Binary Search Tree Analysis

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Abstract

Binary Search Trees are a useful database for storing data, which its elements can be compared one to another (e.g. integers or strings). Programs which use BSTs should support operations like insertions, deletions and creations of new nodes in the tree, while keeping the BST structure valid. This paper will introduce an analysis of such programs, where the purpose is to verify the validity of the BSTs in the program at each point of the execution.

1 Introduction

1.1 BST Definition

A binary search tree is a rooted tree, where each of its nodes has at most two children: "left" and "right". Also, each node contains a key, which in our case would be an integer, such that the keys satisfy the following rule: given a node n with a key d,

- 1. for each key d' of a node in n's left subtree, $d' \leq d$
- 2. for each key d'' of a node in n's right subtree, $d'' \ge d$

1.2 BST Implementation

For analyzing actual programs, we will assume that each node of the BST is represented by a structure (or class) with 3 fields: data, left, right. data is the key stored in the node, and left and right are the left and right children, respectively.

The analyzing method will consider programs such that each statement in it is one of the regular statements: if, while, or one of the commands in table 1.

Command	Effect
createNode(n,d)	Creates a new node n with the key d
setValue(n,d)	Sets the key of the node n to d
setLeft(n, n')	Sets the left child of n to n'
setRight(n, n')	Sets the right child of n to n'

Table 1: Commands table.

2 Lattices and Galois Connection

2.1 Concrete States Lattice

The state at each point of the analyzed program will be considered as a collection of nodes and the values of their fields. Namely, if N is the set of the nodes created in the program, then a state is a **partial** function $s: N \to N \times \mathbb{Z} \times N$, such that s(n) = (n.left, n.data, n.right). I.e. s is an univalent relation and if s(n) isn't defined, we denote it s(n) = #. Actually, n.left or n.right may be null, so we should consider the set $N^+ = N \cup \{null\}$, so a state is $s: N \to N^+ \times \mathbb{Z} \times N^+$.

In a single point in the program, there might be several states that are possible (depends on the inputs). Therefore, we represent each point as a **collection** of states $S \subseteq \{s \mid s : N \to N^+ \times \mathbb{Z} \times N^+\}$. Also, we have to ensure that if s(n) = # (n isn't defined), then there's no $n' \in N$ such that n'.left = n or n'.right = n. We will also need a special element for when we cannot delimit the possible states - this element is denoted by \top .

Finally, the lattice C of the concrete states is defined by:

$$C = P_{<\infty}(\{s \mid s \text{ is a partial function } s: N \to N^+ \times \mathbb{Z} \times N^+$$

s.t. $s(n) = (n_1, d, n_2) \implies s(n_1), s(n_2) \neq \#\}) \cup \{\top\},$

where $P_{<\infty}(D)$ is the collection of the finite subsets of D. The properties of this lattice are:

$$S \sqsubseteq T \iff S \subseteq T$$
$$S \sqcup T := S \cup T$$
$$S \sqcap T := S \cap T$$

For \top , every $S \in C$ satisfy $S \sqsubseteq \top$, $S \sqcup \top = \top \sqcup S = \top$ and $S \sqcap \top = \top \sqcap S = S$. It is easy to check that those definitions create a complete lattice.

2.2 Abstract States Lattice

As the purpose of the analysis is to check the validity of the BST, we would like to define a representation of the concrete states so that it will be easy to check the order of the keys. A BST will be represented by a string that indicates the structure of the BST and the range of the possible values of each node.

Formally, a **BST** string will be defined recursively:

- 1. The empty string, ε , is a BST string.
- 2. If $n \in N$, $d_1, d_2 \in \mathbb{Z}$ and r_1, r_2 are BST strings, then $(r_1n[d_1 d_2]r_2)$ is also a BST string.

It can be seen that a BST string is always an element of the set $(\{(,),[,],-\}\cup\mathbb{Z}\cup N)^*$. Intuitively, the BST string $\omega=(r_1n[d_1-d_2]r_2)$ represents a BST which its root is the node n with the data between d_1 and d_2 , its left subtree is represented by r_1 and its right subtree is represented by r_2 . We will later see that sometimes we would like to express the idea that **we don't know** the identity of the node in a certain place in the tree. Therefore, in the BST string $(r_1n[d_1-d_2]r_2)$, we allow n to be n_{τ} - a special node that was designed for this $(n_{\tau} \notin N)$, and the programmer can't access it).

By T we denote the set of the BST strings. Now, the lattice A of the abstract states is defined by:

$$A = \{X \subseteq T \mid \forall \omega \in X: \ root(\omega) \notin \{null, n_{\tau}\},$$

$$\forall \omega_1, \omega_2 \in X : root(\omega_1) = root(\omega_2) \implies \omega_1 = \omega_2 \} \cup \{\tau\}$$

where root of a BST string defined as follows:

$$root((r_1n[...]r_2)) = n; \ root(\varepsilon) = null$$

And τ is an additional special abstract element, which expresses the idea that we don't know the structure or the keys range in a concrete state.

The reason that we keep **a subset** of BST strings is that there might be more than one BST at the same time in the analyzed program. We can see that two different BST strings in X cannot have the same root, and that the empty string and n_{τ} -rooted strings cannot be in X.

Example 1. A valid abstract state:

Example 1. A valid dostract state:
$$\left\{\left((n_1[0-3])n_0[4-5]\right), \left(n_2[0-0](n_1[0-3])\right)\right\}$$
. The first string has the root n_0 , and the second's root is n_2 .

We now define the partial order over the set. First, we recursively define an order over BST strings, then over the elements of A:

- 1. For any $\omega \in T$, $\varepsilon \leq \omega$,
- 2. $(r_1 n[d_1 d_2]r_2) \leq (r'_1 n'[d'_1 d'_2]r'_2)$ iff:
 - $r_1 \leq r'_1, r_2 \leq r'_2$
 - $d'_1 \le d_1, d_2 \le d'_2$ (i.e. $[d_1, d_2] \subseteq [d'_1, d'_2]$)
 - n = n' or $n' = n_{\tau}$
- 3. $\forall X \in A, \ X \sqsubseteq \tau$

4. For
$$X, Y \in A \setminus \{\tau\}$$
, $X \sqsubseteq Y \iff \forall \omega_1 \in X \exists \omega_2 \in Y \ s.t. \ \omega_1 \preceq \omega_2$

A simple inductive proof would show that \leq is a partial order over the set T, and after that it is easy to verify that \sqsubseteq is reflexive and transitive. The proof of its antisymmetry is the following:

Assume that $X \sqsubseteq Y$ and $Y \sqsubseteq X$.

If
$$X = \tau$$
 or $Y = \tau$, then by \sqsubseteq definition: $X = Y = \tau$.

Else, let $\omega \in X$. There is some $\omega' \in Y$ s.t. $\omega \leq \omega'$, and there is $\omega'' \in X$ s.t. $\omega' \leq \omega''$. Therefore, we get $\omega \leq \omega''$. Note that $\omega \neq \varepsilon$ and that ω, ω''

can't be with the root n_{τ} , so by the definition of $\leq : root(\omega) = root(\omega'')$. But then $\omega = \omega''$ (X cannot contain two different strings with the same root). In conclusion, we have $\omega \leq \omega' \leq \omega$ and that implies $\omega = \omega' \in Y$. We proved that $X \subseteq Y$, and by symmetry: X = Y.

Before the definitions of the \sqcup and \sqcap operators, we define a helper function:

$$treeof_X(n) = \begin{cases} \omega & \exists \omega \in X \text{ s.t. } root(\omega) = n \\ \varepsilon & \text{else} \end{cases}$$

where $X \in A \setminus \{\tau\}$ and $n \in N$. Given a set $X \in A \setminus \{\tau\}$, this function returns the unique *BST string* in X with the specified node as its root. If such string doesn't exists, ε will be returned.

Join and meet will also be defined first to BST strings and then to A:

- 1. For any $\omega \in T$, $\varepsilon \vee \omega = \omega \vee \varepsilon = \omega$
- 2. $(r_1 n[d_1 d_2]r_2) \vee (r'_1 n[d'_1 d'_2]r'_2) = (r_1 \vee r'_1 n[min\{d_1, d'_1\}, max\{d_2, d'_2\}]r_2 \vee r'_2)$
- 3. If $n \neq n'$, $(r_1 n[d_1 d_2]r_2) \vee (r'_1 n'[d'_1 d'_2]r'_2) = (r_1 \vee r'_1 n_\tau [\min\{d_1, d'_1\}, \max\{d_2, d'_2\}]r_2 \vee r'_2)$
- 4. $\forall X \in A, \ \tau \sqcup X = X \sqcup \tau = \tau$
- 5. For $X, Y \in A \setminus \{\tau\}$, $X \sqcup Y = \{treeof_X(n) \lor treeof_Y(n) \mid n \in N\}$
- 6. For any $\omega \in T$, $\varepsilon \wedge \omega = \omega \wedge \varepsilon = \varepsilon$
- 7. $(r_1n[d_1-d_2]r_2) \wedge (r_1'n[d_1'-d_2']r_2') = (r_1 \wedge r_1'n[max\{d_1,d_1'\},min\{d_2,d_2'\}]r_2 \wedge r_2')$
- 8. If $n \neq n'$ and $n, n' \neq n_{\tau}$, $(r_1 n [d_1 d_2] r_2) \wedge (r'_1 n' [d'_1 d'_2] r'_2) = \varepsilon$
- 9. If $n \neq n_{\tau}$, $(r_1 n[d_1 d_2]r_2) \wedge (r'_1 n_{\tau}[d'_1 d'_2]r'_2) = (r_1 \wedge r'_1 n[max\{d_1, d'_1\}, min\{d_2, d'_2\}]r_2 \wedge r'_2)$
- 10. $\forall X \in A, \ \tau \cap X = X \cap \tau = X$
- 11. For $X, Y \in A \setminus \{\tau\}, X \cap Y = \{treeof_X(n) \land treeof_Y(n) \mid n \in N\}$

Example 2.
$$\left((n_1[2-3])n_0[4-6](n_2[8-8])\right) \lor \left((n_1[0-0])n_0[3-5](n_2[6-9])\right) = \left((n_1[0-3])n_0[3-6](n_2[6-9])\right),$$

 $\left((n_1[2-3])n_0[4-6](n_3[8-9])\right) \lor \left(n_0[3-5](n_2[6-9])\right) = \left((n_1[2-3])n_0[3-6](n_\tau[6-9])\right).$

2.3 The Galois Connection

In order to formalize the idea of the BST strings as representations of collections of BSTs, we will now define a Galois connection (C, α, γ, A) between the lattices. Recall that $\alpha: C \to A$ is the abstraction function (maps concrete states to their abstract representations) and $\gamma: A \to C$ is the concretization function (translate the abstract representation into a concrete state).

2.3.1 The Abstraction Function α

Before we can define α , we will define some terms and functions.

- 1. A *cycle* in a state $s: N \to N^+ \times \mathbb{Z} \times N^+$ is a sequence of nodes n_1, n_2, \ldots, n_t such that $\forall i = 1, \ldots, t-1, \ s(n_i) = (n_{i+1}, \ldots)$ or $s(n_i) = (\ldots, n_{i+1})$, and $s(n_t) = (n_1, \ldots)$ or $s(n_t) = (\ldots, n_1)$. i.e. each node is a parent of the next one.
- 2. A **root node**, with respect to a state $s: N \to N^+ \times \mathbb{Z} \times N^+$, is a node $n \in N$ such that $s(n) \neq \#$ and $\forall n' \in N, s(n') \neq (n, ...)$ and $s(n') \neq (..., n)$. Namely, n has no parents in s. For $m \in N$ a set of states S, we denote: $G_m(S) = \{s \in S \mid m \text{ is a root node of } s\}$.
- 3. Given a state $s: N \to N^+ \times \mathbb{Z} \times N^+$ and a node (or null) $n \in N^+$, we define recursively the function $down_s(n)$:
 - $down_s(null) = \varepsilon$
 - For $n \neq null\ s.t.\ s(n) = (n_1, d, n_2),$ $down_s(n) = (down_s(s(n_1))n[d-d]down_s(s(n_2))$

This function creates the matched BST string of the subtree of n. Note that $down_s(n)$ isn't defined only if s has a cycle, and indeed, we use it only for s's without cycles.

Example 3. Let s be defined by:

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\begin{split} s(n_0) &= (n_1, 4, n_3), \\ s(n_1) &= (null, 1, n_2), \\ s(n_2) &= (null, 3, null), \\ s(n_3) &= (null, 6, null). \\ Then: \ down_s(n_0) &= (down_s(n_1)n_0[4-4]down_s(n_3)) = \\ \bigg( \Big( n_1[1-1](n_2[3-3]) \Big) n_0[4-4] \Big( n_3[6-6] \Big) \bigg). \end{split}
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4. Given a state $S \in C$, if S = T we define $\alpha(S) = \tau$. Else,

$$\alpha(S) = \begin{cases} \tau & S \text{ contains a state with a } cycle \\ \bigsqcup_{s \in S} \{down_s(n) \mid n \text{ is a } root \text{ node in } s\} & else \end{cases}$$

As it can be seen, if S contains a state with a cycle, α will return τ - means that we cannot interpret it as a tree at all. Else, we take all the $root\ nodes$ in the states of S and create their $BST\ string$. Then we collect all the created $BST\ strings$ and join them (the join definition can be naturally extended to any finite collection of sets).

A useful fact is that by \sqcup definition, in case that $S \neq \top$ and doesn't contain a state with a *cycle*, $\alpha(S)$ can also be written as:

$$\alpha(S) = \{ \bigvee_{s \in G_m(S)} down_s(m) \mid m \in N \}$$

Lemma 1. Let s be a state. For every node n' s.t. $s(n') \neq \#$, there exists a root node n of s, s.t. $down_s(n')$ is a substring of $down_s(n)$.

Proof. By looking for a parent of n' (i.e. n'' s.t. s(n'') = (n', ...) or <math>s(n'') = (..., n')), then looking for a parent of its parent, and so on, we can find a sequence of nodes: $n_0, n_1, n_2, ..., n_k$ such that:

- n_k is a root node of s,
- $n_0 = n'$,
- $\forall i = 1, ..., k, n_i \text{ is a parent of } n_{i-1}.$

Now we can prove by induction that $down_s(n')$ is a substring of $down_s(n_i)$, for all i

- For i = 0, $down_s(n_0) = down_s(n')$ and we're done.
- For i > 0, w.l.o.g. we assume that $s(n_i) = (n_{i-1}, ...)$. Then, $down_s(n_i) = (down_s(n_{i-1}, ...))$, and since $down_s(n_{i-1})$ has $down_s(n')$ as a substring, so is $down_s(n_i)$.

In conclusion, we get that $n = n_k$ is a root node of s, and $down_s(n') = down_s(n_0)$ is a substring of $down_s(n) = down_s(n_k)$.

2.3.2 The Concretization Function γ

The definition of γ can completely derived from α 's definition, as known from the general theory of Galois Connections. We now write this definition, using the terminology that already mentioned:

For $X \in A$:

$$\gamma(X) = \begin{cases} \top & X = \tau \\ \{s \mid s \text{ doesn't contain a } cycle \text{ and } \forall root \ node \ n \text{ in } s \ \exists \omega \in X : down_s(n) \leq \omega \} \end{cases} \text{ else}$$

In words, every BST that we can build from a state $s \in \gamma(X)$ has to be represented by a (part of) $\omega \in X$.

2.3.3 The Galois Connection Property

To show that (C, α, γ, A) is indeed a Galois connection, the following property should be proved:

$$\forall S \in C \text{ and } X \in A, \ \alpha(S) \sqsubseteq X \iff S \sqsubseteq \gamma(X)$$

We prove the property by proving each implication separately:

• ⇒

If $S = \top$ or S contains a state with a *cycle*, then $\alpha(S) = \tau$, and therefore we know that $\tau \sqsubseteq X$. It is only possible if $X = \tau$, and that means that $\gamma(X) = \top$, so obviously $S \sqsubseteq \top = \gamma(X)$.

Else, S is a set of states which none of them contains a cycle. Given a $s \in S$, we have to show that for every root node n, there is $\omega \in X$ s.t. $down_s(n) \leq \omega$.

Let $n \in N$ be a root node in s. $down_s(n)$ is well defined because s doesn't contain cycles. When applying α on S, $down_s(n)$ is joined with other BST strings, and the result ω' satisfy $down_s(n) \preceq \omega' \preceq \omega$ for some $\omega \in X$ (because it is given that $\alpha(S) \sqsubseteq X$). By transitivity of \preceq , $down_s(n) \preceq \omega$, and we get that $s \in \gamma(X)$.

• <=:

If $X = \tau$, then $\alpha(S) \sqsubseteq X$ is trivially satisfied.

If $S = \top$, then since $S \sqsubseteq \gamma(X)$, it has to be that $\gamma(X) = \top$. That means that $X = \tau$, and of course $\alpha(S) \sqsubseteq X$.

If S contains a state with a cycle, then it's impossible that $X \neq \tau$, because otherwise we have $S \subseteq \gamma(X)$ and $\gamma(X)$ is a set of states **without** cycles. Therefore, $X = \tau$, and again we get instantly that $\alpha(S) \sqsubseteq X$.

Else, fix $n \in N$. For every $s \in G_n(S)$, we know that $s \in \gamma(X)$ and therefore there exists some $\omega_s \in X$ with $down_s(n) \preceq \omega_s$. By \preceq definition, the root of each of these ω_s is n, and therefore they have to be **the same** BST string (because X doesn't contain two different strings with the same root). So, we can denote $\omega_s = \omega$, and then for every $s \in G_n(S)$: $down_s(n) \preceq \omega \implies \bigvee_{s \in G_n(S)} down_s(n) \preceq \omega$.

This is true for all $n \in \mathbb{N}$, and therefore:

$$\alpha(S) = \{ \bigvee_{s \in G_n(S)} down_s(n) \mid n \in N \} \sqsubseteq X$$

3 Transformers

The last step before we can continue to analyzing actual BST programs is to decide how we treat the commands in the program. The commands will act as a transformers on the Abstract lattice: $f^{\#}: A \to A$. The transformers will be tested with respect to f - the effect of the commands on the concrete states.

3.1 Replacement Functions

Most of the abstract transformers will use manipulations on BST strings, especially replacement of substrings with other strings. We now define three helper functions for replacing the left subtree of a node n, the right subtree of n or the value of n.

Given $\omega \in T$, $n \in N$ and $d \in \mathbb{Z}$, the functions $reL_{n,\omega}$, $reR_{n,\omega}$ and $reV_{n,d}$ will be defined recursively:

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• reL_{n,\omega}(\varepsilon) = reR_{n,\omega}(\varepsilon) = reV_{n,d}(\varepsilon) = \varepsilon
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• If n' \notin \{n, n_{\tau}\}, reL_{n,\omega}((r_1n'[d_1 - d_2]r_2)) = (reL_{n,\omega}(r_1)n'[d_1 - d_2]reL_{n,\omega}(r_2))reR_{n,\omega}((r_1n'[d_1 - d_2]r_2)) = (reR_{n,\omega}(r_1)n'[d_1 - d_2]reR_{n,\omega}(r_2))reV_{n,d}((r_1n'[d_1 - d_2]r_2)) = (reV_{n,d}(r_1)n'[d_1 - d_2]reV_{n,d}(r_2))
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• For n, $reL_{n,\omega}((r_1n[d_1-d_2]r_2)) = (\omega \vee reL_{n,\omega}(r_1)n[d_1-d_2]reL_{n,\omega}(r_2))$ $reR_{n,\omega}((r_1n[d_1-d_2]r_2)) = (reR_{n,\omega}(r_1)n[d_1-d_2]\omega \vee reR_{n,\omega}(r_2))$ $reV_{n,d}((r_1n[d_1-d_2]r_2)) = (reV_{n,d}(r_1)n[d-d]reV_{n,d}(r_2))$

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• For n_{\tau}, reL_{n,\omega}((r_{1}n_{\tau}[d_{1}-d_{2}]r_{2})) = (\omega \vee reL_{n,\omega}(r_{1})n_{\tau}[d_{1}-d_{2}]reL_{n,\omega}(r_{2}))
reR_{n,\omega}((r_{1}n_{\tau}[d_{1}-d_{2}]r_{2})) = (reR_{n,\omega}(r_{1})n_{\tau}[d_{1}-d_{2}]\omega \vee reL_{n,\omega}(r_{2}))
reV_{n,d}((r_{1}n_{\tau}[d_{1}-d_{2}]r_{2})) = (reV_{n,d}(r_{1})n_{\tau}[min\{d_{1},d\}-max\{d_{2},d\}]reV_{n,d}(r_{2}))
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As we can see, n_{τ} is treated like it may be n, but also may not.

Lemma 2. $reL_{n,\omega}$, $reR_{n,\omega}$ and $reV_{n,d}$ are monotonic, i.e. $\omega_1 \preceq \omega_2 \implies reL_{n,\omega}(\omega_1) \preceq reL_{n,\omega}(\omega_2)$, $reR_{n,\omega}(\omega_1) \preceq reR_{n,\omega}(\omega_2)$ and $reV_{n,d}(\omega_1) \preceq reV_{n,d}(\omega_2)$

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Lemma 3. reL_{n,\omega}(\omega_1) \vee reL_{n,\omega}(\omega_2) \leq reL_{n,\omega}(\omega_1 \vee \omega_2), reR_{n,\omega}(\omega_1) \vee reR_{n,\omega}(\omega_2) \leq reR_{n,\omega}(\omega_1 \vee \omega_2) and reV_{n,d}(\omega_1) \vee reV_{n,d}(\omega_2) \leq reV_{n,d}(\omega_1 \vee \omega_2).
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The proof of these lemmas is by a simple structural induction, where the second one can be easily derived from the first.

3.2 Transformers Definitions

First of all, for every concrete transformer f and abstract transformer $f^{\#}$, $f(\top) = \top$, $f^{\#}(\tau) = \tau$. An addition concept that should be noticed in the definitions is that in some states, a command may be **not valid** (i.e. create a new node with a name that already exists etc.). In those cases, as it can be seen

from the following definitions, we just ignore the "invalid" states. The following definitions are for the non-trivial cases. In all of the definitions, $s[n \leftarrow a]$ is the same state as s, only with the output of n set to a.

1. For each $S \in C$, $n \in \mathbb{N}$, $d \in \mathbb{Z}$:

$$\llbracket createNode(n,d) \rrbracket(S) = \{ s[n \leftarrow (null,d,null)] \mid s \in S \text{ s.t. } s(n) = \# \}$$

2. For each $S \in C$, $n, n' \in N$:

$$[setLeft(n, n')](S) =$$

$$\{s[n \leftarrow (n',d,n_r)] \mid s \in G_{n'}(S) \text{ s.t. } s(n) = (null,d,n_r)\} \setminus \{s' \mid s' \text{ is a state with a } cycle\}$$

 $\|setRight(n,n')\|(S) =$

$$\{s[n \leftarrow (n_l, d, n')] \mid s \in G_{n'}(S) \text{ s.t. } s(n) = (n_l, d, null)\} \setminus \{s' \mid s' \text{ is a state with a } cycle\}$$

Intuitively, the command setLeft(n, n') makes sense only if n' is already defined as a root node of s, and n' is not one of the ancestors of n (therefore we subtract the states that after the change contain a cycle). Another restriction we added is that n can't have a left child (the same goes for setRight(n, n')).

3. For each $S \in C$, $n \in N$, $d \in \mathbb{Z}$:

$$[setValue(n,d)](S) = \{s[n \leftarrow (n_l,d,n_r)] \mid s \in S \text{ s.t. } s(n) = (n_l,d',n_r)\}$$

We now define the matching abstract transformers:

1. For each $X \in A$, $n \in \mathbb{N}$, $d \in \mathbb{Z}$,

$$[createNode(n,d)]^{\#}(X) = X \sqcup \{(n[d-d])\}$$

2. First, for $X \in A$, $n, n' \in N$ we denote $\omega' = treeof_X(n')$, and then:

$$[setLeft(n, n')]^{\#}(X) = \{reL_{n,\omega'}(\omega) \mid \omega \in X\} \setminus \{\omega'\}$$

Symmetrically,

$$[setRight(n, n')]^{\#}(X) = \{reR_{n,\omega'}(\omega) \mid \omega \in X\} \setminus \{\omega'\}$$

3. For each $X \in A$, $n \in \mathbb{N}$, $d \in \mathbb{Z}$,

$$\llbracket setValue(n,d) \rrbracket^{\#}(X) = \{ reV_{n,d}(\omega) \mid \omega \in X \}$$

3.3 Soundness Property

The following proofs will show that the abstract transformers defined above are **sound**, with respect to the matching concrete transformers. More precisely, we have to show that for every concrete transformer f, the matching abstract transformer $f^{\#}$, and $X \in A$:

$$\alpha(f(\gamma(X))) \sqsubseteq f^{\#}(X)$$

Note that for the edge case $X = \tau$, we get

$$\gamma(X) = \top \implies f(\gamma(X)) = \top \implies \alpha(f(\gamma(X))) = \tau$$

and indeed $f^{\#}(X) = \tau$.

Now we prove the soundness property for the non trivial cases.

1. $[createNode(n, d)]^{\#}$ is sound:

Proof. Suppose $\omega \in \alpha(f(\gamma(X)))$. Then, $\omega = \bigvee_{s' \in G_m(f(\gamma(X)))} down_{s'}(m)$ for some $m \in N$. If m = n then by f's definition, $\forall s' \in G_m(f(\gamma(X)))$ s'(n) = (null, d, null) and then $\forall s' \in G_m(f(\gamma(X)))$ $down_{s'}(n) = (n[d-d]) \implies \omega = \bigvee_{s' \in G_m(f(\gamma(X)))} down_{s'}(n) = (n[d-d]) \in f^{\#}(X)$.

If $m \neq n$, then $down_{s'}(m) = down_s(m)$, where $s' = s[n \leftarrow (null, d, null)]$ and $s \in \gamma(X)$. This fact should be obvious, since s and s' have the same outputs on every node except n, and n can't appear in $down_s(m)$ or in $down_{s'}(m)$. Anyway, it can be simply proved by structural induction. So, we have: $\omega = \bigvee_{s' \in G_m(f(\gamma(X)))} down_{s'}(m) = \bigvee_{s \in G_m((\gamma(X)))} down_s(m) \in \alpha(\gamma(X))$.

By the Galois connection property, we know that $\alpha(\gamma(X)) \subseteq X$, i.e there is $\omega' \in X \subseteq X \cup (n[d-d])$ s.t. $\omega \preceq \omega'$.

This gives us finally: $\alpha(f(\gamma(X))) \sqsubseteq f^{\#}(X)$.

2. $[setLeft(n, n')]^{\#}$ is sound:

Proof. Here are two facts that will help us in the proof:

- Say that $s' \in G_m(f(\gamma(X)))$ for some $m \in N$. In particular, $s' = s[n \leftarrow (n',d,n_r)]$ where $s \in \gamma(X)$ (and $s(n) = (null,d,n_r)$). Suppose now that m isn't a root node of s, and it has a parent m^* . If $m^* \neq n$, then s' has the same output on m^* as s, and therefore m cannot be a root node in s', in contradiction. It means that $m^* = n$, but then $s(m^*) = s(n) = (null,d,n_r)$ which means that $m = n_r$. But that is not possible either, since $s'(n) = (n',d,n_r) \implies m = n_r$ isn't a root node of s'. Therefore, if m is a root node in s', then it is a root node of s.
- With the notations of the last paragraph, we now prove by structural induction that:

 $\forall m \in N^+ \ down_{s'}(m) \leq reL_{n,\omega'}(down_s(m)) \text{ where } \omega' = treeof_X(n').$

- If $down_{s'}(m) = \varepsilon$, then m = null, so $reL_{n,\omega'}(down_s(m)) = reL_{n,\omega'}(\varepsilon) = \varepsilon$.
- If $m \neq n$, and $s(m) = (m_1, d, m_2)$, then $s'(m) = (m_1, d, m_2)$, and by the induction assumption: $down_{s'}(m) = (down_{s'}(m_1)m[d-d]down_{s'}(m_2)) \leq (reL_{n,\omega'}(down_s(m_1))m[d-d]reL_{n,\omega'}(down_s(m_2))) = reL_{n,\omega'}((down_s(m_1)m[d-d]down_s(m_2))) = reL_{n,\omega'}(down_s(m)).$
- If m=n, and $s(n)=(null,d,n_r)$, then $s'(n)=(n',d,n_r)$, and therefore $down_{s'}(n)=(down_{s'}(n')n[d-d]down_{s'}(n_r))$. It has to be that $down_{s'}(n')=down_s(n')$, because the only possible difference between them is on n, which doesn't appear in $down_{s'}(n')$ (if it does, then s' contains a cycle in contradiction to f's definition). Remember that n' is a $root\ node$ of s, and therefore (since $s \in \gamma(X)$) $down_s(n') \leq treeof_X(n') = \omega'$.

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Finally, we got:
                                 down_{s'}(n) = (down_{s'}(n')n[d-d]down_{s'}(n_r)) \leq (\omega'n[d-d]reL_{n,\omega'}(down_s(n_r))) = (down_{s'}(n')n[d-d]down_{s'}(n_r)) \leq ((down_{s'}(n')n[d-d]down_{s'}(n_r)) \leq ((down_{s'}(n')n[d-d]down_{s'}(n')n[d-d]down_{s'}(n')n[d-d]down_{s'}(n')n[d-d]down_{s'}(n')n[d-d]down_{s'}(n')n[d-d]down_{s'}(n')n[d-d]down_{s'}(n')n[d-d]down_{s'}(n')n[d-d]down_{s'}(n')n[d-d]down_{s'}(n')n[d-d]down_{s'}(n')n[d-d]down_{s'}(n')n[d-d]down_{s'}(n')n[d-d]down_{s'}(n')n[d-d]down_{s'}(n')n[d-d]down_{s'}(n')n[d-d]down_{s'}(n')n[d-d]down_{s'}(n')n[d-d]down_{s'}(n')n[d-d]down_{s'}(n')n[d-d]down_{s'}(n')n[d-d]down_{s'}(n')n[d-d]down_{s'}(n')n[d-d]down_{s'}(n')n[d-d]down_{s'}(n')n[d-d]down_{s'}(n')n[d-d]down_{s'}(n')n[d-d]down_{s'}(n')n[d-d]down_{s'}(n')n[d-d]down_{s'}(n')n[d-d]down_{s'}(n')n[d-d]down_{s'}(n')n[d-d]down_{s'}(n')n[d-d]down_{s'}(n')n[d-d]down_{s'}(n')n[d-d]down_{s'}(n')n[d-d]down_{s'}(n')n[d-d]
                                 (\omega' \vee reL_{n,\omega'}(\varepsilon)[d-d]reL_{n,\omega'}(down_s(n_r))) = reL_{n,\omega'}(down_s(n))
      Now, if \omega \in \alpha(f(\gamma(X))), then for some m \in N:
\omega = \bigvee_{s' \in G_m(f(\gamma(X)))} down_{s'}(m) = \bigvee_{s \in G_m(\gamma(X))} down_{s'}(m) \preceq \bigvee_{s \in G_m(\gamma(X))} reL_{n,\omega'}(down_s(m)) \preceq reL_{n,\omega'}(\bigvee_{s \in G_m(\gamma(X))} down_s(m)).
       In the last step we used lemma 3. Note that \bigvee_{s \in G_m(\gamma(X))} down_s(m) \in \alpha(\gamma(X)), and therefore \bigvee_{s \in G_m(\gamma(X))} down_s(m) \preceq \omega'' for some \omega'' \in X. Finally, the standard problem of G_m(\gamma(X)) is the standard problem of G_m(\gamma(X)).
       nally, by lemma 2 we get:
       \omega \leq reL_{n,\omega'}(\omega'') \in f^{\#}(X). Actually, we have to show that \omega \neq treeof_X(n').
       But otherwise, the root of \omega = \bigvee_{s' \in G_m(f(\gamma(X)))} down_{s'}(m) would be n'. It's
       impossible because f(\gamma(X)) doesn't contain states with n' as a root.
        All that shows that \alpha(f(\gamma(X))) \sqsubseteq f^{\#}(X).
                                                                                                                                                                                                              3. [setRight(n, n')]^{\#}:
        Proof. Symmetric to [setLeft(n, n')]^{\#}.
                                                                                                                                                                                                              4. [setValue(n, n')]^{\#} is sound:
        Proof. Otherwise, we first prove the following statement by induction:
       Let m \in \mathbb{N}^+ and s \in \gamma(X) such that s(n) = (n_1, d', n_2) and s(m) \neq \#. We
       denote s' = s[n \leftarrow (n_1, d, n_2)]. Then, down_{s'}(m) = reV_{n,d}(down_s(m)).
               • If down_{s'}(m) = \varepsilon then m = null, which in that case: down_s(m) = \varepsilon,
                     so reV_{n,d}(down_s(m)) = \varepsilon.
               • Else, m \neq null. If m \neq n:
                      down_{s'}(m) = (down_{s'}(m_1)m[d_m - d_m]down_{s'}(m_2)), \text{ where } s'(m) =
                      s(m) = (m_1, d_m, m_2). By induction, (down_{s'}(m_1)m[d_m - d_m]down_{s'}(m_2)) =
                      (reV_{n,d}(down_s(m_1))m[d_m - d_m]reV_{n,d}(down_s(m_2))) =
                      reV_{n,d}((down_s(m_1)m[d_m - d_m]down_s(m_2))) = reV_{n,d}(down_s(m))
               • If m = n: down_{s'}(n) = (down_{s'}(n_1)n[d - d]down_{s'}(n_2)) =
                      (reV_{n,d}(down_s(n_1))n[d-d]reV_{n,d}(down_s(n_2))) =
                     reV_{n,d}((down_s(n_1)n[d'-d']down_s(n_2))) = reV_{n,d}(down_s(n)).
       Each \omega \in \alpha(f(\gamma(X))) is of the form \bigvee_{s' \in G_m(f(\gamma(X)))} down_{s'}(m). From f's definition, it is clear that s' \in G_m(f(\gamma(X))) \iff s' = s[n \leftarrow (n_1, d, n_2)]
        where s \in G_m(\gamma(X)) (Because f doesn't change the structure of the
       states). Therefore:
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 $\omega = \bigvee_{s \in G_m(\gamma(X))} down_{s'}(m) = \bigvee_{s \in G_m(\gamma(X))} reV_{n,d}(down_s(m)) \preceq reV_{n,d}(\bigvee_{s \in G_m(\gamma(X))} down_s(m))$ (the last step by lemma 3). We know that $\bigvee_{s \in G_m(\gamma(X))} down_s(m) \in \alpha(\gamma(X)),$

and by the Galois connection property, there is $\omega' \in X$ s.t. $\bigvee_{s \in G_m(\gamma(X))} down_s(m) \preceq \omega' \implies \omega \preceq reV_{n,d}(\bigvee_{s \in G_m(\gamma(X))} down_s(m)) \preceq reV_{n,d}(\omega') \in f^\#(X)$. So finally we showed: $\alpha(f(\gamma(X))) \sqsubseteq f^\#(X)$.