

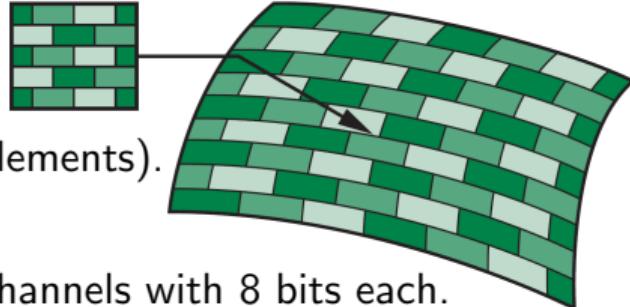
02561 Computer Graphics

Texture mapping

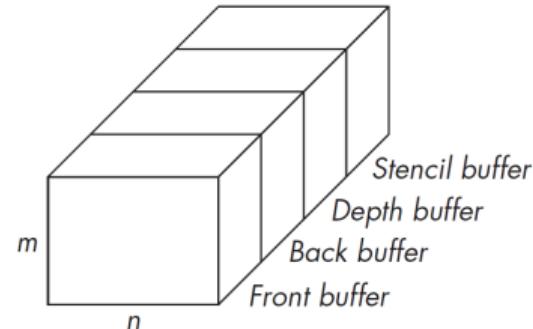
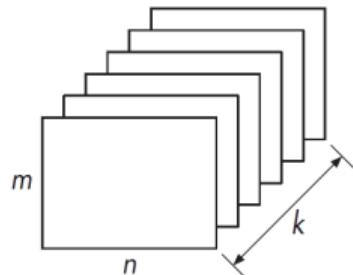
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Images, textures, and buffers



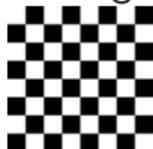
- ▶ A **digital image** is an array of pixels (picture elements).
- ▶ Image resolution and pixel data type vary.
- ▶ The more common type is R8G8B8: 3 colour channels with 8 bits each.
- ▶ A **texture** is an image that we can use to influence the colour of a fragment.
- ▶ A **buffer** is a block of memory: a discrete multidimensional (possibly layered) array.



- ▶ Vertex buffer (1D example): position, colour, texture coordinate, and index layers.
- ▶ Framebuffer (2D example): front colour, back colour, depth, and stencil layers.

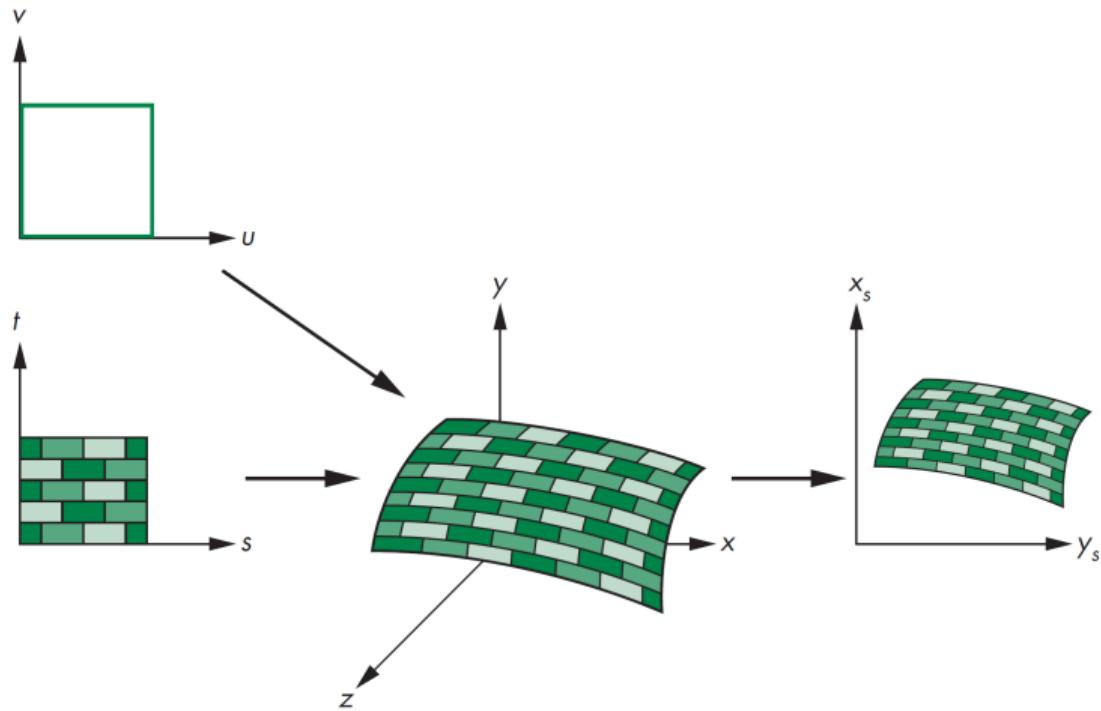
Texture mapping

- ▶ We need:
 - An image.
 - Texture coordinates.



- ▶ Quad example:

```
var texCoords = [  
    vec2(0.0, 0.0),  
    vec2(1.0, 0.0),  
    vec2(0.0, 1.0),  
    vec2(1.0, 1.0) ];
```



- ▶ This data needs to be uploaded to the GPU.
- ▶ Upload texture coordinates as another layer in the vertex buffer (like normals).
- ▶ We can load or generate an image and then upload it as a texture image.

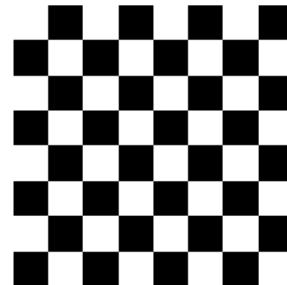
Loading or generating an image

- ▶ Generating an image: create an array of the right type and size:

```
var myTexels = new Uint8Array(4*texSize*texSize); // 4 for RGBA image, texSize is the resolution
```

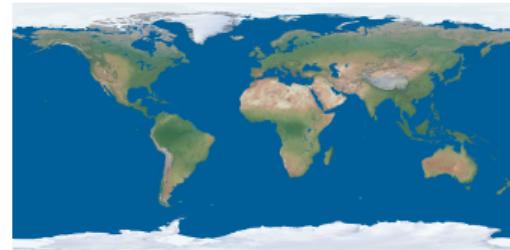
- ▶ Checkerboard example:

```
for(var i = 0; i < texSize; ++i)
  for(var j = 0; j < texSize; ++j)
  {
    var patchx = Math.floor(i/(texSize/numRows));
    var patchy = Math.floor(j/(texSize/numCols));
    var c = (patchx%2 != patchy%2 ? 255 : 0);
    var idx = 4*(i*texSize + j);
    myTexels[idx] = myTexels[idx + 1] = myTexels[idx + 2] = c;
    myTexels[idx + 3] = 255;
  }
```

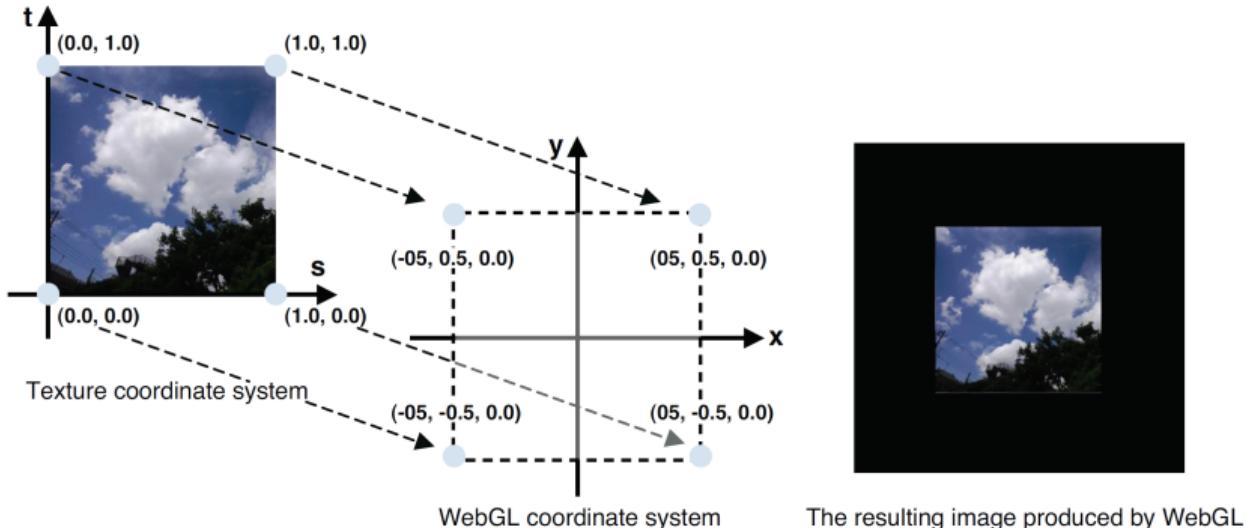


- ▶ Loading an image (asynchronously):

```
var image = document.createElement('img');
image.crossorigin = 'anonymous';
image.onload = function () { /* Insert WebGL texture initialization here */ };
image.src = 'earth.jpg';
```



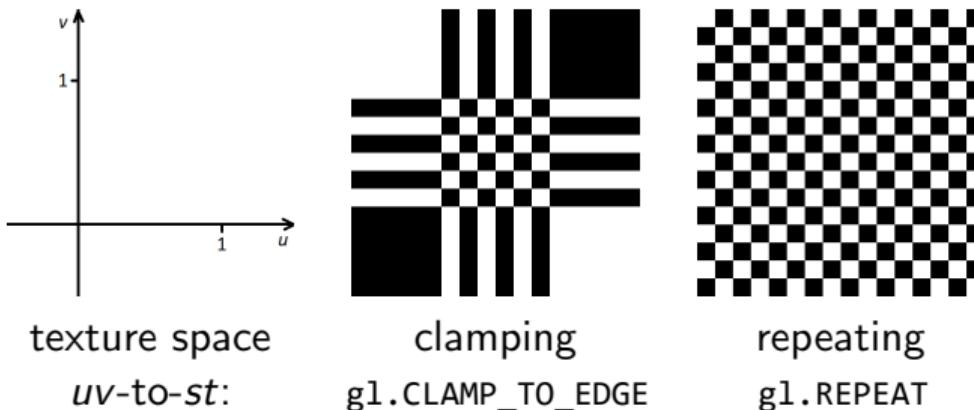
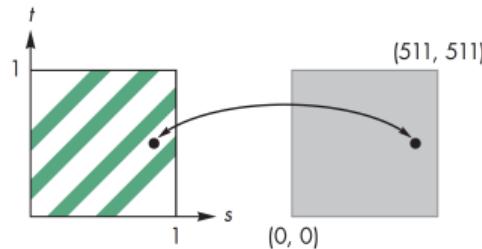
Texture coordinates



- ▶ We assign texture coordinates (u, v) to each vertex.
- ▶ A modeling tool like Blender can be used to generate texture coordinates.
- ▶ This is called a *uv-mapping* of the surface.
- ▶ We can then load texture coordinates together with our triangle mesh.
- ▶ **Project suggestion:** Extend the OBJ parser so that it can load texture coordinates.

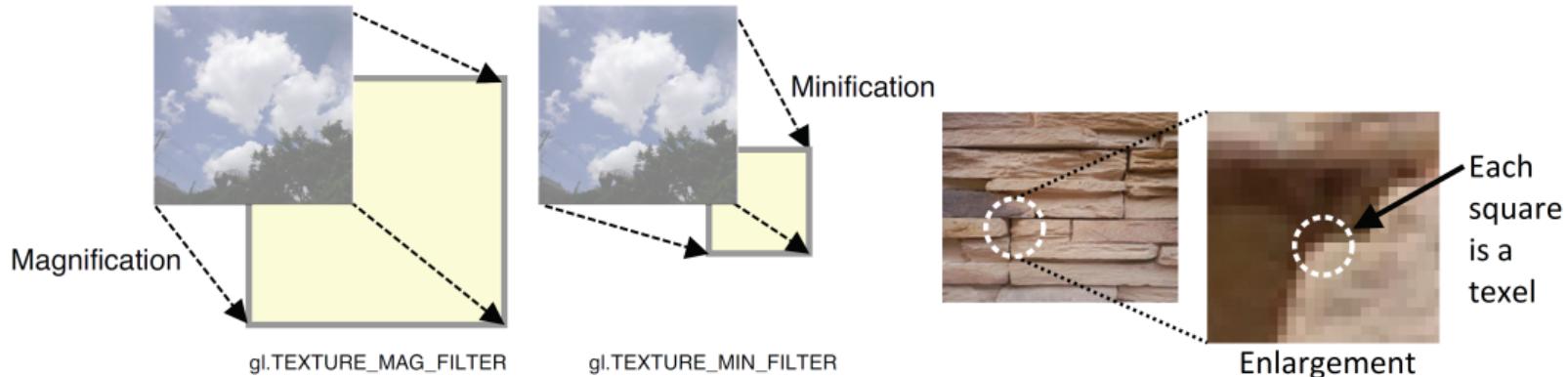
Texture wrapping

- ▶ Let us map the texture image to an st -coordinate system where the image is always in the region with $s, t \in [0, 1]$.
- ▶ We map st -coordinates to uv -coordinates by either clamping u and/or v to $[0, 1]$ or by removing the integer part(s) of u and/or v so that the texture repeats itself throughout the texture space.



```
gl.texParameteri(gl.TEXTURE_2D, gl.TEXTURE_WRAP_S, uv-to-st);  
gl.texParameteri(gl.TEXTURE_2D, gl.TEXTURE_WRAP_T, uv-to-st);
```

Texture magnification and minification



- ▶ Texture magnification: When a texel covers multiple pixels.
- ▶ Texture minification: When a pixel covers multiple texels.
- ▶ Magnification requires interpolation, minification requires averaging.
- ▶ If we don't care, we use nearest-neighbor filtering:

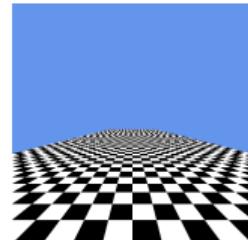
```
gl.texParameteri(gl.TEXTURE_2D, gl.TEXTURE_MIN_FILTER, gl.NEAREST);
gl.texParameteri(gl.TEXTURE_2D, gl.TEXTURE_MAG_FILTER, gl.NEAREST);
```

Exercise: texturing a quad (W06P1)

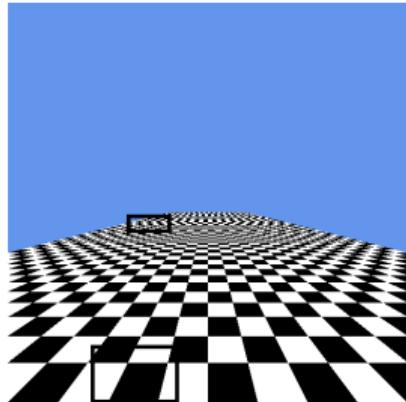
- ▶ Render a quad with
 - ▶ vertex positions: $(-4, -1, -1), (4, -1, -1), (4, -1, -21), (-4, -1, -21)$
 - ▶ texture coordinates: $(-1.5, 0), (2.5, 0), (2.5, 10), (-1.5, 10)$
- ▶ Use identity view matrix and a projection matrix generating a 90° field of view.
- ▶ Generate a checkerboard image and upload it to the GPU using

```
gl.texImage2D(gl.TEXTURE_2D, 0, gl.RGBA, texSize, texSize, 0, gl.RGBA, gl.UNSIGNED_BYTE, myTexels);
```
- ▶ Set minification and magnification filtering modes to `gl.NEAREST`.
- ▶ Set *uv*-to-*st* wrapping mode in the *s* and *t* directions to `gl.REPEAT`.
- ▶ Create attribute and varying variables for the texture coordinates in your shaders.
- ▶ Create a uniform sampler2D and set it to the integer 0 in JavaScript.
- ▶ Use the fragment shader to texture your quad:

```
uniform sampler2D texMap;  
varying vec2 fTexCoord;  
void main() {  
    gl_FragColor = texture2D(texMap, fTexCoord);  
}
```



Texture filtering (bilinear interpolation)



aliasing due to magnification



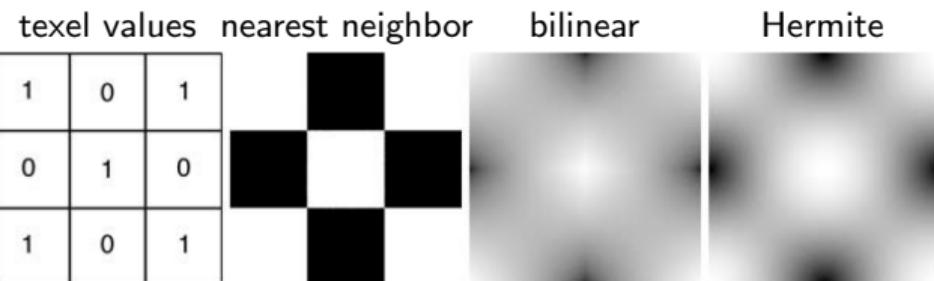
aliasing due to minification



- ▶ When texels are seen up close, we see staircase artifacts.
- ▶ When texels are seen from afar, we don't see the right pattern.
- ▶ Filtering techniques:

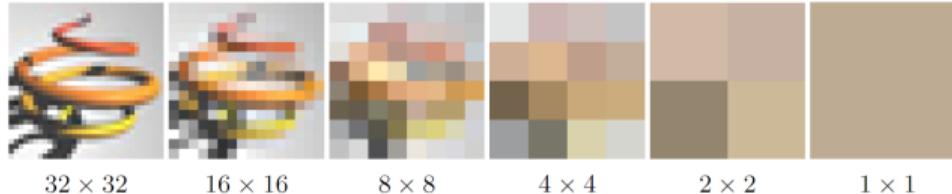
Use `gl.LINEAR`
for bilinear filtering.

texel values		
1	0	1
0	1	0
1	0	1



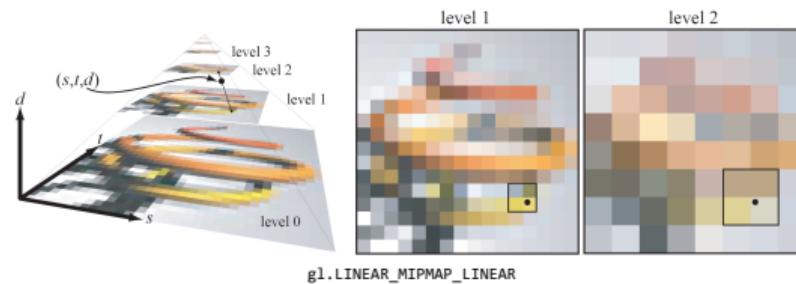
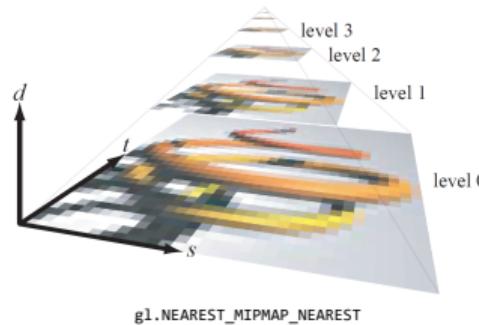
Texture mipmapping

- ▶ Linear filtering has little effect on minification issues.
- ▶ When a texture has a resolution that is powers of two, we can use a box filter.



```
gl.generateMipmap(gl.TEXTURE_2D);
```

- ▶ We can apply the filter iteratively until we reach a level where the number of texels is similar to those covered by a pixel.



References

- Lance Williams. Pyramidal parametrics. Computer Graphics (SIGGRAPH '83) 17(3), pp. 1–11, July 1983.
- Tomas Akenine-Möller. Some notes on Graphics Hardware. Course notes, Lund University, November 2012.

Exercise: try different wrapping and filtering techniques (W06P2)

- ▶ We have the following texture wrapping options:
 - ▶ gl.CLAMP_TO_EDGE
 - ▶ gl.REPEAT
- ▶ For magnification, we have the following filtering options:
 - ▶ gl.NEAREST
 - ▶ gl.LINEAR (gl.NEAREST + 1)
- ▶ For minification, we have the following filtering options:
 - ▶ gl.NEAREST
 - ▶ gl.LINEAR (gl.NEAREST + 1)
 - ▶ gl.NEAREST_MIPMAP_NEAREST
 - ▶ gl.LINEAR_MIPMAP_NEAREST (gl.NEAREST_MIPMAP_NEAREST + 1)
 - ▶ gl.NEAREST_MIPMAP_LINEAR (gl.NEAREST_MIPMAP_NEAREST + 2)
 - ▶ gl.LINEAR_MIPMAP_LINEAR (gl.NEAREST_MIPMAP_NEAREST + 3)
- ▶ Create buttons and selection menus, so that the user can switch between these texturing modes.
- ▶ Remember to request a new animation frame when the user selects a new mode.

Spherical inverse mapping

- ▶ Spherical coordinates provide a *uv*-mapping of the unit sphere: $(u, v) = \left(1 - \frac{\varphi}{2\pi}, \frac{\theta}{\pi}\right)$.
- ▶ The corresponding Euclidean space coordinates are: $(x, y, z) = (\sin \theta \cos \varphi, \sin \theta \sin \varphi, \cos \theta)$.
- ▶ Alternatively, if we want *y* to be the up direction, as in eye space (and in the figure to the right), then $(x, y, z) = (\sin \theta \cos \varphi, \cos \theta, \sin \theta \sin \varphi)$.
- ▶ Inserting *u* and *v*, we have the *uv*-mapping
$$(x, y, z) = (\sin(\pi v) \cos(2\pi(1 - u)), \cos(\pi v), \sin(\pi v) \sin(2\pi(1 - u)))$$
.
- ▶ The inverse mapping provides texture coordinates given a position on the unit sphere (such as a surface normal).
- ▶ We have $y = \cos(\pi v)$ and $\frac{z}{x} = \tan(2\pi(1 - u))$, then
$$u = 1 - \frac{\tan^{-1} \frac{z}{x}}{2\pi} = 1 - \frac{\text{atan}(z, x)}{2\pi}$$
 and $v = \frac{\cos^{-1} y}{\pi}$.

