

My project goes according to the following,

Data Collection:

I used the provided [sample driving data](#) as my data source.

Preprocessing:

To prepare the images I do this:

- 1- Crop the image to filter out unwanted areas
- 2- Resize images to (66,200) to match Nvidia network input size.
- 3- Augment the data by flipping about 50% of left and right images.
- 4- Remove about 75% of low steering angles (lower than 0.05)

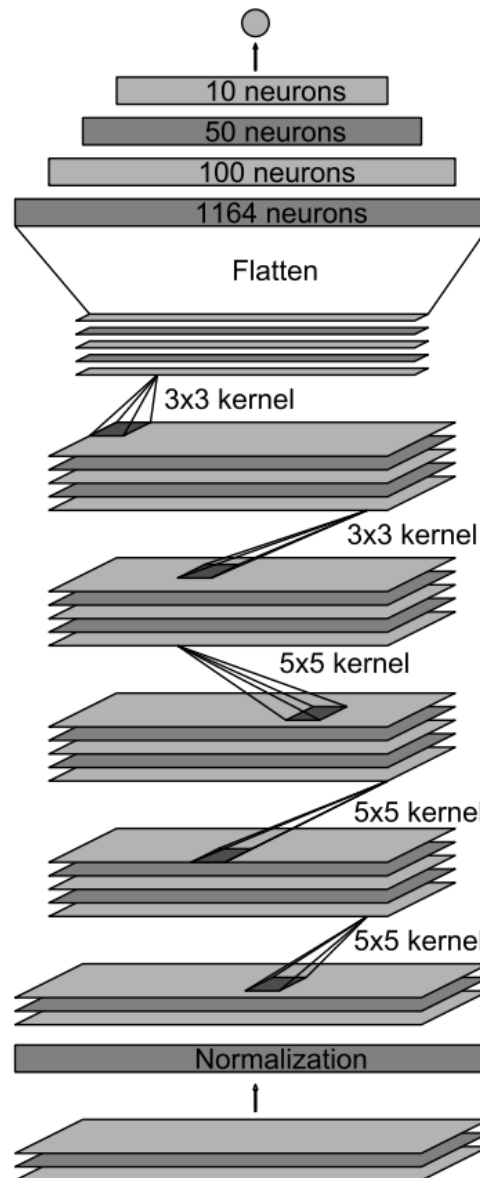
Model Architecture:

I used the recommended Nvidia model in [this paper](#) the model architecture is shown in the figure.

I fed the data folder images to the network through the generator that picks random batch from the images. It picks an image (left, center, right) and flip it randomly about 50% of the time, then yields the batch and feeds it to the network until the whole dataset is used. To avoid overfitting, I added some dropout layers of (0.15).

Model Training:

Then started training many times with different parameters till I reached the current parameters, patch size of 32, epochs number of 5 with Adam optimizer



Output: vehicle control

Fully-connected layer
Fully-connected layer
Fully-connected layer

Convolutional
feature map
64@1x18

Convolutional
feature map
64@3x20

Convolutional
feature map
48@5x22

Convolutional
feature map
36@14x47

Convolutional
feature map
24@31x98

Normalized
input planes
3@66x200

Input planes
3@66x200

Result:

A video of the result can be found in this link:

<https://drive.google.com/file/d/1KwcF9UhXt3Vg3p3K8EdjPXKpAjBQS0G0/view>

Model Architecture (summary output):

Layer (type)	Output Shape	Param #
lambda_3 (Lambda)	(None, 66, 200, 3)	0
lambda_4 (Lambda)	(None, 66, 200, 3)	0
conv2d_6 (Conv2D)	(None, 33, 100, 24)	1824
spatial_dropout2d_6 (Spatial	(None, 33, 100, 24)	0
conv2d_7 (Conv2D)	(None, 17, 50, 36)	21636
spatial_dropout2d_7 (Spatial	(None, 17, 50, 36)	0
conv2d_8 (Conv2D)	(None, 7, 23, 48)	43248
spatial_dropout2d_8 (Spatial	(None, 7, 23, 48)	0
conv2d_9 (Conv2D)	(None, 5, 21, 64)	27712
spatial_dropout2d_9 (Spatial	(None, 5, 21, 64)	0
conv2d_10 (Conv2D)	(None, 3, 19, 64)	36928
spatial_dropout2d_10 (Spatia	(None, 3, 19, 64)	0
flatten_2 (Flatten)	(None, 3648)	0
dropout_3 (Dropout)	(None, 3648)	0
dense_5 (Dense)	(None, 100)	364900
dense_6 (Dense)	(None, 50)	5050
dense_7 (Dense)	(None, 10)	510
dropout_4 (Dropout)	(None, 10)	0
dense_8 (Dense)	(None, 1)	11
Total params: 501,819		
Trainable params: 501,819		
Non-trainable params: 0		