

In[]:= **ClearAll["Global`*"]**; (* HW#2 F23 *)

In[]:= **h[x_] := H Exp** $\left[m \frac{x}{L}\right]$

In[]:= **f = y - h[x]**;

In[]:= **gradf = { $\partial_x f$, $\partial_y f$ }**

Out[]:=

$$\left\{-\frac{e^{\frac{mx}{L}} H m}{L}, 1\right\}$$

In[]:= **n1 = {0, -1}**;

n2 = $\frac{\text{gradf}}{\sqrt{\text{gradf}.\text{gradf}}}$ (* part 1 *)

Out[]:=

$$\left\{-\frac{e^{\frac{mx}{L}} H m}{L \sqrt{1 + \frac{e^{\frac{2mx}{L}} H^2 m^2}{L^2}}}, \frac{1}{\sqrt{1 + \frac{e^{\frac{2mx}{L}} H^2 m^2}{L^2}}}\right\}$$

In[]:= **n1 = {0, -1}**;

n2 = $\left\{-\frac{e^{\frac{mx}{L}} H m}{L \sqrt{1 + \frac{e^{\frac{2mx}{L}} H^2 m^2}{L^2}}}, \frac{1}{\sqrt{1 + \frac{e^{\frac{2mx}{L}} H^2 m^2}{L^2}}}\right\}$;

In[]:= **p[x_] := p0 $\left(1 - k \frac{x^2}{L^2}\right)$**

In[]:= **$\tau[x_, y_] := \tau_0 \left(\frac{x}{L}\right) \left(\frac{y}{h[x]}\right)^2$**

In[]:= **$\sigma = \begin{pmatrix} -p[x] & \tau[x, y] \\ \tau[x, y] & -p[x] \end{pmatrix}$**

Out[]:=

$$\left\{\left\{-p_0 \left(1 - \frac{k x^2}{L^2}\right), \frac{e^{-\frac{2mx}{L}} x y^2 \tau_0}{H^2 L}\right\}, \left\{\frac{e^{-\frac{2mx}{L}} x y^2 \tau_0}{H^2 L}, -p_0 \left(1 - \frac{k x^2}{L^2}\right)\right\}\right\}$$

In[]:= **MatrixForm[σ]**

Out[]:=//MatrixForm=

$$\begin{pmatrix} -p_0 \left(1 - \frac{k x^2}{L^2}\right) & \frac{e^{-\frac{2mx}{L}} x y^2 \tau_0}{H^2 L} \\ \frac{e^{-\frac{2mx}{L}} x y^2 \tau_0}{H^2 L} & -p_0 \left(1 - \frac{k x^2}{L^2}\right) \end{pmatrix}$$

In[]:= **MatrixForm**[(σ /. $y \rightarrow 0$)]

Out[]//MatrixForm=

$$\begin{pmatrix} -p\theta \left(1 - \frac{k x^2}{L^2}\right) & 0 \\ 0 & -p\theta \left(1 - \frac{k x^2}{L^2}\right) \end{pmatrix}$$

In[]:= **MatrixForm**[(σ /. $y \rightarrow h[x]$)]

Out[]//MatrixForm=

$$\begin{pmatrix} -p\theta \left(1 - \frac{k x^2}{L^2}\right) & \frac{x \tau \theta}{L} \\ \frac{x \tau \theta}{L} & -p\theta \left(1 - \frac{k x^2}{L^2}\right) \end{pmatrix}$$

In[]:= **f1** = **n1**. (σ /. $y \rightarrow 0$)

Out[]:=

$$\left\{ 0, p\theta \left(1 - \frac{k x^2}{L^2}\right) \right\}$$

In[]:= **f2** = **n2**. (σ /. $y \rightarrow h[x]$)

Out[]:=

$$\left\{ \frac{e^{\frac{m x}{L}} H m p\theta \left(1 - \frac{k x^2}{L^2}\right)}{L \sqrt{1 + \frac{2 m x}{e^{\frac{m x}{L}} H^2 m^2}}} + \frac{x \tau \theta}{L \sqrt{1 + \frac{2 m x}{e^{\frac{m x}{L}} H^2 m^2}}}, -\frac{p\theta \left(1 - \frac{k x^2}{L^2}\right)}{\sqrt{1 + \frac{2 m x}{e^{\frac{m x}{L}} H^2 m^2}}} - \frac{e^{\frac{m x}{L}} H m x \tau \theta}{L^2 \sqrt{1 + \frac{2 m x}{e^{\frac{m x}{L}} H^2 m^2}}} \right\}$$

In[]:= **f1x** = **f1**[[1]]

f1y = **f1**[[2]]

f2x = **Collect**[**f2**[[1]], {**p** θ , $\tau\theta$ }]

f2y = **Collect**[**f2**[[2]], {**p** θ , $\tau\theta$ }]

Out[]:=

0

Out[]:=

$$p\theta \left(1 - \frac{k x^2}{L^2}\right)$$

Out[]:=

$$\frac{e^{\frac{m x}{L}} H m p\theta \left(1 - \frac{k x^2}{L^2}\right)}{L \sqrt{1 + \frac{2 m x}{e^{\frac{m x}{L}} H^2 m^2}}} + \frac{x \tau \theta}{L \sqrt{1 + \frac{2 m x}{e^{\frac{m x}{L}} H^2 m^2}}}$$

Out[]:=

$$-\frac{p\theta \left(1 - \frac{k x^2}{L^2}\right)}{\sqrt{1 + \frac{2 m x}{e^{\frac{m x}{L}} H^2 m^2}}} - \frac{e^{\frac{m x}{L}} H m x \tau \theta}{L^2 \sqrt{1 + \frac{2 m x}{e^{\frac{m x}{L}} H^2 m^2}}}$$

In[]:= **dA1 = W dx;**

$$dA2 = \sqrt{1 + \frac{e^{\frac{2mx}{L}} H^2 m^2}{L^2}} ;$$

In[]:= **F1x = Simplify[-W $\int_0^L f1x \, dx$] (* minus sign for on surface, not fluid *)**

$$F1y = \text{Simplify}\left[-W \int_0^L f1y \, dx\right]$$

Out[]:=

0

Out[]:=


$$\frac{1}{3} (-3 + k) L p_0 W$$

In[]:= **(* F2xA=-W $\int_0^L \left(t2x \sqrt{1 + \frac{e^{\frac{2mx}{L}} H^2 m^2}{L^2}}\right) dx$ *)**

In[]:= **(* F2yA=-W $\int_0^L \left(t2y \sqrt{1 + \frac{e^{\frac{2mx}{L}} H^2 m^2}{L^2}}\right) dx$ *)**

In[]:= **H = 0.001; L = 0.01; m = 0.4;
k = 0.5; p0 = 1. $\times 10^6$; $\tau_0 = 100. \times 10^3$; W = 1.;**

In[]:= **F1x = NIntegrate[-W f1x, {x, 0, L}]
F1y = NIntegrate[-W f1y, {x, 0, L}]**

 **NIntegrate:** Integral and error estimates are 0 on all integration subregions. Try increasing the value of the MinRecursion option. If value of integral may be 0, specify a finite value for the AccuracyGoal option.

Out[]:=

0.

Out[]:=

-8333.33

In[]:=

$$F2x = \text{NIntegrate}\left[-W \sqrt{1 + \frac{e^{\frac{2mx}{L}} H^2 m^2}{L^2}} f2x, \{x, 0, L\}\right]$$

$$F2y = \text{NIntegrate}\left[-W \sqrt{1 + \frac{e^{\frac{2mx}{L}} H^2 m^2}{L^2}} f2y, \{x, 0, L\}\right]$$

Out[]:=

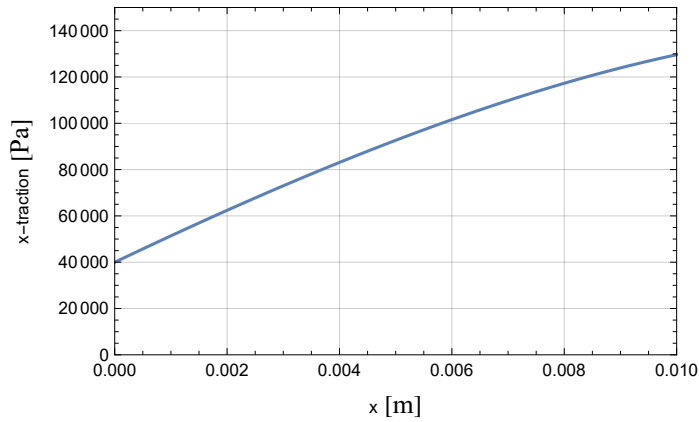
-901.57

Out[]:=

8359.56

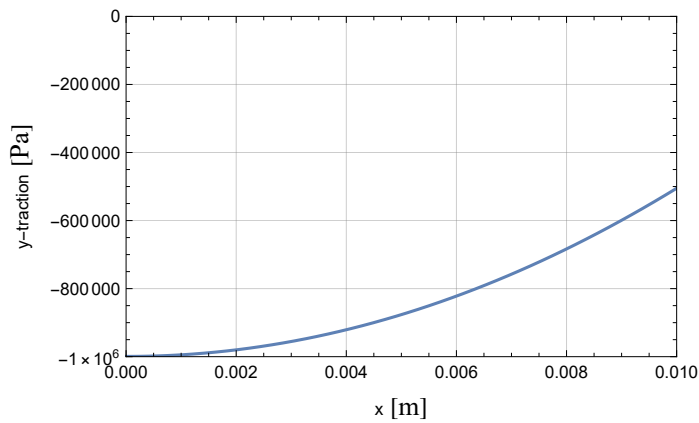
```
In[ ]:= Plot[{f2x}, {x, 0, L}, Frame → True, GridLines → Automatic,
  FrameLabel → {"x [m]", "x-traction [Pa]"}, PlotRange → {{0, 0.01}, {0, 150000}}]
```

Out[]:=



```
In[ ]:= Plot[{f2y}, {x, 0, L}, Frame → True, GridLines → Automatic,
  FrameLabel → {"x [m]", "y-traction [Pa]"}, PlotRange → {{0, 0.01}, {-1000000, 0}}]
```

Out[]:=



```
In[ ]:= ClearAll["Global`*"]; (* HW#2 F23 *)
```

```
In[ ]:= h = H Exp[m x/L]; vx = v y/h (1 - y/h);
```

```
In[ ]:= vy = m v h/H L (1/2 y^2/h^2 - 2 y^3/h^3);
```

```
In[ ]:= Simplify[∂x vx + ∂y vy]
```

Out[]:=

0

```
In[ ]:= v = {vx, vy};
```

```
In[ ]:= xx = {x, y};
```

```
In[ ]:= delv = {{0, 0}, {0, 0}};
Do[Do[delv[[i, j]] =  $\partial_{xx} v[[j]]$ , {i, 1, 2}], {j, 1, 2}];
MatrixForm[Simplify[delv]]
```

Out[]//MatrixForm=

$$\begin{pmatrix} -\frac{e^{-\frac{2mx}{L}} m V\left(\frac{mx}{L} H-2y\right) y}{H^2 L} & -\frac{e^{-\frac{2mx}{L}} m^2 V\left(3 \frac{mx}{L} H-8y\right) y^2}{6 H^2 L^2} \\ \frac{e^{-\frac{2mx}{L}} V\left(\frac{mx}{L} H-2y\right)}{H^2} & \frac{e^{-\frac{2mx}{L}} m V\left(\frac{mx}{L} H-2y\right) y}{H^2 L} \end{pmatrix}$$

```
In[ ]:= delvT = {{0, 0}, {0, 0}};
Do[Do[delvT[[i, j]] = delv[[j, i]], {i, 1, 2}], {j, 1, 2}];
MatrixForm[Simplify[delvT]]
```

Out[]//MatrixForm=

$$\begin{pmatrix} -\frac{e^{-\frac{2mx}{L}} m V\left(\frac{mx}{L} H-2y\right) y}{H^2 L} & \frac{e^{-\frac{2mx}{L}} V\left(\frac{mx}{L} H-2y\right)}{H^2} \\ -\frac{e^{-\frac{2mx}{L}} m^2 V\left(3 \frac{mx}{L} H-8y\right) y^2}{6 H^2 L^2} & \frac{e^{-\frac{2mx}{L}} m V\left(\frac{mx}{L} H-2y\right) y}{H^2 L} \end{pmatrix}$$

```
In[ ]:=  $\gamma$ dot = {{0, 0}, {0, 0}};
Do[Do[ $\gamma$ dot[[i, j]] = delv[[i, j]] + delvT[[i, j]], {i, 1, 2}], {j, 1, 2}];
MatrixForm[Simplify[ $\gamma$ dot]]
```

Out[]//MatrixForm=

$$\begin{pmatrix} -\frac{2 e^{-\frac{2mx}{L}} m V\left(\frac{mx}{L} H-2y\right) y}{H^2 L} & \frac{e^{-\frac{2mx}{L}} V\left(-12 L^2 y+8 m^2 y^3+3 \frac{mx}{L} H\left(2 L^2-m^2 y^2\right)\right)}{6 H^2 L^2} \\ \frac{e^{-\frac{2mx}{L}} V\left(-12 L^2 y+8 m^2 y^3+3 \frac{mx}{L} H\left(2 L^2-m^2 y^2\right)\right)}{6 H^2 L^2} & \frac{2 e^{-\frac{2mx}{L}} m V\left(\frac{mx}{L} H-2y\right) y}{H^2 L} \end{pmatrix}$$

```
In[ ]:=  $\omega$  = {{0, 0}, {0, 0}};
Do[Do[ $\omega$ [[i, j]] = delv[[i, j]] - delvT[[i, j]], {i, 1, 2}], {j, 1, 2}];
MatrixForm[Simplify[ $\omega$ ]]
```

Out[]//MatrixForm=

$$\begin{pmatrix} 0 & \frac{e^{-\frac{2mx}{L}}\left(-3 \frac{mx}{L} H V\left(2 L^2+m^2 y^2\right)+4 V y\left(3 L^2+2 m^2 y^2\right)\right)}{6 H^2 L^2} \\ \frac{e^{-\frac{2mx}{L}} V\left(3 \frac{mx}{L} H\left(2 L^2+m^2 y^2\right)-4 y\left(3 L^2+2 m^2 y^2\right)\right)}{6 H^2 L^2} & 0 \end{pmatrix}$$

```
In[ ]:= Simplify[ $\gamma$ dot[[1, 2]]] == Simplify[ $\gamma$ dot[[2, 1]]]
```

Out[]:=

True

```
In[ ]:= Simplify[ $\omega$ [[1, 2]]] == - $\omega$ [[2, 1]]
```

Out[]:=

True

In[]:= **curlv = Simplify[Cur1[v, {x, y}]]**

Out[]:=

$$\frac{e^{-\frac{2mx}{L}} \left(-3 e^{\frac{mx}{L}} H V (2 L^2 + m^2 y^2) + 4 V y (3 L^2 + 2 m^2 y^2) \right)}{6 H^2 L^2}$$

In[]:= **Simplify[ω[[1,2]]]**

Out[]:=

$$\frac{e^{-\frac{2mx}{L}} \left(-3 e^{\frac{mx}{L}} H V (2 L^2 + m^2 y^2) + 4 V y (3 L^2 + 2 m^2 y^2) \right)}{6 H^2 L^2}$$

In[]:= **Simplify[curlv - ω[[1,2]]]**

Out[]:=

$$0$$