

MANAGING DATA







LEARNING OBJECTIVES

- Learn about the buffer/accessor model and USM for managing data
- Learn how to use these
- Learn how to use data in a kernel function
- Learn how to synchronize data

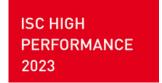






MEMORY MODELS

- In SYCL there are two models for managing data:
 - The buffer/accessor model.
 - The USM (unified shared memory) model.
- Which model you choose can have an effect on how you enqueue kernel functions.











- SYCL separates the storage and access of data
 - A SYCL buffer manages data across the host and any number of devices
 - A SYCL accessor requests access to data on the host or on a device for a specific SYCL kernel function
- Accessors are also used to access data within a SYCL kernel function
 - This means they are declared in the host code but captured by and then accessed within a SYCL kernel function





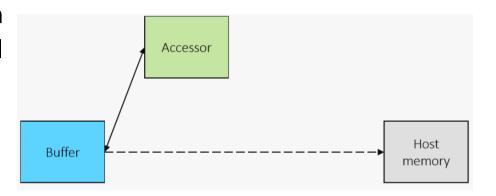
- A SYCL buffer can be constructed with a pointer to host memory
- For the lifetime of the buffer this memory is owned by the SYCL runtime
- When a buffer object is constructed it will not allocate or copy to device memory at first
- This will only happen once the SYCL runtime knows the data needs to be accessed and where it needs to be accessed







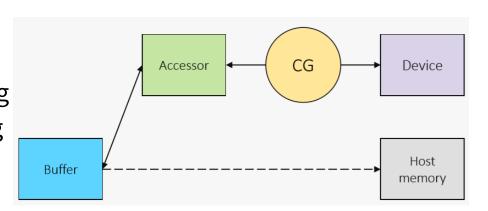
- Constructing an accessor specifies a request to access the data managed by the buffer
- There are a range of different types of accessor which provide different ways to access data







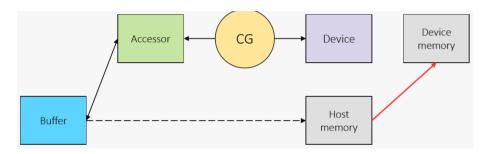
- When an accessor is constructed it is associated with a command group via the handler object
- This connects the buffer that is being accessed, the way in which it's being accessed and the device that the command group is being submitted to







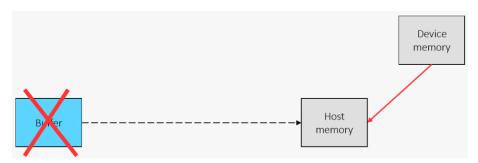
- Once the SYCL scheduler selects the command group to be executed it must first satisfy its data dependencies
- This means allocating and copying data to the device the data is being accessed on if necessary
- If the most recent copy of the data is already on the device then the runtime will not copy again







- Data will remain in device memory after kernels finish executing until another command group requests access in a different device or on the host
- When the buffer object is destroyed it will wait for any outstanding work that is accessing the data to complete and then copy back to the original host memory









```
template <typename dataT, int dimensions>
sycl::buffer;
```

- A buffer manages data across the host application and kernel functions executing on device(s).
- It has a typename which specifies the type of the elements of data it manages.
- It has a dimensionality which specifies the dimensionality that the elements of data are represented in.







CONSTRUCTING A BUFFER

```
int var = 42;
auto buf = sycl::buffer{&var, sycl::range{1}};
```

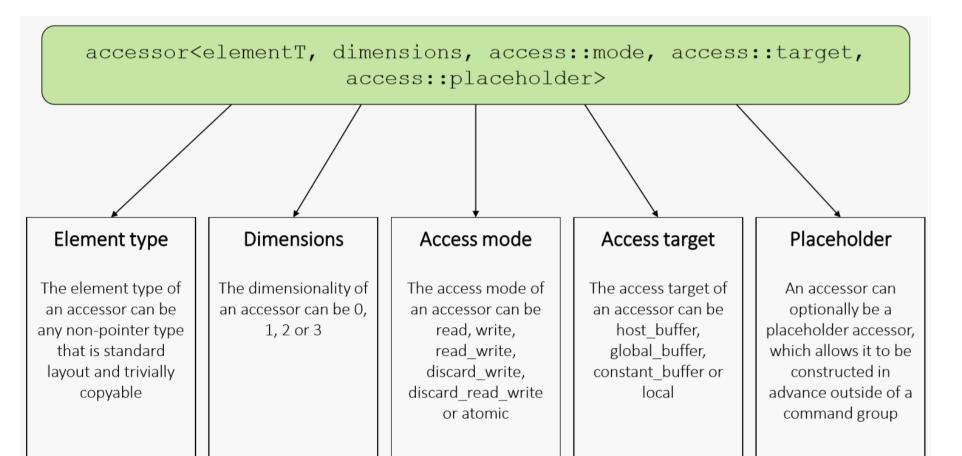
- A buffer can be constructed from a pointer to data for it to manage and a range which describes the number of elements of data.
- Using CTAD the type and the dimensionality can be inferred.







ACCESSOR CLASS







ACCESSOR CLASS

- There are many different ways to use the accessor class.
 - Accessing data on a device.
 - Accessing data immediately in the host application.
 - Allocating local memory.
- For now we are going to focus on accessing data on a device.







CONSTRUCTING AN ACCESSOR

```
auto acc = sycl::accessor{bufA, cgh};
```

- There are many ways to construct an accessor.
- The accessor class supports CTAD so it's not nessesary to specify all of the template arguments.
- The most common way to construct an accessor is from a buffer and a handler associated with the command group function you are within.
 - The element type and dimensionality are infered from the buffer.
 - The access::target is defaulted to access::target::global_buffer.
 - The access::mode is defaulted to access::mode::read write.



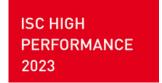




SPECIFYING THE ACCESS MODE

```
auto readAcc = sycl::accessor{bufA, cgh, sycl::read_only};
auto writeAcc = sycl::accessor{bufB, cgh, sycl::write_only};
```

- When constructing an accessor you will likely also want to specify the access::mode
- You can do this by passing one of the CTAD tags:
 - read_only will result in access::mode::read.
 - write_only will result in access::mode::write.







SPECIFYING NO INITIALIZATION

```
auto acc = sycl::accessor{buf, cgh, sycl::no_init};
```

- When constructing an accessor you may also want to discard the original data of a buffer.
- You can do this by passing the no_init property.







ACCESS MODES

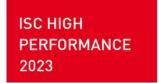
- A read accessor instructs the SYCL runtime that the SYCL kernel function will read the data – cannot be written to within a SYCL kernel function.
- A write accessor instructs the SYCL runtime that the SYCL kernel function will modify the data – creating a dependency for future command groups.
- A **no_init** accessor instructs the SYCL runtime that the SYCL kernel function does not need the initial values of the data removing the dependency on previous command groups.





ACCESSOR RESOLUTION

- If a command group has more than one accessor to the same buffer with conflicting access: mode they are resolved into one:
 - read & write => read_write.
- If a command group has more than one accessor to the same buffer all must have the no_init property for it to apply.
- Within the SYCL kernel function there are still multiple accessors, but they alias to the same memory address.







```
SYCL<sub>TM</sub>
```

gpuQueue.submit([&](handler &cgh) {
 auto in = sycl::accessor{buf, cgh, sycl::read_only};
 auto out = sycl::accessor{buf, cgh, sycl::write_only};
});

- Here in and out both point to buf but one is
 - access::mode::read and
 one is access::mode::write.
- So the SYCL runtime will treat them both as
 - access::mode::read_write.
- Both will point to a single allocation of global memory on the device(s).
- The runtime will resolve the data dependency into access::mode::read write.









```
gpuQueue.submit([&](handler &cgh) {
  auto inA = sycl::accessor{bufA, cgh, sycl::read_only};
  auto inB = sycl::accessor{bufB, cgh, sycl::read_only};
  auto out = sycl::accessor{bufO, cgh, sycl::write_only};
  cgh.single_task<add>([=] {
    out[0] = inA[0] + inB[0];
  });
});
```

- As well as specifying data dependencies an accessor can also be used to access the data from within a kernel function.
- You can do this by calling operator[] on the accessor.
 - This operator can take an id or a size_t.







USM MODEL

- There are different ways USM memory can be allocated; host, device and shared.
- We're going to focus on shared and device allocations.







USM ALLOCATION TYPES

Туре	Description	Accessible on host?	Accessible on device?	Located on
device	Allocations in device memory	×	✓	device
host	Allocations in host memory	✓	>	host
shared	Allocations shared between host and device	√	√	Can migrate between host and device

Figure 6-1. USM allocation types

(from book)









```
void* malloc_device(size_t numBytes, const queue& syclQueue, const property_list &propList = {});
template <typename T>
T* malloc_device(size_t count, const queue& syclQueue, const property_list &propList = {});
```

- A USM device allocation is performed by calling one of the malloc_device functions.
- Both of these functions allocate the specified region of memory on the device associated with the specified queue.
- The pointer returned is only accessible in a kernel function running on that device.
- Synchronous exception if the device does not have aspect::usm_device_allocations.
- This is a blocking operation.
- Calls the underlying cudaMalloc if using CUDA backend.







MALLOC_SHARED

```
void* malloc_shared(size_t numBytes, const queue& syclQueue, const property_list &propList = {});
template <typename T>
T* malloc_shared(size_t count, const queue& syclQueue, const property_list &propList = {});
```

- Both of these functions allocate the specified region of memory on the device associated with the specified queue, as well as host.
- The pointer returned is accessible in CPU code as well as device kernel code, for the device attached to the queue.
- Synchronous exception if the device does not have aspect::usm_device_allocations
- This is a blocking operation.
- Calls the underlying cudaMallocManaged if using CUDA backend.
- Convenient API but potentially slower than malloc_device with explicit memcpys.









void free(void* ptr, queue& syclQueue);

- In order to prevent memory leaks USM device allocations must be free by calling the free function.
- The queue must be the same as was used to allocate the memory.
- This is a blocking operation.









event queue::memcpy(void* dest, const void* src, size_t numBytes, const std::vector &depEvents);

- Data can be copied to and from a USM device allocation by calling the queue's memcpy member function.
- The source and destination can be either a host application pointer or a USM device allocation.
- This is an asynchronous operation enqueued to the queue.
- An event is returned which can be used to synchronize with the completion of copy operation.
- May depend on other events via depEvents









```
event queue::memset(void* ptr, int value, size_t numBytes, const std::vector &depEvents);
event queue::fill(void* ptr, const T& pattern, size_t count, const std::vector &depEvents);
```

- The additional queue member functions memset and fill provide operations for initializing the data of a USM device allocation.
- The member function memset initializes each byte of the data with the value interpreted as an unsigned char.
- The member function fill initializes the data with a recurring pattern.
- These are also asynchronous operations.









Code_Exercises/Exercise_03_Scalar_Add

Implement a SYCL application that adds two variables and returns the result using USM and Buffers.

