

$$\text{General Instantiation: } A = \left\{ \begin{array}{l} L(e_x) = A_{xx}e_x + A_{yx}e_y + A_{zx}e_z \\ L(e_y) = A_{xy}e_x + A_{yy}e_y + A_{zy}e_z \\ L(e_z) = A_{xz}e_x + A_{yz}e_y + A_{zz}e_z \end{array} \right\}$$

$$\text{Rotor: } R = \cos\left(\frac{\theta}{2}\right) + \sin\left(\frac{\theta}{2}\right)e_x \wedge e_y$$

$$\text{Rotor Instantiation: } B = \left\{ \begin{array}{l} L(e_x) = \cos(\theta)e_x - \sin(\theta)e_y \\ L(e_y) = \sin(\theta)e_x + \cos(\theta)e_y \\ L(e_z) = e_z \end{array} \right\}$$

$$\text{Dictionary} = \{e_x : e_y + e_z, \quad e_y : e_x + e_z, \quad e_z : e_y + e_z\}$$

$$\text{Dictionary Instantiation: } C = \left\{ \begin{array}{l} L(e_x) = 0 \\ L(e_y) = 0 \\ L(e_z) = 0 \end{array} \right\}$$

$$\text{List} = [[1, 0, 1], [0, 1, 0], [1, 0, 1]]$$

$$\text{List Instantiation: } D = \left\{ \begin{array}{l} L(e_x) = e_x + e_z \\ L(e_y) = e_y \\ L(e_z) = e_x + e_z \end{array} \right\}$$

$$\text{List} = [e_y + e_z, \quad e_x + e_z, \quad e_x + e_y]$$

$$\text{List Instantiation: } E = \left\{ \begin{array}{l} L(e_x) = e_y + e_z \\ L(e_y) = e_x + e_z \\ L(e_z) = e_x + e_y \end{array} \right\}$$