Task7

2019年6月19日

1 图像处理 +180776+ 胡欣毅 (Python 版)

2 8 周课后

2.1 1. 题目清单

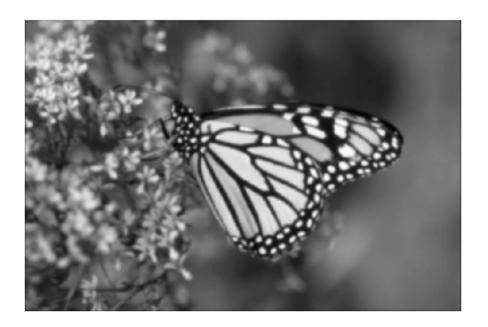
- 1. 利用 Perona-Malik 算法改善图像清晰度
- 2. 利用 Gabor 算法改善图像清晰度

2.2 Perona-Malik 算法

```
In [1]: import numpy as np
        import cv2
        import matplotlib.pyplot as plt
        %matplotlib inline

In [2]: im = cv2.imread('../hudie/3.bmp')
        im = cv2.cvtColor(im , cv2.COLOR_RGB2BGR)

        gray = cv2.cvtColor(im , cv2.COLOR_RGB2GRAY).astype(float)
        plt.imshow(gray,cmap='gray')
        plt.axis("off")
        plt.show()
        gray.shape
```



 $c(x, y, t) = g(|\nabla u|)$

2.2.1 方式一

```
In [6]: def PM1(src , k = 12, lambd = .01):
            Ker_x = np.array([[-1, 0, 1],
                              [-1, 0, 1],
                              [-1, 0, 1]])
           Ker_y = np.array([[1, 1, 1],
                              [0, 0, 0],
                              [-1,-1,-1]
            # Laplace 扩展算子
            laplace = np.array([[1, 1, 1],
                                [1,-8, 1],
                                [1, 1, 1]])
            # grad_u
            grad_x = cv2.filter2D(src, -1 , Ker_x )
            grad_y = cv2.filter2D(src, -1 , Ker_y )
            grad_u = np.abs(grad_x) + np.abs(grad_y)
            # c
            c = get_c(grad_u,k = k)
            # grad_c
            grad_x_c = cv2.filter2D(src, -1 , Ker_x )
            grad_y_c = cv2.filter2D(src, -1 , Ker_y )
            grad_c = np.abs(grad_x_c) + np.abs(grad_y_c)
            # Laplace_u
           Laplace_u = cv2.filter2D(src, -1 , laplace )
            im_out = (src + lambd*(grad_c * grad_u + c* Laplace_u ) )
           return im_out
In [7]: def PM2(src , k = 12, lambd = .001):
            edge = - np.array([[1, 1, 1],
                               [1,-8, 1],
                               [1, 1, 1]])
            # grad_u
            grad_u = cv2.filter2D(src, -1 , edge )
            # c
```

```
c = get_c(grad_u,k = k)
            # grad_c
            grad_c = cv2.filter2D(src, -1 , edge )
            # Laplace_u
           x = cv2.getGaussianKernel(3, 1.0)# 高斯滤波器
           ker = x * x.T
           Laplace_u = cv2.filter2D(src, -1 , ker )
            # out
            im_out = (src + lambd*(grad_c * grad_u + c* Laplace_u ) )
           return im_out
In [8]: # 迭代次数
       step_num = 1
        # copy
       im_out1 = gray.astype(float)
       im_out2 = gray.astype(float)
       for t in range(step_num):
            im_out1 = PM1(im_out1, k = 12, lambd = .002)
            im_out2 = PM2(im_out2, k = 15, lambd = .003)
In [9]: print('原图: ', getImageVar(gray),'\n','PM 算法: ',\
             getImageVar(im_out1),getImageVar(im_out2))
原图: 24.55965163387333
PM 算法: 178.14737824894107 46.61359154302199
In [10]: plt.figure(figsize=(18,12))
        plt.subplot(221)
        plt.imshow(gray,cmap='gray')
        plt.axis("off")
        plt.subplot(223)
        plt.imshow(im_out1,cmap='gray')
        plt.axis("off")
        plt.subplot(224)
        plt.imshow(im_out2,cmap='gray')
```

```
plt.axis("off")
plt.show()
```







2.2.2 方式二

```
for j in range(nx):
                        # 位置信息 边界处理
                        iUp = max(0,i-1)
                        iDown = min(ny-1, i + 1)
                        jLeft = max(0, j - 1)
                        jRight = min(nx-1, j + 1)
                        # 书本 page216
                                        先计算
                                                 deta u
                        deltaN = tmp[iUp,j] - tmp[i,j]
                        deltaS = tmp[iDown,j] - tmp[i,j]
                        deltaE = tmp[i,jRight] - tmp[i,j]
                        deltaW = tmp[i,jLeft] - tmp[i,j]
                        delta_u = np.array([deltaN , deltaS , deltaE , deltaW ])
                        #print(delta_u)
                        # 计算
                                C
                        if (option == 1):
                            c = g(np.abs(delta_u),kappa)
                        elif (option == 2):
                            c = f(np.abs(delta_u),kappa)
                        # 相乘相加 加权赋值
                        res[i,j] += dt * (sum(c * delta_u))
                tmp = res
            return res
In [13]: res = Perona_Malik(src= gray, times =40,dt=.002 ,kappa = 14, option = 1)
        print('原图: ', getImageVar(gray),'\n','PM 算法: ',getImageVar(res))
原图: 24.55965163387333
PM 算法: 23.54068568433893
In [14]: plt.figure(figsize=(18,15))
        plt.subplot(121)
        plt.imshow(gray,cmap='gray')
        plt.axis("off")
        plt.subplot(122)
        plt.imshow(res,cmap='gray')
```

plt.axis("off")
plt.show()





2.3 Gabor 算法

2.3.1 Gabor 第一算法

$$f(x,y) = f(x,y) - t \frac{\partial^2 f}{\partial n^2}$$

```
In [15]: def gabor1(src,t):
            #核四个角度一阶
            ker = np.zeros((3,3,4))
            ker[...,0] = np.array([[0,0,0],
                                  [0,-1,1],
                                  [0,0,0]])
            ker[...,1] = np.array([[0,0,1],
                                   [0,-1,0],
                                   [0,0,0]])
            ker[...,2] = np.array([[0,1,0],
                                   [0,-1,0],
                                   [0,0,0]])
            ker[...,3] = np.array([[1,0,0],
                                   [0,-1,0],
                                   [0,0,0]])
            #核四个角度二阶
```

ker2 = np.zeros((3,3,4))

ker2[...,0] = np.array([[0, 0,0],

```
[1,-2,1],
                                     [0, 0,0]])
            ker2[...,1] = np.array([[0, 0,1],
                                      [0,-2,0],
                                      [1, 0,0]])
            ker2[...,2] = np.array([[0, 1,0],
                                      [0,-2,0],
                                      [0, 1,0]])
            ker2[...,3] = np.array([[1, 0,0],
                                      [0,-2,0],
                                      [0, 0, 1]])
             #四个角度的差分
            d = np.zeros(src.shape +(4,))
            dd = np.zeros(src.shape +(4,))
            for i in range(4):
                d[...,i] = cv2.filter2D(src, -1, ker[...,i])
                dd[...,i] = cv2.filter2D(src, -1, ker2[...,i])
            n_f = np.ones_like(src)
            for row in range(src.shape[0]):
                for col in range(src.shape[1]):
                    # 法向
                    n = np.where( np.abs(d[row,col,:]) ==\
                                 np.max(np.abs(d[row,col,:]) ))[0][0]
                    n_f[row,col] = dd[row,col,n]
            return src - t * n_f
        gabor = gabor1(gray, 0.5)
In [16]: print('原图: ', getImageVar(gray),'\n','PM 算法: ',getImageVar(gabor))
原图: 24.55965163387333
PM 算法: 88.80644580193461
In [17]: plt.figure(figsize=(18,15))
```

```
plt.subplot(121)
plt.imshow(gray,cmap='gray')
plt.axis("off")
plt.subplot(122)
plt.imshow(gabor,cmap='gray')
plt.axis("off")
plt.show()
```





2.3.2 Gabor 第二算法

$$f(x,y) = f(x,y) - t\left(\frac{\partial^2 f}{\partial n^2} - \frac{1}{3}\frac{\partial^2 f}{\partial s^2}\right)$$

```
[0,0,0]])
    #核四个角度二阶
   ker2 = np.zeros((3,3,4))
   ker2[...,0] = np.array([[0, 0,0],
                            [1,-2,1],
                            [0, 0,0]])
   ker2[...,1] = np.array([[0, 0,1],
                             [0,-2,0],
                             [1, 0, 0])
   ker2[...,2] = np.array([[0, 1,0],
                             [0,-2,0],
                             [0, 1,0]])
   ker2[...,3] = np.array([[1, 0,0],
                             [0,-2,0],
                             [0, 0, 1]])
    # 四个角度的差分
   d = np.zeros(src.shape +(4,))
   dd = np.zeros(src.shape +(4,))
   for i in range(4):
        d[...,i] = cv2.filter2D(src, -1, ker[...,i])
        dd[...,i] = cv2.filter2D(src, -1, ker2[...,i])
   n_f = np.ones_like(src)
    s_f = np.ones_like(src)
   for row in range(src.shape[0]):
        for col in range(src.shape[1]):
            # 法向
           n = np.where( np.abs(d[row,col,:]) ==\
                        np.max(np.abs(d[row,col,:]) ))[0][0]
            #切向
            s = (n+2)\%4
           n_f[row,col] = dd[row,col,n]
            s_f[row,col] = dd[row,col,s]
   return src - t * (n_f - s_f /3)
gabor = gabor2(gray, 0.5)
```

```
In [19]: print('原图: ', getImageVar(gray),'\n','PM 算法: ',getImageVar(gabor))
原图: 24.55965163387333
PM 算法: 77.50446275135562

In [20]: plt.figure(figsize=(18,15))
        plt.subplot(121)
        plt.imshow(gray,cmap='gray')
        plt.axis("off")
        plt.subplot(122)
        plt.imshow(gabor,cmap='gray')
        plt.axis("off")
        plt.axis("off")
        plt.show()
```





参考网上

```
abs(nstds * sigma_y * np.cos(theta)))
            ymax = np.ceil(max(1, ymax))
            xmin = -xmax
            ymin = -ymax
            (y, x) = np.meshgrid(np.arange(ymin, ymax + 1), np.arange(xmin, xmax + 1))
            # -----这部分内容是为了确定卷积核的大小-----
            # Rotation
            x_{theta} = x * np.cos(theta) + y * np.sin(theta)
            y_{theta} = -x * np.sin(theta) + y * np.cos(theta)
            # -----这部分正是上面的公式-----
            gb = np.exp(-.5 * (x_theta ** 2 / sigma_x ** 2 + y_theta ** 2 / sigma_y ** 2)) \
                                               * np.cos(2 * np.pi / Lambda * x_theta + psi)
            return gb
In [22]: # 构建 Gabor 滤波器
        # cv2.getGaborKernel(ksize, sigma, theta, lambda, gamma, psi, ktype) 参数说明
        def build_filter():
            ksize = (5,5)
            lamda = np.pi/2.0 # 波长
            direction = 8
            out = np.zeros(ksize)
            for i,theta in enumerate(np.arange(0, np.pi, np.pi / direction)):
                # gabor 方向, 0 度, 22.5 度, 45 度, 67.5 度, 90 度,
                # 112.5 度, 135 度, 157.5 度 共 8 个
                kern = cv2.getGaborKernel(ksize,.7,theta,lamda,\
                                         gamma = 0.5, psi= 0, ktype=cv2.CV_32F)
                #np.maximum(out,kern,out)
                out += kern
            out /= out.sum()
            return out
In [23]: res = cv2.filter2D(gray,-1,build_filter())
        print('原图: ', getImageVar(gray),'\n','PM 算法: ',getImageVar(res))
原图: 24.55965163387333
```

PM 算法: 48.52537066073149

```
In [24]: plt.figure(figsize=(18,15))
        plt.subplot(121)
        plt.imshow(gray,cmap='gray')
        plt.axis("off")
        plt.subplot(122)
        plt.imshow(res,cmap='gray')
        plt.axis("off")
        plt.show()
```





3 图像处理 +180776+ 胡欣毅 (C++ 版)

c++1, c++2