
The Damped Bundle Adjustment Toolbox v0.2 for Matlab

Niclas Börnin
Department of Computing Science
Umeå University
niclas.borlin@cs.umu.se

November 13, 2013

Contents

1	Introduction	3
1.1	Purpose	3
1.2	Limitations	3
1.3	Legal	3
1.4	Scientific publications	3
2	Installation	3
3	Usage	3
3.1	Demos	3
3.1.1	loadplotdemo	3
3.1.2	loadplotdemo2	4
3.1.3	romabundledemo	4
3.1.4	camcaldemo	4
3.2	Using your own data	4
3.2.1	Enabling text export from Photomodeler	4
3.2.2	Export from Photomodeler	4
3.2.3	Loading into Matlab	5
A	Camera model	6

1 Introduction

1.1 Purpose

Matlab toolbox with freely available code for bundle adjustment. Intention to be state-of-the-art.

1.2 Limitations

What it can do.

What it cannot do.

1.3 Legal

1.4 Scientific publications

Refer to any of the papers...

Börlin and Grussenmeyer (2013a) Börlin and Grussenmeyer (2013b)

2 Installation

1. Download the package file `dbat_0.2.zip`.
2. Unpack the package into a directory *dbat*.
3. Inside Matlab, do the following initialization:

```
cd dbat % the directory where you installed the files.  
dbatSetup % set paths, etc.
```
4. Test the installation by executing `loadplotdemo`.
5. If `loadplotdemo` runs without errors and generates a figure with a camera network, the installation is ok.

3 Usage

3.1 Demos

3.1.1 loadplotdemo

The `loadplotdemo` demo loads a modified Photomodeler text export file of the 60-camera, 26000-point project used in Börlin and Grussenmeyer (2013a). The camera network, as computed by Photomodeler, is plotted with camera 1 aligned to the cardinal axes. The result should look like Figure 1.

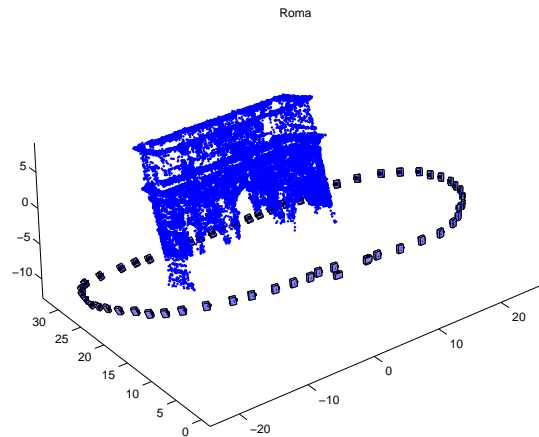


Figure 1: The figure generated by the `loadplotdemo` demo.

3.1.2 `loadplotdemo2`

The `loadplotdemo2` demo loads a modified Photomodeler text export file of a 21-camera, 100-point camera calibration project. The camera network, as computed by Photomodeler, is plotted and should look like Figure 2.

3.1.3 `romabundledemo`

3.1.4 `camcaldemo`

3.2 Using your own data

3.2.1 Enabling text export from Photomodeler

Some versions of Photomodeler do not have the text file export option enabled by default. In that case, follow the following steps to enable it:

1. Right-click on the main window toolbar, select *Customize toolbar...*
2. In the *Commands* tab, select the *File* category.
3. Drag the *Export Text File...* command to a toolbar of your choice.
4. Now you should be able to export your project as a text file by clicking on the *Export Text File* button.

3.2.2 Export from Photomodeler

To import a Photomodeler project into the toolbox, the following steps are valid in Photomodeler Scanner 2012:

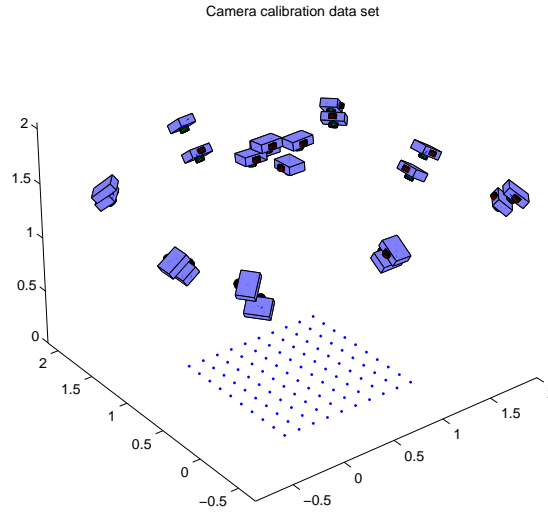


Figure 2: The figure generated by the `loadplotdemo2` demo.

1. Export the project using *Export Text File*. If the *Export Text File* command is not available, follow the instructions in Section 3.2.1.
2. After export, open the *Project/Cameras...* dialog and select the camera that was used in your project.
3. Open the generated text file in a text editor.
 - (a) On the 2nd line (usually reading `0.00005 20`), append the width and height in pixels of your images, e.g. to `0.000500 20 5616 3744`.
 - (b) Inspect the 4th line. For instance, the original data in `roma.txt` was (some trailing zeros removed):
`24.3581 18.1143 12.0 35.96404 24.0 0.00022 -0.0 0.0 0.0 0.0`
 The values correspond to the following camera parameters:
`focal pp_x pp_y format_w format_h K1 K2 K3 P1 P2`.
 Notice that most of the significant digits of `K1–K3` were lost in the text export.
 - (c) Update the parameter values on the 4th line with values from the camera dialog *for each parameter with a larger number of significant digits in the dialog*. This usually means all parameters except `format_w`. In the `roma.txt` test case, the 4th line was modified to:
`24.3581 18.1143 12 35.96404 24 2.174e-4 -1.518e-7 0 0 0`.

3.2.3 Loading into Matlab

1. In matlab, run step 3 from Section 2 if not already done.

2. Set the variable `fName` to the text export file name `fName='c:/path/to/exported/file.txt';`, or select it using `[f,p]=uigetfile('*.txt');` `fName=[f,p];`
3. Run the `loadplotdemo` script. A figure with your camera network, aligned with the first camera and rotated to have +Z 'up', should now have been generated.

References

- N. Börlin and P. Grussenmeyer. Bundle adjustment with and without damping. *Photogrammetric Record*, 28(144):396–415, Dec. 2013a. doi: 10.1111/phor.12037.
- N. Börlin and P. Grussenmeyer. Experiments with metadata-derived initial values and linesearch bundle adjustment in architectural photogrammetry. *ISPRS Annals of the Photogrammetry, Remote Sensing, and Spatial Information Sciences*, II-5/W1:43–48, Sept. 2013b.

A Camera model