

## 说明

有了**力**的定律和运动定律，动力学的根本任务，即在一定环境下求物体的运动问题，似乎就成为求解运动方程的数学问题了。其实，**并非完全如此**。

如果我们在动力学定律的基础上引进一些新的概念和新的物理量，如**动量**、**能量**和**角动量**等，就可进而得到关于这些量的新的规律（包括所谓运动定理以及由此引出的守恒定律），而直接用这些规律去分析质点的运动问题，往往比从运动定律出发**更为方便**。

在力作为位置（或速度、时间）函数的具体形式不十分清楚的情况下（约束力和碰撞中的力就是例子），利用关于动量，能量和角动量的规律，也能为我们求解问题提供一定的信息，使我们获得关于质点系运动的**相关知识**。

即使在牛顿定律不一定适用的许多场合，包括微观领域，守恒定律仍然有效。这样，原来仅仅作为牛顿定律辅助工具而引入的运动定理的推论——**守恒定律**，却成为比牛顿定律**更为基本**的规律。

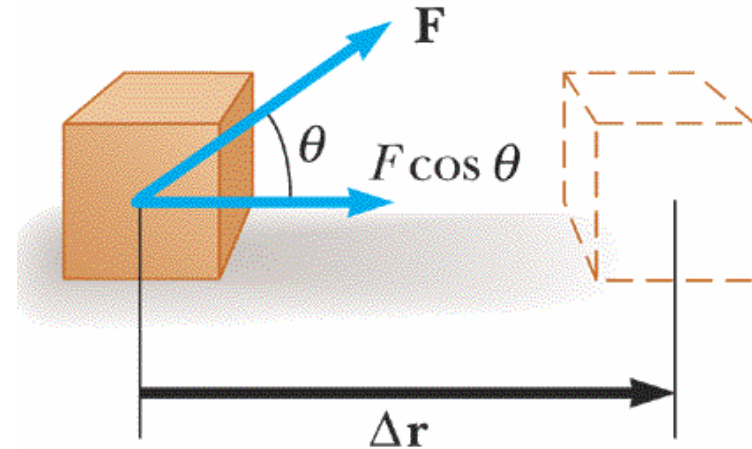
# Chapter 7-8 Work and Energy



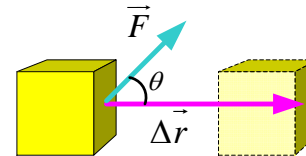
## § 1 Work and Power

Work done by a **constant** force

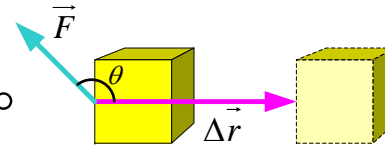
$$W = \vec{F} \cdot \Delta \vec{r} = F |\Delta \vec{r}| \cos \theta$$



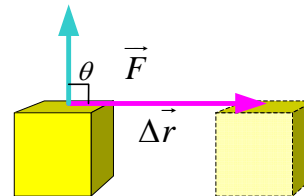
$W$  is positive when  $\theta < 90^\circ$



$W$  is negative when  $\theta > 90^\circ$



$W$  is zero when  $\theta = 90^\circ$



# Work



- Work done by a **varying** force along a **curve** path

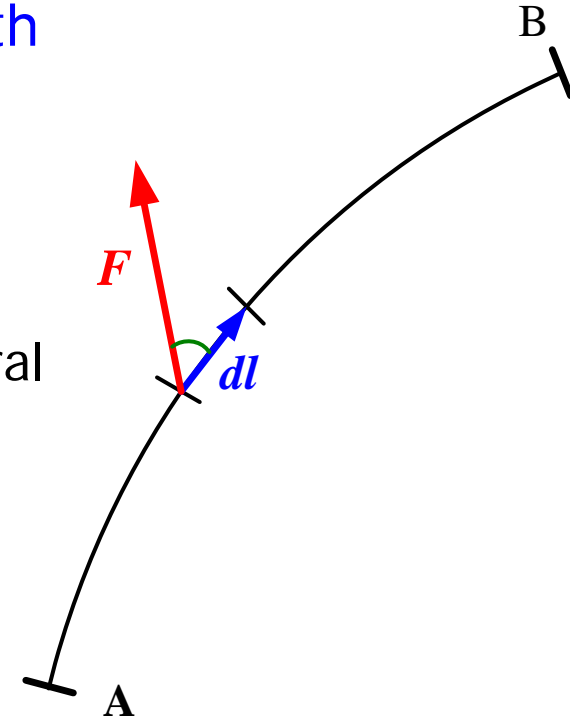
- ➔ Divide the path into a large number of small displacement  $d\vec{l}$

$$W = \int_A^B \vec{F} \cdot d\vec{l}$$

Line integral or path integral

The SI unit of work: Newton•meter or Joule

- ➔ Work is a process quantity.
- ➔ Calculation of work relates to the reference frame.



- ➡ Work done by **multiple** forces.

Total work done is the scalar addition of the work done by each force.

$$W_{net} = \int_A^B \vec{F}_{net} \cdot d\vec{l} = \int_A^B \left( \sum_i \vec{F}_i \right) \cdot d\vec{l} = \sum_i \int_A^B \vec{F}_i \cdot d\vec{l} = \sum_i W_i$$

- The power: The rate at which work is done (P186)

- ➡ Average power:

$$\bar{P} = \frac{\Delta W}{\Delta t}$$

- ➡ Instantaneous power:

$$P = \frac{dW}{dt} = \frac{\vec{F} \cdot d\vec{r}}{dt} = \vec{F} \cdot \vec{v}$$

- ➡ SI unit: watt.

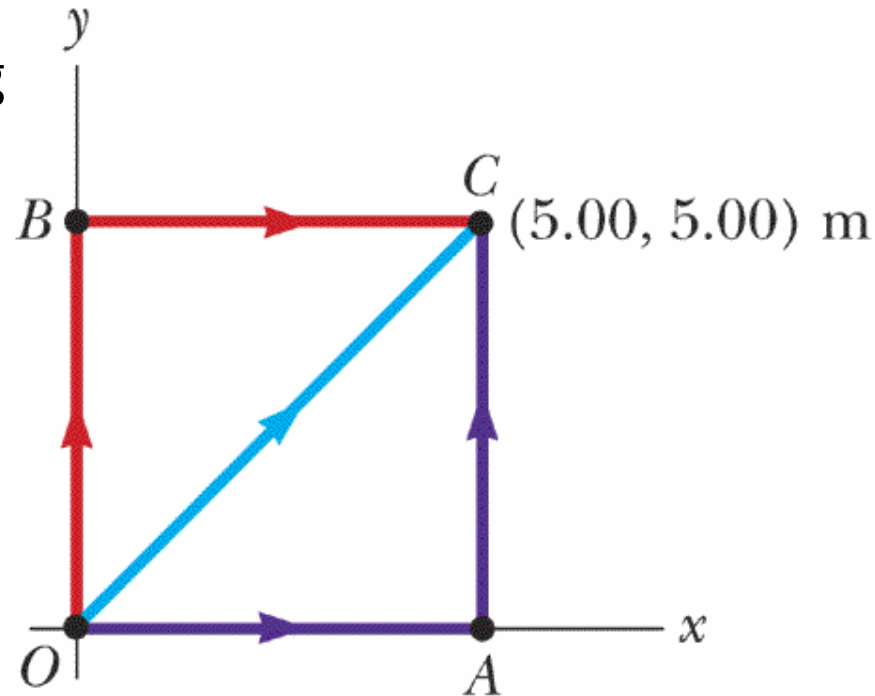
## Example



A force acting on a particle moving in the  $xy$  plane is given by

$$\vec{F} = 2y\hat{i} + x^2\hat{j} \quad (\text{SI})$$

The particle moves from the origin to a final position  $C$  (5.00m, 5.00m). Calculate the work done by  $\vec{F}$  along (1)  $OC$ , (2)  $OAC$ , (3)  $OBC$ .



## Example (continued)



$$\vec{F} = 2y\hat{i} + x^2\hat{j}$$

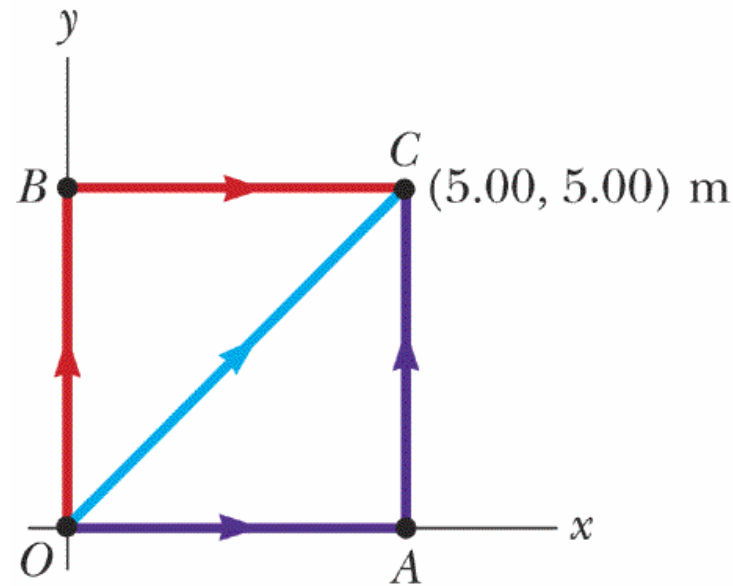
**Solution:**

**(1) Along path  $OC$ :**

$$\begin{aligned}\vec{F} \cdot d\vec{l} &= (F_x\hat{i} + F_y\hat{j}) \cdot (dx\hat{i} + dy\hat{j}) \\ &= F_x dx + F_y dy \\ &= 2ydx + x^2 dy\end{aligned}$$

$$\int_{OC} \vec{F} \cdot d\vec{l} = \int_{OC} (2ydx + x^2 dy) = \int_0^5 2x dx + \int_0^5 y^2 dy = 66.7 \text{ J}$$

$$OC : y = x$$



## Example



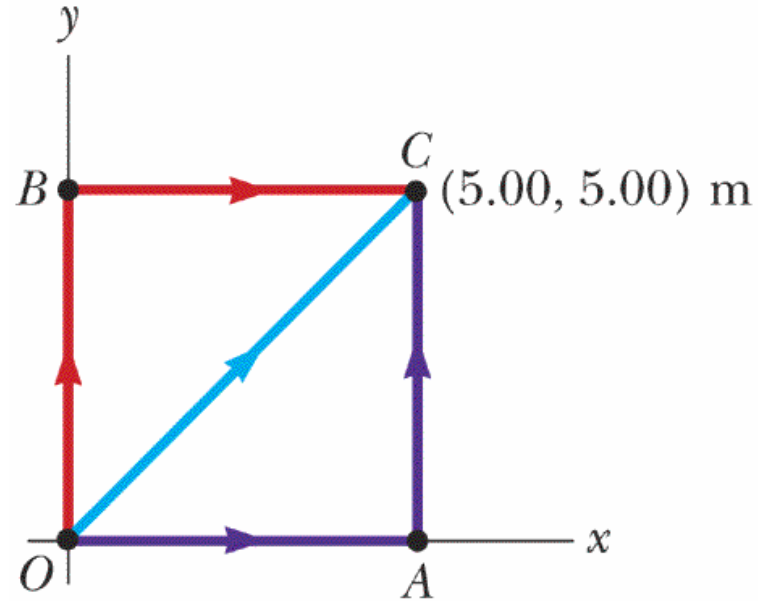
$$\vec{F} = 2y\hat{i} + x^2\hat{j}$$

(2) Along path  $OAC$ :

$$\int_{OAC} \vec{F} \cdot d\vec{l} = \int_{OA} \vec{F} \cdot d\vec{l} + \int_{AC} \vec{F} \cdot d\vec{l}$$

$$= \int_0^5 (2y\hat{i} + x^2\hat{j}) \cdot (dx\hat{i}) + \int_0^5 (2y\hat{i} + x^2\hat{j}) \cdot (dy\hat{j})$$

$$= \underbrace{\int_0^5 2y(=0)dx}_{\text{zero}} + \int_0^5 (x(=5))^2 dy = \int_0^5 25dy = 125 \text{ J}$$



## Example (continued)



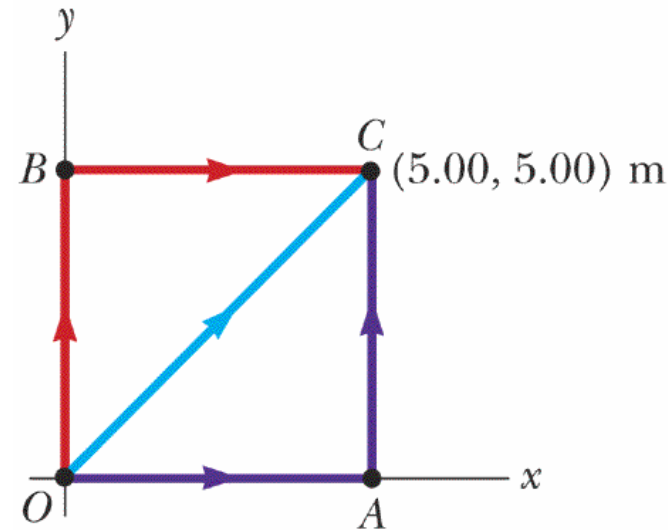
$$\vec{F} = 2y\hat{i} + x^2\hat{j}$$

**(3) Along path  $OBC$ :**

$$\int_{OBC} \vec{F} \cdot d\vec{l} = \int_{OB} \vec{F} \cdot d\vec{l} + \int_{BC} \vec{F} \cdot d\vec{l}$$

$$= \int_0^5 (2y\hat{i} + x^2\hat{j}) \cdot dy \hat{j} + \int_0^5 (2y\hat{i} + x^2\hat{j}) \cdot dx \hat{i}$$

$$= \int_0^5 \underbrace{(x(=0))^2}_{\substack{\uparrow \\ \text{zero}}} dy + \int_0^5 2y(=5) dx = \int_0^5 2 \times 5 dx = 50 \text{ J}$$

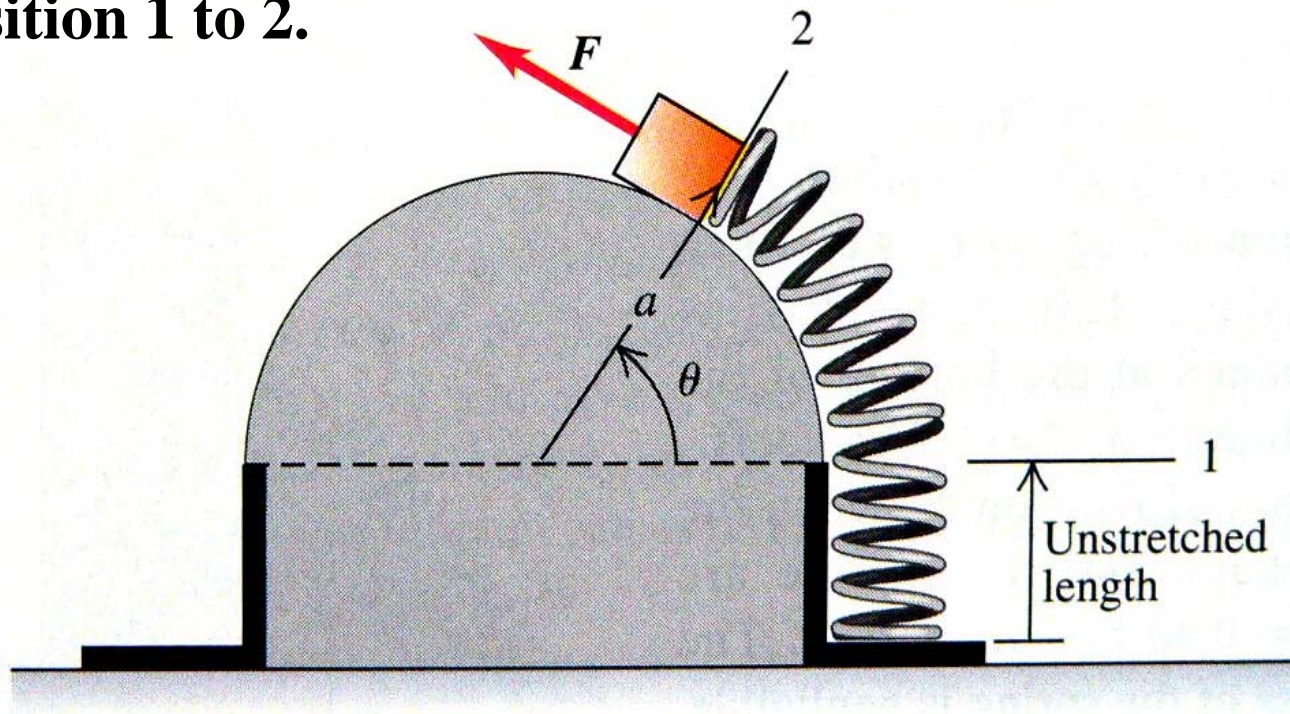




## Example



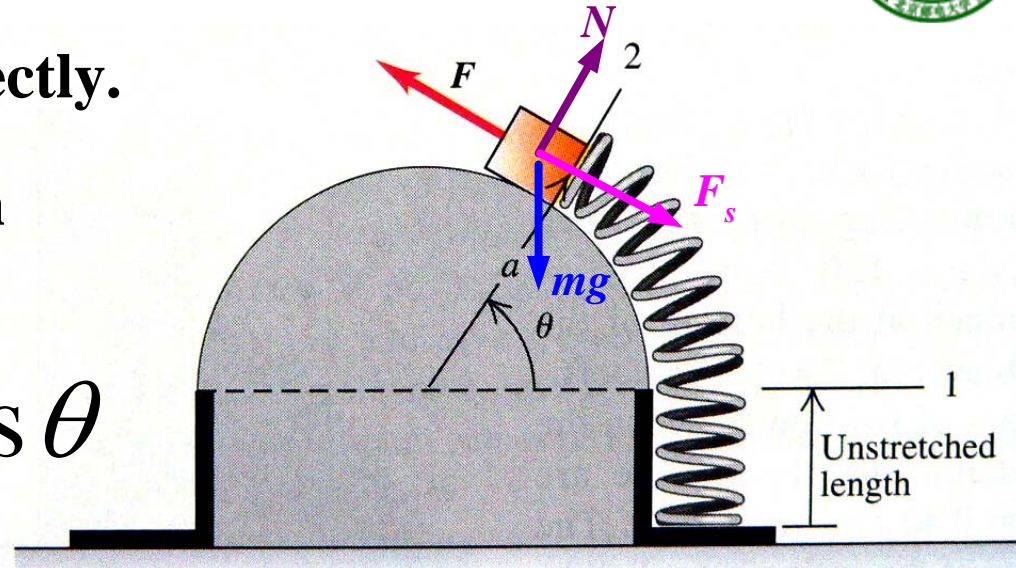
Variable force  $F$  is maintained tangent to a frictionless semicircular surface. By a slowly varying force  $F$ , a block with mass of  $m$  is moved, and spring to which it is attached is stretched from position 1 (unstretched length) to position 2 (  $\theta$  ). The spring has negligible mass and force constant  $k$ . The end of the spring moves in an arc of radius  $a$ . Calculate the work done by the force  $F$  from position 1 to 2.



**Solution I: by integration directly.**

The block is in **equilibrium** in tangential direction:

$$F = k(a\theta) + mg \cos \theta$$



$$W_F = \int_1^2 \vec{F} \cdot d\vec{l} = \int_1^2 F ds$$

$$= \int_0^\theta [k(a\theta) + mg \cos \theta] d(a\theta)$$

$$= ka^2 \int_0^\theta \theta d\theta + mga \int_0^\theta \cos \theta d\theta = \frac{1}{2} ka^2 \theta^2 + mga \sin \theta$$

## § 2 Work – kinetic energy theorem (P156)



$$W_{net} = \int_A^B \sum_i \vec{F}_i \cdot d\vec{r} = \int_A^B \sum_i F_{it} ds = \int_A^B m \frac{dv}{dt} ds = \int_{v_A}^{v_B} mv dv = \frac{1}{2}mv_B^2 - \frac{1}{2}mv_A^2$$

- Kinetic energy:  $K = \frac{1}{2}mv^2$

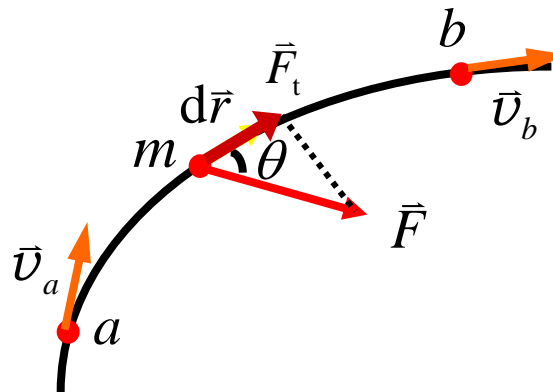
Process quantity

The change of state quantity

- Work – kinetic energy theorem:

$$W_{net} = K_f - K_i$$

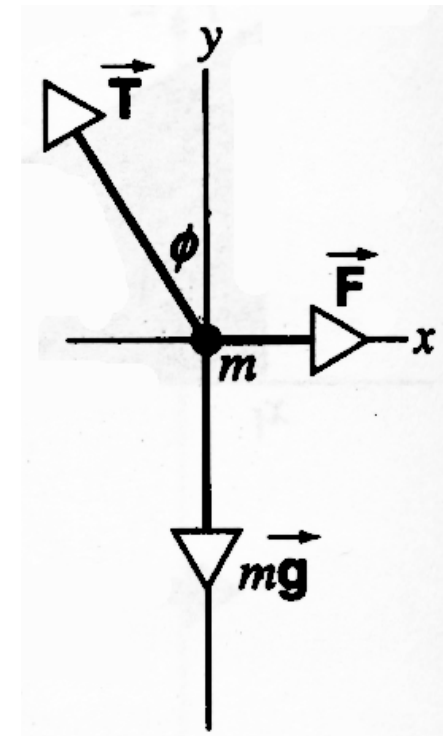
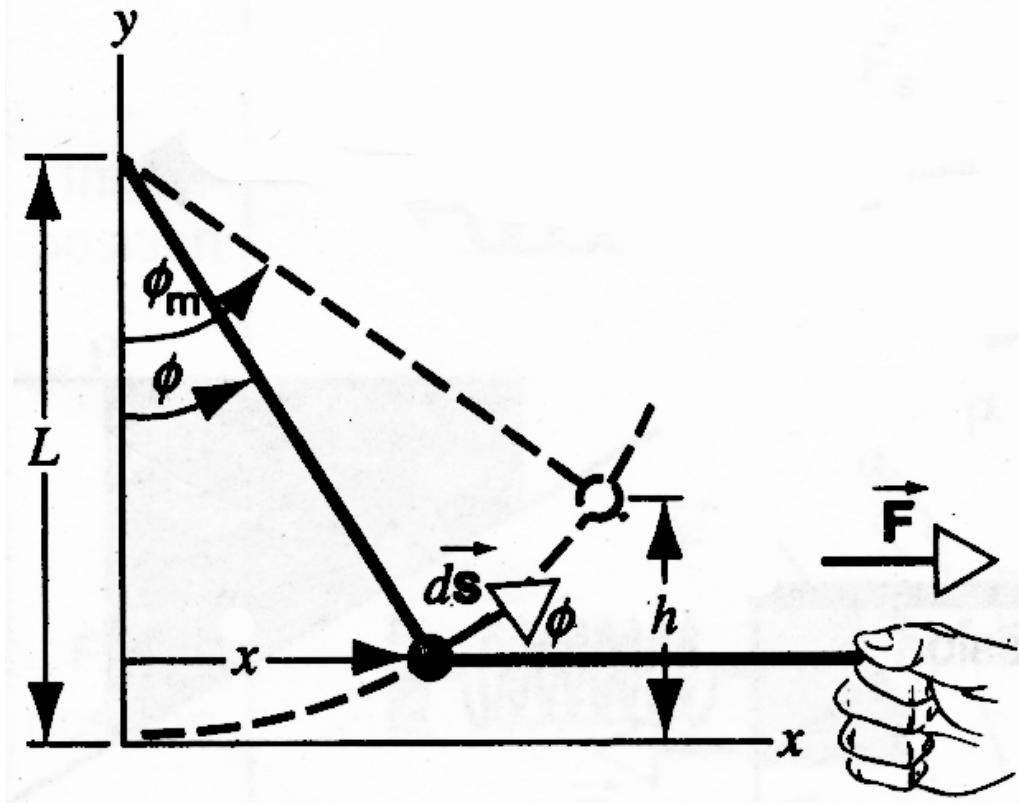
➡ The work done by the net force on a particle equals the change in kinetic energy (valid in the inertial frame of reference).



## Example



A small object of mass  $m$  is suspended from a string of length of  $L$ . The object is pulled sideways by a force  $F$  that is always horizontal, until the string finally makes an angle  $\phi_m$ . The displacement is accomplished at a very small constant speed. Find the work done by all the forces that act on the object.



## Solution



x component:  $F - T \sin \phi = 0$

y component:  $T \cos \phi - mg = 0$

$$F = mg \tan \phi$$

$$W_F = \int_i^f \vec{F} \cdot d\vec{s} = \int_i^f F ds \cos \phi = \int_i^f F dx$$

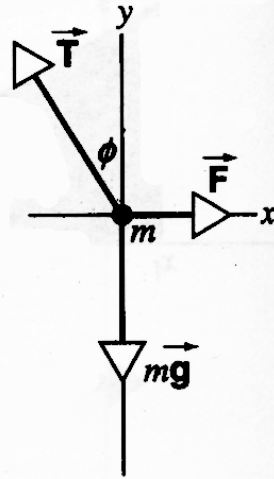
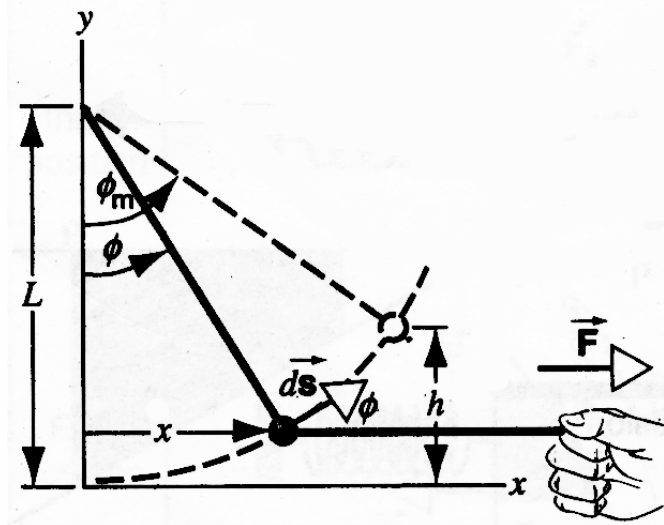
$$x = L \sin \phi, \quad dx = L \cos \phi d\phi$$

$$W_F = \int_0^{\phi_m} mg \tan \phi L \cos \phi d\phi = mgL \int_0^{\phi_m} \sin \phi d\phi = mgL(1 - \cos \phi_m) = mgh$$

$$W_g = \int_i^f (-mg\hat{j}) \cdot (dx\hat{i} + dy\hat{j}) = \int_0^h -mg dy = -mgh$$

$\vec{T}$  is perpendicular to the displacement  $d\vec{s}$  at every point of the motion.

$$W_{net} = W_F + W_g + W_T = mgh - mgh + 0 = 0$$



# Work – kinetic energy theorem

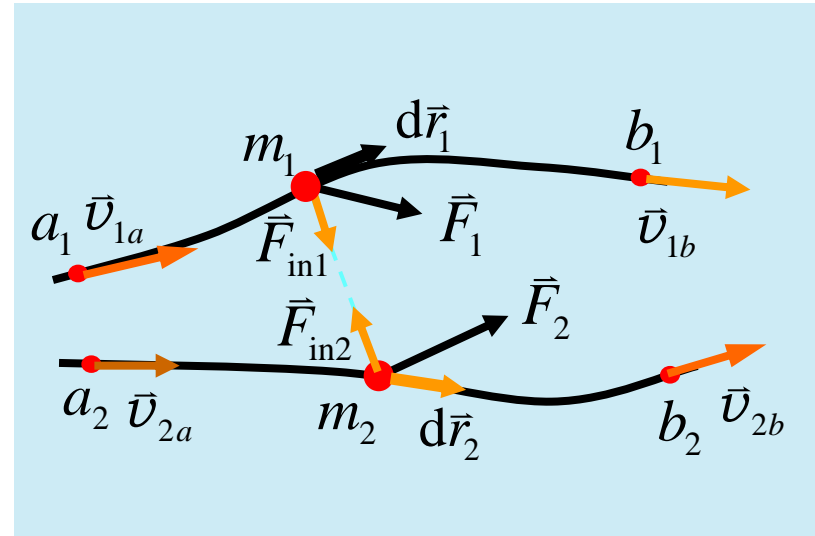


## ■ Work – kinetic energy theorem for the **system** of particles

$$\begin{aligned}\text{For } m_1 \quad W_1 &= \int_{a_1}^{b_1} \vec{F}_1 \cdot d\vec{r}_1 + \int_{a_1}^{b_1} \vec{F}_{\text{in}1} \cdot d\vec{r}_1 \\ &= \frac{1}{2} m_1 v_{1b}^2 - \frac{1}{2} m_1 v_{1a}^2\end{aligned}$$

$$\begin{aligned}\text{For } m_2 \quad W_2 &= \int_{a_2}^{b_2} \vec{F}_2 \cdot d\vec{r}_2 + \int_{a_2}^{b_2} \vec{F}_{\text{in}2} \cdot d\vec{r}_2 \\ &= \frac{1}{2} m_2 v_{2b}^2 - \frac{1}{2} m_2 v_{2a}^2\end{aligned}$$

$$\begin{aligned}&\int_{a_1}^{b_1} \vec{F}_1 \cdot d\vec{r}_1 + \int_{a_2}^{b_2} \vec{F}_2 \cdot d\vec{r}_2 + \int_{a_1}^{b_1} \vec{F}_{\text{in}1} \cdot d\vec{r}_1 + \int_{a_2}^{b_2} \vec{F}_{\text{in}2} \cdot d\vec{r}_2 \\ &= \left( \frac{1}{2} m_1 v_{1b}^2 + \frac{1}{2} m_2 v_{2b}^2 \right) - \left( \frac{1}{2} m_1 v_{1a}^2 + \frac{1}{2} m_2 v_{2a}^2 \right)\end{aligned}$$





## Work – kinetic energy theorem



For a particle

$$W_{net} = K_f - K_i$$

- Work – kinetic energy theorem for the **system** of particles

$$\sum W_{i\text{-external}} + \sum W_{i\text{-internal}} = \sum K_f - \sum K_i$$

- ➡ Generally, the works done by **internal** forces between particles **cannot** be canceled (the displacements of particles are different).

# The work done by a pair of internal forces



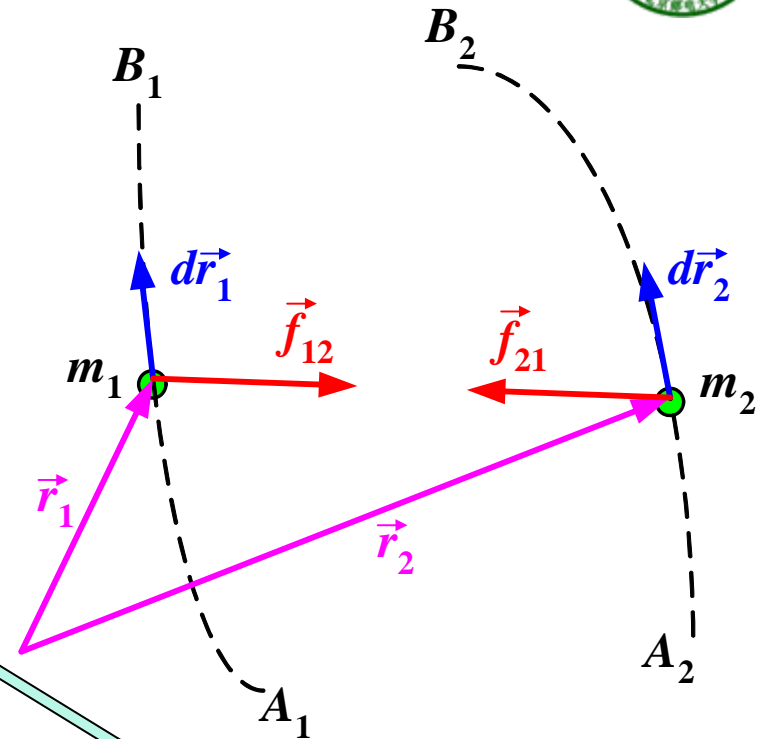
- The work done by a pair of internal forces

$$\vec{f}_{12} = -\vec{f}_{21}$$

For an infinitesimal process

$$\begin{aligned} dW &= \vec{f}_{12} \cdot d\vec{r}_1 + \vec{f}_{21} \cdot d\vec{r}_2 \\ &= \vec{f}_{21} \cdot (d\vec{r}_2 - d\vec{r}_1) = \vec{f}_{21} \cdot d(\underbrace{\vec{r}_2 - \vec{r}_1}_{\text{displacement of 2 relative to 1}}) \\ &= \vec{f}_{21} \cdot d\vec{r}_{21} \end{aligned}$$

- ➡ The calculation of net work done by a pair of internal forces on two particles is **equivalent** to — in the reference frame of particle 1, the calculation of work done by one force acting on particle 2.



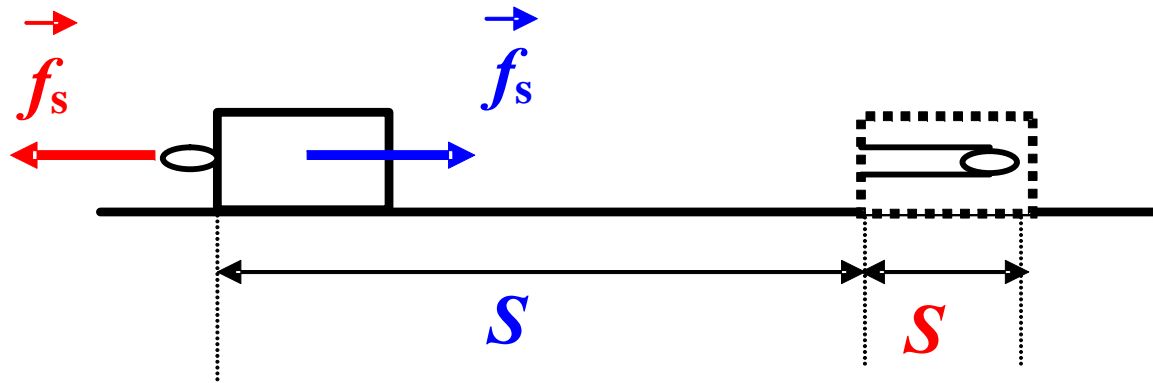
**The displacement of 2 relative to 1**



## Example



A bullet coming from left is shot into a wooden block and passes through a length of  $S'$  in the block. The system of bullet-block comes to a halt after sliding a distance of  $S$ . Calculate the net work done by a pair of friction forces  $f_s$  and  $f_s'$  between the bullet and the block.



## Example



**Solution:**  $\vec{f}_s = -\vec{f}'_s, \quad |\vec{f}_s| = |\vec{f}'_s| = f_s$

**For the block:**

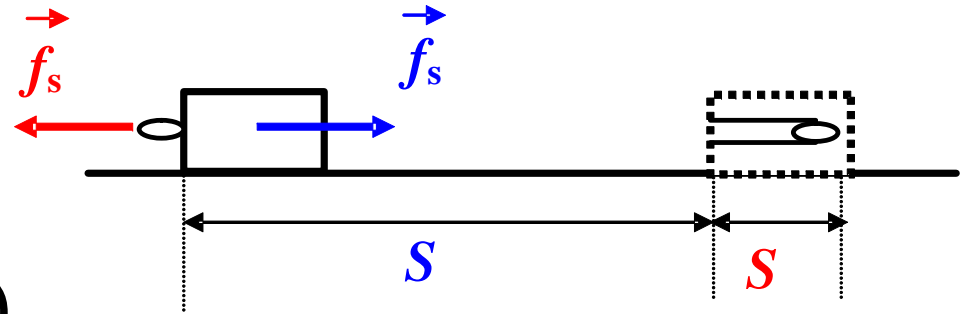
$$W_s = f_s S$$

**For the bullet:**

$$W_{s'} = -f_s (S + S')$$

**The net work:**

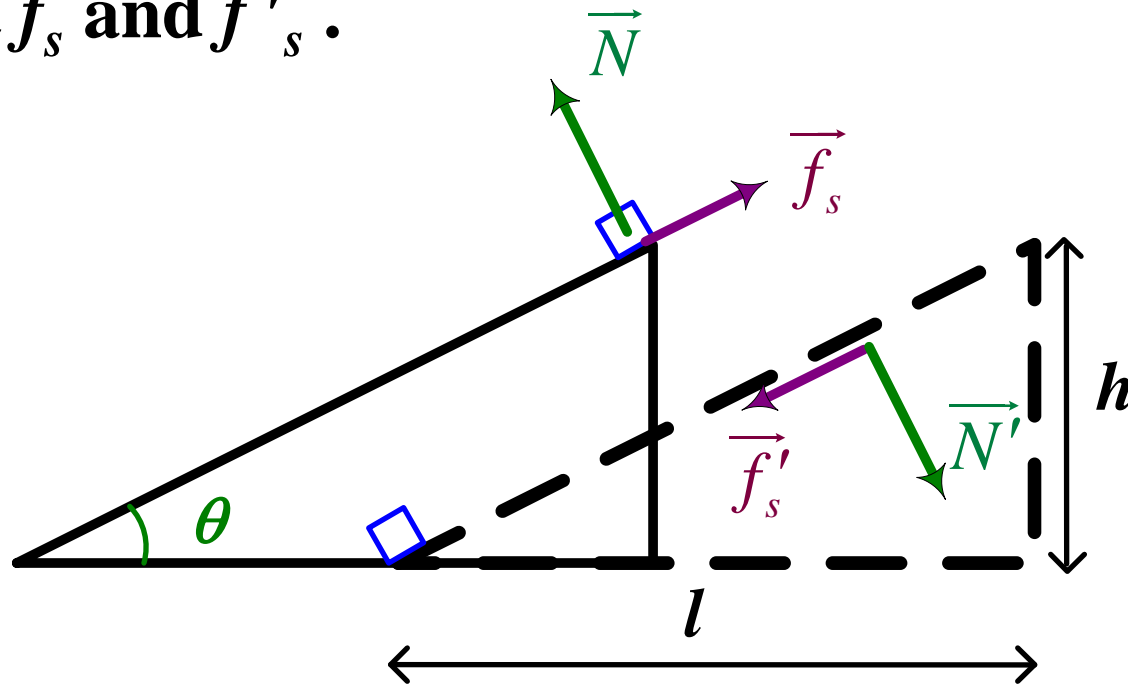
$$W_s^{\text{net}} = W_s + W_{s'} = f_s S - f_s (S + S') = -f_s S'$$



## Example



Calculate the net works done respectively by a pair of normal forces  $\vec{N}$  and  $\vec{N}'$ ,  $\vec{f}_s$  and  $\vec{f}'_s$  between the block and the wedge. Neglecting the frictions except  $\vec{f}_s$  and  $\vec{f}'_s$ .



## Example



**Solution:** The normal force  $\vec{N}$  acting on the block is not perpendicular to the displacement of the block  $\Delta\vec{r}$

Therefore:  $W_N \neq 0$

The normal force  $\vec{N}'$  acting on the wedge is not perpendicular to the displacement of the wedge  $\Delta\vec{S}$ . Therefore:

$$W_{N'} \neq 0$$

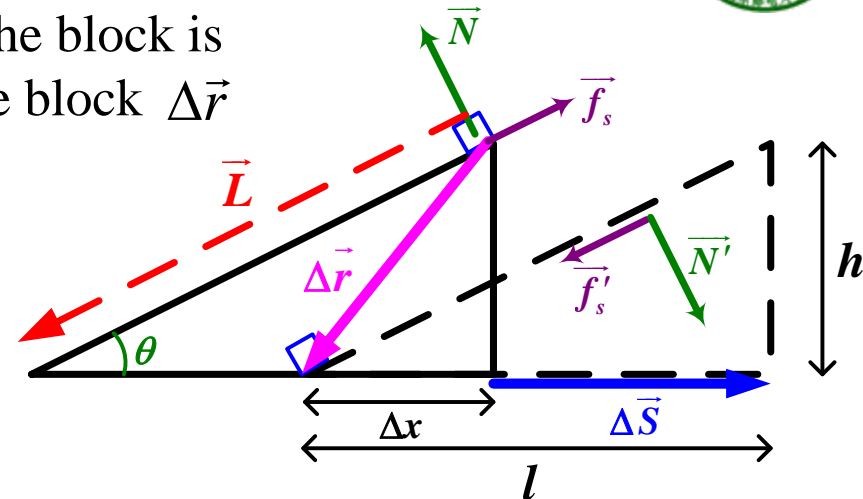
$$\Delta\vec{r} = -\Delta x \hat{i} - h \hat{j}, \quad \vec{N} = -N \sin \theta \hat{i} + N \cos \theta \hat{j}$$

$$\Delta\vec{S} = (l - \Delta x) \hat{i}, \quad \vec{N}' = N \sin \theta \hat{i} - N \cos \theta \hat{j}$$

$$W_N = \vec{N} \cdot \Delta\vec{r} = \Delta x N \sin \theta - h N \cos \theta, \quad \tan \theta = \frac{h}{l}, \quad h \cos \theta = l \sin \theta$$

$$W_{N'} = \vec{N}' \cdot \Delta\vec{S} = l N \sin \theta - \Delta x N \sin \theta,$$

$$W_N^{\text{net}} = W_N + W_{N'} = 0$$



## Example (continued)



$$\Delta \vec{r} = -\Delta x \hat{i} - h \hat{j}$$

$$\Delta \vec{S} = (l - \Delta x) \hat{i}$$

$$\vec{f}_s = f_s \cos \theta \hat{i} + f_s \sin \theta \hat{j}$$

$$\vec{f}' = -f_s \cos \theta \hat{i} - f_s \sin \theta \hat{j}$$

$$W_{f_s} = \vec{f}_s \cdot \Delta \vec{r} = -\Delta x f_s \cos \theta - h f_s \sin \theta$$

$$W_{f'_s} = \vec{f}'_s \cdot \Delta \vec{S} = -l f_s \cos \theta + \Delta x f_s \cos \theta$$

$$\begin{aligned} W_{f_s}^{\text{net}} &= W_{f_s} + W_{f'_s} = -(l \cos \theta + h \sin \theta) f_s \\ &= -(L \cos^2 \theta + L \sin^2 \theta) f_s = -f_s L \end{aligned}$$

