

# Deep Learning

Self-supervised Learning

Technische Hochschule Rosenheim Sommer 2023 Prof. Dr. Jochen Schmidt

#### Acknowledgements



Many of the slides presented here are based on the Deep Learning Slides Summer Semester 2020, courtesy of **A. Maier, V. Christlein, K. Breininger, F. Denzinger, F. Thamm**, Pattern Recognition Lab, Friedrich-Alexander-University Erlangen-Nürnberg. <a href="https://lme.tf.fau.de/">https://lme.tf.fau.de/</a>

### Supervised Learning



- We have seen impressive results achieved with...
  - large amounts of training data and
  - consistent, high-quality annotations.



Mask R-CNN image source [MAT19]

#### The Cost of Annotation



Image-level class labels: ~27 sec



Instance spotting: +14 sec



Instance Segmentation: +80 sec



Source: [Lin14]

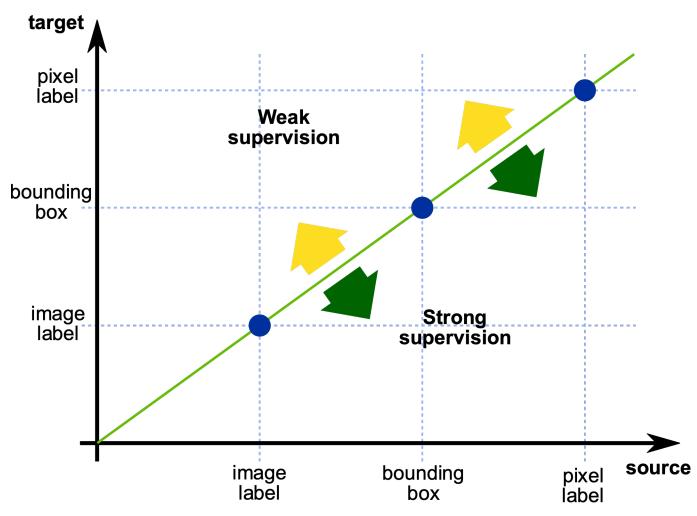


Dense pixel-level annotations: 1.5h

Source: [Cor16]

# Strongly vs Weakly Supervised Learning



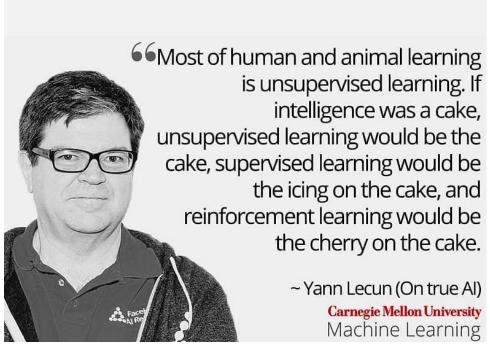


Reproduced from CVPR18 Tutorial: Weakly Supervised Learning for Computer Vision

# Self-supervised Learning – Motivation



- Jitendra Malik: "Supervision is the opium of the AI researcher"
- Alyosha Efros: "The AI revolution will not be supervised"
- Yann LeCun:

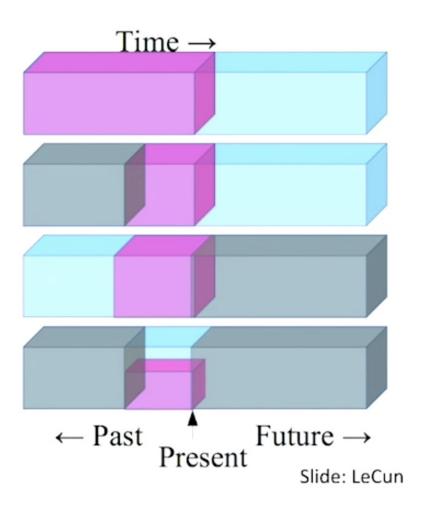


Source: https://www.facebook.com/722677142/posts/10156036317282143/

#### Self-supervised Learning – Idea



- Predict any part of the input from any other part.
- Predict the future from the past.
- Predict the future from the recent past.
- Predict the past from the present.
- Predict the top from the bottom.
- Predict the occluded from the visible
- Pretend there is a part of the input you don't know and predict that.



Source: <a href="https://www.youtube.com/watch?v=710Qt7GALVk">https://www.youtube.com/watch?v=710Qt7GALVk</a>

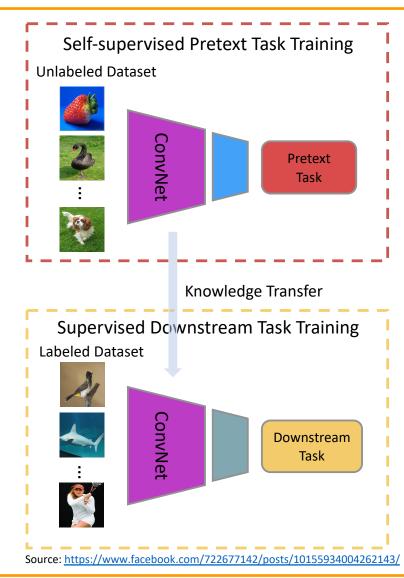
# Self-supervised Learning – Definition





I now call it "self-supervised learning", because "unsupervised" is both a loaded and confusing term.

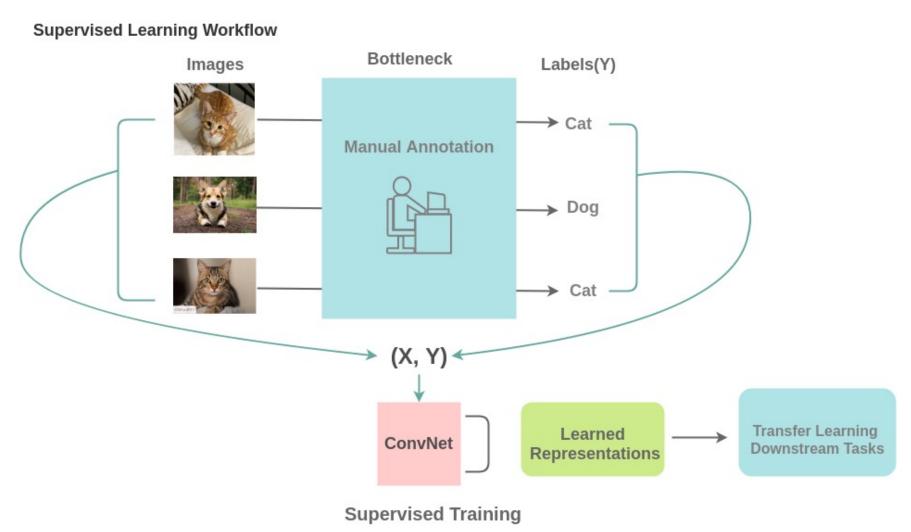
- Subcategory of unsupervised learning
  - Use pretext/surrogate/pseudo tasks in a supervised fashion,
    i.e., we have
    - automatically generated labels
    - that can be used as a measure of correctness (for the loss function)
- Downstream task: retrieval, supervised or semisupervised classification, etc.
- Note: Generative models (e.g., GANs) are also SSL methods



Fakultät für Informatik J. Schmidt DL – Self-supervised 8

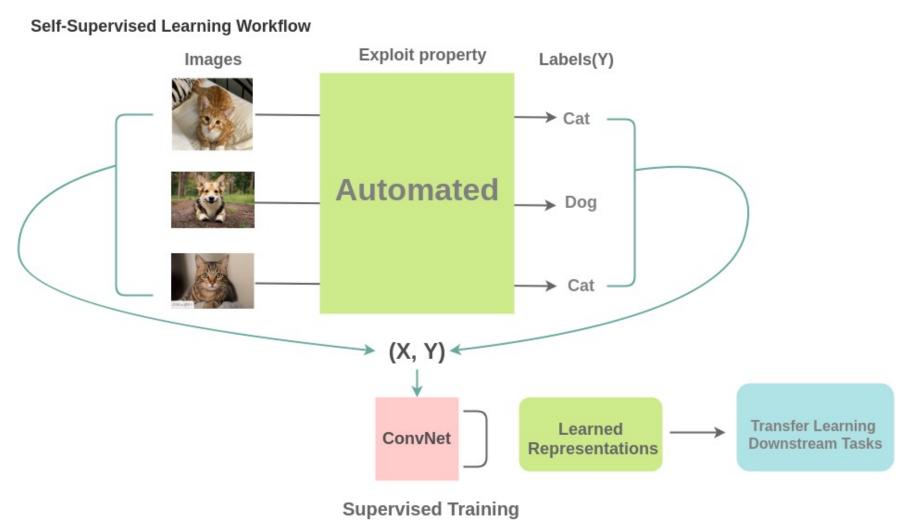
# Advantages of Self-supervised Learning





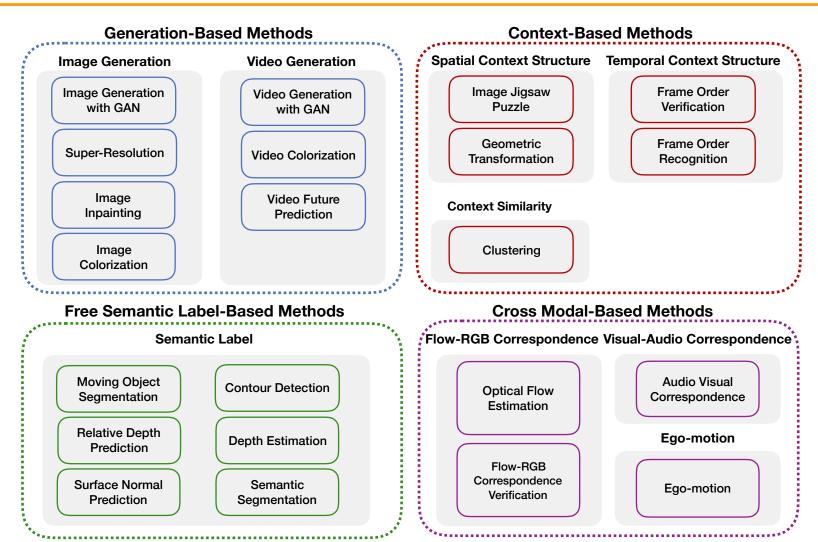
### Advantages of Self-supervised Learning





#### Pretext Tasks Overview

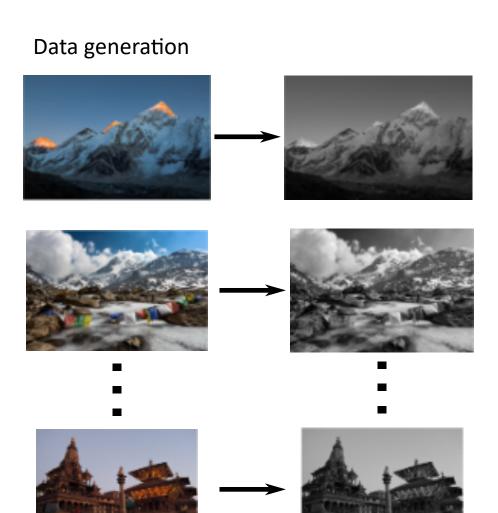




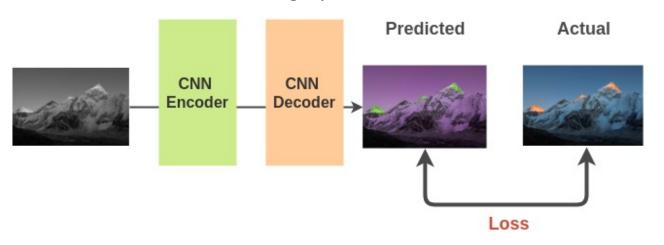
Source: [Jin19]

### Image Colorization





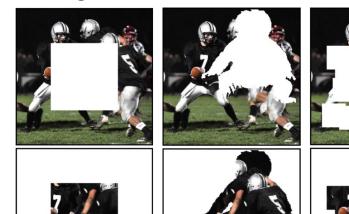
#### Pretext task: l<sub>2</sub> loss between gray and color version



### Image Inpainting

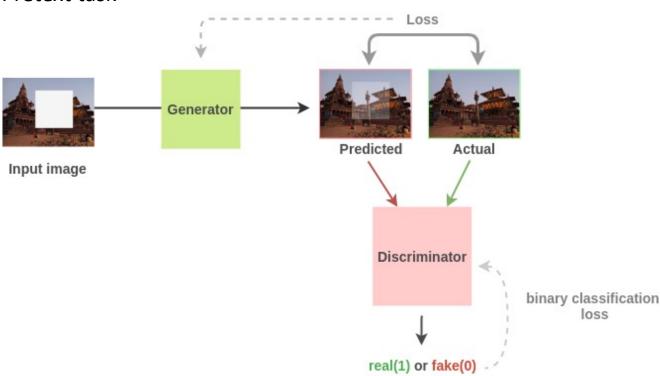


#### Data generation



Source: [Pat16]

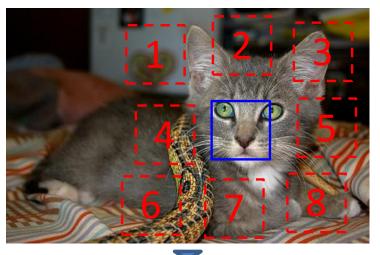
#### Pretext task



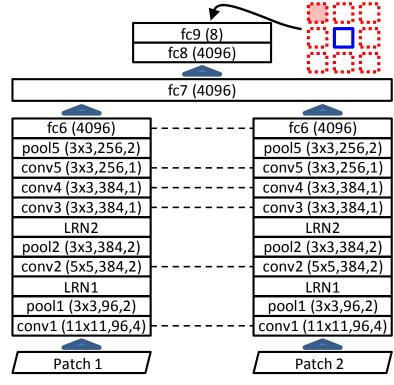
#### Solve Jigsaw Puzzle



Predict spatial configuration of a patch to selected reference patch (blue)



$$X = ( ) ; Y = 3$$



Attention: Avoid trivial shortcuts that the network might learn to use

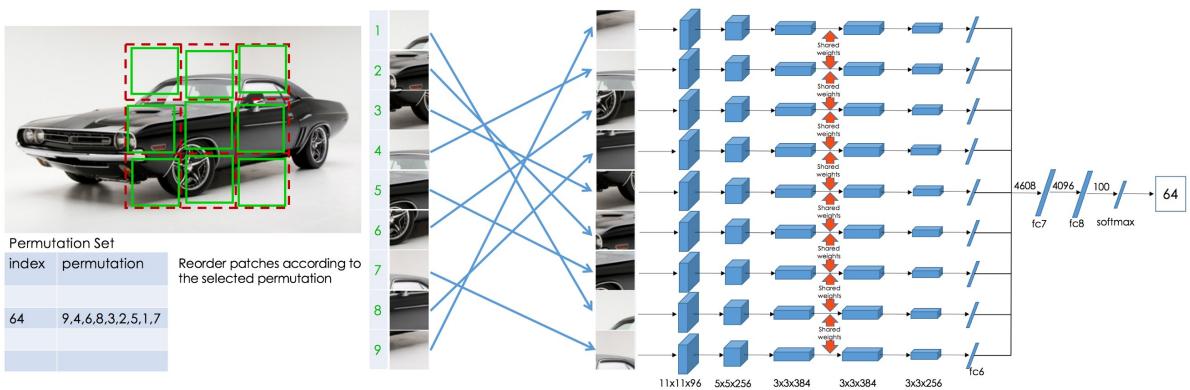
- boundary patterns, continuing textures → use large enough gaps
- prevent network from only learning about color information: introduce chromatic aberration
  - pre-process images by shifting green and magenta toward gray or
  - randomly drop 2 color channels

Source: [Doe15]

#### Solve Jigsaw Puzzle++



#### Predict position of each of the tiles



9 tiles  $\rightarrow$  9! = 362 880 possible permutations

After training of Jigsaw problem: Transfer Learning

- Transfer weights of conv layers to AlexNet
- init fully connected AlexNet layers randomly
- use Fast R-CNN architecture for detection

Source: [Nor16]

### Solve Jigsaw Puzzle++



Number of permutations	Average hamming distance	Minimum hamming distance	Jigsaw task accuracy	Detection performance
1000	8.00	2	71	53.2
1000	6.35	2	62	51.3
1000	3.99	2	54	50.2
100	8.08	2	88	52.6
95	8.08	3	90	52.4
85	8.07	4	91	52.7
71	8.07	5	92	52.8
35	8.13	6	94	52.6
10	8.57	7	97	49.2
7	8.95	8	98	49.6
6	9	9	99	49.7

Detection performance: Evaluated after transfer learning on Pascal VOC dataset

Source: [Nor16]

#### BYOL – Bootstrap Your Own Latent

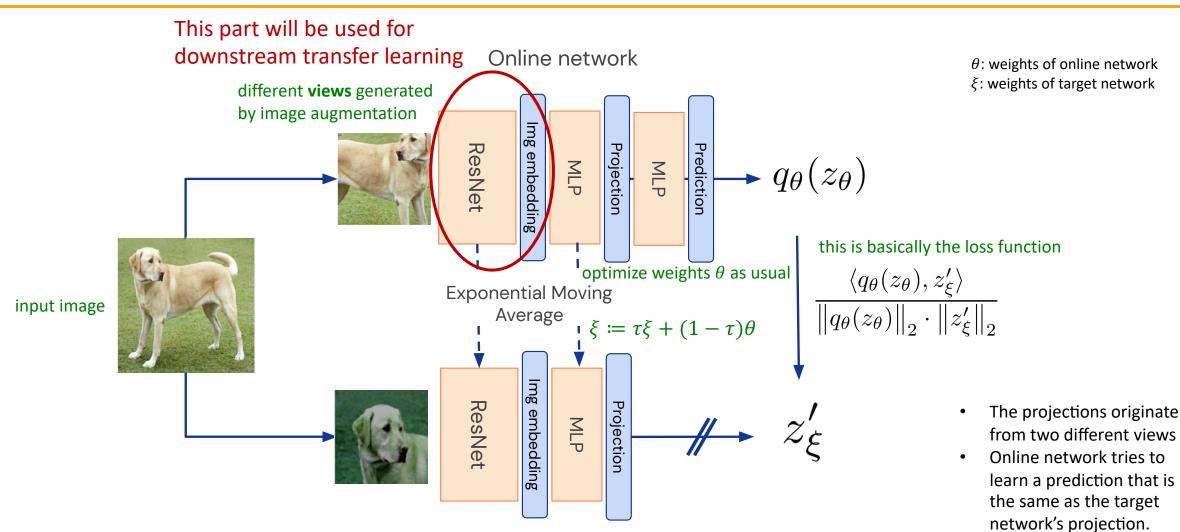


- New approach to self-supervised learning [Gri20]
- Uses two neural networks that learn from each other
- Transfer weights of one network to downstream tasks
  - 74.3% top-1 classification accuracy on ImageNet (ResNet-50), 91.6% top-5
  - 79.6% top-1 classification accuracy on ImageNet (ResNet-200), 94.8% top-5

#### BYOL – Architecture



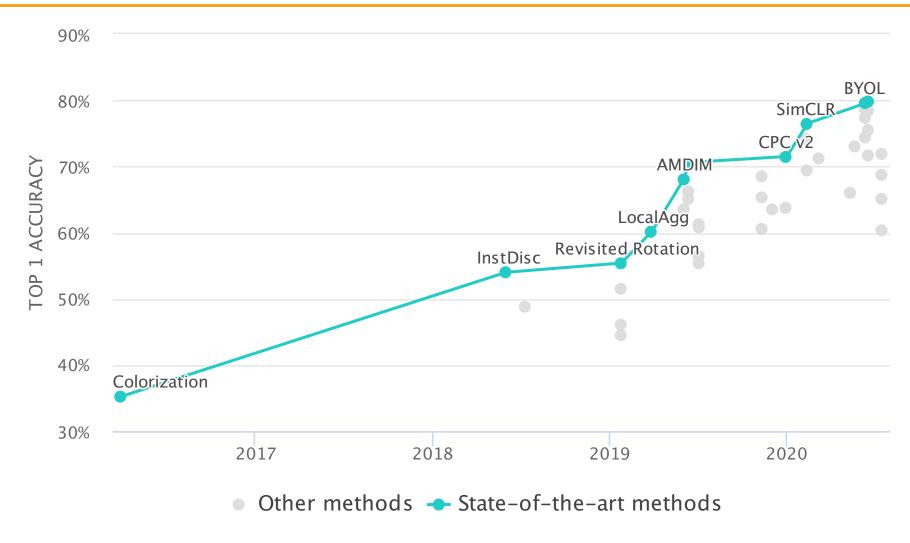
Thus, a loss can be defined.



Target network

### SSL – Classification Performance on ImageNet





Source: https://paperswithcode.com/sota/self-supervised-image-classification-on

#### References



[Cor16] Marius Cordts, Mohamed Omran, Sebastian Ramos, et al. "The Cityscapes Dataset for Semantic Urban Scene Understanding". In: CoRR abs/1604.01685 (2016). arXiv: 1604.01685.

[Doe15] C. Doersch, A. Gupta, and A. A. Efros. "Unsupervised Visual Representation Learning by Context Prediction". In: 2015 IEEE International Conference on Computer Vision (ICCV). Dec. 2015, pp. 1422–1430.

[Gri20] Jean-Bastien Grill, Florian Strub, Florent Altché, et al. "Bootstrap Your Own Latent: A New Approach to Self-Supervised Learning". In: arXiv e-prints, arXiv:2006.07733 (June 2020)

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[Mat19] Matterport, Inc. Mask R-CNN for Object Detection and Segmentation. <a href="https://github.com/matterport/Mask\_RCNN">https://github.com/matterport/Mask\_RCNN</a>

[Nor16] Mehdi Noroozi and Paolo Favaro. "Unsupervised Learning of Visual Representations by Solving Jigsaw Puzzles". In: Computer Vision – ECCV 2016. Cham: Springer International Publishing, 2016, pp. 69–84.

[Pat16] D. Pathak, P. Krähenbühl, J. Donahue, et al. "Context Encoders: Feature Learning by Inpainting". In: 2016 IEEE Conference on Computer Vision and Pattern Recognition (CVPR). 2016, pp. 2536–2544.