Marek Funtowicz

Embedded (C/C++) Software / FPGA Engineer (VHDL)

Personal Details

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Education

2014 – 2017 The University of Sheffield

Electronics and Communication Engineering

Master of Engineering

2013 – 2014 Open Study College

Pure Mathematics

A-Level

2012 – 2014 Central College Nottingham

Electrical and Electronic Engineering

Higher National Diploma

Personal Research and Development

Skill

FPGA: Intel. Xilinx

CPU: x86, ARM, PowerPC

RTL: VHDL

Code: ASM, C, C++, Python,

OS: FreeRTOS, VxWorks,

Linux, Autosar

Debug: J-Link (Ozone)

Com: USB, UART, SPI, I2C,

JTAG, GPIO, TCP, CAN

Circuit: Mentor graphics, Altium,

Multisim,

Test: Oscilloscope, Multimeters

Logic Analyzer

Repo: GIT, Bitbucket, Gerrit

Matrix: Matlab, Octave

Web: HTML, PHP, CSS,

Java script

DB: MySQL

Lang: Polish (Native),

English (Fluent)

CPU & FPGA Computer Platform (C, C++, VHDL, Python)

 \star x86 \rightarrow Powered by Ubuntu

♦ LNX → ARM Cortex-A8 powered by Debian

♦ FPGA → Intel Cyclone IV FPGA for parallel computation

System specification:

♦ x86

→ Graphical User Interface for the overall master control

* x86 → Network Client (Python GUI)

♦ LNX → Network Server (C++ Application)

♦ LNX → Char device for IO between Kernel and User space

LNX → Block RAM device for chip configuration in FPGA

♦ LNX → SPI driver for bidirectional FPGA communication over DMA

❖ LNX → Bidirectional GPIO signaling for FPGA/Kernel ISR processing

LNX → Work queues and kthread design techniques

♦ FPGA → Watchdog interface for Kernel synchronization

♦ FPGA → SPI interface for data serialization and parallelization

♦ FPGA → Parametrized I2C controller driven from LNX Kernel

♦ FPGA → Parametrized FIFO controller driven from LNX Kernel

♦ FPGA → Offload controller and packet switch for FIFO data flow

♦ FPGA → PWM controller for the motor throttle control

♦ FPGA → UART controller for the logs acquisition

FPGA → PID controllers for feedback control :: Pending R&D

FPGA → I2C and SPI buses for sensors connected to the chip

♦ FPGA → I2C and SPI Gyro/Accel devices for measurements

FPGA → SDRAM Controller for measurement storage :: **Development**

Additional work on upgrade to Xilinx Zynq UltraScale+™ MPSoC

❖ Compile Vivado project with simple pinout control using AXI bus

❖ Build petalinux kernel using HW Description exported from Vivado

❖ Boot petalinux kernel from SD card using u-boot

Control output pins defined in Vivado using petalinux bash

♦ Next → Create kernel module to control FPGA

♦ Next → Adapt currently developed kernel module into Xilinx system

❖ Next → Convert the link between CPU and FPGA from SPI to DMA

Software Engineer

Prototyping of the new generation wireless charging systems in the automotive industry (ASM, C)

- ❖ Read and analyze prototype PCB schematics
- Customer defect analysis, compute and test solutions
- ❖ Interrupt monitor to monitor latency of ISR
- Communication problems between the charger and the receiver using ASK and FSK protocols
- ❖ Adaptation of solutions from EPP protocol into newer MPP stack
- Process various number of ADC measurements: voltage, current and temperatures signals
- Integration with the Autosar OS (Davinci code generator)
- Integration with RTD from NXP (Tresos)
- ❖ Integration with Qi-Library from NXP
- Code reviews

Tronel

October 2019 → June 2023

Software Engineer

Complex CPU & FPGA system to emulate the behavior of cellular network (C, C++, VHDL)

- ❖ x86 HTML interface to control load binaries required for specific configuration of cellular network
- ❖ x86 Test Application to configure parameters of LTE or 5G cells
- Store and process cell parameters from Test Application by the PowerPC processor boards using instances of C++ classes
- Configure LTE or 5G cells in FPGA using cell parameters stored by the C++ classes
- Communication of PowerPC processor boards with FPGA over SRIO
- JIRA to process internal and customer issues
- Issues was varying from invalid cell configurations in Test Application with respect to LTE and 5G specifications
- Up to the low level PHY problems like: Thread crashes, PowerPC disassembly and investigation of instruction code to find the bug

Turbo Power Systems

August 2019 → October 2019

Embedded Systems Engineer

Design Firmware and RTL for Power Electronic Device using AURIX 32-bit Tri-Core Microcontroller and ARTIX 7 Xilinx FPGA (Soft Power Bridge)

- ❖ Integration of the LWIP stack drivers with the current CPU stack
- ❖ Investigation of ASCLIN UART drivers for loging and communication
- ❖ Research Microblaze firmware in ARTIX 7 FPGA
- Investigate and analyze circuit schematics and PCB layout

Junior Hardware Engineer

Design computer hardware for capturing, processing and streaming live video using Intel Altera FPGA technology and firmware control

- Design FPGA hardware modules in VHDL
- Design QSYS networks for Nios II processing
- ❖ On-chip memory management for Nios II processing
- ❖ Test RTL modules with Modelsim
- ❖ Test and debug RTL modules with signal tap and live PCB
- ❖ Nios II firmware for communication with FPGA over Avalon bus
- Debug Nios II firmware on live targets
- Integrate BSP and Intel HAL drivers
- Investigate booting codes for embedded Intel Nios II processor
- ❖ FPGA Pin and Chip planning → IO Banks, Voltages, Transceivers
- ❖ Investigate and analyze circuit schematics and PCB layout
- ❖ Integrate FPGA hardware code and CPU firmware with the circuit schematic and PCB Layout

Prototyping embedded graphical processing system using Xilinx FPGA technology and Linux firmware control

- ❖ Develop booting sequence for Zynq Ultrascale MPSoC in QSPI → hand over FPGA control to Linux kernel via U-Boot
- ❖ Research and modify U-boot source → Configure MAC addressing
- ❖ Research XEN Hypervisor → Register XEN watchdog
- ◆ Develop UART communication for Zynq Ultrascale MPSoC → register UARTLITE driver in Linux to communicate with external chip for TMDS processing and HDCP control
- **❖** Research kernel → Version control
- **♦** Research device tree → Petalinux overlay
- **❖** Research root file system → Network configuration
- ❖ Customize Petalinux → Kernel, Root file system and device tree
- ◆ Debug kernel in OS awareness mode → Eclipse environment