

view_frames Result

Recorded at time: 1131.957

map

Broadcaster: /amcl
Average rate: 49.706 Hz
Most recent transform: 1132.034 (-0.077 sec old)
Buffer length: 4.768 sec

odom

Broadcaster: /gazebo
Average rate: 10.215 Hz
Most recent transform: 1131.954 (0.003 sec old)
Buffer length: 4.699 sec

robot_footprint

Broadcaster: /robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (1131.957 sec old)
Buffer length: 0.000 sec

chassis

Broadcaster: /robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (1131.957 sec old)
Buffer length: 0.000 sec

camera

Broadcaster: /robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (1131.957 sec old)
Buffer length: 0.000 sec

hokuyo

Broadcaster: /robot_state_publisher
Average rate: 10.208 Hz
Most recent transform: 1131.957 (0.000 sec old)
Buffer length: 4.702 sec

left_wheel

Broadcaster: /robot_state_publisher
Average rate: 10.208 Hz
Most recent transform: 1131.957 (0.000 sec old)
Buffer length: 4.702 sec

right_wheel