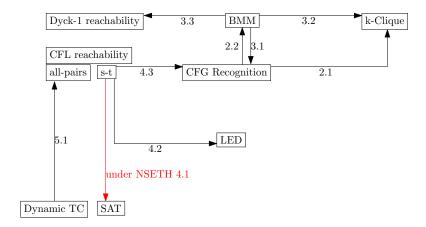
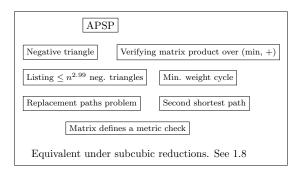
#### Reduction map





 $A \to B \iff$  B has reduction to A  $\longrightarrow$  – no reduction

hypothesis

#### 1. Problem definitions

1.1. **CFG recognition:** given a CFG  $\mathcal{G}$  and a string  $w \in \Sigma^*$  determine if w can be obtained from G (i.e. whether  $w \in \mathcal{L}(\mathcal{G})$ )

Best upper bound [12]:  $\mathcal{O}(n^{\omega} \cdot |\mathcal{G}|^2)$ 

Best combinatorial algorithms:  $\mathcal{O}(n^3/\log^3 n)$ 

**CFG parsing problem:** if  $w \in \mathcal{L}(\mathcal{G})$ , output a possible derivation sequence.

CFG recognition is as hard as CFG parsing up to logarithmic factors [11].

- 1.2. CFL reachability: given a CFG  $\mathcal{L}$  and a labelled graph G
- 1.3. **k-Clique:** decide whether a given undirected unweighted graph on n nodes and  $\mathcal{O}(n^2)$  edges contains a clique on k nodes.

It is a parameterized version of the NP-hard Max-Clique problem.

- 1.4. **SAT.**
- 1.4.1. k-SAT:. Given a k-CNF formula  $\phi$  on n variables. Is there an assignment to the variables that satisfies  $\phi$ ?
- 1.4.2. ETH (Exponential time hypothesis): There is no algorithm that solves k-SAT in time  $2^{o(n)}$  for any k.

- 1.4.3. SETH (Strong exponential time hypothesis): There is no  $\epsilon > 0$  such that k-SAT can be solved in time  $2^{(1-\epsilon)n}$  for any k.
- 1.4.4. NSETH (Nondeterministic strong exponential time hypothesis): There is no  $\epsilon > 0$  such that k-SAT can be solved in time  $2^{(1-\epsilon)n}$  co-nondeterministically for any k.
- 1.5. **BMM.** Given two  $n \times n$  matrices A, B over  $\{0, 1\}$ , Boolean Matrix Multiplication (BMM) is  $(AB)[i, j] = \bigvee_{k=1}^{n} (A(i, k) \wedge B(k, j))$ .

Note that BMM can be computed using an algorithm for integer matrix multiplication in  $\mathcal{O}(n^{\omega})$  time. Still, no combinatorial  $\mathcal{O}(n^{3-\epsilon})$  algorithm is known.

- 1.5.1. BMM conjecture [2]. In the Word RAM model with words of  $\mathcal{O}(\log n)$  bits, any combinatorial algorithm requires  $n^{3-o(1)}$  time in expectation to compute the boolean product of two  $n \times n$  matrices.
- 1.6. **LED.** Given a string  $w \in \Sigma^*$  and a context-free grammar  $\mathcal{G}$  defined over the same alphabet, how many minimum number of repairs (insertions, deletions and substitutions) are required to map w into a valid member of  $\mathcal{G}$ ?
- 1.7. **3SUM.** Determine whether a set  $S \subset \{-n^3, \dots, n^3\}$  of |S| = n integers contains three distinct elements  $a, b, c \in S$  with a + b = c.
- 1.7.1. 3SUM conjecture. In the Word RAM model with words of  $\mathcal{O}(\log n)$  bits, any algorithm requires  $n^{2-o(1)}$  time in expectation to solve 3SUM problem.

#### 1.8. Triangle detection.

1.8.1. Triangle conjecture. There is a constant  $\delta > 0$ , such that in the Word RAM model with words of  $\mathcal{O}(\log n)$  bits, any algorithm requires  $m^{1+\delta-o(1)}$  time in expectation to detect whether an m edge graph contains a triangle.

#### 1.9. APSP (all pairs shortest paths) and others [13]:

- The all-pairs shortest paths problem on weighted digraphs (APSP).
- Detecting if a weighted graph has a triangle of negative total edge weight.
- Listing up to  $n^{2.99}$  negative triangles in an edge-weighted graph.
- Finding a minimum weight cycle in a graph of non-negative edge weights.
- The replacement paths problem on weighted digraphs.
- Finding the second shortest simple path between two nodes in a weighted digraph.
- Checking whether a given matrix defines a metric.
- Verifying the correctness of a matrix product over the (min, +)-semiring (distance product).
- 1.9.1. APSP conjecture. There is a constant c, such that in the Word RAM model with words of  $\mathcal{O}(\log n)$  bits, any algorithm requires  $n^{3-o(1)}$  time in expectation to compute the distances between every pair of vertices in an n node graph with edge weights in  $\{1, \ldots, n^c\}$ .
- 1.9.2. Negative Triangles Over Structures. The negative triangle problem over  $\mathcal{R}$  is defined on a weighted tripartite graph with parts I, J, K. Edge weights between I and J are from  $\mathbb{Z}$ , and all other edge weights are from  $\mathcal{R}$ . The problem is to detect if there are  $i \in I, j \in J, k \in K$  so that  $(w(i, k) \odot w(k, j)) + w(i, j) < 0$ . Note that if one negates all weights of edges between I and J, the condition becomes  $(w(i, k) \odot (k, j)) < w(i, j)$ .

In the special case when  $\bigcirc = +$  and  $\mathcal{R} \subseteq \mathbb{Z} \cup \{--\infty, \infty\}$ , the tripartiteness requirement is unnecessary, and the negative triangle problem is defined on an arbitrary graph with edge weights from  $\mathbb{Z} \cup \{--\infty, \infty\}$ . This holds for the negative triangle problem over both the (min, +) and Boolean semirings.

Note that detecting and finding one negative triangle in a graph problems reduce one to another:

**Lemma** (Folklore). Let T(n) be a function so that  $\frac{T(n)}{n}$  is nondecreasing. If there is a T(n) time algorithm for negative triangle detection over  $\mathcal{R}$  on a graph  $G = (I \cup J \cup K, E)$ , then there is an  $\mathcal{O}(T(n))$  algorithm which returns a negative triangle over  $\mathcal{R}$  in G if one exists.

#### 2. To CFG recongnition

# 2.1. From k-Clique problem [1]:

Summary:  $T(n) \Rightarrow \mathcal{O}(T(n^{k/3+1})) (|G| = \mathcal{O}(1))$ 

## 2.2. From BMM [7]:

Summary:  $\mathcal{O}(|G| \cdot n^{3-\epsilon}) \Rightarrow \mathcal{O}(m^{3-\epsilon/3})$  ( $|G| = \Omega(n^6)!$ ), combinatorial reduction

## 3. To BMM

#### 3.1. From CFG recognition [12]:

Summary:  $\mathcal{O}(n^{\omega}) \Rightarrow \mathcal{O}(n^{\omega})$ 

#### 3.2. From k-Clique [9], [6]:

Summary:  $\mathcal{O}(n^{\omega}) \Rightarrow \mathcal{O}(n^{i+\omega \cdot l}), k = 3 \cdot l + i, i = 0, 1, 2$ 

or  $\mathcal{O}(n^{\omega(\lfloor k/3 \rfloor, \lfloor (k-1)/3 \rfloor, \lfloor k/3 \rfloor)})$ , where  $\mathcal{O}(n^{\omega(r,s,t)})$  denotes the running time of the multiplication of an  $n^r \times n^s$  matrix by an  $n^s \times n^t$  matrix.

Note that detecting arbitrary k-vertex (induced or not) subgraph in n-vertex graph is of the same complexity as detecting k-clique [9].

#### 3.3. From Dyck-1 reachability [3], [8]:

Summary:  $\mathcal{O}(n^{\omega}) \Rightarrow \mathcal{O}(n^{\omega} \cdot \log^2 n)$ , combinatorial reduction [8]

Idea: find bell-shaped paths in  $\mathcal{O}(\log nn^{\omega})$  by getting  $\mathcal{O}(\log n)$  transitive closures; combine Dyck-1 path from bell-shaped paths: in each of  $\mathcal{O}(\log n)$  iterations we remove bell-shaped paths of height at most  $2^i, i = 1, \ldots, \log n$ .

or  $\mathcal{O}(n^{\omega}) \Rightarrow \mathcal{O}(n^{\omega} \cdot \log^3 n)$  in [3] via algebraic matrix encoding of flat Dyck1-Reachability to  $\mathcal{O}(\log n)$  AGMY matrix multiplications.

#### 4. To CFL reachability

## 4.1. To s-t reachability from SAT [5]:

Summary: subcubic certificates for CFL reachability (positive and negative), no reductions under NSETH from SAT (SETH) to CFL reachability.

Proof is based on the following lemma, where by instance  $(G, \lambda, s, t)$  of CFL reachability problem G is a graph,  $\lambda$  is edge-labelling function, s, t are vertices between which we search a path labelled with word from the language.

**Lemma.** Let  $(G, \lambda, s, t)$  be an instance of the CFL reachability problem. There is a linear-time reduction (in the bit-size of the input) to an instance  $(G', \lambda', s', t')$  of the Dyck-2 reachability problem.

4.2. To s-t reachability from LED. Naive reduction: build a path graph labelled with letters of w, add loops marked with every symbol of  $\Sigma$  on every vertex, add edges marked with every symbol of  $\Sigma$  and  $\epsilon$  between pairs of adjacent vertices. Make original edges of zero weight, edges with  $\Sigma$  and  $\epsilon$  symbols of positive weight (you can choose different weight-cost for different operations). Find path between end vertices marked with word formed from grammar with minimum weight.

# 4.3. To s-t reachability from CFG recognition [4]:

Summary:  $\mathcal{O}(n^{3-\epsilon}) \Rightarrow \mathcal{O}(n^{3-\epsilon})$ , combinatorial

**Lemma.** If there exists a combinatorial algorithm that solves the pair Dyck reachability problem in time T(n), where n is the number of nodes of the input graph, then there exists a combinatorial algorithm that solves the CFL parsing problem in time  $\mathcal{O}(n+T(n))$ .

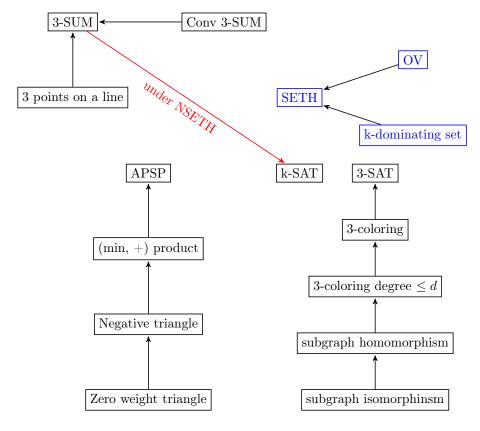
In combination with reduction to BMM we have:

**Theorem** (BMM-hardness: Conditional cubic lower bound). For any fixed  $\epsilon > 0$ , if there is a combinatorial algorithm that solves the pair Dyck reachability problem in  $\mathcal{O}(n^{3-\epsilon})$  time, then there is a combinatorial algorithm that solves Boolean Matrix Multiplication in  $\mathcal{O}(n^{3-\epsilon})$  time.

## 5. To Dynamic TC

# 5.1. From all-pairs CFL reachability [10]:

Summary:  $\mathcal{O}(n^{3-\epsilon}) \Rightarrow \mathcal{O}(n^{3-\epsilon})$ 



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