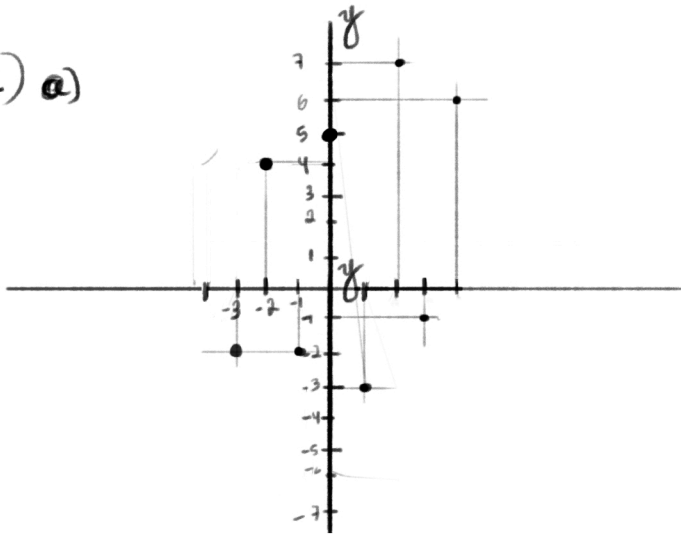


1) a)



$$b) A = \begin{bmatrix} 8 & 0,9893 & -0,038 \\ 0,9893 & 3,9336 & 0,8347 \\ -0,038 & 0,8347 & 7,1755 \end{bmatrix} \cdot \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 4 \\ 2,4768 \\ 28,3065 \end{bmatrix}$$

$$A = G^T \cdot G$$

$$A = \begin{bmatrix} 8 & 0,9893 & -0,038 \\ 0,9893 & 3,9336 & 0,8347 \\ -0,038 & 0,8347 & 7,1755 \end{bmatrix} = \begin{bmatrix} g_{11} & 0 & 0 \\ g_{21} & g_{22} & 0 \\ g_{31} & g_{32} & g_{33} \end{bmatrix} \cdot \begin{bmatrix} g_{11} & g_{12} & g_{13} \\ 0 & g_{22} & g_{23} \\ 0 & 0 & g_{33} \end{bmatrix}$$

$$\begin{matrix} g_{11} = 2,8284 & g_{22} = 1,7802 \\ g_{21} = 0,3497 & g_{32} = 0,4239 \\ g_{31} = -0,0134 & g_{33} = 2,6287 \end{matrix}$$

$$\therefore \vec{z} = \begin{bmatrix} 4,9497 \\ 0,3766 \\ 10,5324 \end{bmatrix}$$

$$\alpha = \begin{bmatrix} 1,8492 \\ -0,6515 \\ 3,9319 \end{bmatrix}$$

$$\phi_2(x) = 1,8492 - 0,6515 \sin(2x) + 3,9319(3x)$$

c)	k	x_k	y_k	$\phi(x_k)$	$\phi(x_k) - y_k$	$[\phi(x_k) - y_k]^2$
	1	-3	-2	-1,9153	0,0847	0,0072
	2	-2	4	5,1314	1,1314	1,2801
	3	-1	-2	-1,4509	0,5491	0,3015
	4	0	5	5,7811	0,7811	0,6101
	5	1	-3	-2,6257	0,3646	0,1327
	6	2	7	6,1175	-0,8825	0,7788
	7	3	-1	-1,5512	-0,5512	0,3038
	8	4	6	4,5226	-1,4774	2,1827

$$L_{r, \min} =$$

$$F_{\min} = \sum_{k=1}^8 [\phi(x_k) - y_k]^2 = 5,5970$$

$$2. a) \quad y = \frac{1}{\alpha_1 + \alpha_2 x + \alpha_3 x^2} \Rightarrow z = \frac{1}{y}, \quad z = \alpha_1 + \alpha_2 x + \alpha_3 x^2$$

$$g_1(x) = \begin{bmatrix} 1 \\ 1 \\ 1 \\ 1 \\ 1 \end{bmatrix}, \quad g_2(x) = \begin{bmatrix} -2 \\ -1 \\ 0 \\ 1 \\ 2 \end{bmatrix}, \quad g_3(x) = \begin{bmatrix} 4 \\ 1 \\ 0 \\ 1 \\ 4 \end{bmatrix}$$

$$A = \begin{bmatrix} \langle g_1, g_1 \rangle & \langle g_1, g_2 \rangle & \langle g_1, g_3 \rangle \\ \langle g_2, g_1 \rangle & \langle g_2, g_2 \rangle & \langle g_2, g_3 \rangle \\ \langle g_3, g_1 \rangle & \langle g_3, g_2 \rangle & \langle g_3, g_3 \rangle \end{bmatrix}, \quad b = \begin{bmatrix} \langle g_1, y \rangle \\ \langle g_2, y \rangle \\ \langle g_3, y \rangle \end{bmatrix}, \quad z = \begin{bmatrix} 4,7619 \\ 4,1666 \\ 5 \\ 8,3333 \\ 12,5 \end{bmatrix}$$

$$\Downarrow$$

$$A = \begin{bmatrix} 5 & 0 & 10 \\ 0 & 10 & 0 \\ 10 & 0 & 34 \end{bmatrix}, \quad b = \begin{bmatrix} 34,7613 \\ 19,6429 \\ 81,5475 \end{bmatrix}$$

$$\begin{bmatrix} 5 & 0 & 10 \\ 0 & 10 & 0 \\ 10 & 0 & 34 \end{bmatrix} \begin{bmatrix} \alpha_1 \\ \alpha_2 \\ \alpha_3 \end{bmatrix} = \begin{bmatrix} 34,7613 \\ 19,6429 \\ 81,5475 \end{bmatrix} \Rightarrow \alpha = \begin{bmatrix} 5,2347 \\ 1,9643 \\ 0,8588 \end{bmatrix}$$

$$z = 5,2347 + 1,9643x + 0,8588x^2$$

$$b) \quad l(x) = 5,2347 + 1,9643x + 0,8588x^2$$

k	x_k	y_k	z_k	$l(x_k)$	$l(x_k) - z_k$	$[l(x_k) - z_k]^2$
1	-2	0,21	4,7619	4,7413	-0,0206	0,0004
2	-1	0,24	4,1666	4,1292	-0,0375	0,0014
3	0	0,2	5	5,2347	0,2347	0,0551
4	1	0,12	8,3333	8,0548	-0,2785	0,0769
5	2	0,08	12,5	12,5485	0,0485	0,0047

$$E = \sum_{k=1}^5 [l(x_k) - z_k]^2 = 0,1425$$

c) O número de etapas foram aumentando pelo aumento de número de variáveis, ocasionando em uma incerteza maior. Portanto, não podemos afirmar que a erro quadrático é mínima.