

①

## Lecture 4

### Review Lec 4 3

$$\begin{array}{c} \text{///} \\ F = m a \\ \text{///} \end{array}$$

fluid  
particle  
(element)

Lec 3

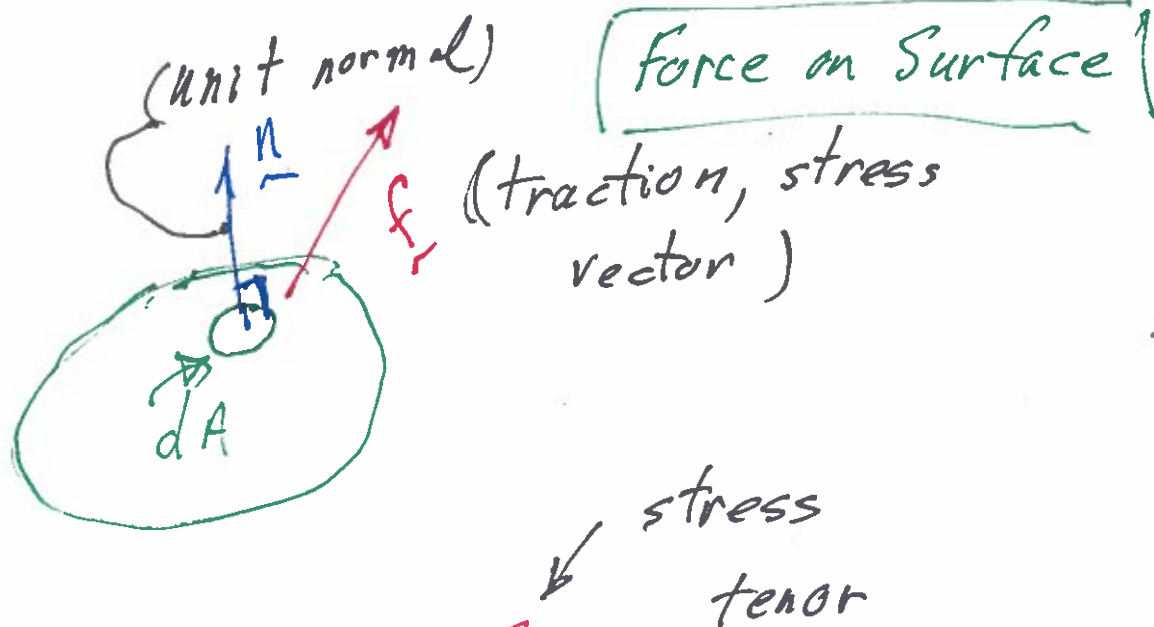
Lec 4

body forces - gravity

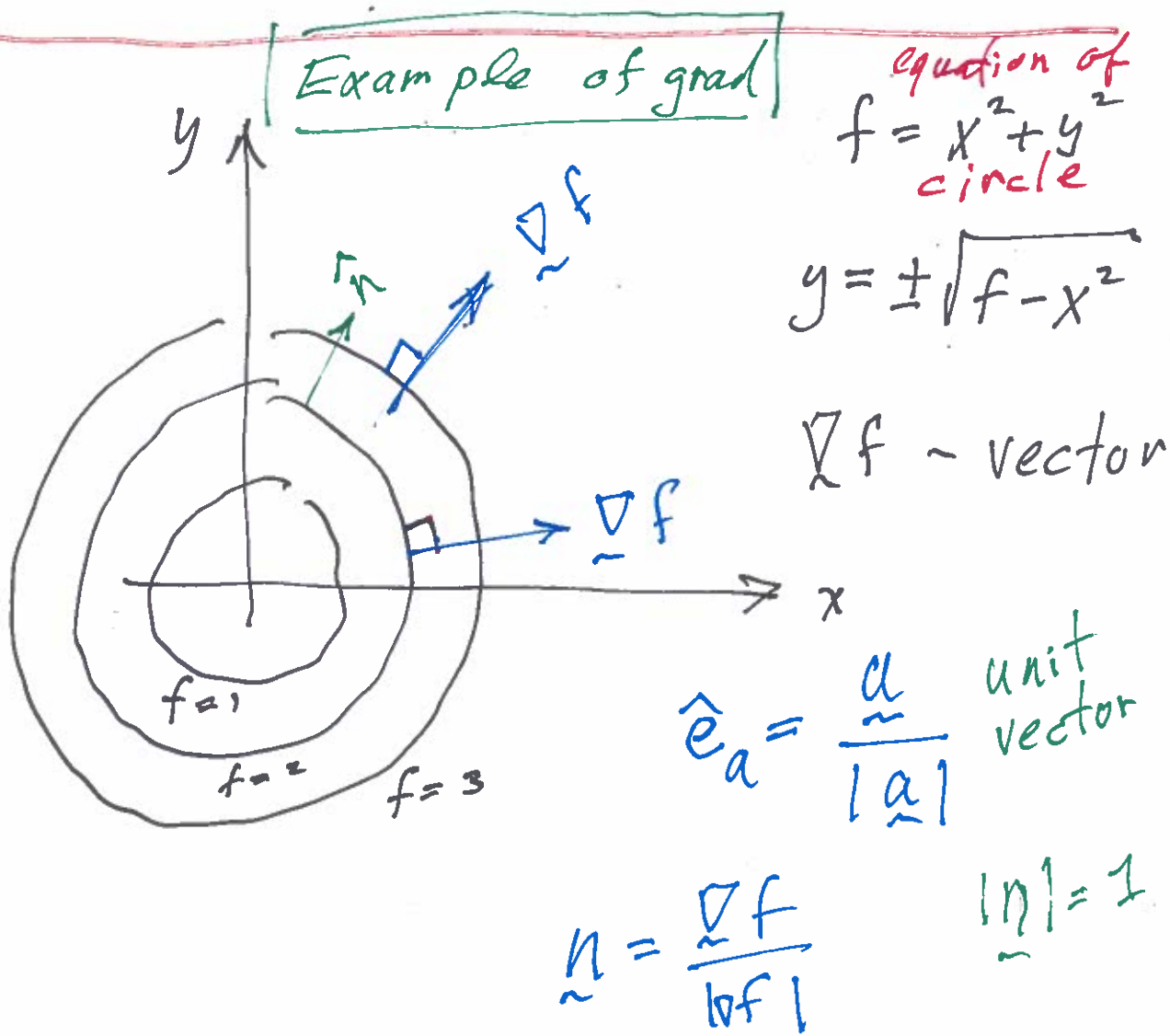
surface forces - ~~traction~~ stress vector

Tensor - tool to manipulate  
vectors

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$$\underline{f} = \underline{n} \cdot \underline{\sigma}$$



~3-

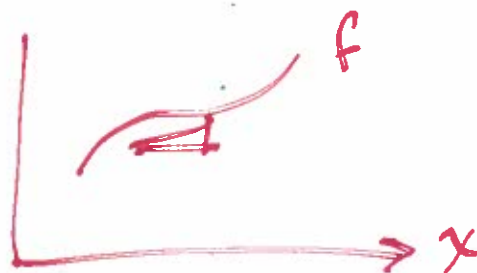
Nabla "del" operator

Use  
of  $\nabla$



Vector 1st  
derivative

$$\frac{\partial f}{\partial x}$$



$\nabla f$  slope in direction  
of largest change

Use of  $\nabla$

derive governing eq.

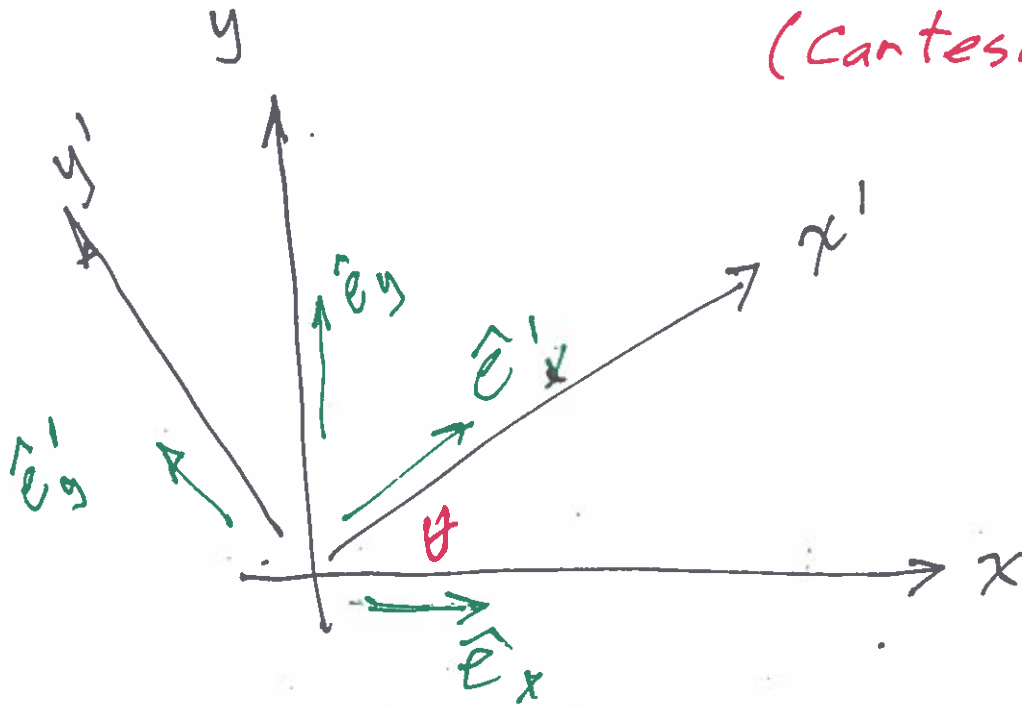
in  $(x, y)$  replace  $\frac{\partial}{\partial x}$ ,  $\frac{\partial}{\partial y}$

by  $\nabla$

Equation is good in any  
system

A-

Find unit vectors  
(Cartesian)



$$\hat{e}'_x = \cos\theta \hat{e}_x + \sin\theta \hat{e}_y$$

$$\hat{e}'_y = -\sin\theta \hat{e}_x + \cos\theta \hat{e}_y$$

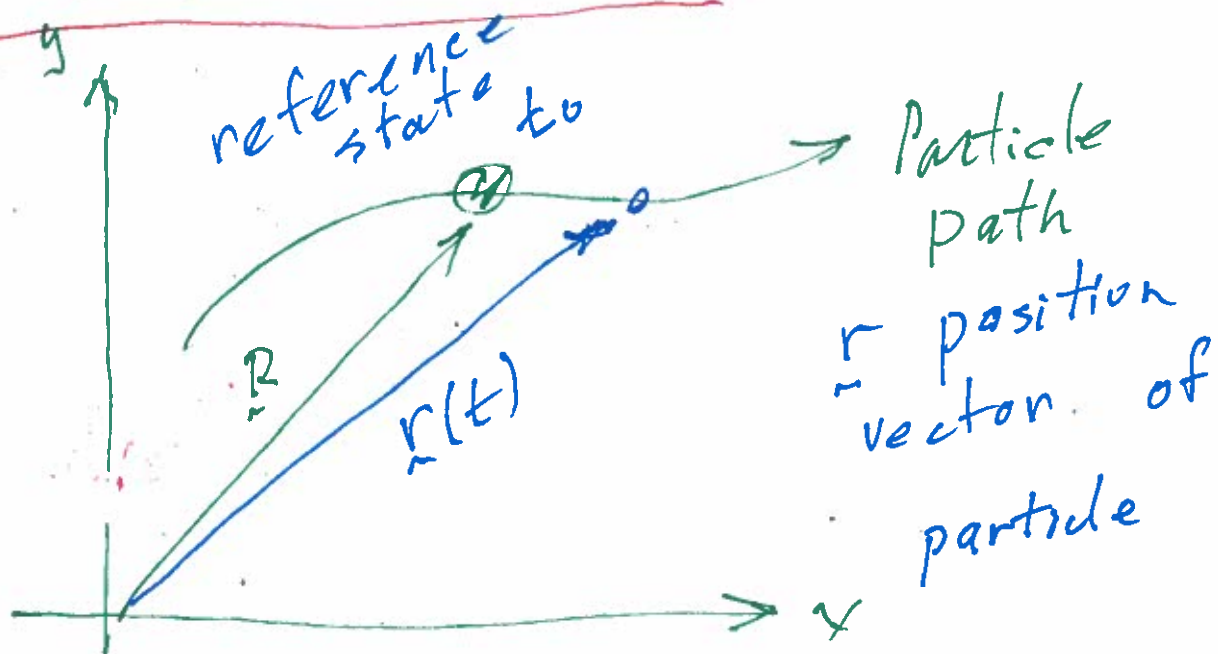
$$\hat{e}_x = \hat{e}'_x \cos\theta - \hat{e}'_y \sin\theta$$

$$\hat{e}_y = \hat{e}'_x \sin\theta + \hat{e}'_y \cos\theta$$

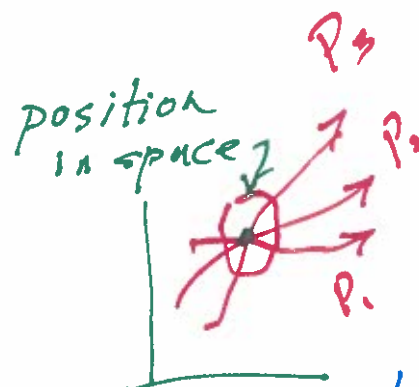
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## Lec 4

acceleration for fluids |  $\vec{F} = m \vec{a}$



Want  $\vec{a} = \frac{d\vec{v}}{dt} \bigg|_{P=\text{const}}$



likely to have  
want

$$\frac{\partial \vec{v}}{\partial t} \bigg|_{x, y, z \text{ const}}$$

$$\vec{r} = \vec{r}(\vec{R}, t)$$

$\vec{R}$  names particle

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$\underline{R}$  at  $t=t_0$  "names  
the particle"

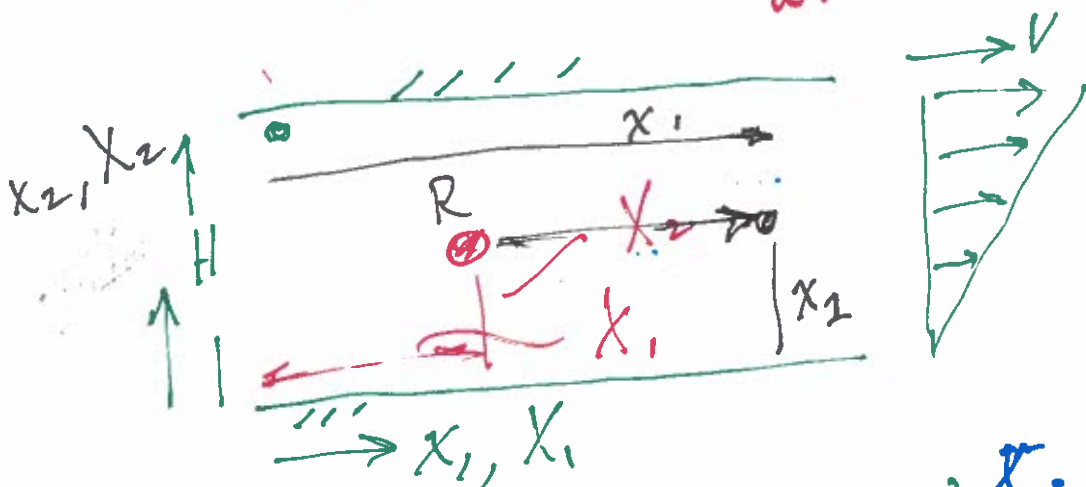
We want

$$\underline{a} = \frac{d\underline{v}}{dt} \Big|_{\underline{R} \text{ fixed}}$$

what particle?  
the one that was  
at location  $\underline{R}$  at  
time  $t_0$

Example

at  $t_0$



$$x_1 = X_1 + v(t - t_0) \frac{X_2}{H}$$

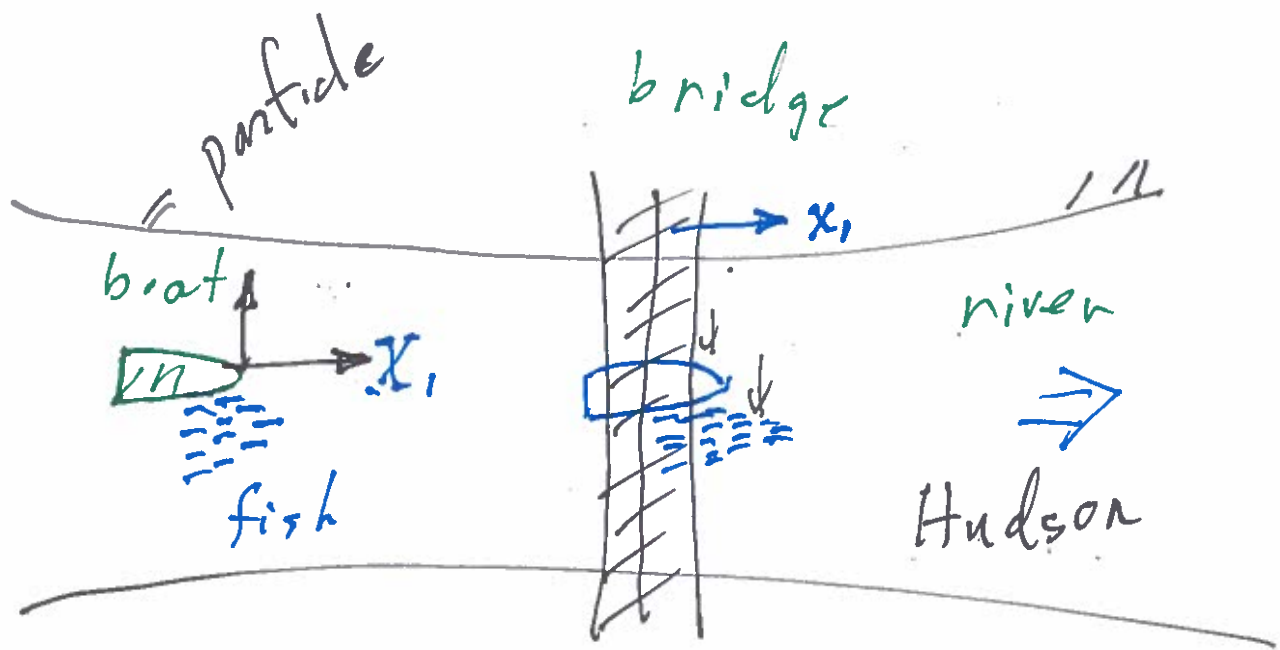
$$x_2 = X_2$$

$$v_1 = \frac{\partial x_1}{\partial t} \Big|_{x_1, x_2 \text{ const}}$$

$$v_2 = \frac{\partial x_2}{\partial t} \Big|_{x_1, x_2} = 0$$

$$v_1 = \frac{v}{H} X_2$$

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boat drifts with current

$$\frac{\# \text{ fish}}{m^2} = f$$

$$\left. \frac{df}{dt} \right|_{\text{boat}} = 0$$

$x_1 = \text{const}$

$$\left. \frac{df}{dt} \right|_{\text{bridge}} \neq 0$$

$x_1 = \text{const}$

$$\left. \frac{df}{dt} \right|_{\text{bridge}} \approx \frac{f(t_2) - f(t_1)}{t_2 - t_1}$$

$t_2 \rightarrow t_1$

-7-

$$\frac{Df}{Dt} = \frac{df}{dt} \Big|_{\text{fixed particle}}$$

material derivative

substantial "

Lagrangian "

$$f = f[x_1(\underline{x}, t), x_2(\underline{x}, t), t]$$

$$\frac{\partial f}{\partial t} \Big|_{x \text{ const}} = \frac{Df}{Dt}$$

$$= \frac{\partial f}{\partial t} + \frac{\partial f}{\partial x_1} \overbrace{\frac{\partial x_1}{\partial t}}^{v_x} + \frac{\partial f}{\partial x_2} \overbrace{\frac{\partial x_2}{\partial t}}^{v_y}$$

Nested derivative rule



-7a-

$$u(x) = \sin x$$

$$f(u) = u^2$$

Nested  
derivatives

$$\frac{df}{dx} = \underbrace{\frac{df}{du}}_{2u} \cdot \underbrace{\frac{du}{dx}}_{\cos x}$$

8-

$$\vec{F} = m \vec{a} \quad \text{volume}$$

$$\rho = \frac{m}{V} \quad \sum \vec{F} = \rho \vec{a} = \rho \frac{D\vec{V}}{Dt}$$

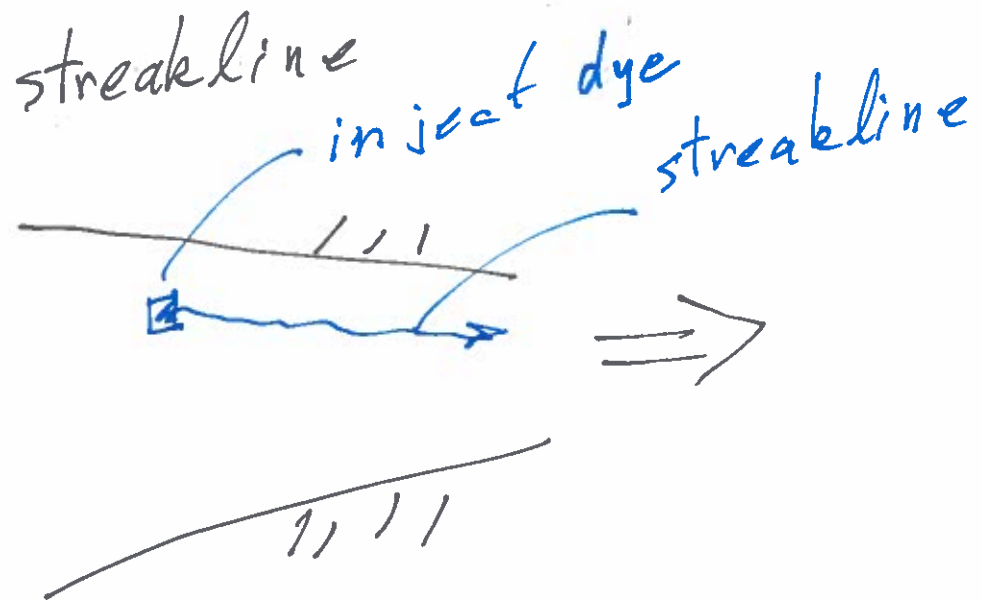
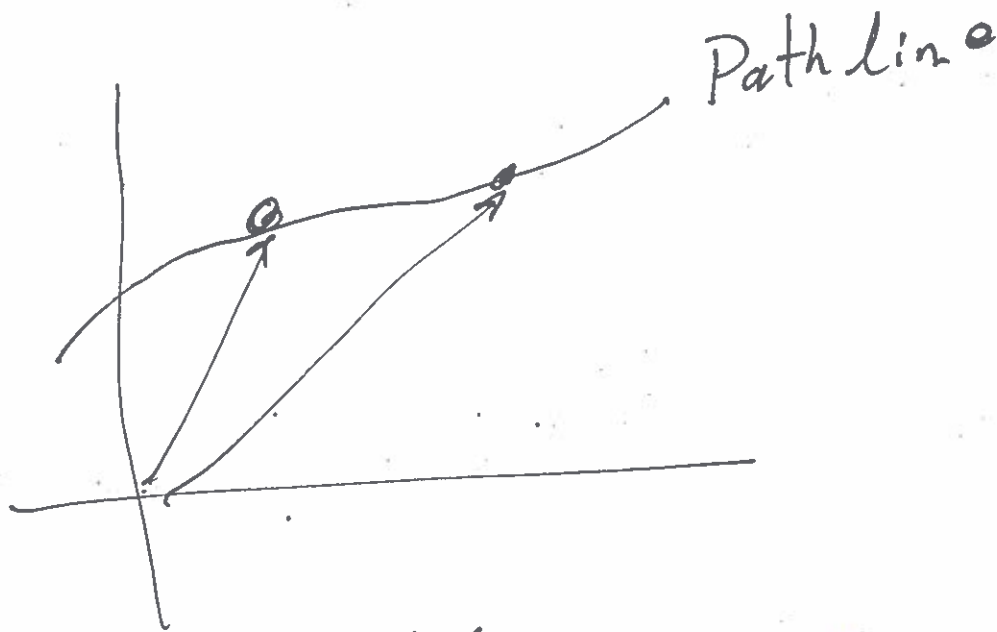
$$\frac{D\vec{V}}{Dt} = \frac{D}{Dt} (V_x \hat{e}_x + V_y \hat{e}_y)$$

$$\frac{DV_x}{Dt} = a_x = \frac{\partial V_x}{\partial t} + V_x \frac{\partial V_x}{\partial x} + V_y \frac{\partial V_x}{\partial y}$$

$$a_y = \frac{\partial V_y}{\partial t} + V_x \frac{\partial V_y}{\partial x} + V_y \frac{\partial V_y}{\partial y}$$

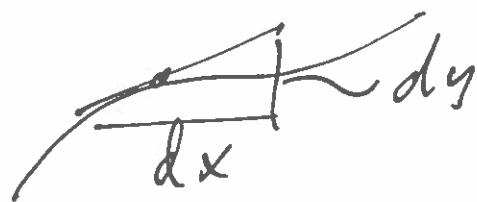
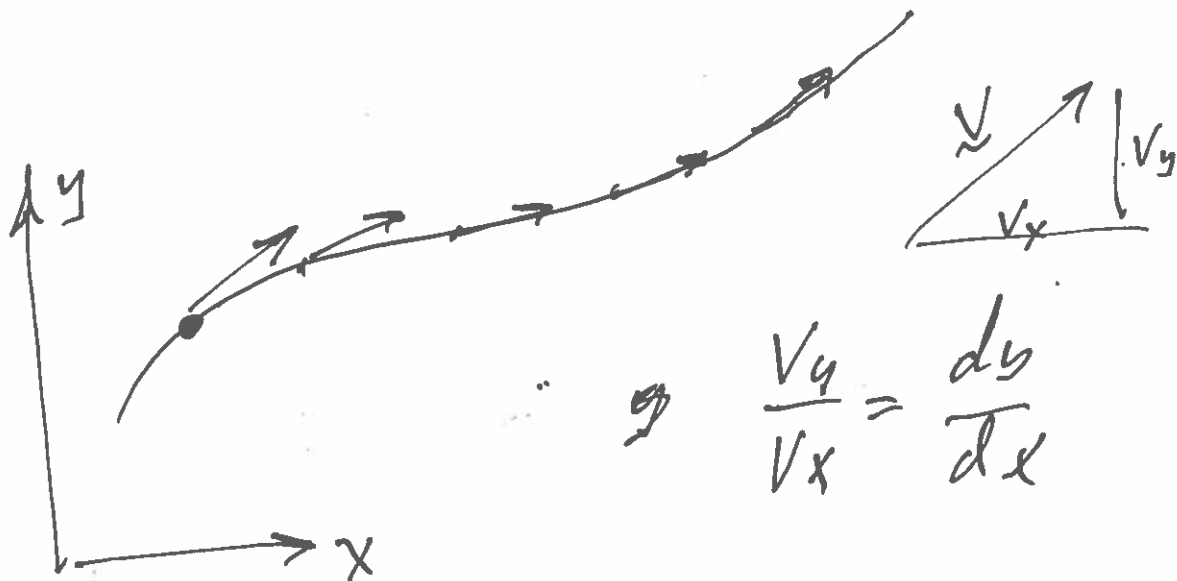
9- Path lines - particle (just did)  
Streak lines  
Streamlines

steady flow:  
all three the same



-10- stream line

one  
instant  
of time

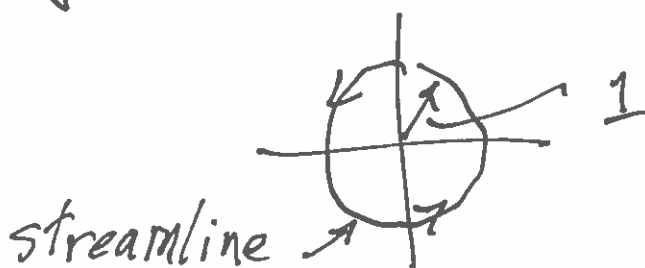


$\psi$  = stream function  $\psi(x, y)$

$\psi = \text{const.} \Rightarrow$  stream line

example:  
 $\psi = x^2 + y^2$

set  $\psi = 1$



-11-  $\psi \Rightarrow$

- 1) visualize the flow
- 2nd

can show:  $V_x = \frac{\partial \psi}{\partial y}$   $V_y = -\frac{\partial \psi}{\partial x}$

- 2) change 2 variable  $V_x, V_y \Rightarrow$   
2 unknowns

to 1 unknown  $\psi(x, y)$