Single-image superresolution of self-similar textures

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under the supervision of

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Introduction

Super-resolution (SR) problem formulation:

$$Y(\eta_1, \eta_2) = \mathcal{D}((B * X)(\eta_1, \eta_2)) + N(\eta_1, \eta_2)$$

Degradation caused due to both decimation and blur

- Decimation, D, causes aliasing in finitely supported (typically small) PSFs.
- Blur kernel, $B(\eta_1, \eta_2)$: Gaussian, averaging, ...
- Noise, $N(\eta_1, \eta_2)$: iid Gaussian noise, typically with low variance



Original image



Blurred image



BM3D Reconstructed



Blurred+subsampled



BM3D Reconstructed



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Super-resolution

The super-resolution problem

- Multi-frame super-resolution: Given $\{Y_i(\eta_1, \eta_2)\}_{i=1}^N$ [Irani and Peleg, 1990, Elad and Feuer, 1997, Yang and Huang, 2010], ...
- Single-frame super-resolution (upscaling): Given a single measurement, N=1 [Freeman et al., 2002, Glasner et al., 2009, Zeyde et al., 2011]
 - The focus of this research: Restore a high-resolution image from a single blurred and subsampled observation.

Texture enhancement

Super-resolution as a specific problem in image enhancement

• Cartoon v. textures - non BV space [Gousseau and Morel, 2001]

Methods for texture enhancement

- Differential equations, $I_t = \nabla \cdot (g(|\nabla I|)\nabla I)$ [Gilboa et al., 2002]
- Sparseness-based, $X = D\alpha + V$ [Yang et al., 2010]
- Example (learning)-based superresolution [Freeman et al., 2002]
 - Single-image example-based [Glasner et al., 2009]
- Texture synthesis [Efros and Leung, 1999]



Relevance and contribution

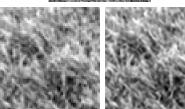
Further research is necessary in textured images

Theoretical model

- Analysis of natural images as realizations of random processes
- Interest in the underlying model

Better models may yield better enhancement algorithms





Example-based SR [Freeman et al., 2002]. Top: Original. Left: Degraded image. Right: Enhanced image.

Texture properties

Types of textures [Lin et al., 2004]

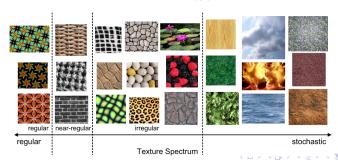
- Regular (structured): pattern-based
- Stochastic: based on random processes,

$$X(\eta_1,\eta_2)=X(\eta_1,\eta_2,\omega)$$

Stochastic textures

- Self-similar, $X_c(at) \stackrel{d}{=} |a|^c X_c(t)$
- Long-range dependencies
- Fractal properties [Barnsley, 1988]

For example: fractional Brownian motion.



Background

• Image model:

$$Y(\eta_1, \eta_2) = \mathcal{D}((B * X)(\eta_1, \eta_2)) + N(\eta_1, \eta_2)$$

• Naive solution: $\hat{X}(\eta_1, \eta_2) = (G * Y)(\eta_1, \eta_2)$, where

$$\tilde{G}(\tilde{\eta}_1, \tilde{\eta}_2) = \tilde{B}^{-1}(\tilde{\eta}_1, \tilde{\eta}_2)$$

Problem: not practical.

 Possible solution: Wiener filtering, Richardson-Lucy deconvolution, L₂-based and TV-based regularization, ...

Regularization

Required for solving ill-posed problems

$$\hat{X}(\eta_1, \eta_2) = \arg\min_{X} \|Y - \mathcal{D}(B * X)\|_2^2 + \lambda \phi(X)$$

Common regularization functions:

- L_2 -based: high gradients are not common, $\phi(x) = \|\nabla X\|_2^2$
- L₁- or TV-based: promotes piecewise-smooth segments

$$\phi(x) = \|\nabla X\|_1$$

- L_p norms, for $p \in (1,2)$
- L₀ pseudo-norm, promotes sparsity:

$$\phi(\alpha) = \|\alpha\|_0, \ X = D\alpha + V$$

Reflect an image model (BV space).

Issues

- Restoration results in cartoon images
- Textured details are lost



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Fractional Brownian motion

$$E[B_H(t)B_H(s)] = \frac{\sigma^2}{2} \left(|t|^{2H} + |s|^{2H} - |t-s|^{2H} \right)$$

- Gaussian, self-similar, fractal process [Mandelbrot and Van Ness, 1968]
- The only self-similar Gaussian process (in 1D)
- Brownian motion for H = 0.5
- Non-stationary, with stationary increments
- Exhibits negative correlation for 0 < H < 0.5
- Can be synthesized *efficiently* in 2D by introducing $\phi(\eta_1, \eta_2)$, autocorrelation of the increments.





□ Figure: fBm for H ∈ {0.1, 0.6} ○ へ ○

Texture model

$$X = X_{LP} + \hat{X}_{HP} + V,$$

where

$$\hat{X}_{HP}(\eta_1,\eta_2)=f(\omega,X_{LP})$$

- $X_{LP}(\eta_1, \eta_2)$ is a low-frequency, degraded, image
- X_{HP}(η₁, η₂) is composed from ∠X_{LP} and an fBm image, B_H(η₁, η₂)
- The high frequencies are an fBm representation of the degraded image

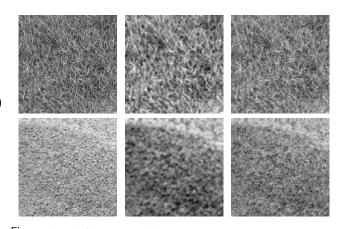


Figure: Example of the texture model. Left: Original image. Middle: X_{LP} . Right: $X(\eta_1,\eta_2)$

Preliminary algorithm

Perform optimization:

$$\hat{X} = \arg\min_{X} ||Y - BX||^2$$

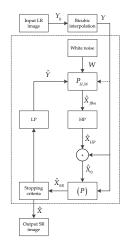
s.t. $X = X_{LP} + \hat{X}_{HP}$
 $\hat{X}_{HP} = f(\omega, X_{LP})$

Solve by iterating:

- **1** Apply constraint, $\hat{X} = X_{LP} + \hat{X}_{HP}$
- 2 Solve proximal point problem,

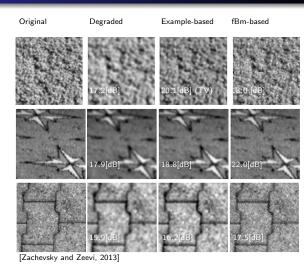
$$\hat{X}_{k+1} = \arg\min_{X} \|Y - BX\|^2 + \alpha \|\hat{X}_k - X\|^2$$

 May be considered as a POCS problem



Results

- Performs well on isotropic stochastic textures.
- Recovers missing details according to the model.
- PSNR or MSE-based comparison methods not applicable (PSNR < 20[dB])

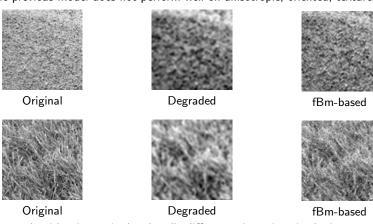


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Disadvantages

The previous model does not perform well on anisotropic, oriented, textures.



A new algorithm is required to handle different orientations in the image.

Tensor diffusion

Basic reaction-diffusion equation for deblurring [Welk et al., 2005]:

$$\hat{X} = \arg\min_{X} \|Y - BX\|^2 + \lambda \Phi(\nabla X)$$

$$X_t = -B^T * (B * X - Y) + \lambda \nabla \cdot (D(\nabla X) \nabla X)$$

$$D = (\omega_1, \omega_2) \begin{pmatrix} \lambda_1 & 0 \\ 0 & \lambda_2 \end{pmatrix} \begin{pmatrix} \omega_1 \\ \omega_2 \end{pmatrix}$$

where

$$\omega_1 \parallel \nabla X$$
, $\omega_2 \perp \nabla X$

- Performs anisotropic diffusion, used in various image enhancements tasks
- Applies different diffusion coefficients, according to orientation.
- Can be used for super-resolution.



Tensor diffusion

Adapted for texture enhancement:

- Modified reaction term: $\left(X_{HP} \hat{X}_{HP}\right)^2$, recovers degraded high frequencies
- Diffusion tensor modified: $D\left(\nabla\left(X+\alpha Y_{\phi}\right)\right)$, preserves texture orientation New scheme:

$$X_{t} = 2B^{T}(BX - Y) - 2H(\hat{X}_{HP} - HX) + \beta\nabla \cdot (\Psi'(|\nabla X + \alpha\nabla Y_{\phi}|^{2})\nabla(X + \alpha Y_{\phi}))$$

where $Y_{\phi}(\eta_1, \eta_2)$ is a stochastic image, obtained by a function derived from the degraded image itself.

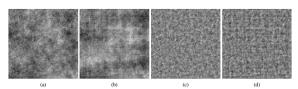


Figure: Original fBm, fBm from $\phi(\eta_1,\eta_2)$ and high-pass versions

Modified diffusion equation

Visualizing the two additions (zoomed-in images)



Original image



Degraded image



Original PDE



New reaction, $(X_{HP} - \hat{X}_{HP})^2$



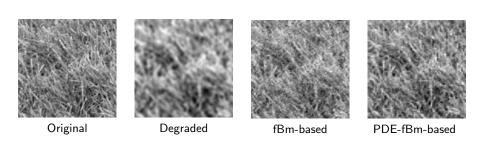
New tensor, $D(\nabla(X + \alpha Y_{\phi}))$



Modified PDE

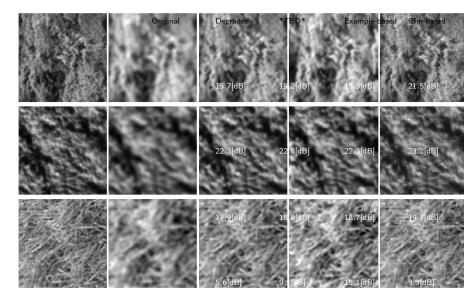
Comparison with the first algorithm

Recall the previous result



The current algorithm restores missing details, according to the texture orientation.

Results



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Theoretical tasks

- Creating a unified model which will contain both SR algorithms.
- Geometrical framework
 - Representation in higher spaces and performing color processing [Sochen et al., 1998]

$$\mathcal{C}_t = rac{1}{\sqrt{|oldsymbol{g}|}} \sum_{\mu,
u=1}^2 \partial_\mu \left(\sqrt{|oldsymbol{g}|} \left(oldsymbol{g}^{-1}
ight)_{\mu,
u} \partial_
u \mathcal{C}
ight)$$

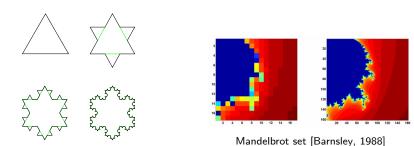
- Textures as a manifold, embedded in a suitable space, providing an intrinsic metric for comparison [Kimmel et al., 2000].
- Derive a statistical model for textures



Further research

Geometric fractals

- Geometric fractals appear in various natural images.
- The structure can be exploited for an image model and SR scheme.



Koch snowflake [von Koch, 1904]



Classification and denoising

Classification

- The dominant feature of stochastic textures is self-similarity
- This can be exploited to classify images
- Features: self-similarity index, correlation
- Further features are required
- Segmentation

Image denoising

- Overlap of high-frequency details with that of noise
- The model may prove useful in performing texture denoising



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Introduction Self-similar texture model Anisotropic self-similar model Further research References

Backup follows

Fractional Brownian motion synthesis

1 Naive [Hoefer et al., 1992]: Construct $R_B(t,s)$, the autocorrelation function of the fBm:

$$E[B_{H}(t)B_{H}(s)] = \frac{\sigma^{2}}{2} \left(|t|^{2H} + |s|^{2H} - |t - s|^{2H} \right)$$

$$\sigma_{B}^{2} = \frac{\sigma_{B}^{2}}{2} \frac{\cos(\pi H)}{\pi H} \Gamma(1 - 2H)$$

Inefficient due to use of Cholesky decomposition.

- 2 Via the Fourier domain [Kaplan and Kuo, 1996]:
 - First- and second-order increments are stationary.
 - Their autocorrelations are expressed via a structure function, $\phi(\eta_1, \eta_2)$.
 - Fields with these autocorrelation functions can be efficiently synthesized via the Fourier domain.
 - 2D fBm is obtained by summation of the increments.





Anisotropic diffusion

Non-linear isotropic diffusion [Perona and Malik, 1990]:

$$egin{array}{lcl} X_t & = &
abla \cdot \left(g(|
abla X_\sigma|)
abla X
ight) \ g(s^2) & = & rac{1}{1+\left(rac{s^2}{K^2}
ight)} \end{array}$$

- Adaptive: diffusion coefficient inversely proportional to norm of gradient
- Done isotropically, regardless of orientation

Weickert anisotropic diffusion [Weickert, 1998]:

$$\begin{array}{lcl} X_t & = & \nabla \cdot \left(D(\nabla X) \nabla X \right) \\ D & = & \left(\omega_1, \omega_2 \right) \begin{pmatrix} \lambda_1 & 0 \\ 0 & \lambda_2 \end{pmatrix} \begin{pmatrix} \omega_1 \\ \omega_2 \end{pmatrix}$$

• For edge preserving denoising: λ_1 similar to Perona and Malik, and λ_2 =0.1. Enhances edges according to orientation.

Modified diffusion equation

• A nonstationary field with stationary increments can be synthesized using a generating (structure) function, $\phi(\eta_1, \eta_2)$ [Pesquet-Popescu and Larzabal, 1997]:

$$\phi(\Delta_1, \Delta_2) = var(F(\eta_1, \eta_2) - F(\eta_1 - \Delta_1, \eta_2 - \Delta_2))$$

$$\phi_{fBm}(\Delta_1, \Delta_2) = (\Delta_1^2 + \Delta_2^2)^H \triangleq r^{2H}$$

• The empirical image, $Y_{\phi}(\eta_1, \eta_2)$, is obtained by an inverse process using an empirical structure function.

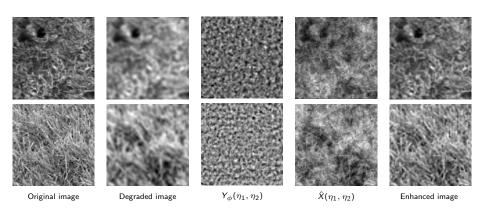
$$\hat{\phi}(\eta_1, \eta_2) = f_1(Y(\eta_1, \eta_2)) \quad \Rightarrow \quad \hat{B}_{\hat{\phi}}(\eta_1, \eta_2) = f_2(\hat{\phi}, \omega)$$

- Due to the self similarity, the correlations are suitable for the superresolution image.
- The inverse process is performed via solving an ill-posed least squares problem:

$$\underline{\phi} = \arg\min_{\mathbf{x}} \left\| D\underline{\mathbf{x}} - \underline{\mathbf{r}} \right\|_2$$

• Further methods can be explored to find more suitable empirical structure functions.

Empirical function in algorithm progress



• Further study necessary for empirical image.

