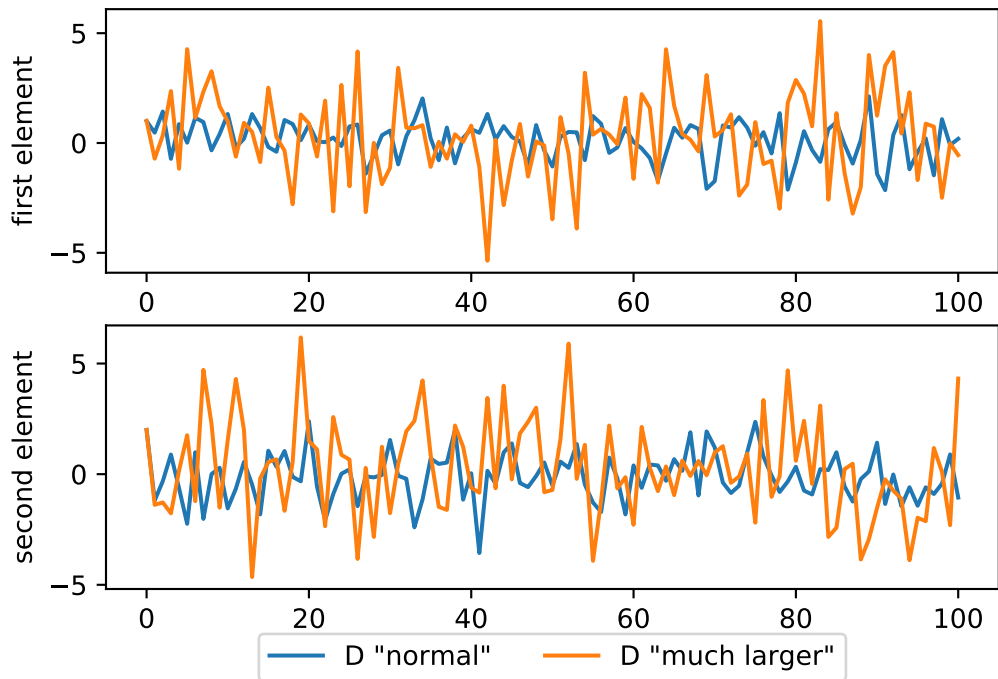
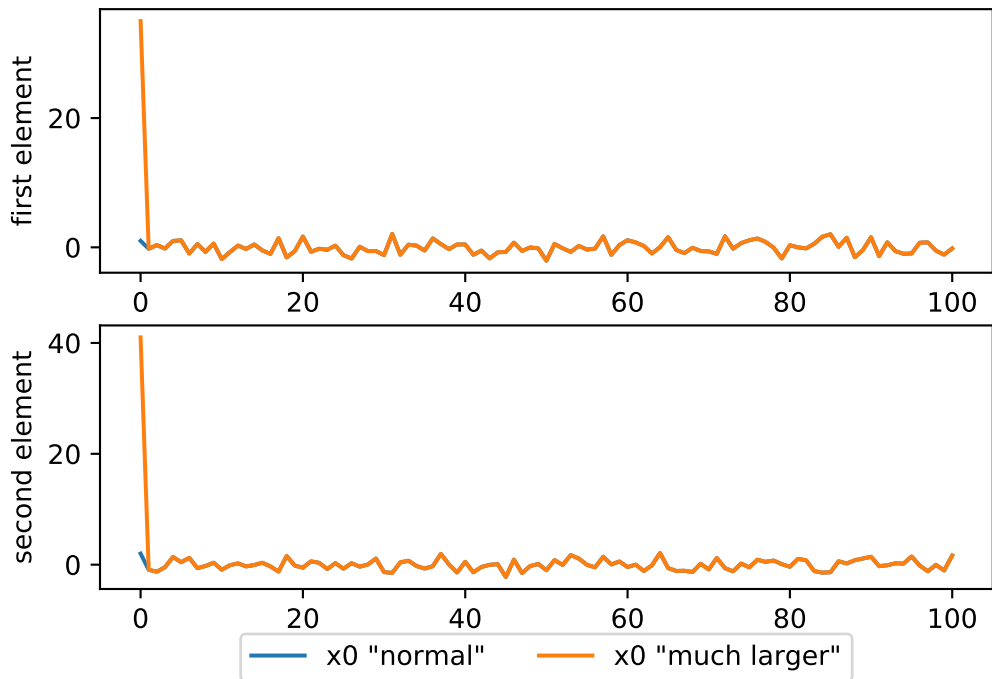


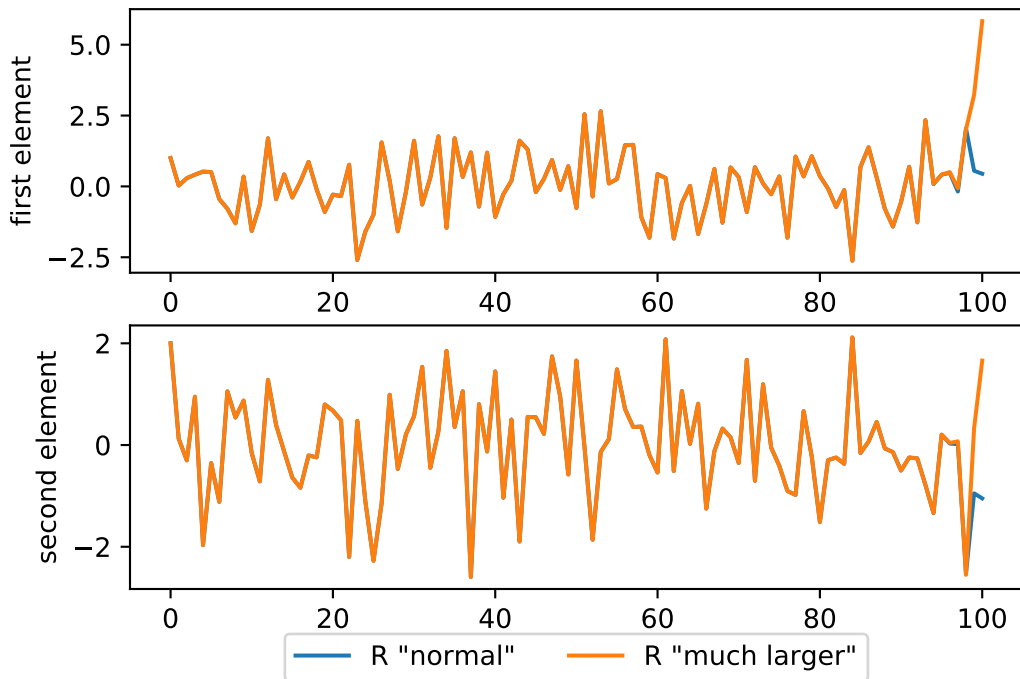
Behavior of the system for two covariance matrices (D)



Behavior of the system for two initial states (x_0)



Behavior of the system for two input-cost matrices (R)



Behavior of the system optimal control vs steady-state control

