

view_frames Result
Recorded at time: 1750002994.872387

map

Broadcaster: default authority
Average rate: 28.768
Buffer length: 3.337
Most recent transform: 9184.164
Oldest transform: 9180.827

robot_odom

Broadcaster: default authority
Average rate: 100.315
Buffer length: 3.17
Most recent transform: 9183.217
Oldest transform: 9180.047

robot_base_footprint

Broadcaster: default authority
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

robot_base_link

Broadcaster: default authority
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

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Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

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Oldest transform: 0.0

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Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

Broadcaster: default authority
Average rate: 100.315
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Most recent transform: 9183.217
Oldest transform: 9180.047

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robot_back_left_visual_wheel_link

robot_back_right_visual_wheel_link

robot_base_docking_contact

robot_base_logo_front

robot_base_logo_left

robot_base_logo_rear

robot_base_logo_right

robot_base_chapa

robot_front_laser_base_link

robot_front_left_visual_wheel_link

robot_front_right_visual_wheel_link

robot_rear_laser_base_link

robot_vectornav_base_link

robot_back_left_wheel_link

robot_back_right_wheel_link

robot_front_left_wheel_link

robot_front_right_wheel_link

Broadcaster: default authority
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

robot_front_laser_link

Broadcaster: default authority
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

robot_rear_laser_link

Broadcaster: default authority
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

robot_vectornav_link