$$\begin{aligned} & v = v^x \boldsymbol{e_x} + v^y \boldsymbol{e_y} + v^z \boldsymbol{e_z} \\ & \boldsymbol{A} = A^x \boldsymbol{e_x} + A^y \boldsymbol{e_y} + A^z \boldsymbol{e_z} \\ & \boldsymbol{v} \cdot \nabla = v^x \frac{\partial}{\partial x} + v^y \frac{\partial}{\partial y} + v^z \frac{\partial}{\partial z} \\ & \nabla^2 = \frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2} + \frac{\partial^2}{\partial z^2} \\ & \boldsymbol{v} \cdot \nabla f = v^x \partial_x f + v^y \partial_y f + v^z \partial_z f \\ & \nabla^2 f = \partial_x^2 f + \partial_y^2 f + \partial_z^2 f \\ & \nabla^2 \boldsymbol{A} = \left(\partial_x^2 A^x + \partial_y^2 A^x + \partial_z^2 A^x\right) \boldsymbol{e_x} + \left(\partial_x^2 A^y + \partial_y^2 A^y + \partial_z^2 A^y\right) \boldsymbol{e_y} + \left(\partial_x^2 A^z + \partial_y^2 A^z + \partial_z^2 A^z\right) \boldsymbol{e_z} \\ & \bar{\nabla} \cdot \boldsymbol{v} = v^x \frac{\partial}{\partial x} + v^y \frac{\partial}{\partial y} + v^z \frac{\partial}{\partial z} \\ & \boldsymbol{X} \cdot \nabla = x \frac{\partial}{\partial x} + y \frac{\partial}{\partial y} + z \frac{\partial}{\partial z} \\ & \bar{\boldsymbol{X}} \cdot \nabla = x \frac{\partial}{\partial x} + y \frac{\partial}{\partial y} + z \frac{\partial}{\partial z} \\ & \boldsymbol{X} \cdot \nabla - \bar{\nabla} \cdot \boldsymbol{X} = -3 \\ & \nabla^2 = \nabla \cdot \nabla = \frac{2}{r} \frac{\partial}{\partial r} + \frac{\partial^2}{\partial r^2} + \frac{1}{r^2 \tan(\theta)} \frac{\partial}{\partial \theta} + r^{-2} \frac{\partial^2}{\partial \theta^2} + \frac{1}{r^2 \sin^2(\theta)} \frac{\partial^2}{\partial \phi^2} \\ & (\nabla^2) f = \frac{1}{r^2} \left(r^2 \partial_r^2 f + 2r \partial_r f + \partial_\theta^2 f + \frac{\partial_\theta f}{\tan(\theta)} + \frac{\partial_\phi^2 f}{\sin^2(\theta)} \right) \\ & \nabla \cdot (\nabla f) = \frac{1}{r^2} \left(r^2 \partial_r^2 f + 2r \partial_r f + \partial_\theta^2 f + \frac{\partial_\theta f}{\tan(\theta)} + \frac{\partial_\phi^2 f}{\sin^2(\theta)} \right) \end{aligned}$$

 $X = xe_x + ye_y + ze_z$