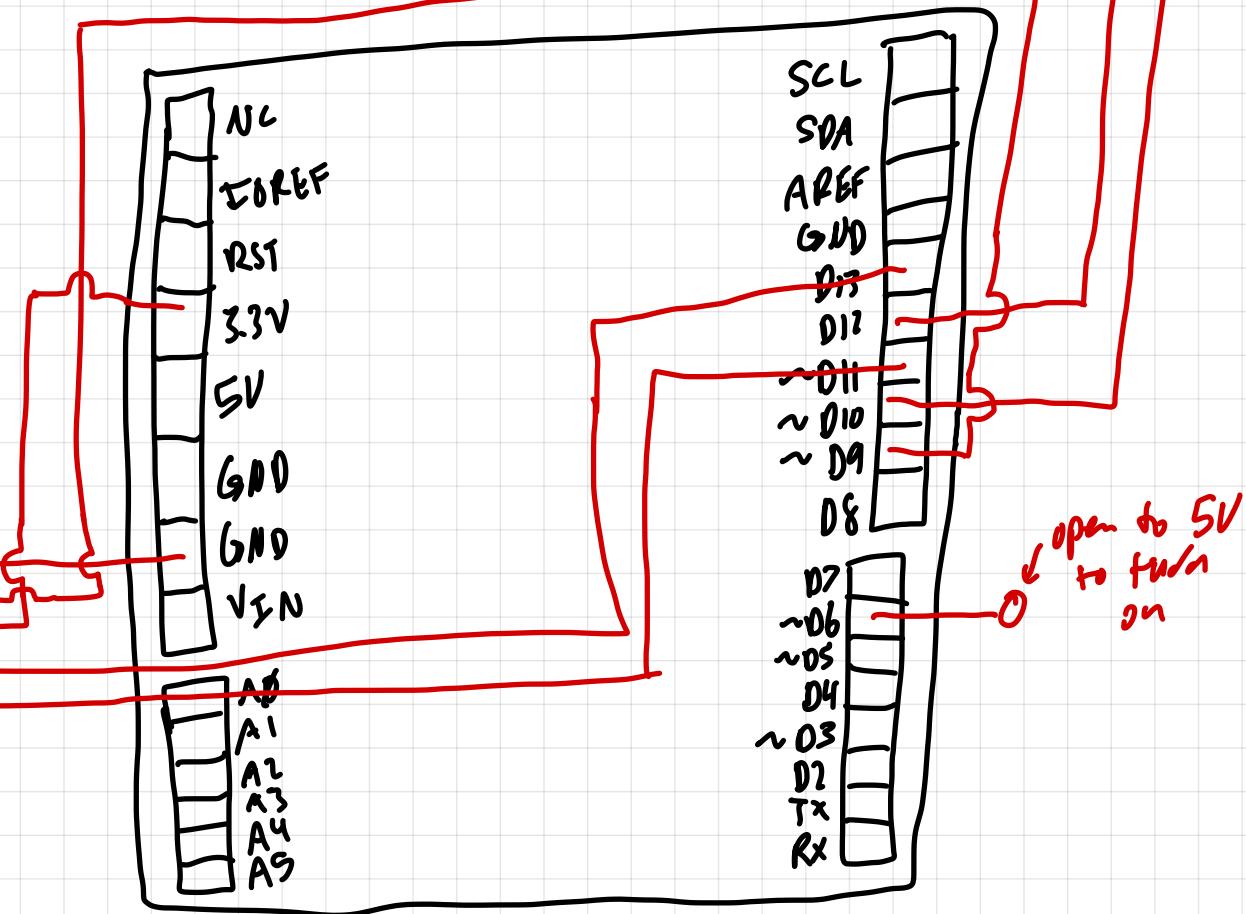


→ This side to sensor!



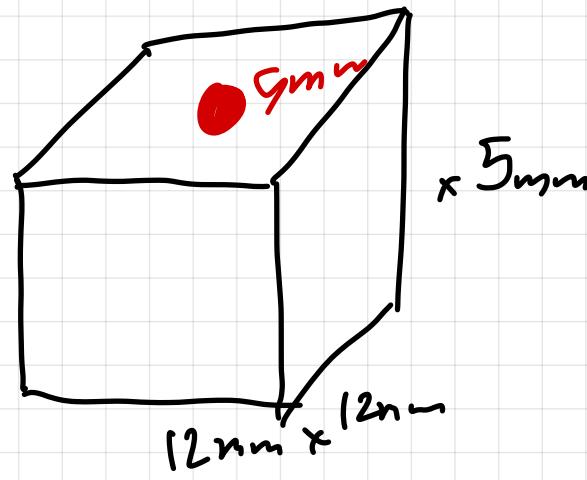
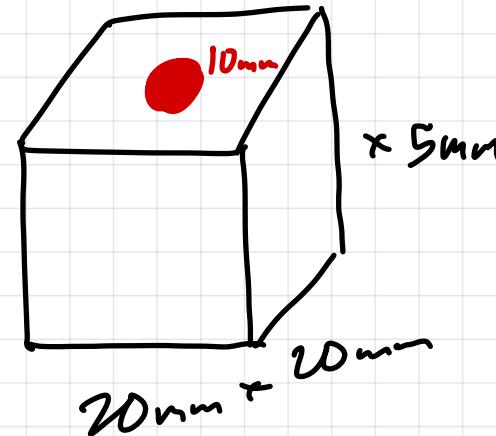
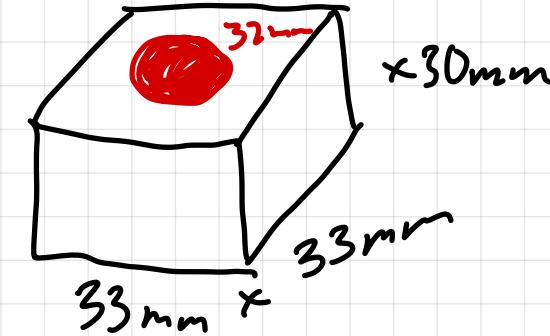
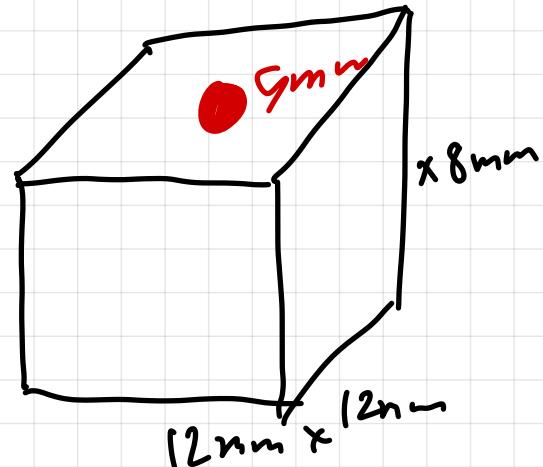
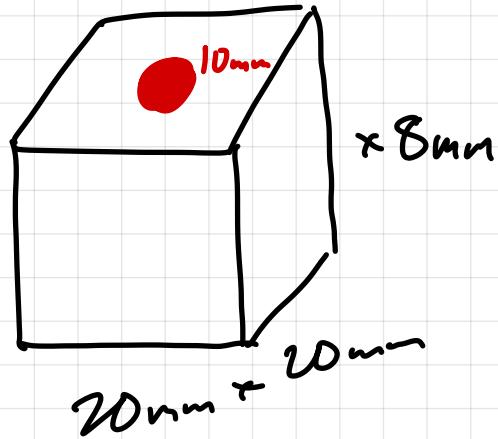
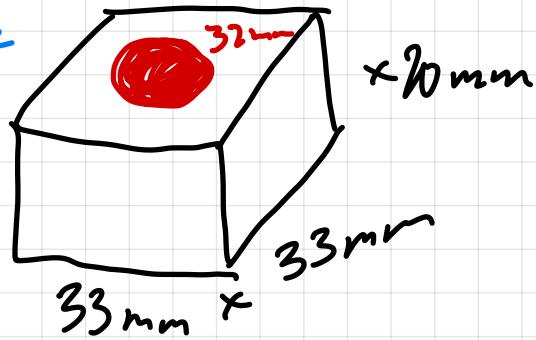
(DROY)

Arduino Uno



Elastomer Designs

Square



Material:

VyttaFlex 20

EcoFlex 00-50

EcoFlex 00-20

EcoFlex 00-10

Gains:

1x

2x

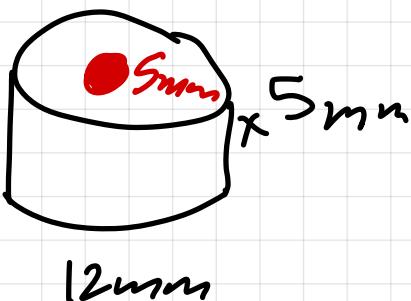
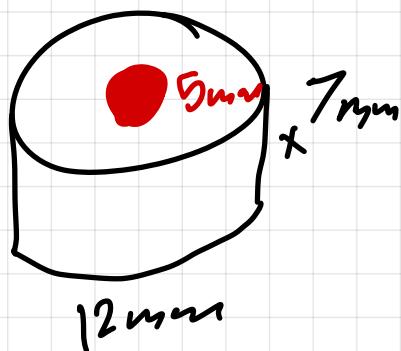
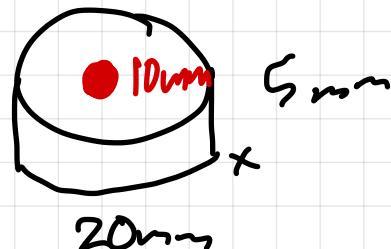
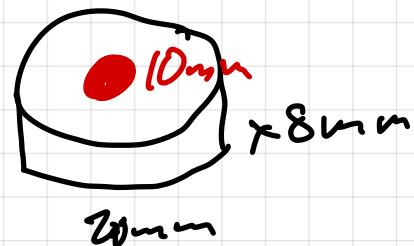
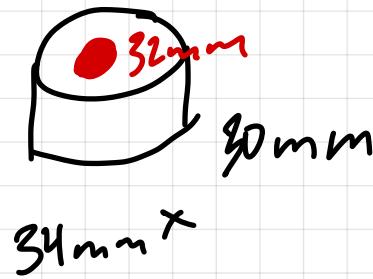
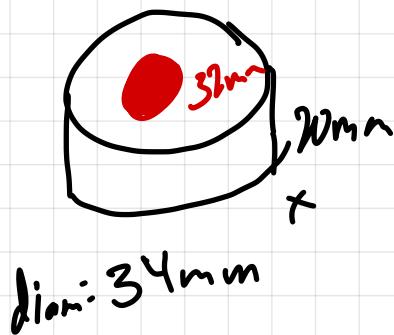
2.5x

3x

4x

5x

Circle

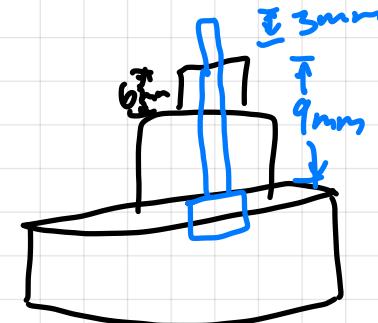
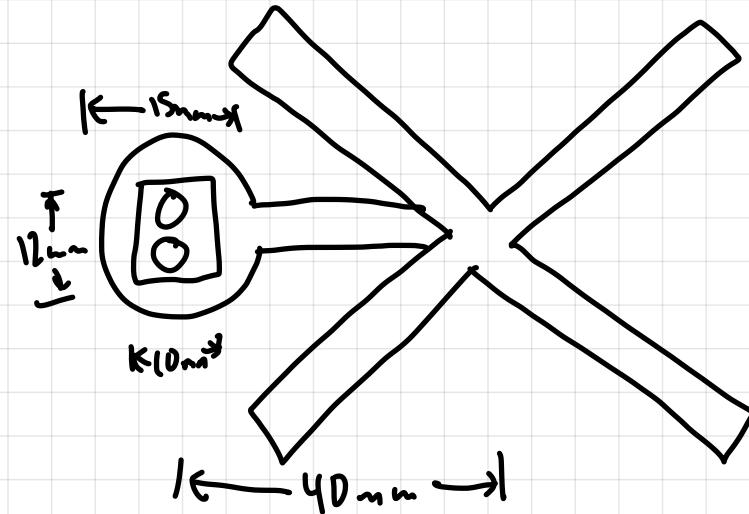
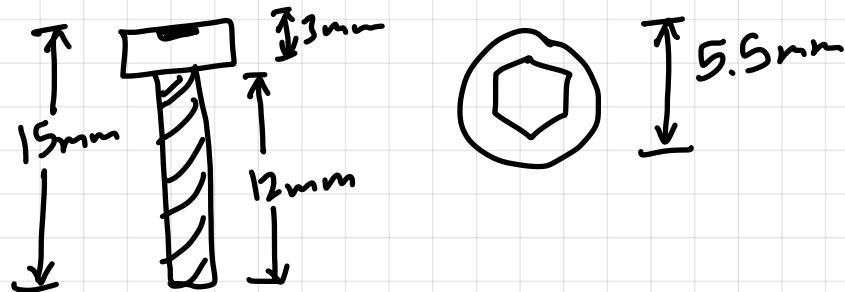


Material:

- VyttaFlex 20
- EcoFlex 00-50
- EcoFlex 00-20
- EcoFlex 00-10

Gain:

- 1x
- 2x
- 2.5x
- 3x
- 4x
- 5x



Print Times/Volumes:

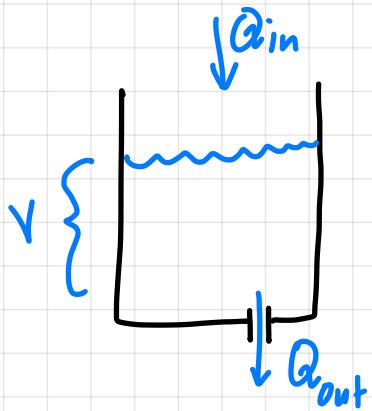
Load Cell Bottom \rightarrow 6 hr / 36.24 mL

Load Cell Top \rightarrow 7 hr / 110.33 mL

Anchor Magnetic Section \rightarrow 7.5 hr / 107.15 mL

Anchor Filleted Section \rightarrow 7.5 hr / 230.04 mL

Dynamic Testing



$$\frac{dV}{dt} = Q_{in} - Q_{out}$$

$$Q_{in} = Q_{out} + \frac{dV}{dt} = V A_{exit} C_d + \frac{dV}{dt}$$

$$V = \sqrt{2gh}$$

$$g = 9.81 \text{ m/s}^2$$

h = height of fluid

$$Q_{in} = \frac{dV}{dt} + \sqrt{2gh} A_e C_d$$

$$\rho = \frac{m}{V}$$

h is derived from manometer reading:

$$h = \frac{m}{\rho A_c}$$

m = mass from manometer [kg]

ρ = density of water [kg/m³]

A_c = chamber cross-sectional area [m²]

$$Q_{in} = \frac{dV}{dt} + \sqrt{2g \frac{m}{\rho A_c}} A_e C_d$$

$$\frac{dV}{dt} = \frac{V_f - V_i}{\Delta t} = \frac{C_v \left(\sqrt{2g \frac{m_f}{PA_c}} A_e - \sqrt{2g \frac{m_i}{PA_c}} A_e \right)}{\Delta t} = \frac{A_e \sqrt{\frac{2g}{PA_c}} (\sqrt{m_f} - \sqrt{m_i}) C_v}{\Delta t}$$

$$Q_{in} = \frac{C_v A_e \sqrt{\frac{2g}{PA_c}} (\sqrt{m_f} - \sqrt{m_i})}{\Delta t} + \sqrt{2g \frac{m_f}{PA_c}} A_e C_d$$

C_v = coefficient of velocity (experimentally determined)

$$m = \alpha x + \beta$$

m = mass (g)

α, β = constants given by calibration

x = B-field measurement (μT)

$$Q_{in} = \frac{C_v A_e \sqrt{\frac{2g}{PA_c}} \left(\sqrt{\alpha x_f + \beta} - \sqrt{\alpha x_i + \beta} \right)}{\Delta t} + \sqrt{2g \frac{\alpha x_f + \beta}{PA_c}} A_e C_d$$

$$\frac{C_V A_e \sqrt{\frac{2g}{\rho A_c} (\alpha x_f + \beta - \alpha x_i + \beta)}}{\Delta t} + \sqrt{\frac{2g}{\rho A_c} (\alpha x_f + \beta)} A_e C_d$$

Δt



$$\frac{C_V A_e \sqrt{\frac{2g\alpha}{\rho A_c} (x_f - x_i)}}{\Delta t} + \sqrt{\frac{2g}{\rho A_c} (\alpha x_f + \beta)} A_e C_d$$

$Q_{in} =$

$$= \frac{C_V A_e \sqrt{\frac{2g}{\rho A_c}} \int (x_f - x_i)}{\Delta t} + \sqrt{\frac{2g}{\rho A_c}} \int \alpha x_f + \beta A_e C_d$$

$$= A_e \sqrt{\frac{2g}{\rho A_c}} \left(\frac{C_V \int x_f - x_i}{\Delta t} + C_d \int \alpha x_f + \beta \right)$$

$$\frac{\sqrt{2} A_e \left(\Delta t C_d \sqrt{\frac{g(\alpha x_f + \beta)}{\rho A_c}} + C_V \left(\sqrt{\frac{g(\beta + \alpha x_f)}{\rho A_c}} - \sqrt{\frac{g(\beta + \alpha x_i)}{\rho A_c}} \right) \right)}{\Delta t}$$

$$\frac{\sqrt{2} A_e (\Delta t C_d \sqrt{\frac{g(\alpha x_f + \beta)}{g A_c}} + C_v \left(\sqrt{\frac{g(\beta + \alpha x_f)}{g A_c}} - \sqrt{\frac{g(\beta + \alpha x_i)}{g A_c}} \right))}{\Delta t}$$

$$Q_{in} = \frac{C_v A_e \sqrt{\frac{2g\alpha}{g A_c}} \left(\sqrt{x_f - x_i} \right)}{\Delta t} + \sqrt{2g \frac{\alpha x_f + \beta}{g A_c}} A_e C_d$$

C_v = coefficient of velocity for fluid (unitless/experimentally determined)

A_e = exhaust cross-sectional area (m^2)

Δt = gravitational acceleration (9.81 m/s^2)

g = calibrated slope for B-field \rightarrow mass conversion ($\text{kg/}\mu\text{T}$)

α = calibrated y-int for B-field \rightarrow mass conversion (kg)

β = final measured B-field (μT)

x_f = initial measured B-field (μT)

x_i = density of fluid (kg/m^3)

ρ = chamber cross-sectional area (m^2)

A_c = chamber cross-sectional area (m^2)

C_d = coefficient of discharge for fluid (unitless/experimentally determined)

Δt = increment of measurement (s)

Dimensional Analysis:

$$Q_{in} = \frac{C_v A e \sqrt{\frac{2g\alpha}{\rho A_c}} (x_f - x_i)}{\Delta t} + \sqrt{2g \frac{\alpha x_f + \beta}{\rho A_c}} A e C_d$$

$$= \frac{[m \cdot J \cdot K] [m^2]}{[s]} \underbrace{\frac{[m/s^2] [kg/m^3]}{[kg/m^3] [m^2]}}_{\cancel{[kg/m^3]}} (\cancel{\sqrt{[kg]}}) + \sqrt{\frac{[m/s^2] [kg/\mu T] [\mu T] + [kg]}{[kg/m^3] [m^2]}} [m^2] [m \cdot J \cdot K]$$

$$\frac{m^2 \cdot \sqrt{\frac{m \cdot m^3}{m^2 \cdot s^2}}}{s} = \frac{m^2 \cdot \sqrt{\frac{m^2}{s^2}}}{s} \\ = \frac{m^2 \cdot \frac{m}{s}}{s} = \frac{m^3}{s^3}$$

$$\frac{dV}{dt} = Q_{in} - Q_{out} \rightarrow Q_{in} = \frac{dV}{dt} + Q_{out}$$

$$Q_{out} = C_d A e \sqrt{2g \frac{m}{\rho A_c}}$$

$$Q_{in} = \frac{dV}{dt} + C_d A_c \sqrt{2g \frac{m}{\rho A_c}}$$

$$\frac{dV}{dt} = \frac{V_f - V_i}{\Delta t}$$

$$V = Ah = \frac{m}{\rho}$$

$$Q_{in} = \frac{\frac{m_f}{\rho} - \frac{m_i}{\rho}}{\Delta t} + C_d A_c \sqrt{2g \frac{m_f}{\rho A_c}}$$

$$= \frac{m_f - m_i}{\rho \Delta t} + C_d A_c \sqrt{2g \frac{m_f}{\rho A_c}}$$

$$= \frac{(\alpha x_f + \beta) - (\alpha x_i + \beta)}{\rho \Delta t} + C_d A_c \sqrt{2g \frac{\alpha x_f + \beta}{\rho A_c}}$$

$$Q_{in} = \frac{\alpha (x_f - x_i)}{\rho \Delta t} + C_d A_c \sqrt{2g \frac{\alpha x_f + \beta}{\rho A_c}}$$

Final Derivation ($O(h)$ FFD)

$$Q_{in} = \frac{\alpha}{\rho \Delta t} (x_f - x_i) + C_d A_e \sqrt{2g \frac{\alpha x_f + \beta}{\rho A_c}}$$

α = calibrated slope from B-field \rightarrow mass conversion ($\text{kg}/\mu\text{T}$)

β = calibrated y-int from B-field \rightarrow mass conversion (kg)

x_f = final B-field value (μT)

x_i = initial B-field value (μT)

ρ = density of fluid (kg/m^3)

Δt = time increment (s)

C_d = coefficient of discharge of fluid (unitless/experimentally determined)

A_e = exhaust cross-sectional area (m^2)

A_c = chamber cross-sectional area (m^2)

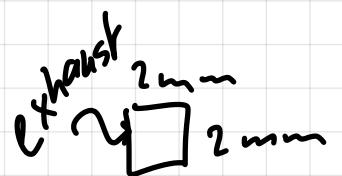
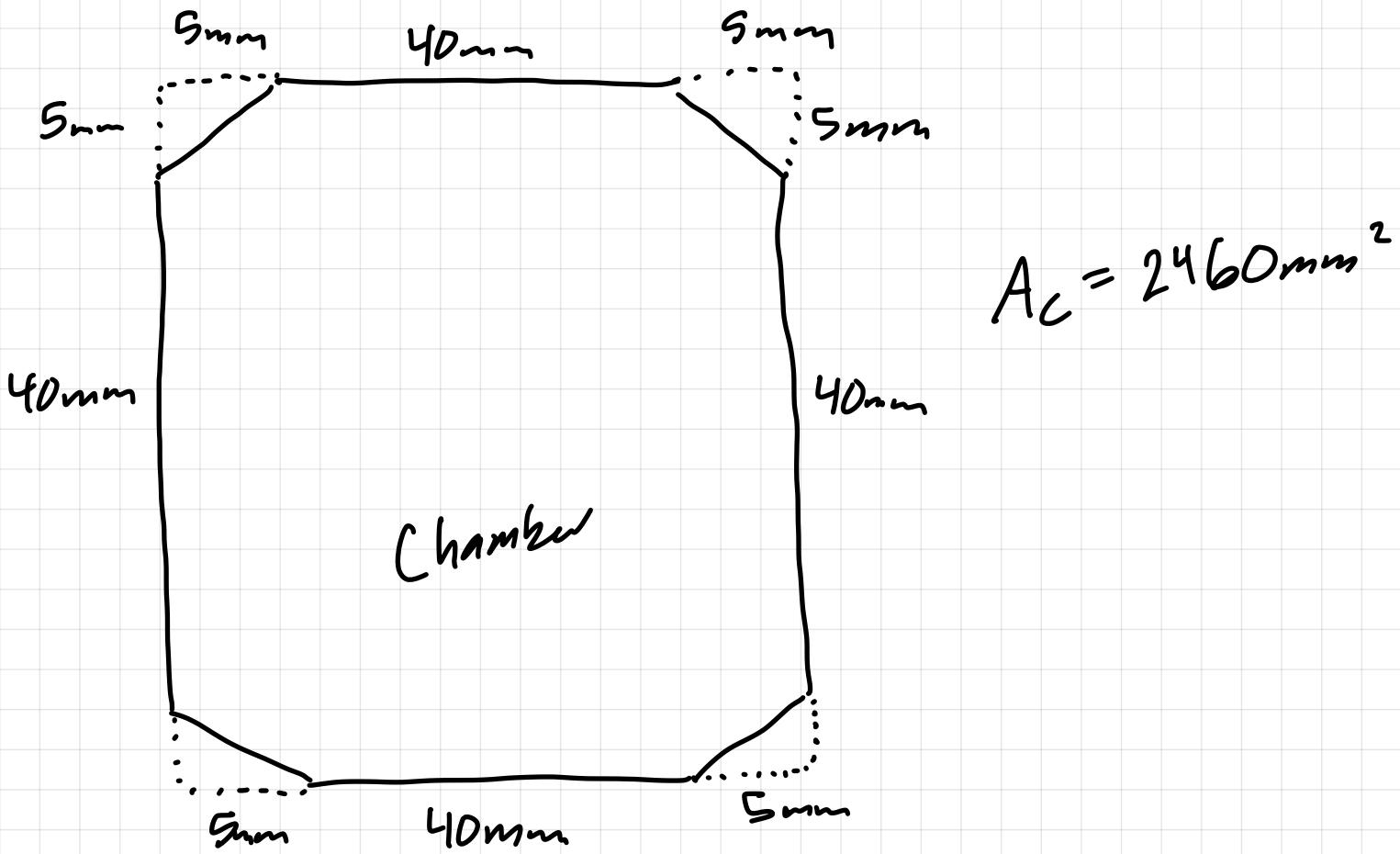
Dimensional Analysis:

$$[Q_{in}] = \frac{\text{m}^3}{\text{s}}$$

$$\frac{[\text{kg}/\mu\text{T}]}{[\text{kg}/\text{m}^3][\text{s}]} \left[\frac{[\mu\text{T}]}{[\text{s}]} + [\emptyset] \right] [\text{m}^2] \sqrt{\frac{[\text{m}/\text{s}]}{[\text{kg}/\text{m}^3]}} \sqrt{\frac{[\mu\text{T}]}{[\text{m}^2]}}$$

$$\frac{\frac{\text{m}^3}{\text{s}}}{\frac{\text{m}^3}{\text{s}}} + \text{m}^2 \sqrt{\frac{\text{m}^2}{\text{s}^2}} = \frac{\text{m}^3}{\text{s}} + \frac{\text{m}^3}{\text{s}}$$

$$\frac{\text{m}^3}{\text{s}}$$



$$A_e = 4 \text{ mm}^2$$

$$h_{\max} = 60 \text{ mm}$$

$$m_{\max} = \rho_{\text{air}} \cdot A_C h_{\max} = 0.00000997 \frac{\text{kg}}{\text{mm}^3} \cdot 2460 \text{ mm}^2 \cdot 60 \text{ mm} = 147.157 \text{ g}$$

$$Q_{in} = \frac{dV}{dt} + C_d A e \sqrt{2g \frac{\alpha x_f + \beta}{\rho A c}}$$

$$V(t) = \frac{M_t}{\rho} = \frac{\alpha x_t + \beta}{\rho}$$

FFO:

$$\frac{dV}{dt} = \frac{V_{i+1} - V_i}{\Delta t} + O(h)$$

$$\frac{dV}{dt} = \frac{-V_{i+2} + 4V_{i+1} - 3V_i}{2\Delta t} + O(h^2)$$

BFD:

$$\frac{dV}{dt} = \frac{V_i - V_{i-1}}{\Delta t} + O(h)$$

$$\frac{dV}{dt} = \frac{3V_i - 4V_{i-1} + V_{i-2}}{2\Delta t} + O(h^2)$$

CFD:

$$\frac{dV}{dt} = \frac{V_{i+1} - V_{i-1}}{2\Delta t} + O(h^2)$$

$$\frac{dV}{dt} = \frac{-V_{i+2} + 8V_{i+1} - 8V_{i-1} + V_{i-2}}{12\Delta t} + O(h^3)$$

$$\frac{dV}{dt} = \frac{-V_{i+2} + 4V_{i+1} - 3V_i}{2\Delta t} + O(h^2)$$

$$\frac{dV}{dt} = \frac{-\frac{\alpha x_{i+2} + \beta}{\rho} + 4 \frac{\alpha x_{i+1} + \beta}{\rho} - 3 \frac{\alpha x_i + \beta}{\rho}}{2\Delta t} = \frac{-(\alpha x_{i+2} + \beta) + 4(\alpha x_{i+1} + \beta) - 3(\alpha x_i + \beta)}{2\rho\Delta t}$$

$$= \frac{-\cancel{\alpha x_{i+2} - \beta} + 4\cancel{\alpha x_{i+1} + \beta} - 3\cancel{\alpha x_i - \beta}}{2\rho\Delta t}$$

$$= \frac{-\alpha x_{i+2} + 4\alpha x_{i+1} - 3\alpha x_i}{2\rho\Delta t} = \frac{\alpha}{2\rho\Delta t} (4x_{i+1} - x_{i+2} - 3x_i)$$

FFD $O(h^2)$

$$Q_{in} = \frac{\alpha}{2\rho\Delta t} (4x_{i+1} - x_{i+2} - 3x_i) + C_d A_e \sqrt{2g} \frac{\alpha x_{i+2} + \beta}{\rho A_c}$$

$$\frac{dV}{dt} = \frac{V_i - V_{i-1}}{\Delta t}$$

$$\frac{dV}{dt} = \frac{\cancel{\alpha x_i + \beta}}{S} - \frac{\cancel{\alpha x_{i-1} + \beta}}{S} = \frac{\cancel{\alpha x_i + \beta} - \cancel{\alpha x_{i-1} + \beta}}{S \Delta t} = \frac{\alpha}{g \Delta t} (x_i - x_{i-1})$$

BFD O(h):

$$Q_{in} = \frac{\alpha}{g \Delta t} (x_i - x_{i-1}) + C_d A_c \sqrt{2g \frac{\alpha x_i + \beta}{S A_c}}$$

$$\frac{dV}{dt} = \frac{3V_i - 4V_{i-1} + V_{i-2}}{2\Delta t}$$

$$\frac{dV}{dt} = \frac{3 \cancel{\alpha x_i + \beta} - 4 \cancel{\alpha x_{i-1} + \beta} + \cancel{\alpha x_{i-2} + \beta}}{2\Delta t} = \frac{\alpha}{2g\Delta t} (3x_i - 4x_{i-1} + x_{i-2})$$

BFD O(h²):

$$Q_{in} = \frac{\alpha}{2g\Delta t} (3x_i - 4x_{i-1} + x_{i-2}) + C_d A_c \sqrt{2g \frac{\alpha x_i + \beta}{S A_c}}$$

$$\frac{dV}{dt} = \frac{V_{i+1} - V_{i-1}}{2\Delta t}$$

$$\frac{\frac{\alpha x_{i+1} + \beta}{\rho} - \frac{\alpha x_{i-1} + \beta}{\rho}}{2\Delta t} = \frac{\alpha}{2\rho\Delta t} (x_{i+1} - x_{i-1})$$

CFO $O(h^2)$:

$$Q_{in} = \frac{\alpha}{2\rho\Delta t} (x_{i+1} - x_{i-1}) + CdAe \sqrt{2g \frac{\alpha x_{i+1} + \beta}{\rho A_c}}$$

$$\frac{dV}{dt} = \frac{-V_{i+2} + 8V_{i+1} - 8V_{i-1} + V_{i-2}}{12\Delta t}$$

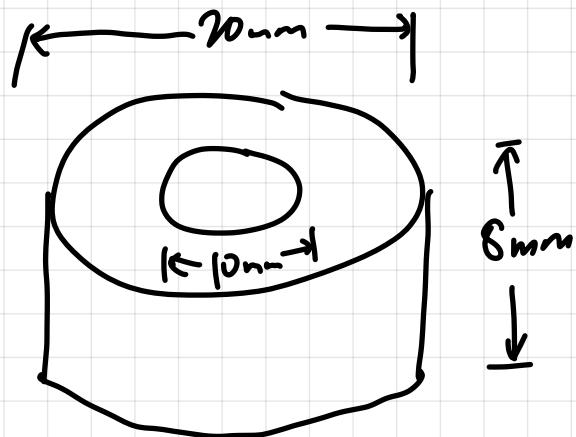
$$\frac{dV}{dt} = \frac{-\frac{\alpha x_{i+2} + \beta}{\rho} + 8 \frac{\alpha x_{i+1} + \beta}{\rho} - 8 \frac{\alpha x_{i-1} + \beta}{\rho} + \frac{\alpha x_{i-2} + \beta}{\rho}}{12\Delta t}$$

$$= \frac{\alpha}{12\rho\Delta t} (x_{i-2} + 8x_{i+1} - 8x_{i-1} - x_{i+2})$$

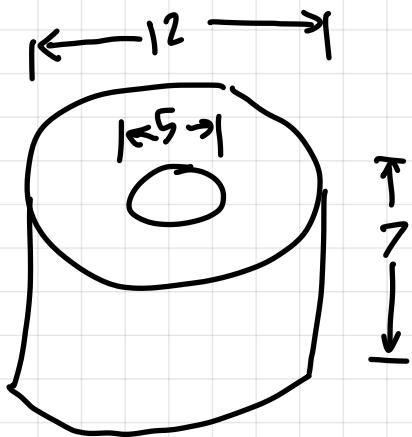
CFO $O(h^4)$:

$$Q_{in} = \frac{\alpha}{12\rho\Delta t} (x_{i-2} + 8x_{i+1} - 8x_{i-1} - x_{i+2}) + CdAe \sqrt{2g \frac{\alpha x_{i+2} + \beta}{\rho A_c}}$$

C-10m-8t

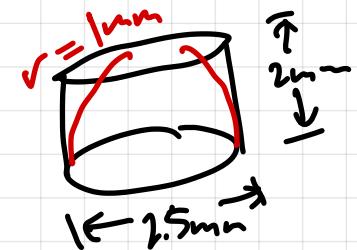


C-5m-7t

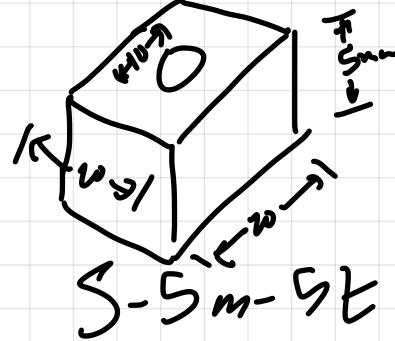


Magnet Thickness: 2.5mm

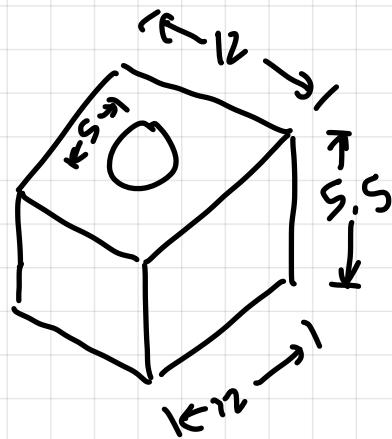
Arms Dimensions:



S-10m-5t



S-5m-5t



$$B(z) = \alpha \left(\frac{z+2mm}{\sqrt{(z+2mm)^2 + S^2 mm^2}} - \frac{z}{\sqrt{z^2 + S^2 mm^2}} \right)$$

compressed



$$Z(m) = \frac{P}{\gamma (1+2f^2)} = \frac{\frac{mg}{A}}{\gamma (1+2f^2)} = \frac{mg}{\gamma A (1+2f^2)}$$

$$f = \frac{\gamma R^2}{2\pi RL} = \frac{2S\gamma mm^2}{20\pi mm^2} = \frac{S}{4} = 1.25$$

$$\gamma = 12 \text{ psi} \cdot \frac{6894.76 \text{ Pa}}{1 \text{ psi}} = 82737.12 \text{ Pa}$$

$$\gamma = 82737.12 \frac{\text{N}}{\text{m}^2} \cdot \frac{1 \text{ m}^2}{(1000)^2 \text{ mm}^2} = 0.08273712 \frac{\text{N}}{\text{mm}^2}$$

$$A = \pi R^2 = 25\pi$$

$$g = 9.81 \frac{\text{m}}{\text{s}^2} \cdot \frac{1000 \text{ mm}}{1 \text{ m}} = 9810 \frac{\text{mm}}{\text{s}^2}$$

$$Z(m) = \frac{9810 \text{ m}}{(0.08273712)(25\pi)(1+2(1.25)^2)}$$

$$\beta_m = \alpha \left(\sqrt{\left(\frac{9810}{(0.08273712)(25\pi)(1+2(1.25)^2)} + 2 \right)^2 + 25} - \sqrt{\left(\frac{9810}{(0.08273712)(25\pi)(1+2(1.25)^2)} + 2 \right)^2 + 25} \right)$$

$$\beta = \frac{9810}{25\pi r(1+2f^2)}$$

$$\beta = \alpha \left(\frac{\beta_m + 2}{\sqrt{(\beta_m + 2)^2 + 25}} - \frac{\beta_m}{\sqrt{(\beta_m)^2 + 25}} \right)$$

$$\beta \sqrt{(\beta_m + 2)^2 + 25} = \alpha \left(\beta_m + 2 - \frac{\sqrt{(\beta_m + 2)^2 + 25}}{\sqrt{(\beta_m)^2 + 25}} \beta_m \right)$$

$$(\beta_m + 2)(\beta_m + 2)$$

$$\beta^2 m^2 + 2\beta m + 2\beta m + 4 = \beta^2 m^2 + 4\beta m + 4$$

$$B \sqrt{\beta_m^2 + 4\beta_m + 29} = \alpha \beta_m + 2\alpha - \frac{\sqrt{\beta_m^2 + 4\beta_m + 29}}{\sqrt{\beta_m^2 + 25}} \alpha \beta_m$$

$$\frac{B \sqrt{\beta_m^2 + 4\beta_m + 29} - 2}{1 - \frac{\sqrt{\beta_m^2 + 4\beta_m + 29}}{\sqrt{\beta_m^2 + 25}}} = \beta_m \left(1 - \frac{\sqrt{\beta_m^2 + 4\beta_m + 29}}{\sqrt{\beta_m^2 + 25}} \right)$$

$$\frac{\frac{B}{\alpha} - 2}{1 - \frac{1}{\sqrt{\beta_m^2 + 25}}} = \beta_m$$

$$F = \frac{mg}{A} = \frac{0.001 \cdot 9.81}{25\pi}$$

$$\frac{B}{\alpha} - 2 = \beta_m - \frac{\beta_m}{\sqrt{\beta_m^2 + 25}}$$

$$S_r = \sum (y_{true} - y_{pred})^2$$

$$S_{y/x} = \sqrt{\frac{S_r}{n-DOF}}$$

DOF = degrees of freedom (# of fitted variables)

Example: If a_0 , a_1 , and a_2 are the variables fit,

then $DOF = 3$. In linear regression $DOF = 2$ since slope a_1 and intercept a_0 are 2 fitted variables.

$$x = \frac{mg}{\gamma A(1+2f^2)} = \frac{L}{\gamma(1+2f^2)}$$

$$B(z) = \alpha \left(\frac{\frac{z+2mm}{\sqrt{(z+2mm)^2 + S_{mm}^2}} - \frac{z}{\sqrt{z^2 + S_{mm}^2}}}{\sqrt{(z+2mm)^2 + S_{mm}^2}} \right)$$

γ = thickness
of
magnet

$$B(m) = \alpha \left(\frac{\frac{mg}{\gamma A(1+2f^1)} + r}{\sqrt{\left(\frac{mg}{\gamma A(1+2f^1)} + r\right)^2 + R^2}} - \frac{\frac{mg}{\gamma A(1+2f^2)}}{\sqrt{\left(\frac{mg}{\gamma A(1+2f^2)}\right)^2 + R^2}} \right)$$

$$B(m) = \alpha \left(\frac{\frac{mg}{\partial A(1+2f^2)} + \zeta}{\sqrt{\left(\frac{mg}{\partial A(1+2f^2)} + \zeta\right)^2 + R^2}} - \frac{\frac{mg}{\partial A(1+2f^2)}}{\sqrt{\left(\frac{mg}{\partial A(1+2f^2)}\right)^2 + R^2}} \right)$$

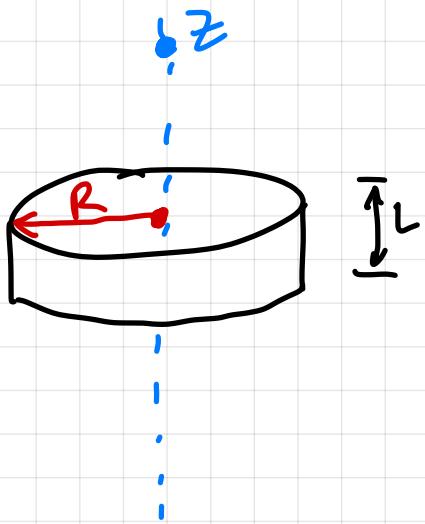
$$h = \frac{m}{gA}$$

$$B(m) = \alpha \left(\frac{\frac{\rho gh}{\gamma(1+2f^2)} + \zeta}{\sqrt{\left(\frac{\rho gh}{\gamma(1+2f^2)} + \zeta\right)^2 + R^2}} - \frac{\frac{\rho gh}{\gamma(1+2f^2)}}{\sqrt{\left(\frac{\rho gh}{\gamma(1+2f^2)}\right)^2 + R^2}} \right)$$

$$B(m) = \frac{\mu_0 M}{2} \left(\frac{z + \zeta}{\sqrt{(z + \zeta)^2 + R^2}} - \frac{z}{\sqrt{z^2 + R^2}} \right)$$

$$\left[\frac{A}{m} \right] \left(\frac{m}{m} - \frac{m}{m} \right) \rightarrow \frac{A}{m} \cdot \frac{m}{m} = \frac{A}{m}$$

$$B(z) = \frac{\mu_0 M}{2} \left(\frac{z}{\sqrt{z^2 + R^2}} - \frac{z - L}{\sqrt{(z - L)^2 + R^2}} \right)$$



$$B(z) = \frac{\mu_0 M}{2} \left(\frac{z + H_m}{\sqrt{(z + H_m)^2 + R^2}} - \frac{z}{\sqrt{z^2 + R^2}} \right)$$

$$B(z) = \frac{\mu_0 M}{2} \left(\frac{z + L}{\sqrt{(z + L)^2 + R^2}} - \frac{z}{\sqrt{z^2 + R^2}} \right)$$

z = thickness - deflection

$$B - \frac{\mu_0 M}{2} \left(\frac{z + L}{\sqrt{(z + L)^2 + R^2}} - \frac{z}{\sqrt{z^2 + R^2}} \right) = \emptyset$$

$$P = g j h$$

$$\frac{F}{A} = g j h$$

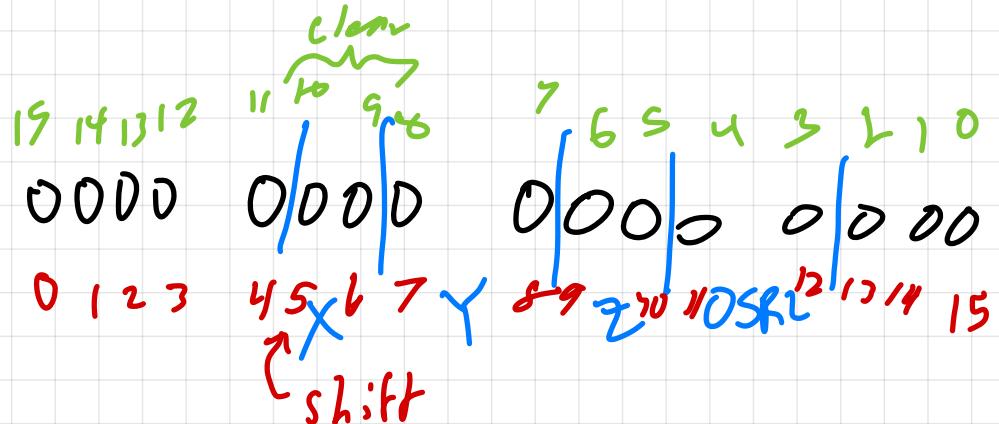
$$F = g j h A \rightarrow \cancel{\frac{1000 \text{kg}}{\text{m}^3}} \cdot 9.81 \text{m/s}^2 \cdot 50 \times 10^{-3} \text{m} \cdot (50 \times 10^{-3})^2 \text{m}^2$$

Read Measurement z, y, x : $0100\ 1110 = 0x4E$

Single Measurement z, y, x : $0011\ 1110 = 0x3E$

Read Measurement z, x, y, t : $0100\ 1111 = 0x4F$

Single Measurement z, x, y, t : $0011\ 1111 = 0x3F$



To Clear X:

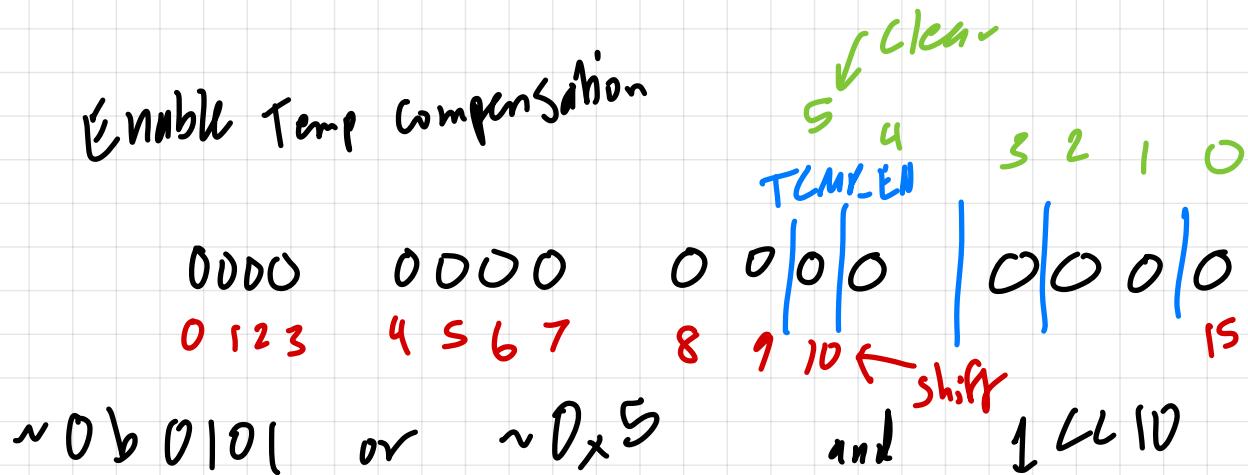
data & = ~0b0000 0110 0000 0000
or

data & = ~0x0600

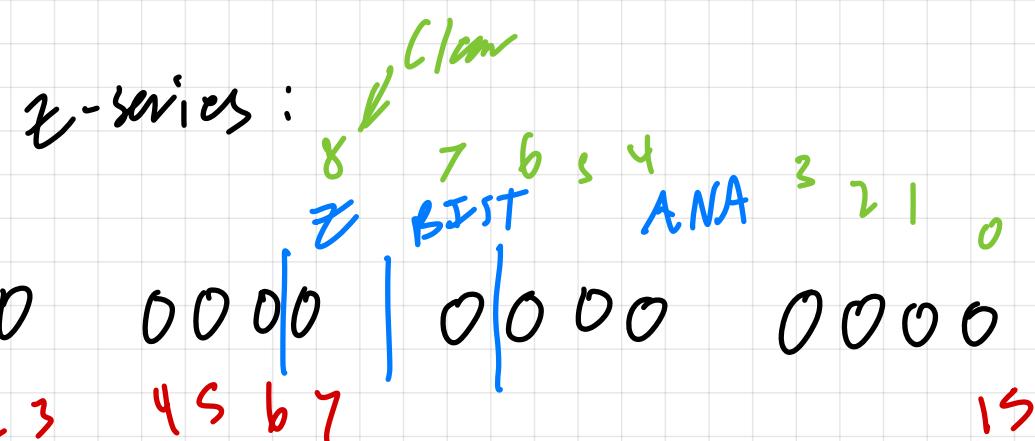
Then set Resolution:

data |= resolution && 5

Enable Temp Compensation



$0x0400 = 0b\ 0000\ 0100\ 0000\ 0000$

χ -series : 

0000 0001 0000 0000

$0x0100$