

# CS 221 C++ Advanced Evaluation Assignment

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# 1.

<https://github.com/Id405/cs-221-eval-assignments/blob/main/eval-8/1.cpp>

```
1  #include <algorithm>
2  #include <cmath>
3  #include <memory>
4  #include <string>
5  #include <tuple>
6  #include <vector>
7  using namespace std;
8
9  // Previous homework
10 class Car {
11 private:
12     double x;
13     double y;
14     double milesPerGallon;
15     double fuelTankCapacityGallons;
16     double fuelGallons;
17
18 protected:
19     void setX(double toX) { x = toX; }
20     void setY(double toY) { y = toY; }
21     void setFuelGallons(double gallons) { fuelGallons = gallons; }
22     void burnGallons(double gallons) { fuelGallons -= gallons; }
23
24 public:
25     Car(double x, double y, float milesPerGallon, double fuelTankCapacityGallons,
26         double fuelGallons)
27         : x(x), y(y), milesPerGallon(milesPerGallon),
28           fuelTankCapacityGallons(fuelTankCapacityGallons) {}
29     double getMilesPerGallon() { return milesPerGallon; }
30     double getFuelTankCapacityGallons() { return fuelTankCapacityGallons; }
31     double getFuelGallons() { return fuelGallons; }
32     double getX() { return x; }
33     double getY() { return y; }
34     bool moveTo(double destinationX, double destinationY) {
35         double gallonCost = hypot(getX() - destinationX, getY() - destinationY) *
36             getMilesPerGallon();
37         if (gallonCost > getFuelGallons()) {
38             return false;
39         }
40
41         burnGallons(gallonCost);
42         setX(destinationX);
43         setY(destinationY);
44         return true;
45     }
46     double refillTank() {
47         double refilledGallons = fuelTankCapacityGallons - fuelGallons;
48         return refilledGallons;
49     }
50 };
51
52 vector<Car> moveToPoint(vector<Car> cars, double destinationX,
53     double destinationY) {
```

```

54     vector<Car> result;
55     for (Car car : cars) {
56         if (car.moveTo(destinationX, destinationY)) {
57             result.push_back(car);
58         }
59     }
60
61     return result; // Return array with size and a lot of other helpful things
62                 // like god (the C++ standard library) intended us to do. This
63                 // helpful construct is called a vector. I know its not an
64                 // array. I know its not an array. I know its not an array. I
65 }
66
67 class GasStation {
68 private:
69     double x;
70     double y;
71     double pricePerGallon;
72
73 public:
74     GasStation(double x, double y, double pricePerGallon)
75         : x(x), y(y), pricePerGallon(pricePerGallon) {}
76     double getX() { return x; }
77     double getY() { return y; }
78     double getPricePerGallon() { return pricePerGallon; }
79 };
80
81 tuple<vector<Car>, vector<double>>
82 moveToPointGasStations(vector<Car> cars, vector<GasStation> gasStations,
83                         double destinationX, double destinationY) {
84     vector<Car> resultCar;
85     vector<double> resultCost;
86
87     for (Car car : cars) {
88         double cost = 0;
89
90         for (int i = gasStations.size(); i > 0; i--) {
91             if (car.moveTo(destinationX, destinationY)) {
92                 resultCar.push_back(car);
93                 resultCost.push_back(cost);
94                 continue;
95             }
96
97             GasStation gasStation = gasStations.at(i);
98             if (car.moveTo(gasStation.getX(), gasStation.getY())) {
99                 cost += car.refillTank() * gasStation.getPricePerGallon();
100             } else {
101                 continue;
102             }
103         }
104     }
105
106     return {resultCar, resultCost};
107 }
108
109 // Homework 8
110 class Bus : public Car {

```

```

111 private:
112     int maxPassengers;
113     vector<int> passengers;
114     double milesPerGallonPenaltyPerPassenger;
115
116 public:
117     double getMilesPerGallon() {
118         return Car::getMilesPerGallon() -
119             passengers.size() * milesPerGallonPenaltyPerPassenger;
120     }
121
122     bool moveTo(double destinationX, double destinationY) {
123         double gallonCost = hypot(getX() - destinationX, getY() - destinationY) *
124             getMilesPerGallon();
125         if (gallonCost > getFuelGallons()) {
126             return false;
127         }
128
129         burnGallons(gallonCost);
130         setX(destinationX);
131         setY(destinationY);
132         return true;
133     }
134
135     vector<int> generateRoute() {
136         vector<int>::iterator it = unique(passengers.begin(), passengers.end());
137         vector<int> results = passengers;
138         results.erase(it);
139
140         return results;
141     }
142 };
143
144 class Provider {
145 private:
146     string name;
147     string role;
148 };
149
150 class Patient {
151 private:
152     string name;
153     string condition;
154 };
155
156 class MedicalCenter {
157 private:
158     vector<Provider> providers;
159     vector<Patient> patients;
160
161 public:
162     vector<Patient> getPatients() { return patients; }
163
164     vector<Provider> getProviders() { return providers; }
165 };
166
167 class Ambulance : Car, MedicalCenter {

```

```

168 private:
169     int patientCapacity;
170     int providerCapacity;
171     double gasMileagePenalty;
172
173 public:
174     double getMilesPerGallon() {
175         return Car::getMilesPerGallon() -
176             getPatients().size() * getProviders().size() * gasMileagePenalty;
177     }
178
179     bool moveTo(double destinationX, double destinationY) {
180         double gallonCost = hypot(getX() - destinationX, getY() - destinationY) *
181             getMilesPerGallon();
182         if (gallonCost > getFuelGallons()) {
183             return false;
184         }
185
186         burnGallons(gallonCost);
187         setX(destinationX);
188         setY(destinationY);
189         return true;
190     }
191 };
192
193 vector<Car> moveToPoint(vector<unique_ptr<Car>> cars, double destinationX,
194                       double destinationY) {
195     vector<Car> result;
196     for (auto &car : cars) {
197         if ((*car).moveTo(destinationX, destinationY)) {
198             result.push_back(*car);
199         }
200     }
201
202     return result; // Return array with size and a lot of other helpful things
203                   // like god (the C++ standard library) intended us to do. This
204                   // helpful construct is called a vector. I know its not an
205                   // array. I know its not an array. I know its not an array. I
206 }
207
208 int main() { return 0; }

```

## 2.

<https://github.com/Id405/cs-221-eval-assignments/blob/main/eval-8/2.cpp>

```
1  #include <iostream>
2  #include <memory>
3  #include <vector>
4  using namespace std;
5
6  template <typename T> class BSTNode {
7  private:
8      unique_ptr<BSTNode<T>> left;
9      unique_ptr<BSTNode<T>> right;
10     unique_ptr<T> data;
11
12 public:
13     BSTNode(T value) {
14         data = make_unique<T>(value);
15         left = nullptr;
16         right = nullptr;
17     }
18
19     ~BSTNode() {
20         left.reset();
21         right.reset();
22         data.reset();
23     }
24
25     T getData() { return data; }
26
27     BSTNode<T> getLeft() { return *left; }
28
29     BSTNode<T> getRight() { return *right; }
30
31     bool leftIsNull() { return *left == nullptr; }
32     bool rightIsNull() { return right == nullptr; }
33
34     void resetLeft() { left.reset(); }
35     void resetRight() { right.reset(); }
36
37     void releaseLeft() { left.release(); }
38     void releaseRight() { right.release(); }
39
40     BSTNode<T> setLeft(BSTNode<T> node) {
41         left.reset();
42         left = make_unique<T>(node);
43     }
44
45     BSTNode<T> setRight(BSTNode<T> node) {
46         right.reset();
47         right = make_unique<T>(node);
48     }
49 };
50
51 template <typename T> class BST {
52 private:
53     unique_ptr<BSTNode<T>> trunk;
```

```

54     int size;
55
56 public:
57     BST(vector<T> values) {
58         for (T value : values) {
59             insert(value);
60         }
61     }
62
63     ~BST() { trunk.reset(); }
64
65     void insert(T value) {
66         unique_ptr<BSTNode<T>> node = make_unique<T>(BSTNode<T>(value));
67
68         if (trunk == nullptr) {
69             trunk = node;
70             size++;
71             return;
72         }
73
74         BSTNode<T> currentNode = *trunk;
75
76         bool side = value < currentNode.getData();
77
78         while (side ? !currentNode.leftIsNull() : !currentNode.rightIsNull()) {
79             currentNode = side ? currentNode.left() : currentNode.right();
80             side = value < currentNode.getData();
81         }
82
83         if (side) {
84             currentNode.setLeft(node);
85         } else {
86             currentNode.setRight(node);
87         }
88
89         size++;
90         return;
91     }
92
93     void insertNode(T node) {
94         T value = node.getData();
95
96         if (trunk == nullptr) {
97             trunk = node;
98             size++;
99             return;
100         }
101
102         BSTNode<T> currentNode = *trunk;
103
104         bool side = value < currentNode.getData();
105
106         while (side ? !currentNode.leftIsNull() : !currentNode.rightIsNull()) {
107             currentNode = side ? currentNode.left() : currentNode.right();
108             side = value < currentNode.getData();
109         }
110

```

```

111     if (side) {
112         currentNode.setLeft(node);
113     } else {
114         currentNode.setRight(node);
115     }
116
117     size++;
118     return;
119 }
120
121 void remove(T value) {
122     if (trunk == nullptr) {
123         return;
124     }
125
126     bool currentNodeIsRoot = true;
127     BSTNode<T> currentNodeBranch = *trunk;
128     BSTNode<T> currentNode = *trunk;
129
130     bool side = value < currentNode.getData();
131
132     while (currentNode.getData() != value) {
133         currentNodeBranch = currentNode;
134         currentNodeIsRoot = false;
135
136         side = value < currentNode.getData();
137         if (side ? currentNode.leftIsNull() : currentNode.rightIsNull()) {
138             return;
139         }
140
141         currentNode = side ? currentNode.left() : currentNode.right();
142     }
143
144     if (currentNode.leftIsNull()) {
145         if (currentNode.rightIsNull()) {
146             if (currentNodeIsRoot) {
147                 trunk.reset();
148             } else {
149                 if (side) {
150                     currentNodeBranch.resetLeft();
151                 } else {
152                     currentNodeBranch.resetRight();
153                 }
154             }
155         } else {
156             if (currentNodeIsRoot) {
157                 BSTNode<T> *newTrunk = trunk.releaseRight();
158                 delete trunk;
159                 trunk = make_unique<T>(newTrunk);
160             } else {
161                 BSTNode<T> *node;
162                 if (side) {
163                     node = currentNodeBranch.releaseLeft();
164                 } else {
165                     node = currentNodeBranch.releaseLeft();
166                 }
167

```



```

168         currentNodeBranch.setRight((*node).getRight());
169         delete node;
170     }
171 }
172 } else {
173     if (currentNodeIsRoot) {
174         BSTNode<T> *newTrunk = trunk.releaseLeft();
175         BSTNode<T> right = *trunk.releaseRight();
176         delete trunk;
177         trunk = make_unique<T>(newTrunk);
178         insert(right);
179     } else {
180         BSTNode<T> *node;
181         if (side) {
182             node = currentNodeBranch.releaseLeft();
183         } else {
184             node = currentNodeBranch.releaseLeft();
185         }
186
187         currentNodeBranch.setRight((*node).getRight());
188         insertNode((*node).releaseRight());
189         delete node;
190     }
191 }
192
193 return;
194 }
195 };
196
197 int main() {
198     return 0;
199 }

```