

# **Operating System**



Edited by: Dr. Akram Alhammadi



## **Chapter 1: Introduction**





## **Chapter 1: Introduction**

- What Operating Systems Do
- Computer-System Organization
- Computer-System Architecture
- Operating-System Structure
- Operating-System Operations
- Process Management
- Memory Management
- Storage Management
- Protection and Security





## What is an Operating System?

- A program that acts as an intermediary between a user of a computer and the computer hardware
- Operating system goals:
  - Execute user programs and make solving user problems easier
  - Make the computer system convenient to use
  - Use the computer hardware in an efficient manner





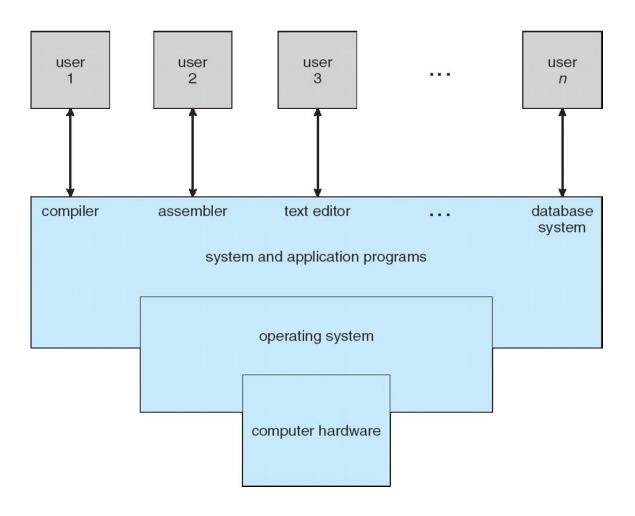
## **Computer System Structure**

- Computer system can be divided into four components:
  - **Hardware** provides basic computing resources
    - ▶ CPU, memory, I/O devices
  - Operating system
    - Controls and coordinates use of hardware among various applications and users
  - Application programs define the ways in which the system resources are used to solve the computing problems of the users
    - Word processors, compilers, web browsers, database systems, video games
  - Users
    - People, machines, other computers





### Four Components of a Computer System







## **What Operating Systems Do**

- Depends on the point of view
- Users want convenience, ease of use and good performance
  - Don't care about resource utilization
- But shared computer such as mainframe or minicomputer must keep all users happy (care about resource utilization)
- Users of dedicate systems such as workstations have dedicated resources but frequently use shared resources from servers(compromise between individual usability and resource utilization)
- Handheld computers are resource poor, optimized for usability and battery life
- Some computers have little or no user interface, such as embedded computers in devices and automobiles





## **Operating System Definition**

- OS is a resource allocator
  - Manages all resources
  - Decides between conflicting requests for efficient and fair resource use
- OS is a control program
  - Controls execution of programs to prevent errors and improper use of the computer





## **Operating System Definition (Cont.)**

- No universally accepted definition
- "The one program running at all times on the computer" is the kernel.
- Everything else is either
  - a system program (ships with the operating system) , or
  - an application program.





## **Computer Startup**

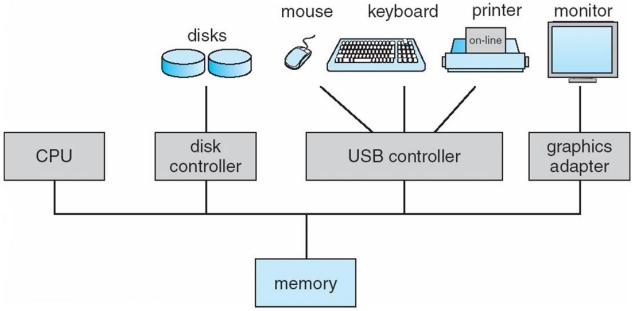
- bootstrap program is loaded at power-up or reboot
  - Typically stored in ROM or EPROM, generally known as firmware
  - Initializes all aspects of system
  - Loads operating system kernel and starts execution





## **Computer System Organization**

- Computer-system operation
  - One or more CPUs, device controllers connect through common bus providing access to shared memory
  - Concurrent execution of CPUs and devices competing for memory cycles







## **Computer-System Operation**

- I/O devices and the CPU can execute concurrently
- Each device controller is in charge of a particular device type
- Each device controller has a local buffer
- CPU moves data from/to main memory to/from local buffers
- I/O is from the device to local buffer of controller
- Device controller informs CPU that it has finished its operation by causing an interrupt





## **Common Functions of Interrupts**

- Interrupt transfers control to the interrupt service routine generally, through the interrupt vector, which contains the addresses of all the service routines
- Interrupt architecture must save the address of the interrupted instruction
- A trap or exception is a software-generated interrupt caused either by an error or a user request
- An operating system is interrupt driven





## **Interrupt Handling**

- The operating system preserves the state of the CPU by storing registers and the program counter
- Determines which type of interrupt has occurred:
  - Polling (based on time of interrupt)
  - vectored interrupt system (Based on priority)
- Separate segments of code determine what action should be taken for each type of interrupt





#### **Storage Definitions and Notation Review**

The basic unit of computer storage is the **bit**. A bit can contain one of two values, 0 and 1. All other storage in a computer is based on collections of bits. Given enough bits, it is amazing how many things a computer can represent: numbers, letters, images, movies, sounds, documents, and programs, to name a few. A **byte** is 8 bits, and on most computers it is the smallest convenient chunk of storage. For example, most computers don't have an instruction to move a bit but do have one to move a byte. A less common term is **word**, which is a given computer architecture's native unit of data. A word is made up of one or more bytes. For example, a computer that has 64-bit registers and 64-bit memory addressing typically has 64-bit (8-byte) words. A computer executes many operations in its native word size rather than a byte at a time.

Computer storage, along with most computer throughput, is generally measured and manipulated in bytes and collections of bytes.

A **kilobyte**, or **KB**, is 1,024 bytes

- a **megabyte**, or **MB**, is 1,024<sup>2</sup> bytes
- a **gigabyte**, or **GB**, is 1,024<sup>3</sup> bytes
- a **terabyte**, or **TB**, is 1,024<sup>4</sup> bytes
- a **petabyte**, or **PB**, is 1,024<sup>5</sup> bytes

Computer manufacturers often round off these numbers and say that a megabyte is 1 million bytes and a gigabyte is 1 billion bytes. Networking measurements are an exception to this general rule; they are given in bits (because networks move data a bit at a time).



## **Storage Structure**

- Main memory only large storage media that the CPU can access directly
  - Random access
  - Typically volatile
- Secondary storage extension of main memory that provides large nonvolatile storage capacity
- Hard disks rigid metal or glass platters covered with magnetic recording material
  - Disk surface is logically divided into tracks, which are subdivided into sectors
  - The disk controller determines the logical interaction between the device and the computer
- Solid-state disks faster than hard disks, nonvolatile
  - Various technologies
  - Becoming more popular





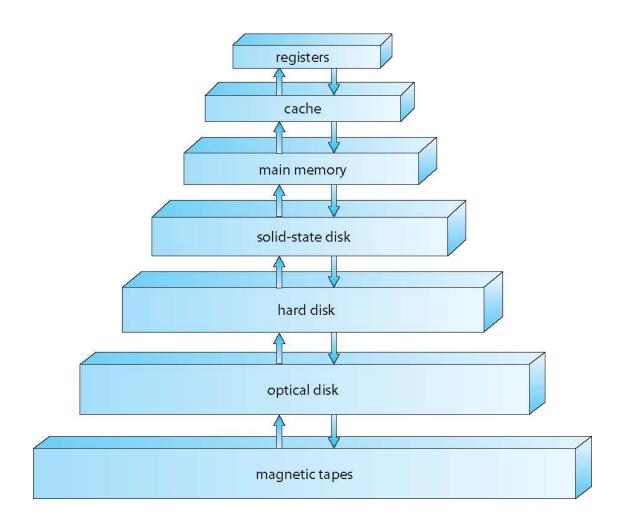
## **Storage Hierarchy**

- Storage systems organized in hierarchy
  - Speed
  - Cost
  - Volatility
- Caching copying information into faster storage system; main memory can be viewed as a cache for secondary storage
- Device Driver for each device controller to manage I/O
  - Provides uniform interface between controller and kernel





## **Storage-Device Hierarchy**







## **Caching**

- Important principle, performed at many levels in a computer (in hardware, operating system, software)
- Information in use copied from slower to faster storage temporarily
- Faster storage (cache) checked first to determine if information is there
  - If it is, information used directly from the cache (fast)
  - If not, data copied to cache and used there
- Cache smaller than storage being cached
  - Cache size and replacement policy





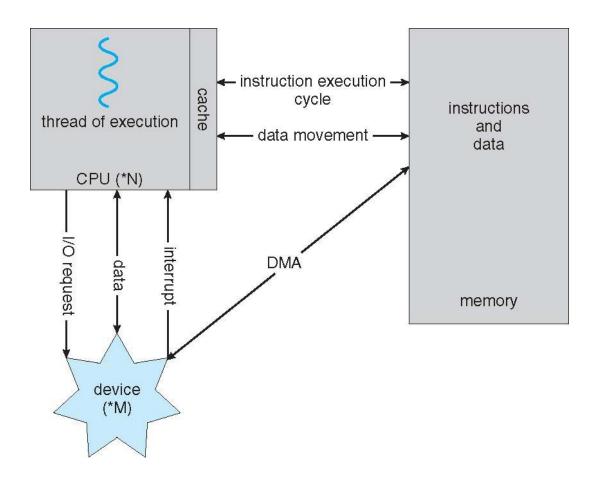
## **Direct Memory Access Structure**

- Used for high-speed I/O devices able to transmit information at close to memory speeds
- Device controller transfers blocks of data from buffer storage directly to main memory without CPU intervention





## **How a Modern Computer Works**



A von Neumann architecture





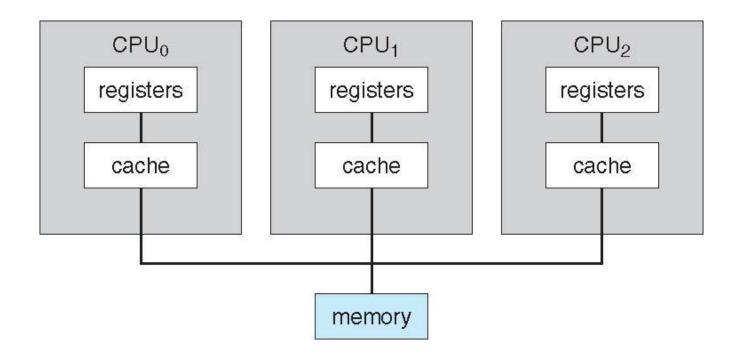
## **Computer-System Architecture**

- Most systems use a single general-purpose processor
  - Most systems have special-purpose processors as well
- Multiprocessors systems growing in use and importance
  - Also known as parallel systems, tightly-coupled systems
  - Multiprocessor systems have three main advantages:
    - Increased throughput
    - 2. Economy of scale
    - 3. Increased reliability graceful degradation or fault tolerance
  - Two types:
    - Asymmetric Multiprocessing each processor is assigned a special task.
    - 2. Symmetric Multiprocessing each processor performs all tasks





### **Symmetric Multiprocessing Architecture**

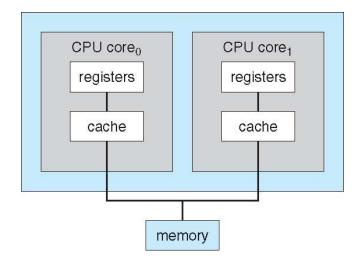






## A Dual-Core Design

- Multi-chip and multicore
- Systems containing all chips
  - Chassis containing multiple separate systems







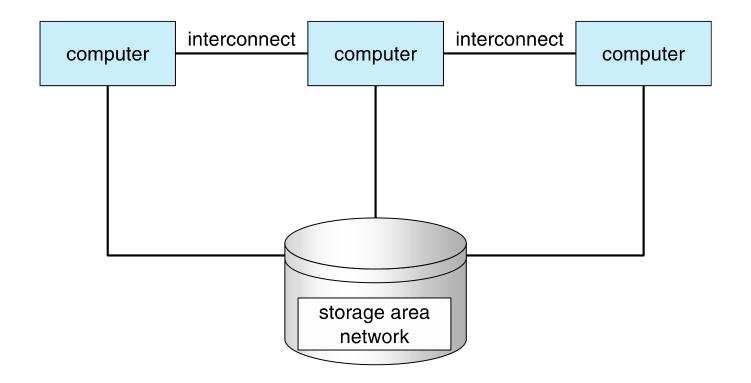
## **Clustered Systems**

- Like multiprocessor systems, but multiple systems working together
  - Usually sharing storage via a storage-area network (SAN)
  - Provides a high-availability service which survives failures
    - Asymmetric clustering has one machine in hot-standby mode
    - Symmetric clustering has multiple nodes running applications, monitoring each other
  - Some clusters are for high-performance computing (HPC)
    - Applications must be written to use parallelization
  - Some have distributed lock manager (DLM) to avoid conflicting operations





## **Clustered Systems**







## **Operating System Structure**

- Multiprogramming (Batch system) needed for efficiency
  - Single user cannot keep CPU and I/O devices busy at all times
  - Multiprogramming organizes jobs (code and data) so CPU always has one to execute
  - A subset of total jobs in system is kept in memory
  - One job selected and run via job scheduling
  - When it has to wait (for I/O for example), OS switches to another job
- Timesharing (multitasking) is logical extension in which CPU switches jobs so frequently that users can interact with each job while it is running, creating interactive computing
  - Response time should be < 1 second</li>
  - Each user has at least one program executing in memory ⇒process
  - If several jobs ready to run at the same time ⇒ CPU scheduling
  - If processes don't fit in memory, swapping moves them in and out to run
  - Virtual memory allows execution of processes not completely in memory

