HANDLING ERRORS AND DEBUGGING

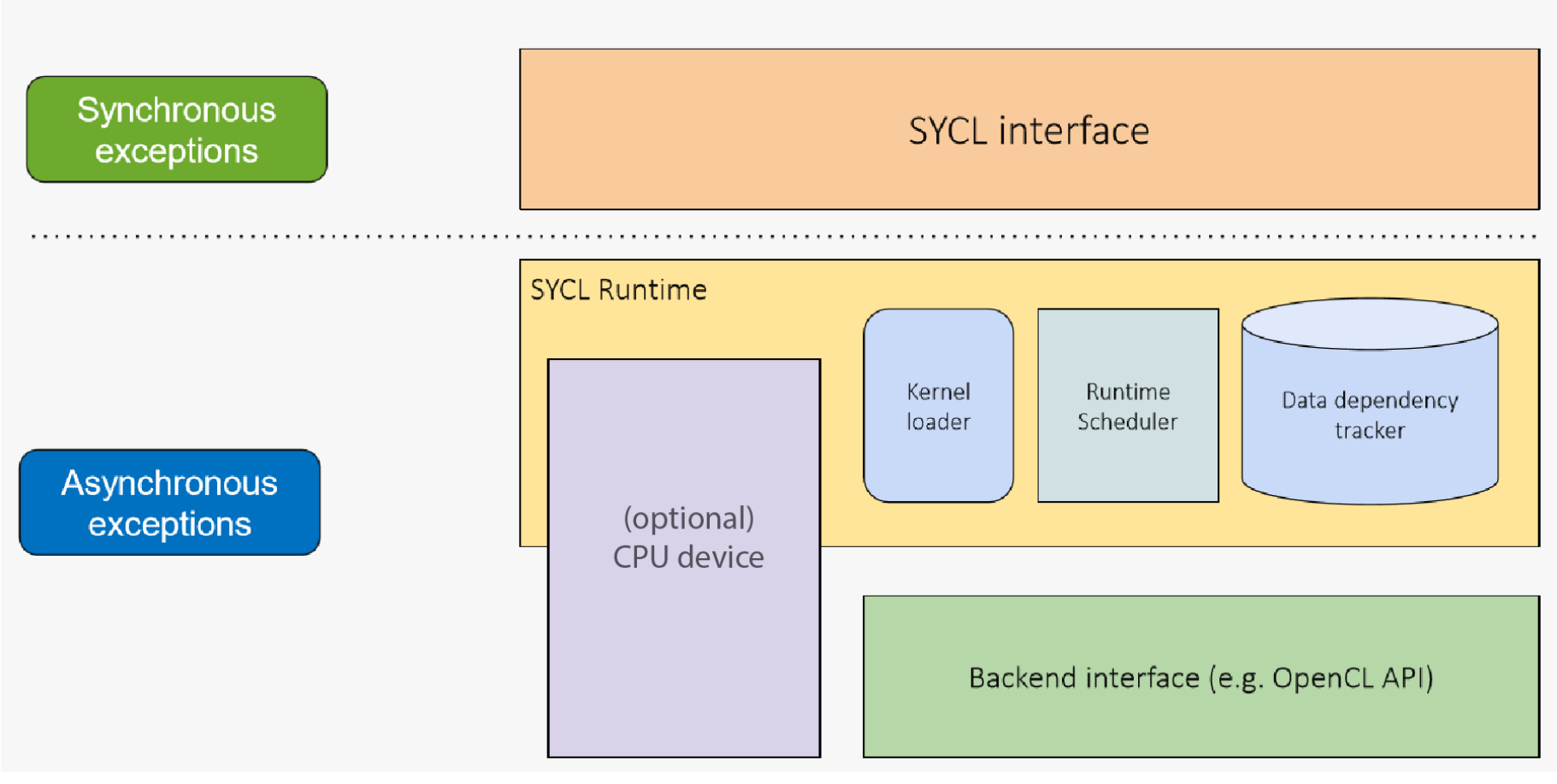
LEARNING OBJECTIVES

- Learn about how SYCL handles errors
- Learn about the difference between synchronous and asynchronous exceptions
- Learn how to handle exceptions and retrieve further information
- Learn about the host device and how to use it

SYCL EXCEPTIONS

- In SYCL errors are handled by throwing exceptions.
- It is crucial that these errors are handled, otherwise your application could fail in unpredictable ways.
- In SYCL there are two kinds of error:
    - Synchronous errors (thrown in user thread) .
    - Asynchronous errors (thrown by the SYCL scheduler).

SYCL EXCEPTIONS



HANDLING ERRORS

```
class add;

int main() {
  std::vector<float> dA{ 7, 5, 16, 8 }, dB{ 8, 16, 5, 7 }, dO{ 0, 0, 0, 0 };
    queue gpuQueue(gpu_selector{});
    buffer bufA{dA};
    buffer bufB{dB};
    buffer bufO{dO};

    gpuQueue.submit([&](handler &cgh) {
      auto inA = accessor{bufA, cgh, read_only};
      auto inB = accessor{bufB, cgh, read_only};
      auto out = accessor{bufO, cgh, write_only};

      cgh.single_task<add>(bufO.get_range(), [=](id<1> i) {
        out[i] = inA[i] + inB[i];
      });
    }).wait();
}
```

- If errors are not handled, the application can fail:
  - SYCL 1.2.1 application will fail silently.
  - SYCL 2020 provides a default async handler that will call `std::terminate` when an asynchronous error is thrown.

```
class add;

int main() {
  std::vector<float> dA{ 7, 5, 16, 8 }, dB{ 8, 16, 5, 7 }, dO{ 0, 0, 0, 0 };
  try {
    queue gpuQueue(gpu_selector{});

    buffer bufA{dA};
    buffer bufB{dB};
    buffer bufO{dO};

    gpuQueue.submit([&](handler &cgh) {
          auto inA = accessor{bufA, cgh, read_only};
      auto inB = accessor{bufB, cgh, read_only};
      auto out = accessor{bufO, cgh, write_only};

      cgh.single_task<add>(bufO.get_range(), [=](id<1> i) {
        out[i] = inA[i] + inB[i];
      });
    }).wait();

  } catch (...) { /* handle errors */ }
}
```

- Synchronous errors are typically thrown by SYCL API functions.
- In order to handle all SYCL errors you must wrap everything in a try-catch block.

```
class add;

int main() {
  std::vector<float> dA{ 7, 5, 16, 8 }, dB{ 8, 16, 5, 7 }, dO{ 0, 0, 0, 0 };
  try{
    queue gpuQueue(gpu_selector{}, async_handler{});

    buffer bufA{dA};
    buffer bufB{dB};
    buffer bufO{dO};

    gpuQueue.submit([&](handler &cgh) {
          auto inA = accessor{bufA, cgh, read_only};
      auto inB = accessor{bufB, cgh, read_only};
      auto out = accessor{bufO, cgh, write_only};

      cgh.single_task<add>(bufO.get_range(), [=](id<1> i) {
        out[i] = inA[i] + inB[i];
      });
    }).wait();

    gpuQueue.throw_asynchronous();
  } catch (...) { /* handle errors */
}
```

```
class add;

int main() {
  std::vector<float> dA{ 7, 5, 16, 8 }, dB{ 8, 16, 5, 7 }, dO{ 0, 0, 0, 0 };
  try{
    queue gpuQueue(gpu_selector{}, [=](exception_list eL) {
      for (auto e : eL) { std::rethrow_exception(e); }
    });

    buffer bufA{dA};
    buffer bufB{dB};
    buffer bufO{dO};

    gpuQueue.submit([&](handler &cgh) {
          auto inA = accessor{bufA, cgh, read_only};
      auto inB = accessor{bufB, cgh, read_only};
      auto out = accessor{bufO, cgh, write_only};

      cgh.single_task<add>(bufO.get_range(), [=](id<1> i) {
        out[i] = inA[i] + inB[i];
      });
    }).wait();

    gpuQueue.throw_asynchronous();
  } catch (...) { /* handle errors */ }
}
```

```
int main() {
  std::vector<float> dA{ 7, 5, 16, 8 }, dB{ 8, 16, 5, 7 }, dO{ 0, 0, 0, 0 };
  try {
    queue gpuQueue(gpu_selector{}, [=](exception_list eL) {
      for (auto e : eL) { std::rethrow_exception(e); }
    });

    ...

    gpuQueue.throw_asynchronous();
  } catch (const std::exception& e) {
    std::cout << "Exception caught: " << e.what()
     << std::endl;
  }
}
```

- Once rethrown and caught, a SYCL exception can provide information about the error
- The `what` member function will return a string with more details

```
int main() {
  std::vector<float> dA{ 7, 5, 16, 8 }, dB{ 8, 16, 5, 7 }, dO{ 0, 0, 0, 0 };
  try {
    queue gpuQueue(gpu_selector{}, [=](exception_list eL) {
      for (auto e : eL) { std::rethrow_exception(e); }
    });

    ...

    gpuQueue.throw_asynchronous();
  } catch (const sycl::exception& e) {
    std::cout << "Exception caught: " << e.what();
    std:: cout << " With OpenCL error code: "
     << e.get_cl_code() << std::endl;
  }
}
```

- In SYCL 1.2.1, if the exception has an OpenCL error code associated with it this can be retrieved by calling the `get_cl_code` member function
- If there is no OpenCL error code this will return `CL_SUCCESS`
- SYCL 2020 provides the `error_category_for` templated free function that allows checking for the category of the exception depending on the backend used (e.g. `backend::opencl`), and `e.code().value()` will correspond to the backend error code.

```
int main() {
  std::vector<float> dA{ 7, 5, 16, 8 }, dB{ 8, 16, 5, 7 }, dO{ 0, 0, 0, 0 };

  queue gpuQueue(gpu_selector{}, [=](exception_list eL) {
    for (auto e : eL) { std::rethrow_exception(e); }
  });
  context gpuContext = gpuQueue.get_context();

  try {
  ...
    gpuQueue.wait_and_throw();
  } catch (const sycl::exception& e) {
    if (e.has_context()) {
      if (e.get_context() == gpuContext) {
        /* handle error */
      }
    }
  }
}
```

- The `has_context` member function will tell you if there is a SYCL context associated with the error
- If that returns true then the `get_context` member function will return the associated SYCL context object

EXCEPTION TYPES

- In SYCL 1.2.1 there are a number of different exception types that inherit from `std::exception`
    - E.g. `runtime_error`, `kernel_error`
- SYCL 2020 only has a single `sycl::exception` type which provides different error codes
    - E.g. `errc::runtime`, `errc::kernel`

DEBUGGING SYCL KERNEL FUNCTIONS

- Every SYCL 1.2.1 implementation is required to provide a host device
  - This device executes native C++ code but is guaranteed to emulate the SYCL execution and memory model
- This means you can debug a SYCL kernel function by switching to the host device and using a standard C++ debugger
  - For example gdb

- SYCL 2020 only guarantees that a device will always be available, and users can query the `host_debuggable` device aspect to check whether they can use the same functionality as the SYCL 1.2.1 host device

```
class add;

int main() {
  std::vector<float> dA{ 7, 5, 16, 8 }, dB{ 8, 16, 5, 7 }, dO{ 0, 0, 0, 0 };
  try{
    queue hostQueue(aspect_selector<aspect::host_debuggable>(), async_handler{});

    buffer bufA{dA};
    buffer bufB{dB};
    buffer bufO{dO};

    hostQueue.submit([&](handler &cgh) {
          auto inA = accessor{bufA, cgh, read_only};
      auto inB = accessor{bufB, cgh, read_only};
      auto out = accessor{bufO, cgh, write_only};

      cgh.single_task<add>(bufO.get_range(), [=](id<1> i) {
        out[i] = inA[i] + inB[i];
      });
    });
    hostQueue.wait_and_throw();
  } catch (...) { /* handle errors */ }
}
```

QUESTIONS

EXERCISE

Code_Exercises/Exercise_4_Handling_Errors/source

Add error handling to a SYCL application for both synchronous and asynchronous errors.