

Marek Funtowicz

Embedded (C/C++) Software / FPGA Engineer (VHDL)

Personal Details

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Education

2014 – 2017 The University of Sheffield

Electronics and Communication Engineering

Master of Engineering

2012 – 2014 Central College Nottingham

Electrical and Electronic Engineering

Higher National Diploma

Skill

FPGA: Intel, Xilinx

CPU: x86, ARM, PowerPC

RTL: VHDL, Verilog

Code: ASM, C, C++, Python

OS: FreeRTOS, VxWorks,
Linux, Autosar OS

Build: Makefile, Yocto(basic)
Clang, Ninja, Cmake

Debug: J-Link (Ozone), gdb

Com: UART, SPI, I2C, JTAG,
GPIO, CAN, ASK, FSK,
TCP/UDP, ARP/NDP,
ETH, ICMP, Wi-Fi,
USB, CSI

Crypto: AES-128

Circuit: Mentor graphics, Altium,
Multisim

Test: Oscilloscope, Multimeter,
Logic Analyzer

Matrix: Matlab, Octave

Web: HTML, PHP, CSS,
Java script

DB: MySQL

CI/CD: GIT, Bitbucket,
Gerrit, Jenkins

Mgmt: JIRA, JAZZ

Personal Research and Development (C, C++, VHDL)

CPU & FPGA Embedded Computing Platform with GPU Acceleration

- ❖ x86 → Master controller and main system coordinator
- ❖ LNX → ARM Cortex-A57 running Ubuntu OS platform
- ❖ FPGA → Cyclone IV chip for high-speed parallel tasks
- ❖ Xilinx → Integration with Zynq™ UltraScale+™ MPSoC
- ❖ GPU → NVIDIA Maxwell architecture with 128 CUDA cores

AI Drone System Specification → Project Repository

- ❖ x86 → Kernel-level secured network stack implementation
- ❖ x86 → Handles network protocols ICMP, ARP/NDP and TCP/UDP
- ❖ x86 → AES-128 TCP/UDP encryption and decryption
- ❖ x86 → Video receiver for drone camera monitoring
- ❖ LNX → USB/CSI camera stream transmitter unit
- ❖ LNX → Qt5 GUI for drone system debugging/control
- ❖ LNX → Char device driver for user/kernel IO link
- ❖ LNX → Block RAM interface to configure FPGA peripherals
- ❖ LNX → SPI DMA driver for FPGA data exchange
- ❖ LNX → GPIO signals for FPGA/kernel ISR handling
- ❖ LNX → Kernel work queues, tasklet and threaded design techniques
- ❖ LNX → Spinlock and mutex for synchronization of Kernel space
- ❖ LNX → FPGA controlled scheduler for Kernel space RTOS operations
- ❖ LNX → Memory allocation monitor in Kernel space
- ❖ FPGA → Interrupt vector handler for Kernel commands
- ❖ FPGA → Watchdog interface for Kernel/FPGA synchronization
- ❖ FPGA → SPI link for data (de)serialization ops
- ❖ FPGA → Linux data exchange via FIFO for real-time processing
- ❖ FPGA → Offload controller and packet switch for FIFO data flow
- ❖ FPGA → Parameteric I2C and SPI controllers driven from LNX Kernel
- ❖ FPGA → PWM controller for the motor throttle control
- ❖ FPGA → UART assembler and transmission controller for logs capture
- ❖ FPGA → I2C and SPI Gyro/Accel devices for measurements
- ❖ FPGA → 133MHz SDRAM controller for captured measurements
- ❖ FPGA → SDRAM Measurement storage controller :: **Development**
- ❖ FPGA → Accelerated PID Controller for DC motor feedback :: **Pending**
- ❖ Xilinx → Petalinux based @ HW description to link with FPGA logic
- ❖ Xilinx → Port FPGA Driver into Xilinx Linux Kernel
- ❖ Xilinx → Convert the link between CPU and FPGA form SPI into DMA
- ❖ GPU → Accelerated processing of measurements from FPGA :: **Pending**
- ❖ GPU → Accelerated camera signal video drivers :: **Pending**

Software Engineer**Prototyping of the new generation wireless charging systems in the automotive industry (ASM, C)**

- ❖ Read and analyze prototype PCB schematics for debugging purposes
- ❖ Customer defect analysis, computation and testing solutions
- ❖ Develop interrupt monitor to monitor latency of ISR
- ❖ Investigate communication problems between the charger and the receiver using ASK and FSK protocols
- ❖ Adaptation of existing versions of the protocol into newer stack
- ❖ Process various number of ADC measurements: voltage, current and temperatures signals
- ❖ Diagnostics system control with respect to collected measurements
- ❖ Integration with the Autosar OS (Davinci code generator)
- ❖ Integration with RTD from NXP (Tresos)
- ❖ Integration with Qi-Library from NXP
- ❖ Code reviews

Software Engineer**Complex CPU & FPGA system to emulate the behavior of cellular network (C, C++, VHDL)**

- ❖ x86 HTML interface to control FPGA and CPU binaries required for specific configuration of cellular network
- ❖ x86 Applications to configure parameters of LTE/5G cells
- ❖ Store and process cell parameters from x86 Applications by the processor boards using instances of C++ classes
- ❖ Configure LTE/5G cells inside FPGA using cell parameters from the instances of C++ classes
- ❖ Communication interface between FPGA and CPU over SRIO
- ❖ Process internal and customer issues using JIRA management system
- ❖ Issues varying from invalid configurations of LTE/5G cells in Applications with respect to LTE/5G specifications
- ❖ Up to the low level PHY problems like: Thread crashes, code disassembly and investigation of instruction code to find the bug

Embedded Systems Engineer**Design Firmware and RTL for Power Electronic Device using AURIX 32-bit Tri-Core Microcontroller and ARTIX 7 Xilinx FPGA**

- ❖ Integration of the LWIP stack drivers with the current CPU stack
- ❖ Investigation of ASCLIN UART drivers for logging and communication
- ❖ Research Microblaze firmware in ARTIX 7 FPGA
- ❖ Investigate and analyze circuit schematics and PCB layout

Junior Hardware Engineer**Design computer hardware for capturing, processing and streaming live video using Intel Altera FPGA technology and firmware control**

- ❖ Design FPGA hardware modules in VHDL
- ❖ Design QSYS networks for Nios II processing
- ❖ On-chip memory management for Nios II processing
- ❖ Test RTL modules with Modelsim
- ❖ Test and debug RTL modules with signal tap and live PCB
- ❖ Nios II firmware for communication with FPGA over Avalon bus
- ❖ Debug Nios II firmware on live targets
- ❖ Integrate BSP and Intel HAL drivers
- ❖ Investigate booting codes for embedded Intel Nios II processor
- ❖ FPGA Pin and Chip planning → IO Banks, Voltages, Transceivers
- ❖ Investigate and analyze circuit schematics and PCB layout
- ❖ Integrate FPGA hardware code and CPU firmware with the circuit schematic and PCB Layout

Prototyping embedded graphical processing system using Xilinx FPGA technology and Linux firmware control

- ❖ Develop booting sequence for Zynq Ultrascale MPSoC in QSPI → hand over FPGA control to Linux kernel via U-Boot
- ❖ Research and modify U-boot source → Configure MAC addressing
- ❖ Research XEN Hypervisor → Register XEN watchdog
- ❖ Develop UART communication for Zynq Ultrascale MPSoC → register UARTE driver in Linux to communicate with external chip for TMDS processing and HDCP control
- ❖ Research kernel → Version control
- ❖ Research device tree → Petalinux overlay
- ❖ Research root file system → Network configuration
- ❖ Customize Petalinux → Kernel, Root file system and device tree
- ❖ Debug kernel in OS awareness mode → Eclipse environment