



# Theoretical Computer Science

## Complexity Theory

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- Time and space complexity
- Order of complexity, O-Notation
- Optimization using the example of divide and conquer
- Complexity Classes P, NP
- NP completeness & NP hard problems
- Other problem classes

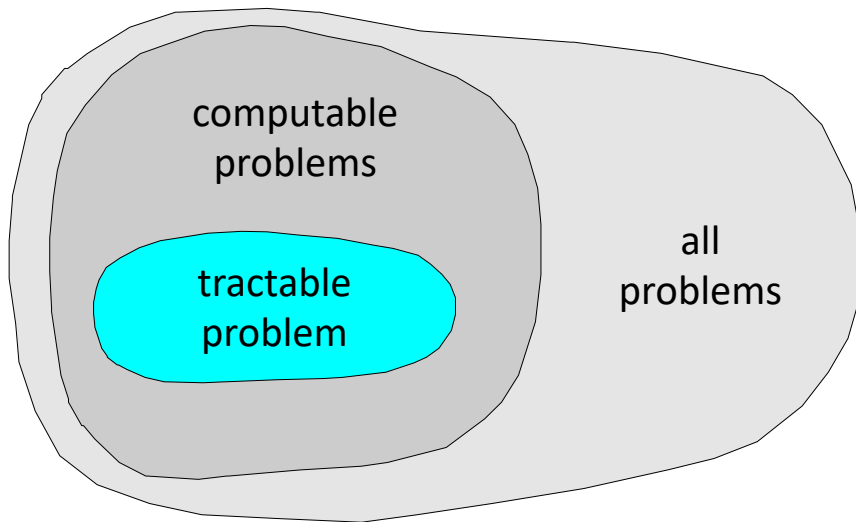
- Previous chapter: computability
  - is a problem in principle solvable with computers – does an algorithm exist?
- Now: How much effort is required for solving a computable problem, in particular
  - **Time complexity** (how much computation time is required dependent on amount of input data?)
  - **Space complexity** (how much memory is required dependent on amount of input data?)
- In the following: Mainly time complexity
  - space complexity is considered using the same methods & notations
  - but is often less important in practice



- Only a part of the computable problems is tractable
- The others take too long or require too much memory for practical purposes

We can consider the time complexity of

- a specific **algorithm**: Number of steps required to solve a problem.
- a **problem**: Time complexity required by an **optimal** algorithm for solving the problem.



- **Worst-case complexity**

- how “long” does the algorithm take maximum (for the “worst-case” structure of input data)
- often: complexity = worst-case complexity

- **Best-case complexity**

- how “long” does the algorithm take at least (with optimal structure of input data)

- **Average-case complexity**

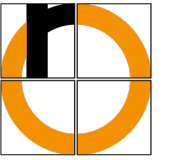
- expected complexity with a typical structure of data (“average runtime”)

**Example:** Linked list containing 20 (or in general:  $n$ ) family names, search for a name

Name is in last element → 20 steps or  $n$  steps

Name is in first element → 1 step

Name is in middle element → 10 steps or  $\frac{n}{2}$  steps



# Order of Complexity

- Dependent on the size of the input data → Parameter  $n$ 
  - How does the algorithm behave when the amount of input data increases?
  - We want **a function**. Not a measured time.
- Omit “unimportant” constants
  - Constant factors such as: computer hardware used, programming language used and its compiler, or clock frequency of the CPU
  - Complexity should only depend on the algorithm, not on the hardware used
- We will look at an upper bound („asymptotic time complexity“)

- $O(f(n)) = \{g: \mathbb{N} \rightarrow \mathbb{N} \mid \exists m > 0, c > 0 \text{ where } \forall n \geq m: |g(n)| \leq c \cdot |f(n)|\}$
- i.e.,  $O(f(n))$  is the **set** of all functions  $g(n)$ ,
  - for which there exist the two constants  $m, c$ ,
  - such that for all  $n \geq m$  it holds that  $|g(n)| \leq c \cdot |f(n)|$
- in other words:  $g(n)$  grows at most as fast as  $f(n)$
- and this applies **asymptotically**, i.e., from a certain point on, for  $n \rightarrow \infty$
- Usual notation:  $g(n) = O(f(n))$ 
  - e.g.,  $g(n) = O(n^2)$
  - technically not correct: „ $\in$ “ should be used (it is a set)
  - Problem: The operator  $=$  is not symmetrical here:  
 $O(n) = O(n^2)$  is true, but not  $O(n^2) = O(n)$



- $f(n) = 50n + 3 = O(n)$ 
  - $c = 51, m = 3$
- $f(n) = 2n^2 - 50n + 3 = O(n^2)$ 
  - $|2n^2 - 50n + 3| \leq 2n^2 + |50n| + 3 \leq 2n^2 + 50n^2 + 3n^2 = 55n^2 = |55n^2|$
  - therefore  $|2n^2 - 50n + 3| \leq 55 |n^2|$
  - and thus:  $c = 55, m = 1$
- In general:
  - **only** the **fastest growing term** is relevant
  - all slower growing terms and constant factors are omitted
- $f(n) = 3 \ln n = O(\ln n)$
- $f(n) = \ln n^c = O(\ln n)$ 
  - $\ln n^c = c \ln n \rightarrow$  constant factor
- $f(n) = 3 \log_2 n = O(\ln n)$ 
  - $\log_2 n = \ln n / \ln 2 \rightarrow$  constant factor
- In general:
  - Base of a logarithm is irrelevant
  - Constant exponents under the logarithm are irrelevant

- $f(n) = \log n - 3n + 2n^3 + 2^n = O(2^n)$
- $f(n) = \log n - 3n + 2n^3 + 10^n = O(10^n)$
- $f(n) = \log n - 3n + 2n^3 + 2^n + 10^n = O(10^n)$
- In general:  
Changing the base of an exponential function is relevant
- $f(n) = 50n + 3 = O(2^n)$
- $f(n) = 2n^2 - 50n + 3 = O(2^n)$
- $f(n) = \ln n - 3n + 2n^3 = O(2^n)$
- $f(n) = 3 \ln n = O(2^n)$
- In general:
  - above statements are correct, but not very helpful
  - we are looking for a **tight** upper bound

- introduced by Paul Bachmann 1894
- named after Edmund Landau (1877 – 1938)
- Here: Two other symbols in addition to O-notation ( $\Omega$ ,  $\Theta$ )

$g = O(f)$	$g$ grows at most as fast as $f$ (upper bound)	$ g(n)  \leq c \cdot  f(n) $
$g = \Omega(f)$	$g$ grows at least as fast as $f$ (lower bound)	$ g(n)  \geq c \cdot  f(n) $
$g = \Theta(f)$	$g$ grows just as fast as $f$	$c_0 \cdot  g(n)  \leq  f(n)  \leq c_1 \cdot  g(n) $

# Typical Orders of Complexity

Name	Complexity	Rating	Examples	Typical Algorithm Structure
Constant complexity	$O(1)$	optimal, rare	Hashing	Most statements are executed only once or a few times.
Logarithmic complexity	$O(\log n)$	very good	Binary search in sorted list	Solve a problem by converting it to a smaller one, while reducing the runtime by a constant proportion.
Linear complexity	$O(n)$	good	Linear search in unsorted list	Optimal case for an algorithm that has to process $n$ input data – each element must be touched exactly once (or constantly often).
Log-linear or quasilinear complexity	$O(n \log n)$	still good	Good sorting sort methods, e.g., Mergesort, Quicksort (on average); FFT	Solve a problem by splitting it into smaller problems that are solved independently and then combined.
Quadratic complexity	$O(n^2)$	poor	Poor sorting methods, e.g., Bubblesort, Quicksort (worst case)	Typical for problems where all $n$ elements need to be processed in pairs (2 nested for loops). Can only be used for relatively small problems.
Cubic complexity	$O(n^3)$	poor	Matrix-Multiplication	3 nested for loops. Can only be used for small problems.
Exponential complexity	$O(a^n)$	disastrous	Travelling-Salesman (cleverly implemented)	Typical for brute-force solutions, e.g., trying out all possible variants. Only few algorithms of this complexity can be used in practice.
Factorial complexity	$O(n!)$	even worse...	Travelling-Salesman (brute-force)	

Note:  $a^n$  grows faster than **any** polynomial  $n^k$  for any  $a > 1$

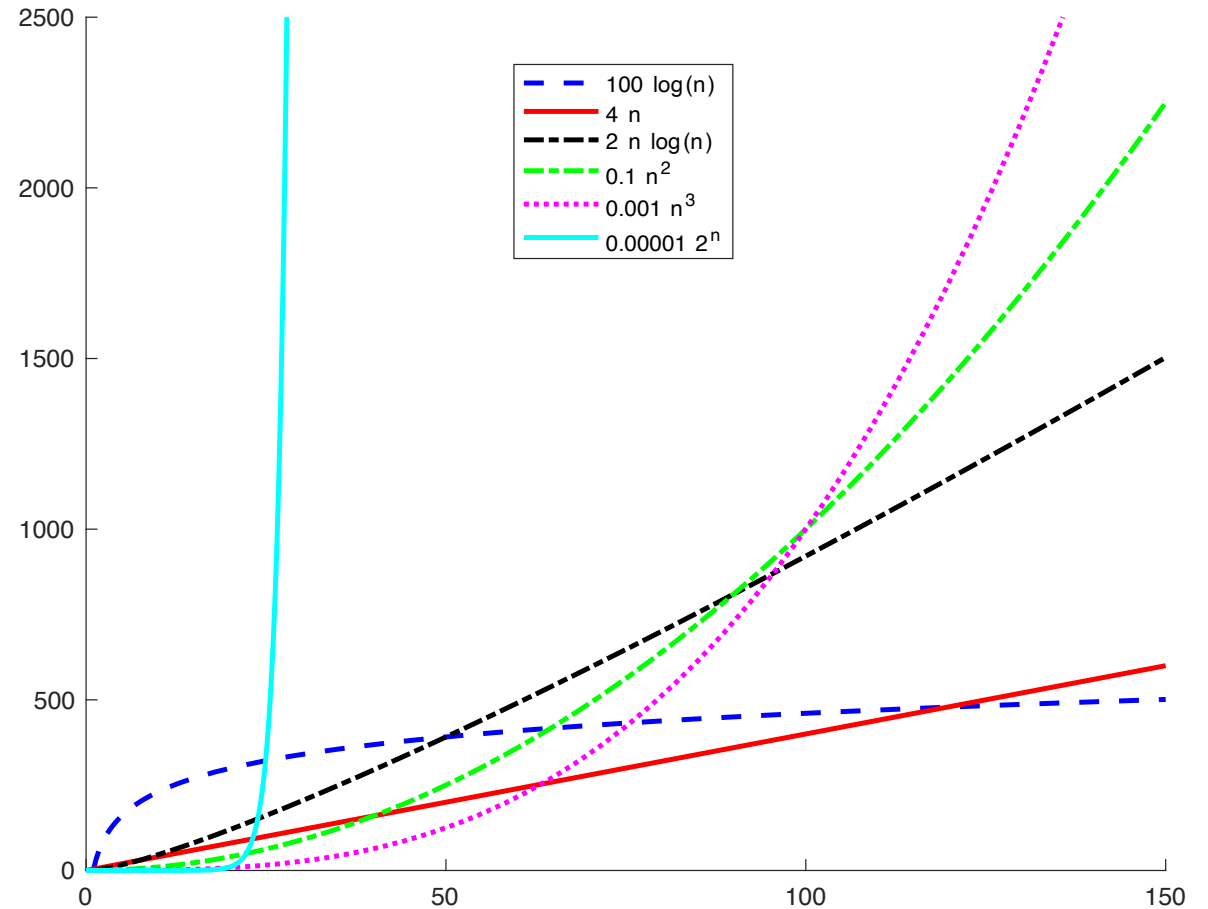
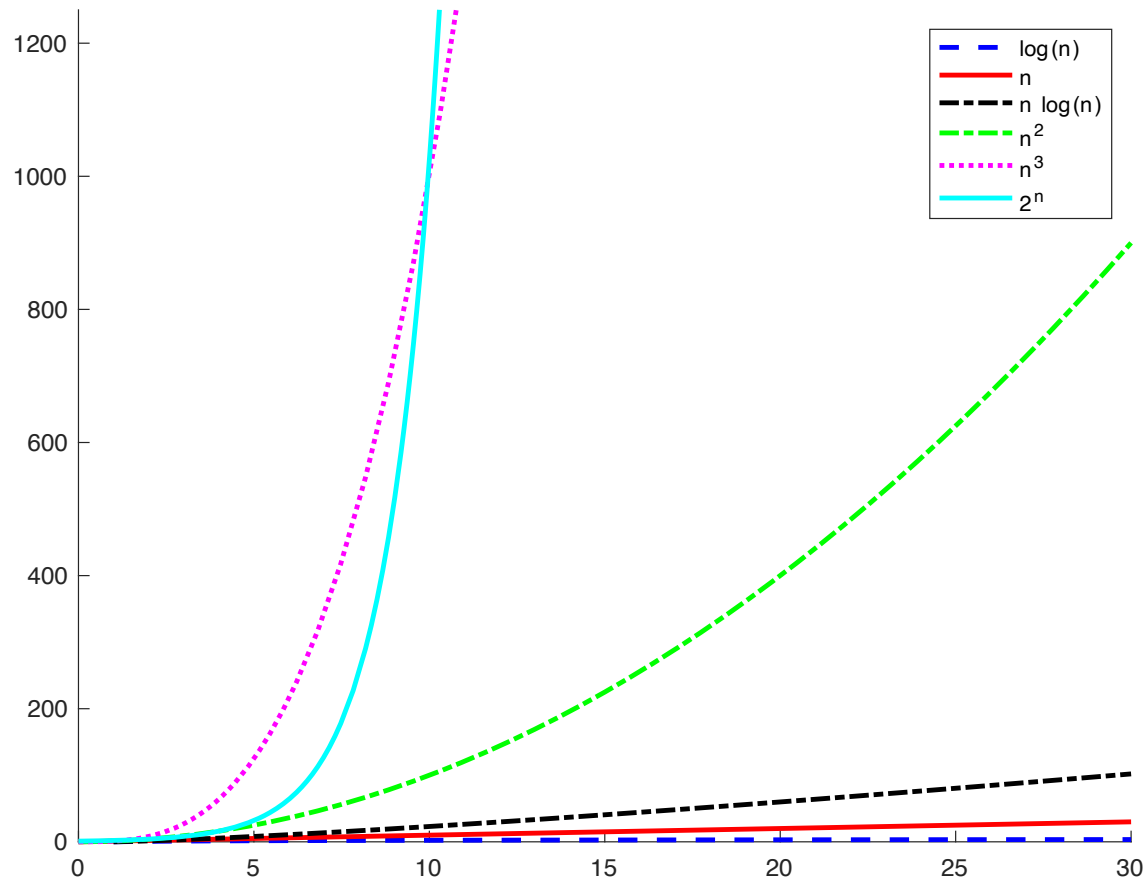
# O-Notation – Examples

$n$	$O(n)$	$O(n^2)$	$O(2^n)$
1	1 $\mu$ sec	1 $\mu$ sec	2 $\mu$ sec
10	10 $\mu$ sec	100 $\mu$ sec	$\sim 1$ msec
100	100 $\mu$ sec	10 msec	$\sim 4 \cdot 10^{16}$ years
1000	1 msec	1 sec	$\sim 8 \cdot 10^{288}$ years

Caution: the O-notation applies only asymptotically for  $n \rightarrow \infty$

$n$	$O(100 \cdot n) = O(n)$	$O(0.1 \cdot n^2) = O(n^2)$	$O(0.0001 \cdot 2^n) = O(2^n)$
1	100 $\mu$ sec	0.1 $\mu$ sec	0.0002 $\mu$ sec
10	1 msec	10 $\mu$ sec	$\sim 0.1$ $\mu$ sec
100	10 msec	1 msec	$\sim 4 \cdot 10^{12}$ years
1000	100 msec	100 msec	$\sim 8 \cdot 10^{284}$ years

# Function Growth – Examples



Basic instructions (no function calls):

```
a = 15;
```

 $O(1)$ 

```
x = x * a;
```

 $O(1)$ 

If we combine these two instructions, we get  
 $O(1) + O(1) = O(2) = O(1)$

No matter how many basic instructions, it's  $O(1)$

Nested loops:

( $n$  = amount of data,  $B$  = block of constant time complexity  $O(1)$ )

```
for(int i = 0; i < n; i++) {  
    B;  
}
```

 $O(n)$ 

```
for(int i = 0; i < n; i++) {  
    for(int j = 0; j < n; j++) {  
        B;  
    }  
}
```

 $O(n^2)$ 

```
for(int i = 0; i < n; i++) {  
    for(int j = 0; j < i; j++) {  
        B;  
    }  
}
```

 $O(n^2)$ 

```
for(int i = 0; i < n; i++) {  
    for(int j = 0; j < 100; j++) {  
        B;  
    }  
}
```

 $O(n)$

Loop, changing loop counter using \* or / instead of + or –:

```
i = 1;
while(i < n) {
    B;
    i = i * 2;
}
```

$O(\log_2 n) = O(\log n)$

Recursion:

```
int factorial(int n) {
    if (n == 0)
        return 1;
    else
        return n * factorial(n-1);
}
```

$O(n)$

Recursion is often hard to analyze

```
int doSomething(int a, int b) {
    // Pre-condition: a < b
    if (a == b)
        return 0;
    else
        return (doSomething(a+1, b) - doSomething(a, b-1));
}
```

$O(2^n)$

(this recursion results in a binary call-tree)



- Typical variants of recursion are considered in the following
  - see also: Divide-and-Conquer formula later in this set of slides
- Formulas for calculating complexity  $C_n$  are given independently of a specific algorithm
- It holds:  $n$  = amount of input data,  $C_n$  = number of steps required in total,  $C_0 = 0$
- Variant 1
  - Loop over input data in each step
  - One element is removed before recursive call

$$C_n = C_{n-1} + n$$

unfold recursion:

$$C_n = 0 + 1 + 2 + \dots + (n-3) + (n-2) + (n-1) + n = \frac{1}{2} n(n+1) = O(n^2 / 2) = O(n^2)$$

- Variant 2

- Loop over input data in each step
- Input data are halved before recursion

$$C_n = C_{n/2} + n$$

$$\begin{aligned} C_n &= \dots + n/8 + n/4 + n/2 + n = \\ &= (\dots + 1/8 + 1/4 + 1/2 + 1) n \\ &= O(2n) = O(n) \end{aligned}$$

- Variant 3

- Effort within a step is constant  
(= independent of input data size)
- Input data are halved before recursion

$$C_n = C_{n/2} + 1$$

$$C_n = \underbrace{1 + 1 + \dots + 1}_{\log_2 n \text{ times}} = O(\log_2 n) = O(\log n)$$

- Variant 4

- Loop over input data in each step
- Input data are split into two halves before recursion

$$C_n = 2C_{n/2} + n$$

$$C_n = O(n \log n)$$

- Variant 5

- Effort within a step is constant  
(= independent of input data size)
- Input data are split into two halves before recursion

$$C_n = 2C_{n/2} + 1$$

$$C_n = O(2n) = O(n)$$

Let  $c$  and  $a_i$  be constants.

- $c = O(1)$
- $c \cdot f(n) = O(f(n))$
- $O(f(n)) + O(f(n)) = O(f(n))$
- $O(O(f(n))) = O(f(n))$
- $g(n) = a_k \cdot n^k + a_{k-1} \cdot n^{k-1} + \dots + a_0 = O(n^k)$
- $O(f(n)) \cdot O(g(n)) = O(f(n) \cdot g(n))$
- $O(f(n)) + O(g(n)) = O(\max\{f(n), g(n)\})$

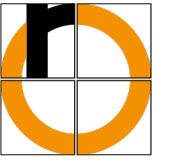
Application to Analysis of Algorithms: How to obtain the total complexity from parts?

**Basic instructions** are  $O(1)$

**Iteration**  $n$ -times in a loop with body  $O(\text{alg})$ :  $O(n \cdot \text{alg})$

**Sequences**  $\text{alg1}; \text{alg2}; \text{alg3};$   
 $O(\text{alg1}) + O(\text{alg2}) + O(\text{alg3}) = O(\max\{\text{alg1}, \text{alg2}, \text{alg3}\})$

**IF THEN**  $\text{alg 1}$  **ELSE**  $\text{alg2}$   
 $O(\max\{\text{alg1}, \text{alg2}\})$



# Algorithm Optimization Using the Example of Divide and Conquer

- Find a better algorithm to solve a given problem
  - better = lower time (or sometimes space) complexity
- Optimization is problem dependent,
- and also, what we count as a relevant operation for time complexity
  - Mathematical algorithms (as the following example): Number of arithmetic operations
    - We'll count multiplications and additions
    - In the past, typically only multiplications were counted (as they used to be many times slower)
  - For searching and sorting: Count number of comparisons required

- How can we compute the value of a polynomial function  $f(x)$  at  $b$ , i.e.,  $f(b)$ ?  
 $f(x) = a_0 + a_1x + a_2x^2 + \dots + a_nx^n$
- Complexity “naïve” method for calculating  $f(b)$ :
  - Calculation of powers  $x^2, \dots, x^n$ :
    - $2 + 3 + 4 + \dots + n = n(n+1)/2 - 1$  multiplications:  $O(n^2/2)$
  - $n$  multiplications by coefficients  $a_i$
  - $n$  additions
  - result:  $n(n+1)/2 - 1 + 2n = O(n^2/2 + 2n) = O(n^2)$
- Re-using powers that have already been calculated
  - in each step only one additional multiplication, total:  $n - 1$
  - results in  $2n - 1$  multiplications and  $n$  additions
  - total:  $3n - 1 = O(3n) = O(n)$

- Horner's method
  - factoring out:  $f(x) = a_0 + x (a_1 + x (a_2 + x (a_3 + \dots + x (a_{n-1} + a_n x) \dots))$
- Complexity
  - $n$  multiplications and  $n$  additions
  - (due to  $O$ -notation it doesn't matter whether it is actually  $n - 1$  or  $n - 2$  or ...)
  - total:  $O(2n) = O(n)$
- Note: The Fast Fourier Transform (FFT) is better still:  
It can be used to evaluate a polynomial at  $n$  positions in parallel with  $O(n \log n)$

- Divide and Conquer:
  - A very important algorithm development paradigm
  - Break down a problem into non-overlapping sub-problems
  - Combine the individual solutions to a complete solution
  - Do this recursively
- Often:
  - Divide data into two parts
  - process these separately
- Examples
  - Quicksort, Mergesort
  - Karatsuba's method for multiplying long integers
  - Fast Fourier transform (FFT)



- Effort to break down a problem of size  $n$  into  $a$  sub-problems of size  $n/b$ :

$$C(n) = a C(n/b) + \Theta(n^k) \quad \text{for } a \geq 1, b, n > 1$$
$$C(1) = 1$$

- $\Theta(n^k)$ : Effort for splitting and combining data in each step

- $C(n)$  can be estimated as follows:

$$C(n) = \begin{cases} \Theta(n^k) & \text{if } a < b^k \\ \Theta(n^k \log n) & \text{if } a = b^k \\ \Theta(n^{\log_b a}) & \text{if } a > b^k \end{cases}$$

$$C(n) = a C(n/b) + \Theta(n^k)$$

$$C(n) = \begin{cases} \Theta(n^k) & \text{if } a < b^k \\ \Theta(n^k \log n) & \text{if } a = b^k \\ \Theta(n^{\log_b a}) & \text{if } a > b^k \end{cases}$$

- $C(n) = 2 C(n/2) + O(n) \rightarrow O(n \log n)$
- $C(n) = 2 C(n/2) + O(n^2) \rightarrow O(n^2)$
- $C(n) = 8 C(n/3) + O(n^2) \rightarrow O(n^2)$
- $C(n) = 9 C(n/3) + O(n^2) \rightarrow O(n^2 \log n)$
- $C(n) = 10 C(n/3) + O(n^2) \rightarrow O(n^{\log_3 10}) = O(n^{2.09})$

# Example: Integer Multiplication

- Multiplication of two integers with  $n$  digits each as taught in school
- Example:

1	2	3	4	5	.	6	7	8	9	0
					7	4	0	7	0	
					8	6	4	1	5	
					9	8	7	6	0	
					1	1	1	1	0	5
+						0	0	0	0	0
					8	3	8	1	0	2
					0	5	0			

Complexity:  $O(n^2)$  – corresponds to the size of the table

Can we do better?

- by Karatsuba and Ofman (1962)
- Idea: Split the  $n$ -digit integers  $A$  and  $B$  into two parts:
  - In the middle, at position  $n/2$

- $A = a_1 10^{n/2} + a_2$  and  $B = b_1 10^{n/2} + b_2$

- Product:

$$\begin{aligned} AB &= (a_1 10^{n/2} + a_2) (b_1 10^{n/2} + b_2) \\ &= a_1 b_1 10^n + (a_1 b_2 + a_2 b_1) 10^{n/2} + a_2 b_2 \end{aligned}$$

- 4  $n/2$ -digit multiplications
- Combination of results:
  - Shift by  $n/2$  and  $n$  digits, respectively
  - Addition



**Complexity:**  $C(n) = 4 C(n/2) + O(n)$   
 $C(n) = a C(n/b) + \Theta(n^k)$

$$C(n) = \begin{cases} \Theta(n^k) & \text{if } a < b^k \\ \Theta(n^k \log n) & \text{if } a = b^k \\ \Theta(n^{\log_b a}) & \text{if } a > b^k \end{cases} \quad 4 > 2^1$$

$\log_2 4 = 2 \rightarrow O(n^2)$  – same as before...

Further re-formulization:

$$\begin{aligned} AB &= (a_1 10^{n/2} + a_2) (b_1 10^{n/2} + b_2) \\ &= a_1 b_1 10^n + (a_1 b_2 + a_2 b_1) 10^{n/2} + a_2 b_2 \\ &= a_1 b_1 10^n + ((a_1 + a_2)(b_1 + b_2) - a_1 b_1 - a_2 b_2) 10^{n/2} + a_2 b_2 \end{aligned}$$

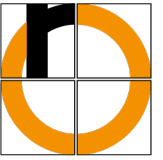
- 3  $n/2$ -digits multiplications (instead of 4)
- Combination of results:
  - Shift by  $n/2$  and  $n$  digits, respectively
  - Addition

**Complexity:**  $C(n) = 3 C(n/2) + O(n)$   
 $C(n) = a C(n/b) + \Theta(n^k)$

$$C(n) = \begin{cases} \Theta(n^k) & \text{if } a < b^k \\ \Theta(n^k \log n) & \text{if } a = b^k \\ \Theta(n^{\log_b a}) & \text{if } a > b^k \end{cases} \quad 3 > 2^1$$

$$\log_2 3 = 1.585 \rightarrow O(n^{1.585})$$

- Of course, this applies to any number system
  - and is typically implemented in base 2
- You can still do better:
  - does not have a big impact in practice, however
  - Schönhage-Strassen (1971):  $O(n \log n \log \log n)$
  - Fürer (2007):  $O(n \text{ld} n 2^{O(\text{ld}^* n)})$ 
    - where  $\text{ld}^* n$  = the smallest  $i$ , for which  $\text{ld} \text{ld} \dots \text{ld} n \leq 1$ , where  $i$  = #times  $\text{ld}$  (base 2 log) has been used
    - Examples:
      - $\text{ld}^* 2 = 1$ ,  $\text{ld}^* 4 = 2$ ,  $\text{ld}^* 16 = 3$ ,  $\text{ld}^* 65536 = 4$
    - Publication: <https://wwwmath.uni-muenster.de/u/cl/WS2007-8/mult.pdf>
  - Covanov and Thomé (2016):  $O(n \text{ld} n 2^{2\text{ld}^* n})$ 
    - Publication: <https://arxiv.org/abs/1502.02800>
  - Harvey and van der Hoeven (2018):  
 $O(n \text{ld} n 2^{2\text{ld}^* n})$  is a **lower bound** for complexity
    - Publication: <https://arxiv.org/abs/1802.07932>



# Complexity Classes $P - NP$

- The existence of an algorithm is no guarantee that the problem can be solved in practice
  - computation time or memory (space complexity) may be too high to be useful
- Questions:
  - Which complexity orders are still acceptable?
  - Can we define a class of tractable problems?



Problem size that can be handled in 1 hour

Complexity	Problem Size Today	Using a 100x Faster Computer	Using a 1000x Faster Computer
$n$	$N_1$	$100 N_1$	$1000 N_1$
$n^2$	$N_2$	$10 N_2$	$32 N_2$
$n^3$	$N_3$	$4,6 N_3$	$10 N_3$
$n^5$	$N_4$	$2,5 N_4$	$4 N_4$
$2^n$	$N_5$	$N_5 + 6,6$	$N_5 + 10$
$3^n$	$N_6$	$N_6 + 4,2$	$N_6 + 6,3$

Observation: With exponential complexity, a faster computer is practically useless!

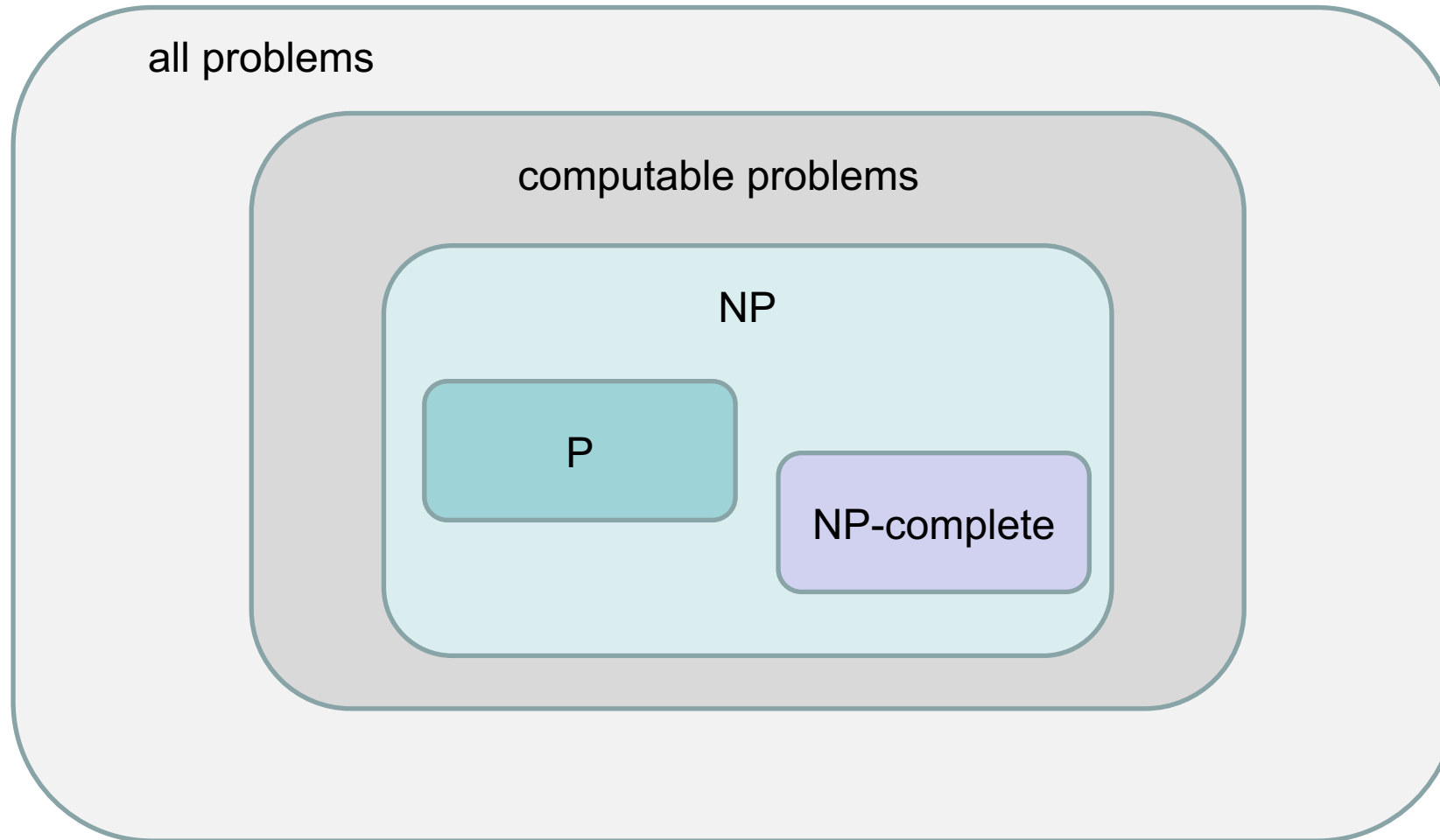
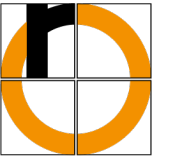
- A decision problem is called **efficiently solvable (or tractable)** if there is an algorithm with time complexity  $O(p(n))$ 
  - $p(n)$  is a polynomial of any degree
  - i.e., algorithms with polynomial runtime
- **Class P** contains all decision problems that can be **solved** by a **deterministic** Turing Machine in **polynomial** time, i.e., all tractable problems

- **Class NP** contains all decision problems that can be solved by a **nondeterministic** Turing Machine in polynomial time
- NP stands for **N**ondeterministic **P**olynomial time
- obviously:  $P \subseteq NP$ 
  - any deterministic TM is also a nondeterministic TM that has no choice in state transitions
  - however, a nondeterministic TM can, in polynomial time
    - “Guess” an exponential number of solutions
    - and check them in parallel
- NP contains all **efficiently verifiable** decision problems
  - the nondeterministic TM “guesses” the solution in polynomial time
  - which can then be checked for correctness in polynomial time by a deterministic TM

- Given: A natural number  $n$
- Sought: Decomposition into prime factors
  - or, weaker: Integer Factorization – decomposition into integer factors
- Factorization is time-consuming: What are the prime factors of 8633?
- Verification of a solution is easy:
  - Factors:  $89 \cdot 97 = 8633$
- Notes:
  - The problem above is not a decision problem, but can easily be formulated as one:  
Does  $n$  have a prime factor smaller than some integer  $k$ ?
  - Whether prime factorization actually is difficult is an open problem ... it's probably not in P, but also not as complicated as some other problems (the NP-complete ones)

- *Erfüllbarkeitsproblem der Aussagenlogik*
- Given: Propositional logic formula (*Aussagen-)logischer Ausdruck*): AND  $\wedge$ , OR  $\vee$ , NOT  $\neg$
- Sought: Are there variable values for which the expression is “true”?
- Searching is time-consuming:  $(\neg x_1 \vee x_2) \wedge x_3 \wedge (x_2 \vee x_3) \wedge (x_1 \vee x_2 \vee \neg x_3)$
- Checking is easy:  $x_1 = 0, x_2 = 1, x_3 = 1$
- Note: this problem is proven to be difficult...

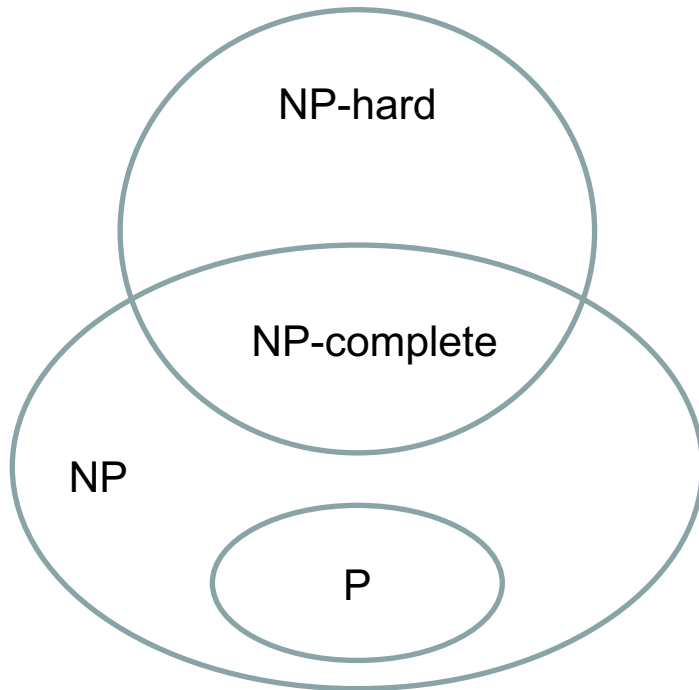
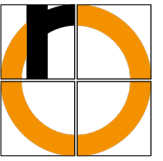
- Arguably **the** most important question of theoretical computer science: Is  $P = NP$ ?
  - are the two problem classes perhaps not different at all?
  - this problem has been open since the 1970s and has not yet been solved
  - it was added to the list of Millennium Problems in 2000
    - contains 7 unsolved problems of mathematics (6 of them still open)
    - a prize money of 1 million US dollars is offered for the proof  
<https://www.claymath.org/millennium-problems/p-vs-np-problem>
- Significance
  - there are a lot of problems
    - of which you can easily show that they are in NP
    - for which, however, no polynomial algorithm is known so far
  - it could be that we just have not found one yet ( $P = NP$ )
    - This would mean: All efficiently verifiable decision problems are efficiently solvable
  - or that none exists ( $P \neq NP$ )
- General belief:  $P \neq NP$



Assumption:  $P \neq NP$

- A problem  $X$  is called **NP-hard** (*NP-schwer*) if it is at least as difficult as any problem in NP
  - i.e., for all problems  $L \in \text{NP}$ :  $L \leq_p X$  (polynomial-time reduction)
- A problem  $X$  is called **NP-complete** (*NP-vollständig*) if it is NP-hard and is in NP
- Polynomial-time Reduction (*polynomielle Reduktion*)
  - A decision problem  $A$  is called **polynomial-time reducible** to  $B$  if there is an algorithm  $f$  with **polynomial** complexity that transforms an input  $x$  of  $A$  into an input  $f(x)$  of  $B$ , such that both result in the same output:  
We can solve  $A$  by transforming its input it in polynomial time to  $B$ , and then solve  $B$  instead.
  - Notation:  $A \leq_p B$
  - In particular, this means:
    - if  $A \leq_p B$  and  $B$  is efficiently solvable ( $B \in P$ ), then  $A$  is also efficiently solvable ( $A \in P$ )
    - if  $A \leq_p B$  and  $B$  is efficiently verifiable ( $B \in \text{NP}$ ), then  $A$  is also efficiently verifiable ( $A \in \text{NP}$ )
- Note:
  - no exact equivalence transformation of problems  $A$  and  $B$  is required
  - but: both give the same solution, i.e., a “yes” or “no” answer ( $A$  &  $B$  are decision problems)





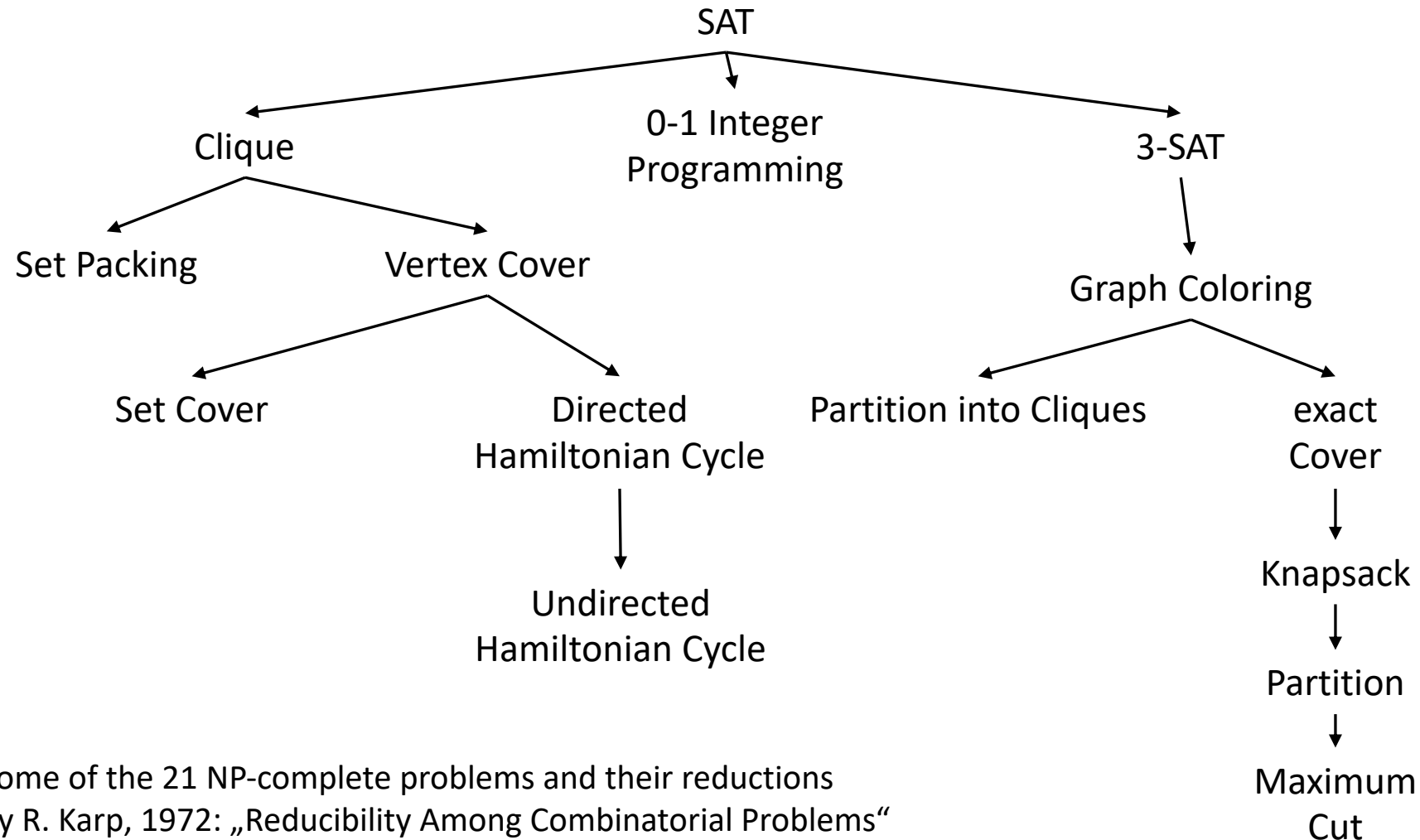
Assumption:  $P \neq NP$

- NP-complete = the most difficult problems of class NP
- If there is **even a single** NP-complete problem in P, then  $P = NP$ 
  - as all problems in NP can then be reduced to it polynomially
  - proof of a problem as being NP-complete thus is practically synonymous with the fact that there are (likely) no efficient algorithms for this problem
- if we have a first NP-complete problem C, we can show the NP-completeness of other problems X by polynomial-time reduction of X to C:  $C \leq_p X$

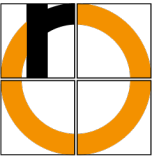
- Do NP-complete problems exist at all?
- Yes: **Boolean Satisfiability Problem (SAT)**
  - the first problem proven to be NP-complete
  - Proof 1971 by S. Cook
    - „The Complexity of Theorem Proving Procedures”
    - In 1982 he received the Turing Award
- Given: Propositional logic formula  $F$
- Sought: Is  $F$  satisfiable? I.e., are there variable values from  $\{0, 1\}$  for which  $F$  is 1?
- Proof consists of two parts
  - $SAT \in NP$  (not so complicated)
    - Principle: NTM “guesses” solution and checks its correctness (in polynomial time)
  - SAT is NP-hard (more difficult...)
  - For details see literature

- **Any problem in NP is polynomial-time reducible to SAT:**  $X \leq_p \text{SAT}$ ,  $X \in \text{NP}$
- Deterministic algorithms for solving SAT have exponential complexity  $2^{O(n)}$ 
  - typical brute-force solution: try all variable combinations
  - this results in an upper bound for the complexity of all problems in NP of  $2^{p(n)}$ 
    - $p(n)$  is a polynomial
- Note:
  - We consider **decision** problems here
    - i.e., problems that can be answered by “yes” or “no”
  - Finding the actual solution can be even more difficult

- We can now easily show that **other problems X** are also **NP-complete**: **Reduce SAT to X**
  - $SAT \leq_p X$  (= solve SAT by transforming its input to X, then solve X)
  - X is at least as hard as SAT, but still in NP (it's a polynomial-time transformation!)
- Several thousand NP-complete problems are known, from various domains
- A selection can be found, e.g., here:  
[http://en.wikipedia.org/wiki/List\\_of\\_NP-complete\\_problems](http://en.wikipedia.org/wiki/List_of_NP-complete_problems)
- If you find an algorithm with polynomial time complexity for **any** one of them, then you
  - automatically have a polynomial algorithm for all problems in NP
  - have proven that  $P = NP$
- If you can show of **any** one of them that it is not in P, then
  - none of them is in P
  - and we have  $P \neq NP$

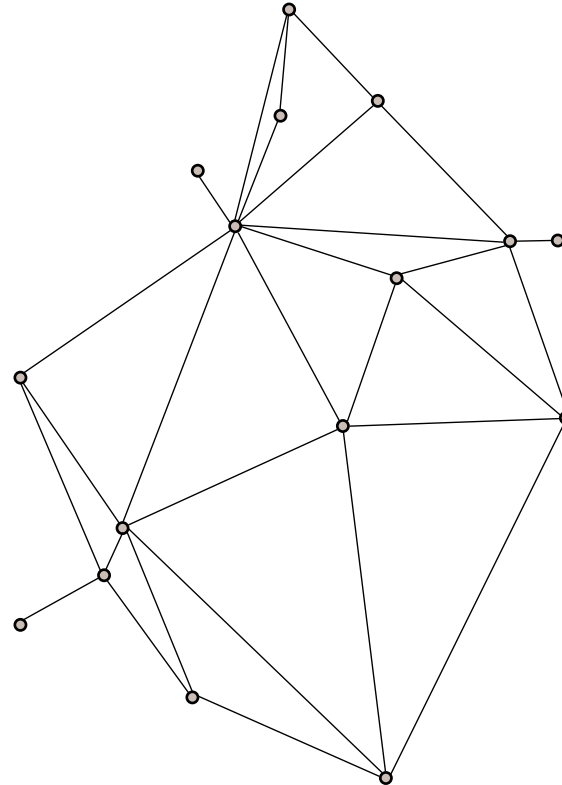
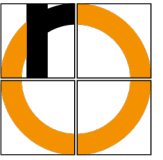


- Restriction of SAT
- Given: Propositional logical formula  $F$  in conjunctive normal form (CNF) with a maximum of 3 variables per term
- Sought: Is  $F$  satisfiable? I.e., are there variable values from  $\{0, 1\}$  for which  $F$  is 1?
- It can be shown:  $\text{SAT} \leq_p \text{3-SAT} \rightarrow \text{3-SAT is NP-complete}$
- Notes:
  - any logical formula can be transformed into CNF
  - however, this requires exponential effort, and we need a polynomial reduction
  - Luckily, polynomial reduction does not require exact equivalence,
  - but only: if  $F$  can be fulfilled, then the transformed formula  $F'$  can also be fulfilled (and vice versa)
- all  $k$ -SAT problems with  $k \geq 3$  are NP-complete
- 2-SAT, on the other hand, is in P



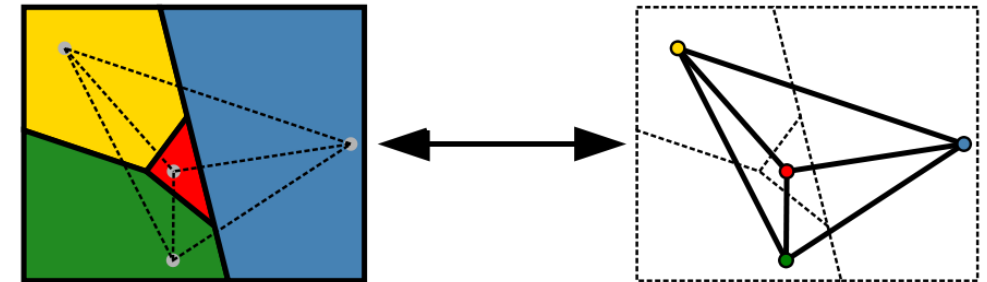
Is it possible to color a map with  $k$  colors in such a way that neighboring countries always have different colors?





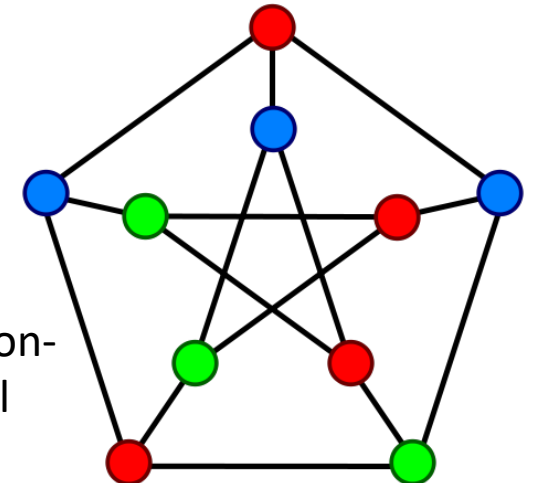
This is the **graph coloring** (*Graphfärbung*) problem:

- the vertices are colored,
- the edges define neighborhood.



© [Inductiveload](#), [Four Colour Planar Graph](#), [CC BY-SA 3.0](#)

We can do this for non-planar graphs as well



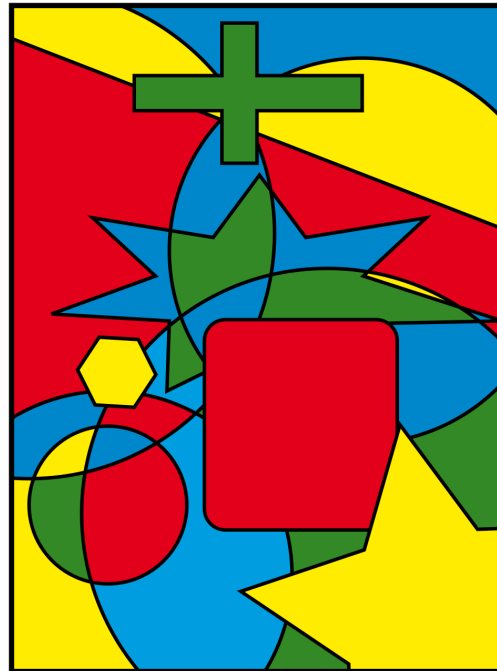
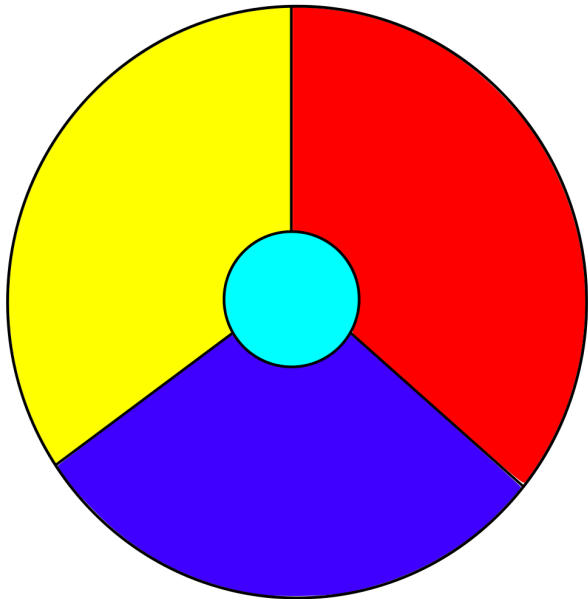


- General graphs
  - k-coloring for  $k \geq 3$  is NP-complete
  - 2-coloring is in P
- Planar graphs
  - 2-coloring is in P
  - 3-coloring is in NP-complete
  - k-coloring for  $k \geq 4$  has **constant runtime**!
- Reminder:  
We consider the **decision** problem:  
Can the graph be colored using k colors?

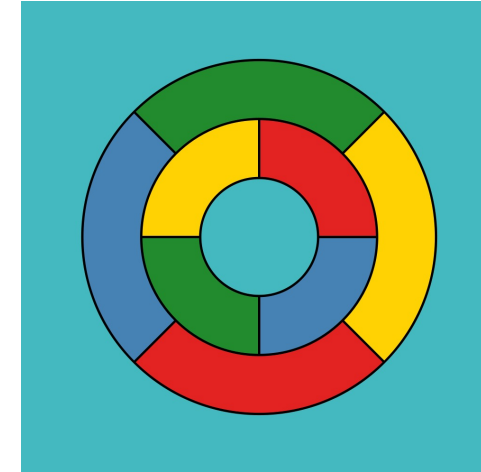
## The **Four Color Theorem**

- 4 colors are always sufficient to color a planar graph (map)
- Assumption existed since 1852
- One of the first problems proven with the help of a computer system (1976)
- A formal proof with the help of a theorem prover followed in 2004

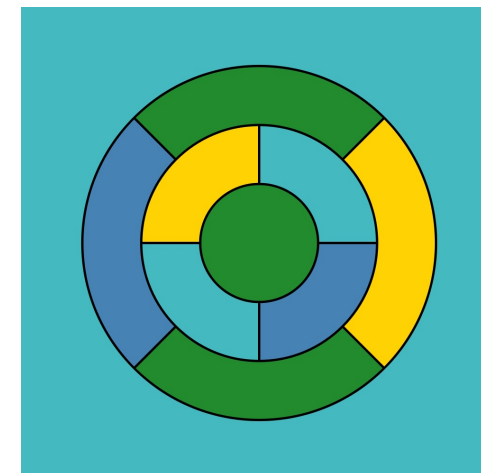
# Four Color Theorem



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Coloring using 5 colors...



...but 4 suffice.

In addition to coloring maps, many other applications

- Scheduling
  - Scheduling processes in operating systems
  - Assignment of aircraft to flights
  - Allocation of bandwidth to radio/television stations, mobile communications, ...
  - Creating class schedules (with constraints regarding rooms, students, teachers)
- Compilers
  - which variable values are kept in registers?
- Sudoku
  - special graph, 81 nodes, 9 colors

- Given:  $n$  cities, as well as the distances (km, time, cost, ...) in between
- Sought: Which sequence of cities is the shortest round trip?
  - all cities should be included exactly once
  - as a decision problem: Is there a round trip with a length smaller than a given constant  $k$ ?
- Corresponds to Hamilton circles in graphs
  - each city is a vertex
  - every connection between cities is an edge
  - the distance corresponds to an edge weight

- TSP (decision problem) is NP-complete
  - the time complexity of the naïve solution is even  $O(n!)$ 
    - this would not be in NP; remember: an upper bound for the complexity of all problems in NP is  $O(2^{p(n)})$
  - good algorithms reduce this to  $O(2^n)$
- TSP (actual solution) is NP-hard
- How hard it is  $O(n!)$ ?
  - suppose you need a computation time of 1 second for the shortest round trip through 10 cities
  - then, for 20 cities, 670 442 572 800 seconds are needed = 21259 **years**

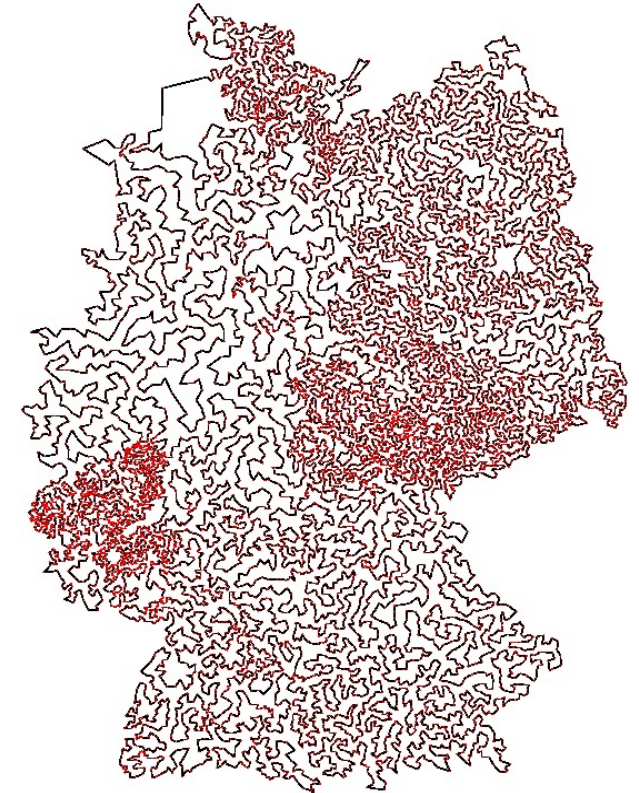
# TSP – Example



- Round trip through the 15 largest cities in Germany
- There are  $14! / 2$  different round trips
  - $14! / 2 = 43\,589\,145\,600$
- The one shown is the shortest round trip



- Round trip through 15,112 German cities (2001)
  - Use of 110 CPUs
  - equivalent computing time (500MHz Alpha CPU): **22.6 years**
- Round trip through 24,978 Swedish cities (2004)
  - Length: 72,500 km
  - Linux-Cluster with 96 Intel Xeon 2.8GHz CPUs (dual core)
  - equivalent computing time (2.8GHz dual core Xeon): **84.8 years**
- Layout of electronic circuits
  - 85,900 nodes (2005/06) – the current record for TSP
  - equivalent computing time (2.4GHz AMD Opteron): **136 years**



(c) <https://www.math.uwaterloo.ca/tsp/gallery/itours/d15112.html>

- For more examples & data see: <http://www.math.uwaterloo.ca/tsp/optimal/index.html>

- We do not have any efficient algorithms to find **optimal** solutions to problems like TSP or creating class schedules
  - Highly likely, these do not exist (assumption:  $P \neq NP$ )
  - Note: Even if  $P = NP$ , we would not have an efficient algorithm for round trips, as we are not interested in the decision problem but rather the actual round trip (which is NP-hard but not NPC)
- In practice: Find approximations using optimization algorithms
  - these find **suboptimal** solutions, but much faster
  - based, e.g., on (non-linear) numerical optimization, statistics, or probabilistic algorithms
  - in some cases, like TSP, we can establish lower bounds and give estimates on the solution's quality

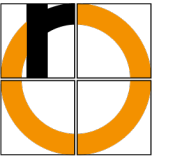




- 1,904,711 city locations throughout the world
- Best tour found so far (15 Feb 2021): 7,515,755,956 m
  - not starting from scratch,
  - but based on a tour of length 7,515,767,286 m on 11 Feb 2021
  - difference: 11,330 m
  - this is considered a huge improvement!
- Improvement between Oct 2011 and June 2020: 7,604 m
- A lower bound for the tour is 7,512,218,268 m
  - difference to best solution so far: 3,549,018 m (= 0.0471%)
- Details & data see: <https://www.math.uwaterloo.ca/tsp/world/index.html>



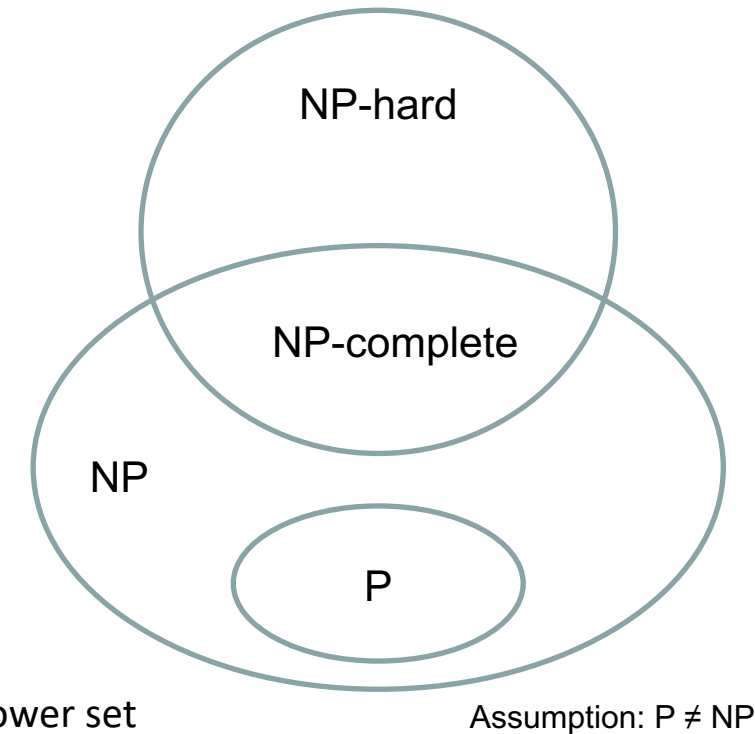
(c) <https://www.math.uwaterloo.ca/tsp/world/index.html>



# Other Problem Classes



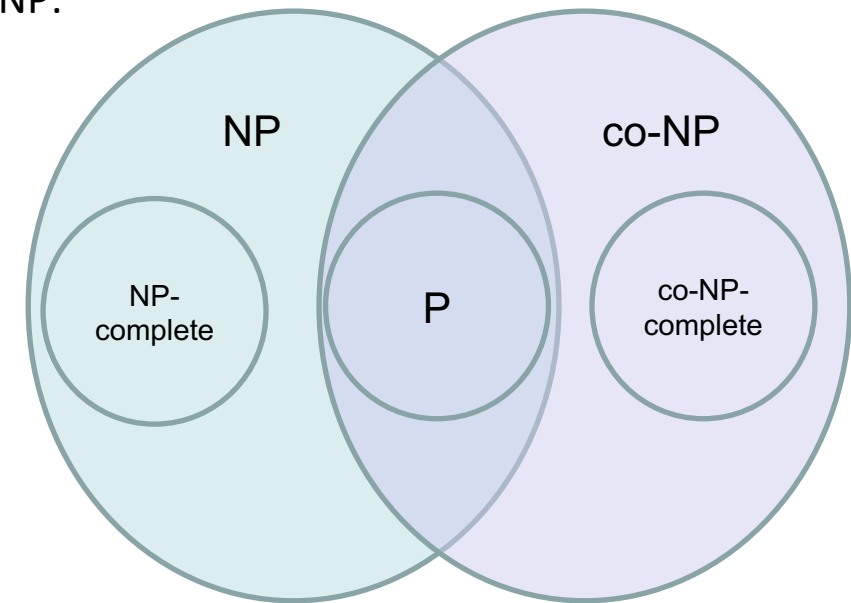
- Proof that problems lie in NP is not possible here
- so these are even more difficult than NP-complete problems
- Examples:
  - Word problem for type-1 languages
  - Inequivalence of regular expressions
    - and thus: for regular grammars or nondeterministic finite automata
    - Note: Equivalence of **deterministic** finite automata is in P
      - Conversion nondeterministic  $\rightarrow$  deterministic requires construction of the power set
      - and thus has exponential complexity

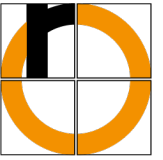


Assumption:  $P \neq NP$

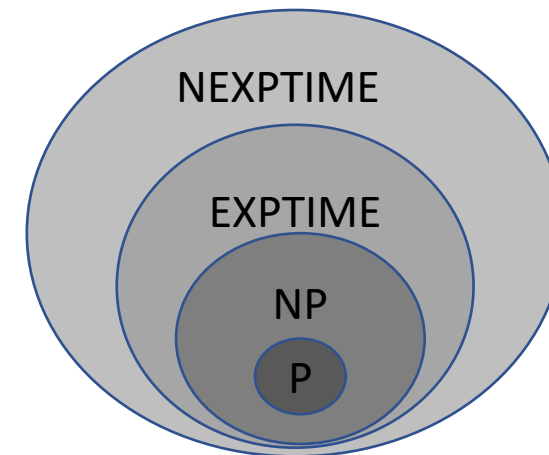


- **co-NP**: Set of decision problems whose **complements** are contained in NP
- Example: The PRIMES problem
  - „Is a number prime?“ is in NP
  - „Is a number not prime (= composed)? “ is in co-NP
- Since P is closed with regard to complement, we do know for sure:  $P = \text{co-P}$
- General belief:  $\text{NP} \neq \text{co-NP}$ 
  - if it can be proven for any NP-complete problem that it is in both, NP and co-NP:  
 $\text{NP} = \text{co-NP}$
  - so far none has been found, hence the general belief
  - in the case of  $P = \text{NP}$ :  $\text{NP} = \text{co-NP}$  holds
- By the way, PRIMES is in NP **and** co-NP
  - this is a very strong indication that a problem is not NP-complete
  - and in fact, PRIMES is in P
  - a polynomial algorithm was published in 2002



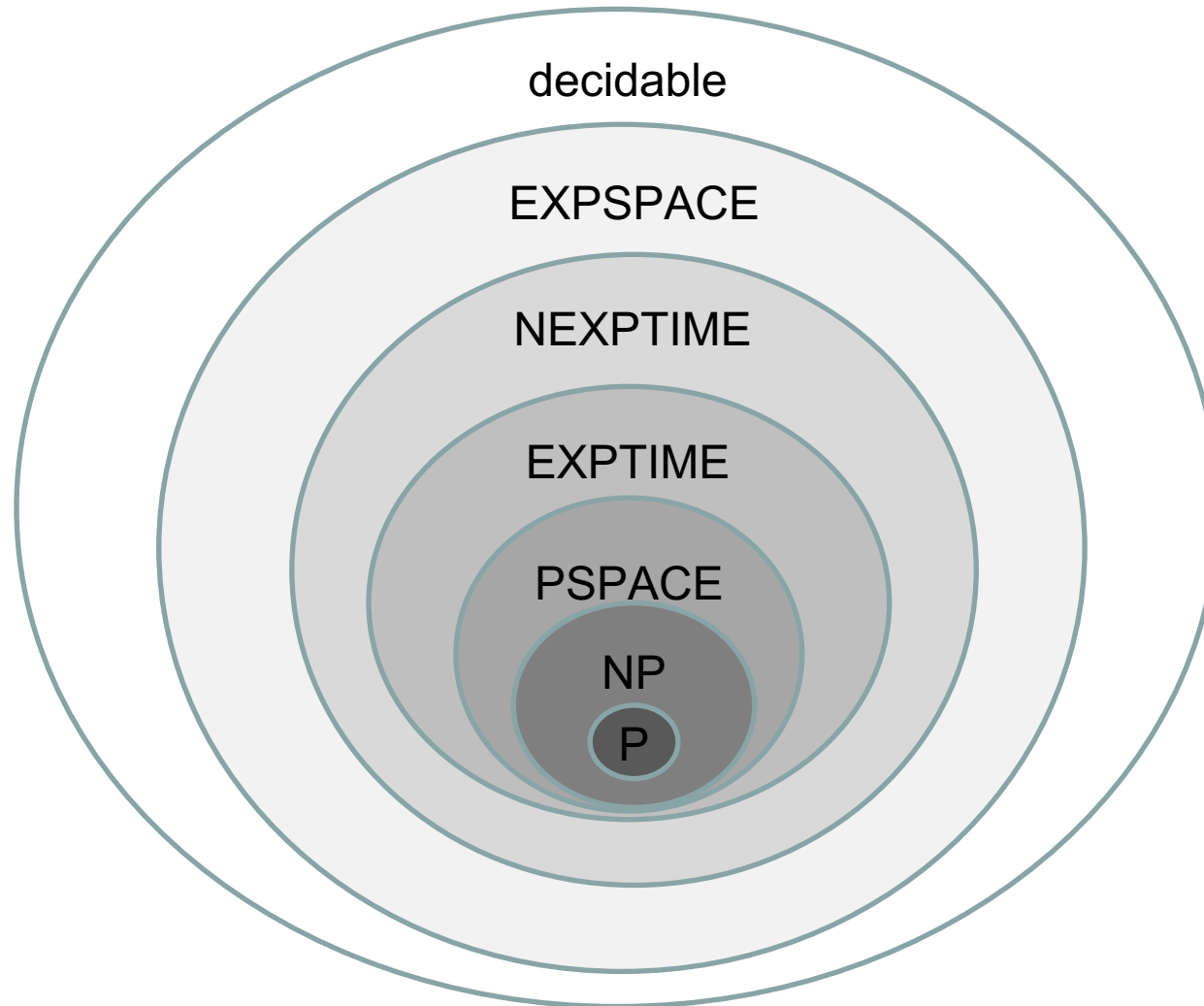
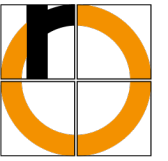


- EXPTIME
  - Set of all decision problems that can be solved by a **deterministic** TM in time  $O(2^{p(n)})$ 
    - $p(n)$  is a polynomial
  - there are EXPTIME-complete problems, e.g.,
    - modified halting problem: Does a deterministic TM halt after at most  $k$  steps?
    - Position analysis for generalized chess, checkers, go (arbitrary number of pieces on arbitrary sized board)
- NEXPTIME
  - corresponding class for nondeterministic TM
- Remarks
  - if  $P = NP$ , then  $EXPTIME = NEXPTIME$
  - But:  $P \subsetneq EXPTIME$  and  $NP \subsetneq NEXPTIME$



- PSPACE
  - Set of all decision problems that can be solved by a **deterministic** TM with **polynomial space**
- NPSPACE
  - corresponding class for nondeterministic TM
- Obviously:  $P \subseteq PSPACE$  and  $NP \subseteq NPSPACE$ 
  - a TM can write at most polynomial many symbols to the tape in a polynomial number of steps (time)
- It can be proven:  $PSPACE = NPSPACE$
- There are PSPACE-complete problems, e.g.,
  - Word problem for type-1 languages
  - Satisfiability of Boolean formulas with quantifiers ( $\forall, \exists$ )

- EXPSPACE
  - Set of all decision problems that can be solved by a **deterministic** TM with **space**  $O(2^{p(n)})$ 
    - $p(n)$  is a polynomial
- NEXPSPACE
  - corresponding class for nondeterministic TM
- It holds
  - $\text{EXPSPACE} = \text{NEXPSPACE}$
  - $\text{PSPACE} \subsetneq \text{EXPSPACE}$
  - $\text{EXPTIME} \subseteq \text{EXPSPACE}$  (likely:  $\text{EXPTIME} \subsetneq \text{EXPSPACE}$ )
- There are EXPSPACE-complete problems, e.g.,
  - Do two given regular expressions define different languages?



And there are more..., e.g.,

- for probabilistic algorithms
- below P
- for quantum computers
- to consider the calculation of a solution instead of the decision problem (the functional problem)



- Order of complexity: O-Notation
  - is asymptotic
  - efficiency: separation between polynomial and exponential complexity
  - in practice, it will already get hard from approx.  $O(n^4)$
- Complexity Classes
  - P: Decision problems that can be solved by a deterministic TM in polynomial time
  - NP: as P for deterministic TM  $\rightarrow O(2^{p(n)})$  for deterministic algorithms
- NP-completeness
  - Problems that are NP-hard and completely contained in NP
  - They are all connected by polynomial-time reduction
  - Whether  $P = NP$  is one of the great unsolved problems of computer science
  - Belief, based on many indications:  $P \neq NP$
  - There are a lot of NP-complete problems with practical relevance

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