$$\frac{\partial f}{\partial x} = y^{2}(x-1) + x^{2}(x+1) = xy^{2} - y^{2} + x^{3} + x^{4}$$

$$\frac{\partial f}{\partial x} = y^{2} + 3x^{2} + 2x$$

$$\Rightarrow P_{n}(0|0)$$

$$\frac{\partial f}{\partial x} = 2xy - 2y$$

$$\frac{\partial f}{\partial y} = 6x + 2$$

$$\frac{\partial^{2} f}{\partial y^{2}} = 2x - 2$$

$$\frac{\partial^{2} f}{\partial y^{2}} = 2y$$

$$\Rightarrow P_{2}(1|1\sqrt{5}i)$$

$$P_{3}(1|1-\sqrt{5}i)$$

$$P_{4}(0|0)$$

$$P_{5}(0|0)$$

$$P_{5}(0|0)$$

$$P_{7}(0|0)$$

$$P$$

The sufficient condition of second order is just a sufficient condition since in some cases you can tell that all Points are above the minima. In the example $x^2 + y^4$, the minima is the origin and every other possible point P(x,y) is greater than 0 on the z-achsis. Therefore you don't need any Hessian to determine the type of (0|0).

/3 By the necessary condition of first order, you can tell where a stationary point is if you know where the gradient of x equals zero.

$$h(x,y) = x^2y^2 + x^4 - 2x^2 + 1$$

$$\nabla h(x,y) = \begin{pmatrix} \frac{\partial h}{\partial x} \\ \frac{\partial h}{\partial y} \end{pmatrix} = \begin{pmatrix} 2xy^2 + 4x^3 - 4x \\ 2yx^2 \end{pmatrix}$$

$$O = 2 \times x^2$$

$$0 = 2 \cdot 0 \cdot 0$$

$$O = 2 \times y^{2} + 4 \times^{3} - 4 \times$$

$$O = 2 \times y^{2} \qquad -> O = 2 \cdot 0 \cdot 0^{2}$$

$$Y = 0 \qquad -> P_{1}(0|0)$$

$$X = 0$$

$$0 = 2.0.0^2 + 4.0^3 - 4.0$$

$$Cet x = 0:$$

$$0 = 2.0 \cdot y^{2} + 4.0^{3} - 4.0$$

$$0 = 2 \times \cdot 0^2 + 4 \times^3 - 4 \times$$

$$O = 4x^3 - 4x$$

$$0 = \times (4 \times^{2} - 4)$$

$$P_{1}(0|0) \qquad P_{3} (-1) = 0$$

By the sufficient condition, calculating the Hessian determines the type of these points.

$$H = \begin{pmatrix} 2y^2 + 12x^2 - 4 & 4xy \\ 4xy & 2x^2 \end{pmatrix}$$

$$D_2 = 24 - 8 > 0$$

$$\frac{\partial^2 h}{\partial^2 x} : 72 - 4 > 0 - > local min P_2$$

$$D_3 = 24 - 8 > 0$$

$$\frac{\partial^2 h}{\partial^2 x}$$
: 12-430 -> local min P_3